

4 绘制开环传递函数的极坐标幅相特性

$$G(s) = \frac{K}{s(16s^2 + 6.4s + 1)}$$

$$\begin{aligned} G(j\omega) &= \frac{K}{j\omega(-16\omega^2 + j6.4\omega + 1)} \\ &= -\frac{6.4K}{(1-16\omega^2)^2 + (6.4\omega)^2} - j\frac{(1-16\omega^2)K}{\omega[(1-16\omega^2)^2 + (6.4\omega)^2]} \end{aligned}$$

起点和终点

$$G(j0) = -6.4K - j\infty$$

$$G(j\infty) = 0$$

与实轴交点

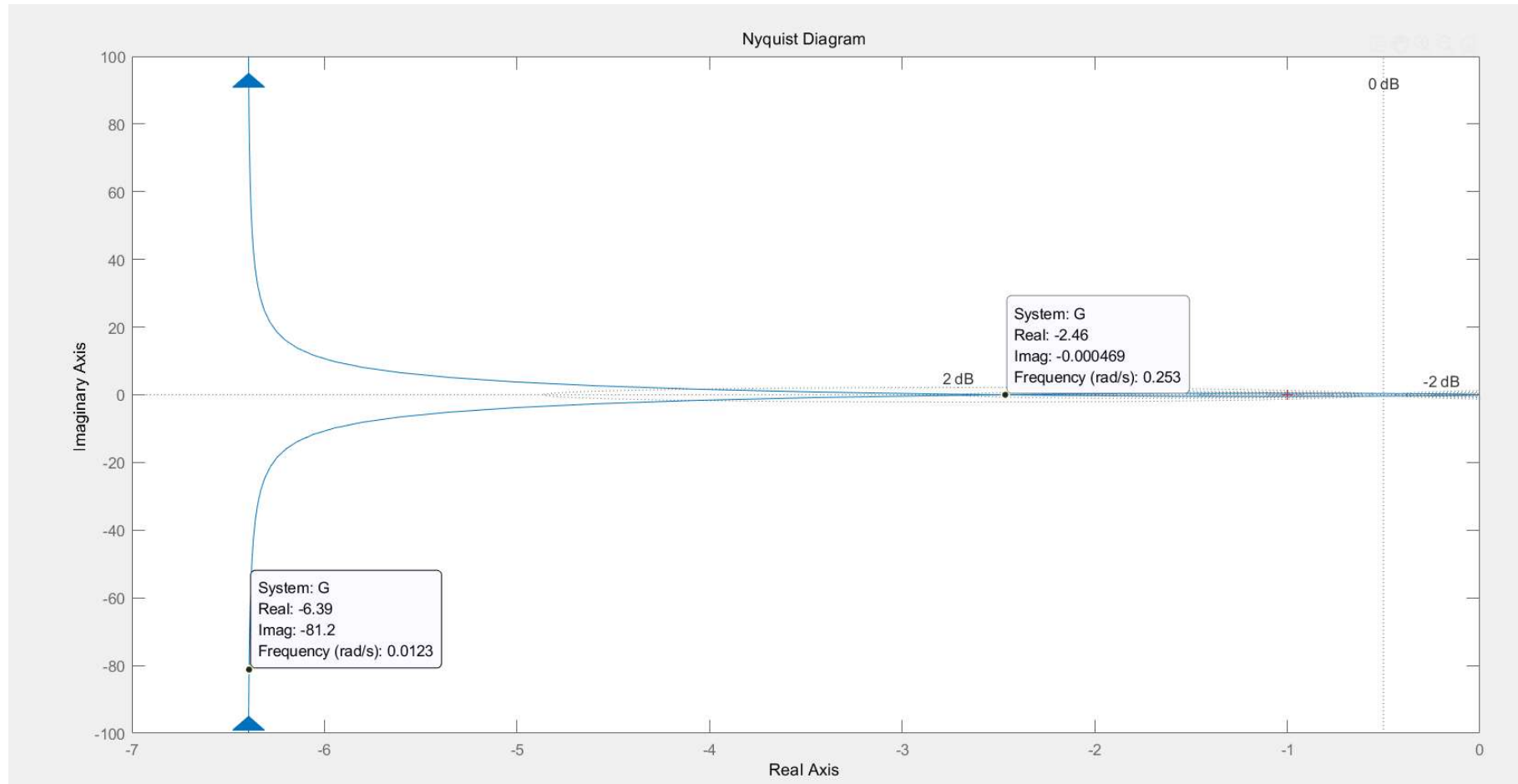
$$\text{Im}[G(j\omega)] = 0$$

$$\rightarrow \omega_x = 0.25, G(j\omega_x) = -2.5K$$

作业4讲解

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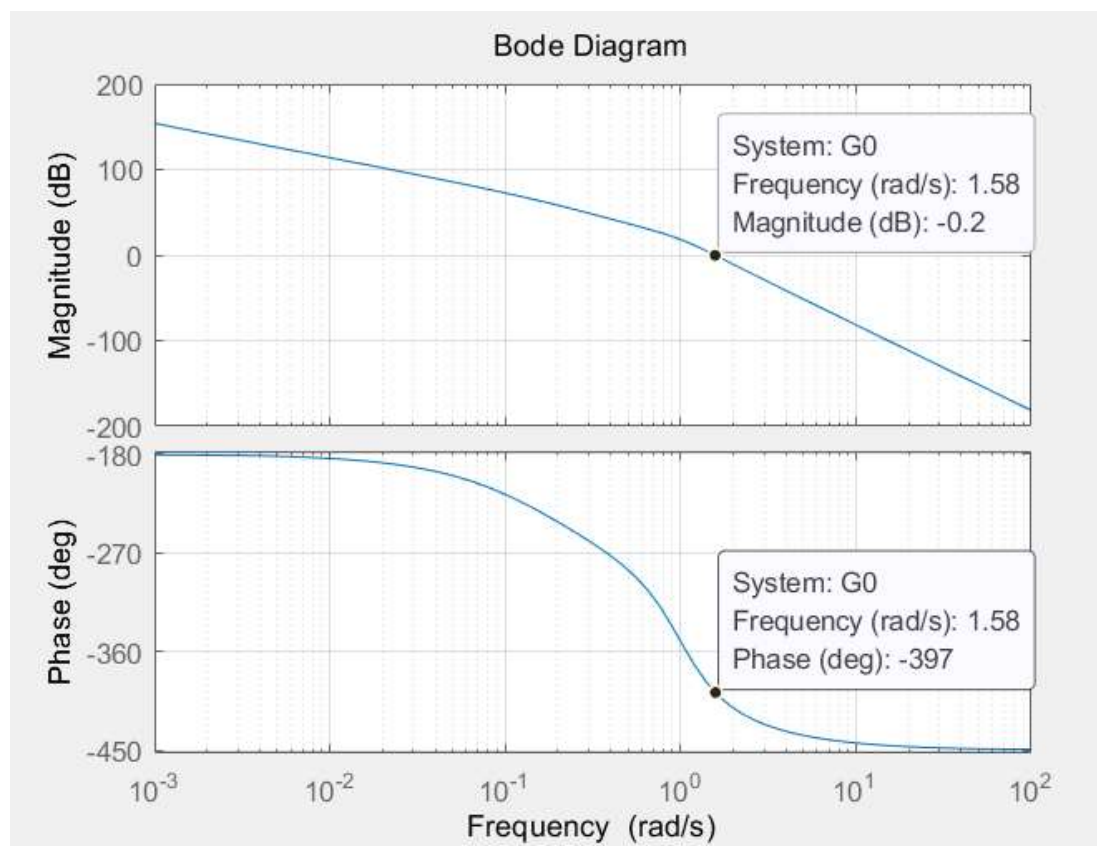
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绘制开环传递函数的博德图

$$G(s) = \frac{50}{s^2 (s^2 + s + 1)(6s + 1)}$$



- 6 设单位负反馈系统开环传递函数如下，要求设计一串联校正网络，使校正后的系统开环增益 $K = 5$ ，相角裕度不低于40度，幅值裕度不小于10dB

$$G(s) = \frac{K}{s(s+1)(0.5s+1)}$$

$k = 5$ 对于校正前的系统

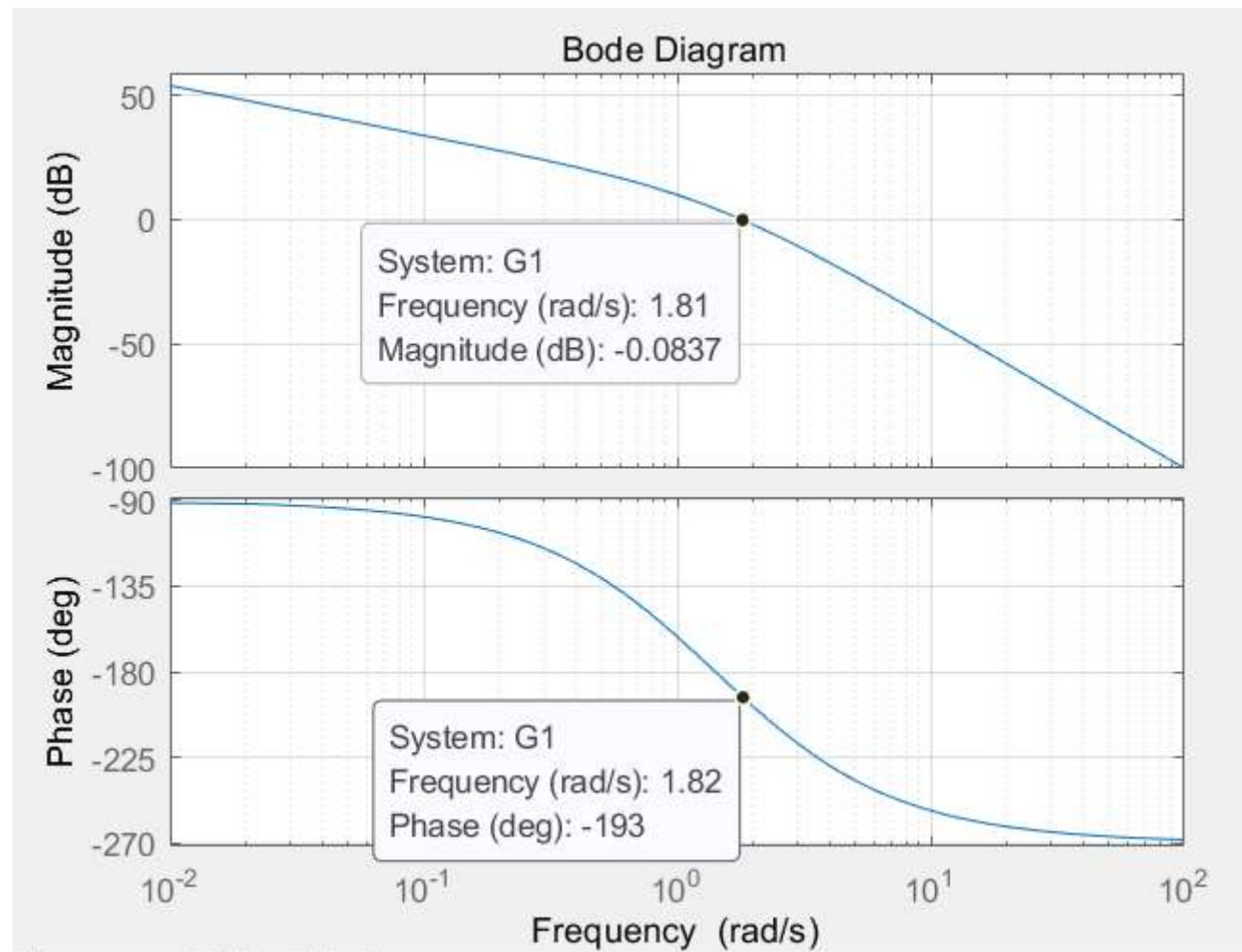
$$\text{令 } L(\omega)=0, \text{ 可得 } \omega_c = 2.1544$$

$$20\lg 5 = 40\lg 2 + 60\lg \frac{\omega_c}{2}$$

$$\gamma = 180^\circ - 90^\circ - \arctan \omega_c - \arctan(0.5\omega_c) = -22.23^\circ < \gamma^*$$

系统不稳定，选用滞后校正

未校正的系统



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$$\varphi(\omega_c'') = \gamma^* + 5^\circ = 45^\circ$$

$$-90^\circ - \arctan \omega_c'' - \arctan(0.5\omega_c'') = 45^\circ$$

$$\arctan \omega_c'' + \arctan(0.5\omega_c'') = 45^\circ$$

$$\omega_c'' = 0.5$$

$$20 \lg \beta + L(\omega_c'') = 0$$

$$\frac{1}{\beta T} = 0.1\omega_c''$$



$$\beta = \frac{1}{25}$$

$$T = 500$$

用渐近线简化,
也可以用准确值

$$G_c(s) = \frac{1 + \beta Ts}{1 + Ts} = \frac{1 + 20s}{1 + 500s}$$

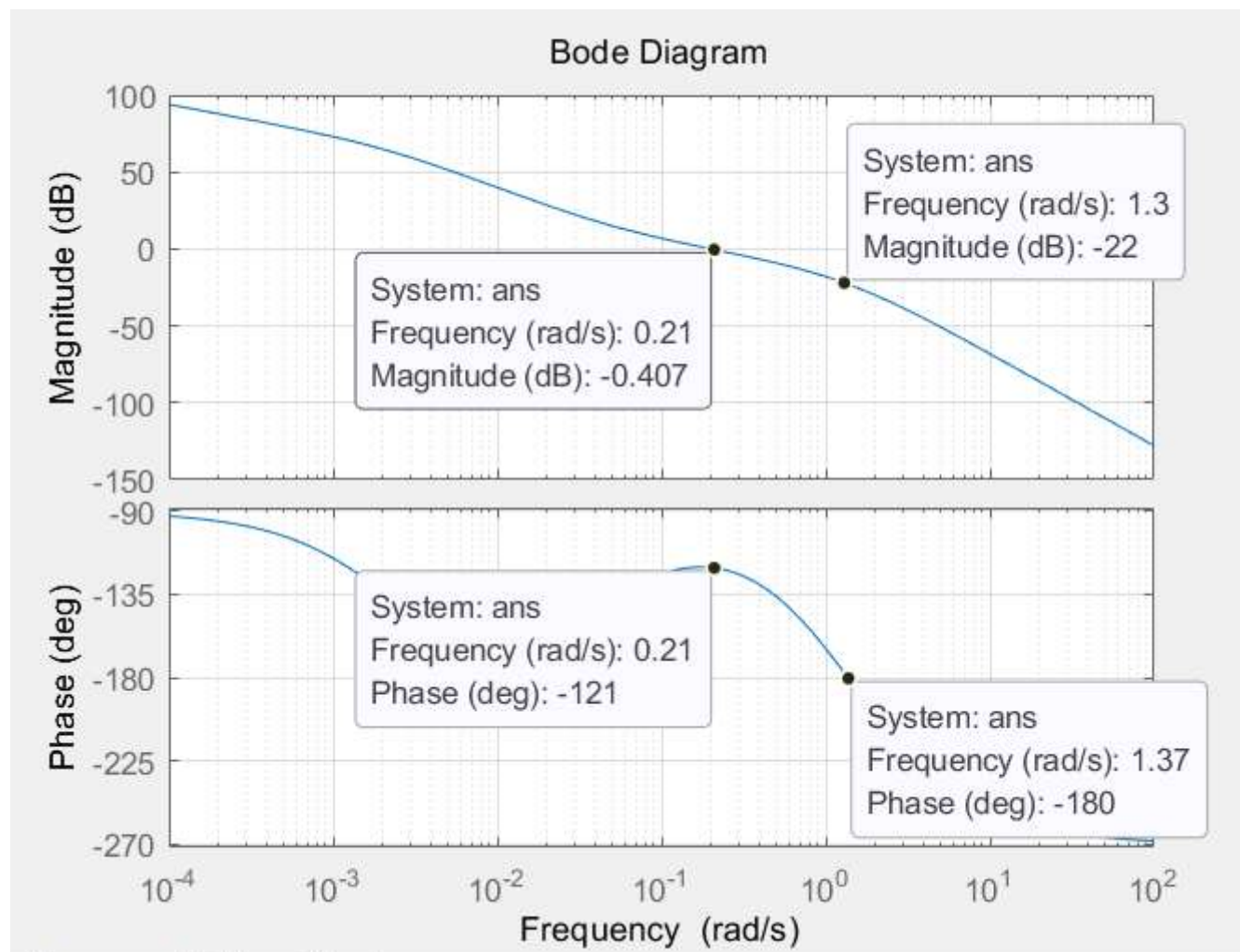
$$G'(s) = G(s)G_c(s) = \frac{5}{s(s+1)(0.5s+1)} \cdot \frac{1+20s}{1+500s}$$

$$\gamma'' = 180^\circ + \phi_c(\omega_c'') + \phi(\omega_c'')$$

$$= 180^\circ + \arctan(20\omega_c'') - \arctan(500\omega_c'') - 90^\circ - \arctan \omega_c'' - \arctan(0.5\omega_c'') = 44^\circ$$

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校正后的系统



偏差是由于渐近线引起