# **Material Summary: Working with Images**

# 1. Image Processing

### 1.1 Loading and Inspecting Images

- There are many ways to read an image
- One of the easiest is using scikit-image

```
from skimage.io import imread
tiger_image = imread("tiger.jpg")
```

Displaying the image

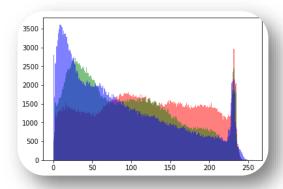
```
plt.imshow(tiger_image)
```

- The image is actually a matrix of pixels
  - Each pixel is an array of three values:  $R, G, B \in [0; 255]$
  - Grayscale images only have one value per pixel
- Most image processing algorithms are easier to understand on grayscale images

```
red = tiger_image[:, :, 0]
green = tiger_image[:, :, 1]
blue = tiger_image[:, :, 2]
```

### 1.2 Image Histogram

- As usual, histograms tell us how the values are distributed
- How many dark values, how many light values
- Maximum brightness, peaks, etc.



- Histograms need to have a single variable
  - Take each channel separately, e.g., red
  - Convert the 2D matrix to 1D array: image.ravel()
  - Show the histogram as usual
    - It's common to use 256 bins

```
plt.hist(red.ravel(), bins = 256, color = "red")
plt.show()
```

We can also plot all channels on a single histogram



## 1.3 Converting to Grayscale

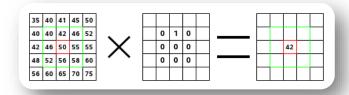
- Sometimes working per channel is not necessary
- We can combine all three channels and get a grayscale image
- Simplest way: get the mean of all values

- Better way: use coefficients for each channel
  - The human eye discerns colors differently
  - Were more sensitive to green colors
  - Some formulas are given here

- Depending on the image, the differences may or may not be easy to see
- For art purposes, we can experiment with our own coefficients for combining all channels

#### 1.4 Convolution

- Convolution kernel (filter)
  - A small, usually 3x3, matrix of numbers
- Convolution process
  - **Input**: image, kernel
  - Output: new image



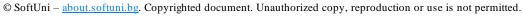
- Combining the image and a kernel:
  - Apply the kernel over each pixel
  - Multiply the values **element-wise** (Hadamard product)
  - Sum all values
  - Assign the sum to the corresponding pixel in the output image
    - Image corners are treated in different ways, not really important how
- The choice of kernel depends what the output image will represent

from scipy.ndimage.filters import convolve convolve(image, kernel)















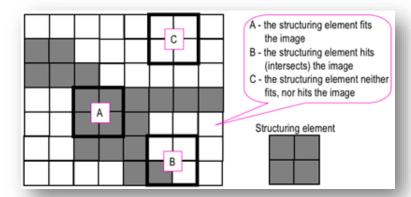


Example: **box blur** 

```
box_blur_kernel = np.array([
  [1, 1, 1],
  [1, 1, 1],
  [1, 1, 1]
1) / 9
blurred = convolve(tiger_grayscale, box_blur_kernel)
plt.imshow(tiger_grayscale[150:250, 300:400], cmap = "gray")
plt.show()
plt.imshow(blurred[150:250, 300:400], cmap = "gray")
plt.show()
```

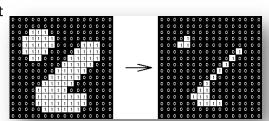
## 1.5 Image Morphology

- Four main operations (see this tutorial)
  - Dilation
  - **Erosion**
  - **Opening**
  - Closing
- A simple series of algorithms for image transformation
- Basic methodology
  - Choose a structuring element (e.g., 2x2 square or cross)
  - Move the element around the image
  - Apply an operation
- Input: binary image
  - Pixel values **0** and **1**, **not** [**0**; **255**]
  - This is called thresholding
- **Output:** transformed image

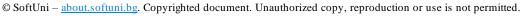


First get all values inside the structuring element

- Erosion: replace all values with the min value
  - Strips away a layer of pixels
  - Holes become larger
  - Small regions are eliminated
- Dilation: replace all values with the max value

















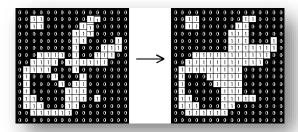
- Gaps become smaller
- Small gaps are filled in

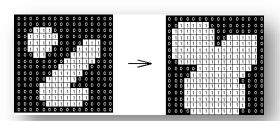
## Opening: erosion followed by dilation

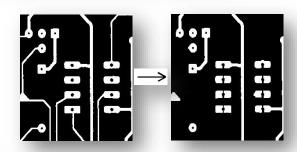
- Pixels which survived erosion are restored to their original size
- Opens up a gap between two objects connected by thin bridges

## Closing: dilation followed by erosion

Fills in holes in the regions while keeping the initial region sizes







## 1.6 Other Operations on Images

- Matrix operations pixel-wise
  - One image:
    - Addition, Gain, Negative
    - Resampling, Cutting
  - Transformations perspective, warp, etc.
  - Two (or more) images:
    - Addition (multiple exposure)
    - **Subtraction (difference)**
    - **Division (normalization)**
    - **Averaging**
- Thresholding (usually 2 levels)
- Fourier transform, filtering and convolution
- Contrast enhancement
- Histogram equalization
- Stacking (many **2D images** ⇒ **one 3D image**)
- Analysis:
  - Measurements, Segmentation, Object extraction / Identification
  - **Enhancements, Inpainting**



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