

1 设单位负反馈系统的开环传递函数为：

$$G_0(s) = \frac{K}{s(0.1s + 1)(0.2s + 1)}$$

试设计一校正装置，使系统满足下列性能指标：

静态速度误差系数： $K_v = 30$

相角裕度： $\gamma \geq 40^\circ$

2 已知单位负反馈系统的开环传递函数

$$G(s) = \frac{K_0}{s(0.1s + 1)(0.001s + 1)}$$

试用频率法设计串联超前校正装置,

相角裕度: $\gamma \geq 45^\circ$

静态速度误差系数: $K_v = 1000s^{-1}$

练习讲解

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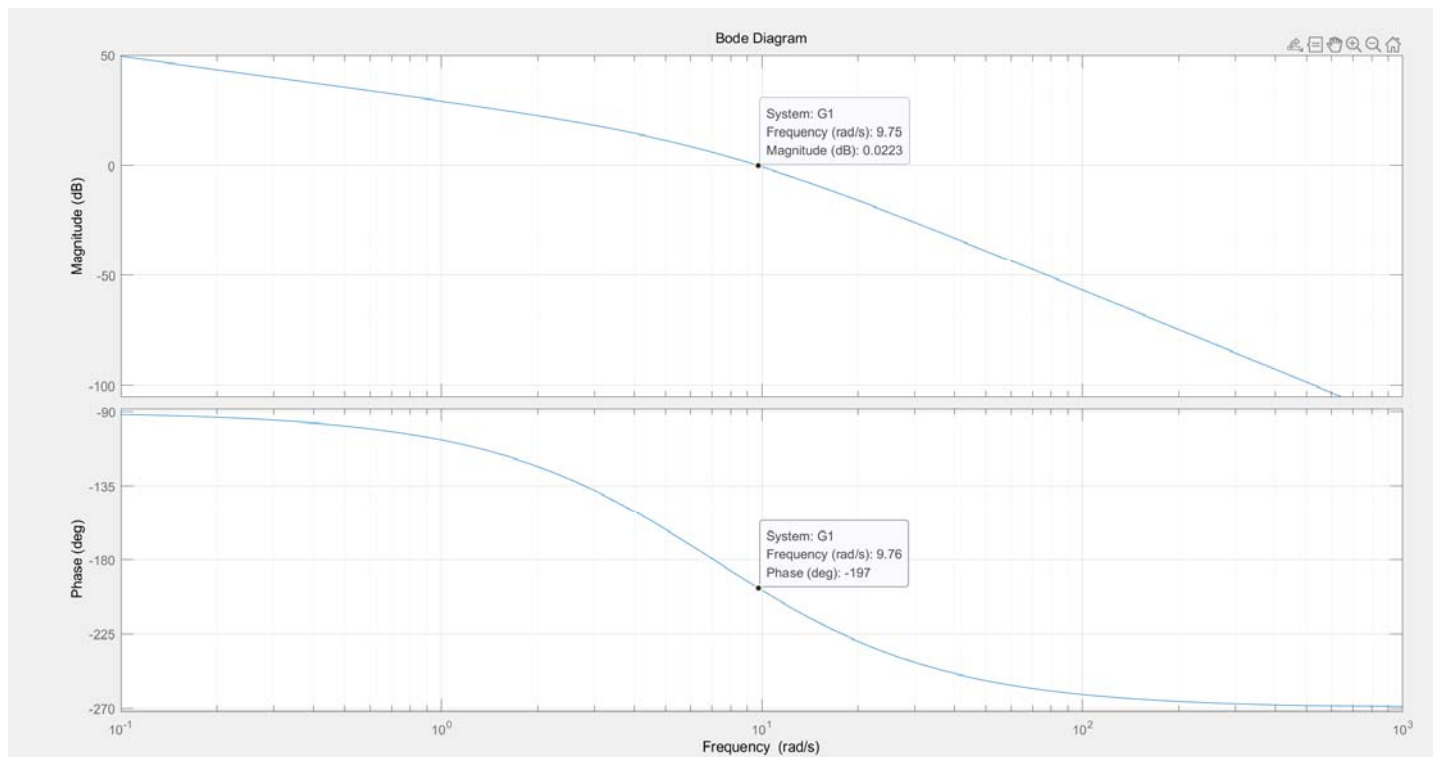
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$$G_0(s) = \frac{K}{s(0.1s + 1)(0.2s + 1)}$$

静态速度误差系数: $K_v = 30$

相角裕度: $\gamma \geq 40^\circ$

$$K = K_v = 30 \quad G_0(s) = \frac{30}{s(0.1s + 1)(0.2s + 1)}$$

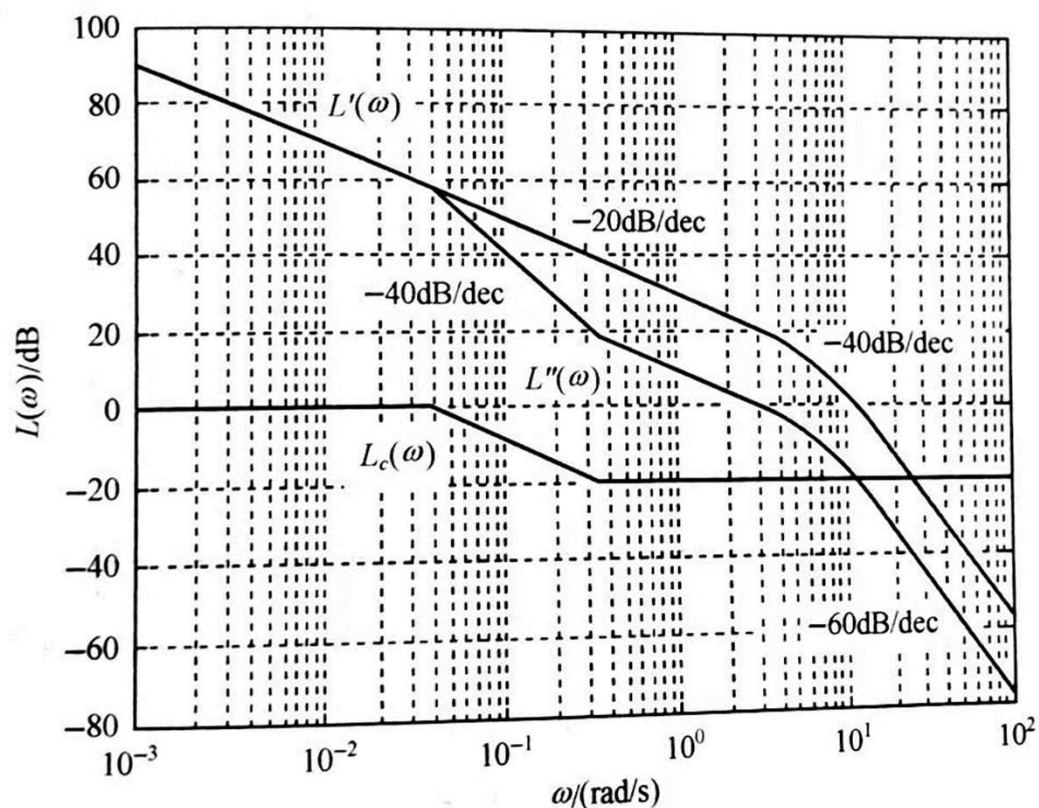


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截止频率: $\omega_c' = 11.45 \text{ rad/s}$

$$\gamma' = (180^\circ - 90^\circ - \arctan 0.1\omega_c' - \arctan 0.2\omega_c') \Big|_{\omega_c'=12.25} = -25.26^\circ$$

系统不稳定, 采用滞后校正



1

$$\varepsilon = 6^\circ$$

$$\gamma'(\omega_c'') = \gamma'' + \varepsilon = 46^\circ$$



$$\gamma'' = 90^\circ - \arctan 0.1\omega_c'' - \arctan 0.2\omega_c''$$



$$\omega_c'' = 2.74 \text{ rad} / \text{s}$$



$$L'(\omega_c'') = 20.79 \text{ dB}$$

$$20 \lg b = -L'(\omega_c'')$$



$$\frac{1}{bT} = 0.14\omega_c''$$

$$b = 0.1$$

$$T = 26.07$$

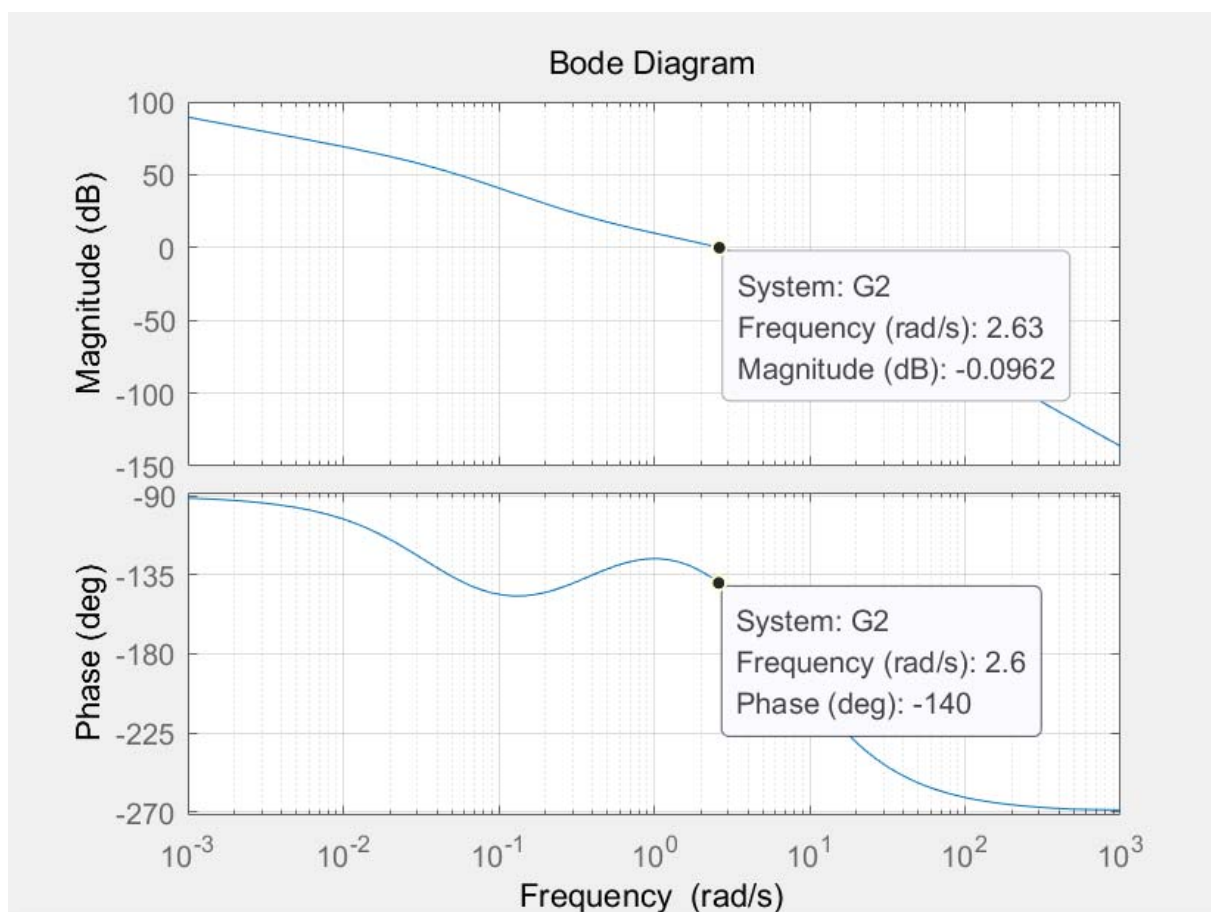
$$G_c(s) = \frac{1+bTs}{1+Ts} = \frac{1+2.61s}{1+26.07s}$$

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1 校验:

$$G_c(s) = \frac{1 + 2.61s}{1 + 26.07s} \quad G_c(s)G_0(s) = \frac{30(2.61s + 1)}{s(0.1s + 1)(0.2s + 1)(26.07s + 1)}$$



课堂练习_第六章

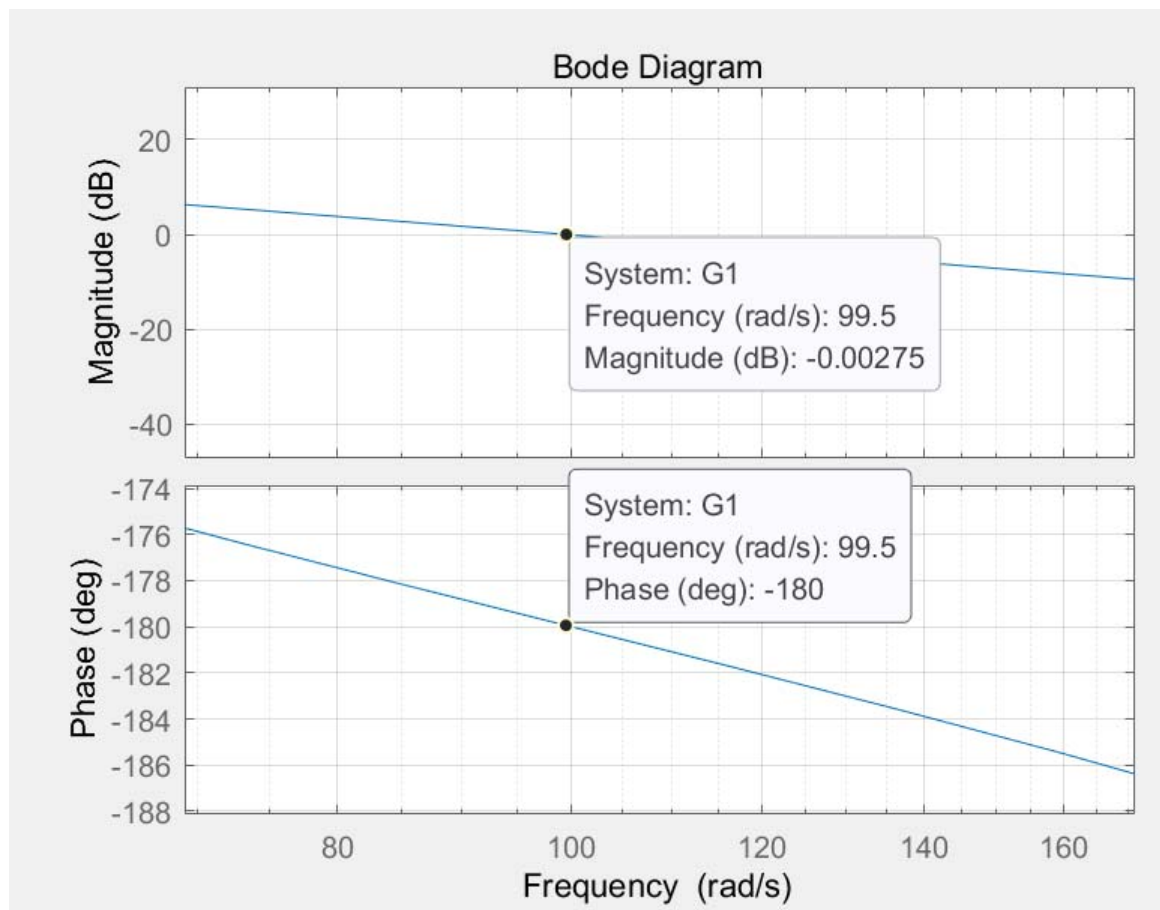
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2

$$G(s) = \frac{K_0}{s(0.1s + 1)(0.001s + 1)}$$

相角裕度: $\gamma \geq 45^\circ$

静态速度误差系数: $K_v = 1000s^{-1}$



2

$$G(s) = \frac{K_0}{s(0.1s + 1)(0.001s + 1)}$$

相角裕度: $\gamma \geq 45^\circ$

静态速度误差系数: $K_v = 1000s^{-1}$

超前校正传递函数: $G_c(s) = \frac{1 + \alpha Ts}{1 + Ts} (\alpha > 0)$



$$\varphi_m = \gamma - \gamma_0 + (5 \sim 10^\circ)$$

$$\varphi_m = \gamma + \Delta\varphi = 50^\circ$$



$$a = \frac{1 + \sin \varphi_m}{1 - \sin \varphi_m}$$

$$\omega_m = \frac{1}{\sqrt{a}T}$$

2

$$G(s) = \frac{K_0}{s(0.1s + 1)(0.001s + 1)}$$

相角裕度: $\gamma \geq 45^\circ$

静态速度误差系数: $K_v = 1000s^{-1}$

$$G_c(s) = \frac{0.01694s + 1}{0.002124s + 1}$$

