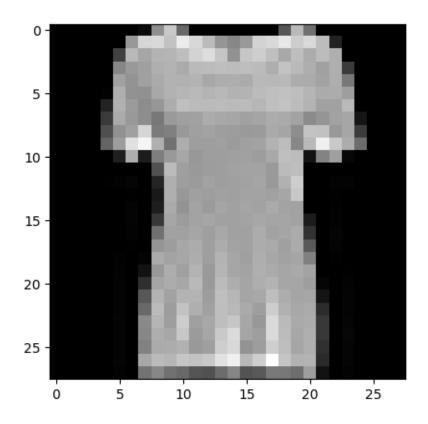
# hw 1

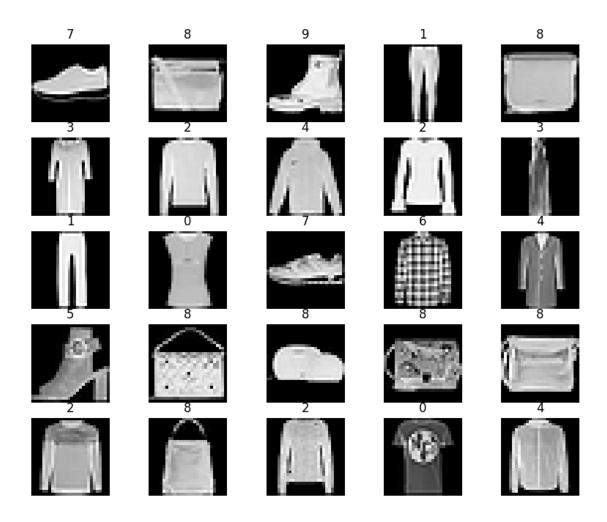
## May 11, 2025

```
[25]: import numpy as np
      import torch
      import torch.nn as nn
      import torch.optim as optim
      # PyTorch TensorBoard support
      # from torch.utils.tensorboard import SummaryWriter
      # import torchvision
      # import torchvision.transforms as transforms
      from datetime import datetime
      import torchvision
      import torchvision.transforms as transforms
      from torchvision.datasets import FashionMNIST
      import matplotlib.pyplot as plt
      %matplotlib inline
      from torch.utils.data import random_split
      from torch.utils.data import DataLoader
      import torch.nn.functional as F
      from PIL import Image
      #import torchvision.transforms as T
 []: # load the dataset
      fmnist_dataset = FashionMNIST(root = 'data/', download=True, train = True,__
       →transform = transforms.ToTensor())
      print(fmnist_dataset)
     Dataset FashionMNIST
         Number of datapoints: 60000
         Root location: data/
         Split: Train
         {\tt StandardTransform}
     Transform: ToTensor()
```

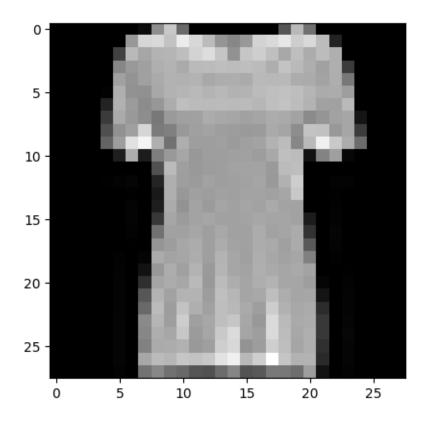
```
[]: # fmnist_dataset has 'images as tensors' so that they can't be displayed.
      \hookrightarrow directly
     sampleTensor, label = fmnist_dataset[10]
     print(sampleTensor.shape, label)
     tpil = transforms.ToPILImage() # using the __call__ to
     image = tpil(sampleTensor)
     image.show()
     # The image is now convert to a 28 X 28 tensor.
     # The first dimension is used to keep track of the color channels.
     # Since images in the MNIST dataset are grayscale, there's just one channel.
     # The values range from 0 to 1, with 0 representing black, 1 white and the \Box
     →values between different shades of grey.
     print(sampleTensor[:,10:15,10:15])
     print(torch.max(sampleTensor), torch.min(sampleTensor))
     plt.imshow(sampleTensor[0,:,:],cmap = 'gray')
    torch.Size([1, 28, 28]) 0
    tensor([[[0.6510, 0.5961, 0.6196, 0.6196, 0.6275],
              [0.6235, 0.6000, 0.6157, 0.6196, 0.6353],
              [0.6196, 0.6078, 0.6353, 0.6196, 0.6275],
              [0.5961, 0.6275, 0.6196, 0.6314, 0.6275],
              [0.5765, 0.6431, 0.6078, 0.6471, 0.6314]])
    tensor(1.) tensor(0.)
[]: <matplotlib.image.AxesImage at 0x7f2eb5120140>
```



```
[]: # Print multiple images at once
figure = plt.figure(figsize=(10, 8))
cols, rows = 5, 5
for i in range(1, cols * rows + 1):
    sample_idx = torch.randint(len(fmnist_dataset), size=(1,)).item()
    img, label = fmnist_dataset[sample_idx]
    figure.add_subplot(rows, cols, i)
    plt.title(label)
    plt.axis("off")
    plt.imshow(img.squeeze(), cmap="gray")
plt.show()
```



[29]: <matplotlib.image.AxesImage at 0x7f2eb58337a0>



## 0.1 Training and validation data

```
[]: train_data, validation_data = random_split(fmnist_dataset, [50000, 10000])
## Print the length of train and validation datasets
print("length of Train Datasets: ", len(train_data))
print("length of Validation Datasets: ", len(validation_data))

batch_size = 128
train_loader = DataLoader(train_data, batch_size, shuffle = True)
val_loader = DataLoader(validation_data, batch_size, shuffle = False)
## MNIST data from pytorch already provides held-out test set!
```

length of Train Datasets: 50000
length of Validation Datasets: 10000

## 0.2 Multi-class Logistic Regression (a building block of DNN)

```
# we gradually build on this inherited class from pytorch
model = nn.Linear(input_size, num_classes)
```

We define the class with multiple methods so that we can train, evaluate, and do many other routine tasks with the model.

Particularly, we are looking at multi-class logistic regression (a generalization of one-class logistic regression) using the softmax function (more about this in a few cells down)

```
[32]: # Slowly build the model, first with basic
      class MnistModel(nn.Module):
          def init (self):
              super().__init__()
              self.linear = nn.Linear(input_size, num_classes)
          def forward(self, xb):
              # view xb with two dimensions, 28 * 28(i.e 784)
              # One argument to .reshape can be set to -1(in this case the first_{\sqcup}
       \rightarrow dimension).
              # to let PyTorch figure it out automatically based on the shape of the
       ⇔original tensor.
              xb = xb.reshape(-1, 784)
              print(xb)
              out = self.linear(xb)
              print(out)
              return(out)
      model = MnistModel()
      print(model.linear.weight.shape, model.linear.bias.shape)
      list(model.parameters())
     torch.Size([10, 784]) torch.Size([10])
[32]: [Parameter containing:
       tensor([[ 0.0302, -0.0244, -0.0221, ..., -0.0354, -0.0011, -0.0191],
               [0.0059, -0.0298, -0.0335, ..., -0.0161, -0.0181, 0.0215],
               [0.0003, 0.0097, 0.0043, ..., 0.0126, 0.0231, -0.0112],
               [0.0083, 0.0251, 0.0005, ..., -0.0079, 0.0301, -0.0188],
               [0.0186, 0.0183, -0.0347, ..., -0.0200, 0.0312, 0.0024],
               [0.0249, 0.0170, -0.0062, ..., 0.0070, -0.0275, -0.0029]],
              requires_grad=True),
       Parameter containing:
       tensor([-0.0216, -0.0106, 0.0346, 0.0050, -0.0052, 0.0162, 0.0206, 0.0106,
                0.0218, -0.0220], requires_grad=True)]
[33]: # Alway check the dimensions and sample data/image
      for images, labels in train_loader:
```

```
outputs = model(images)
         break
      print('Outputs shape: ', outputs.shape) # torch.Size([128, 10])
      print('Sample outputs: \n', outputs[:2].data) # example outputs
     tensor([[0.0000, 0.0000, 0.0000, ..., 0.0000, 0.0000, 0.0000],
             [0.0000, 0.0000, 0.0000, ..., 0.0000, 0.0000, 0.0000],
             [0.0000, 0.0000, 0.0000, ..., 0.0000, 0.0000, 0.0000],
             [0.0000, 0.0000, 0.0000, ..., 0.0000, 0.0000, 0.0000],
             [0.0000, 0.0000, 0.0000, ..., 0.0039, 0.0000, 0.0000],
             [0.0000, 0.0000, 0.0000, ..., 0.0000, 0.0000, 0.0000]])
     tensor([[-0.2234, 0.2386, -0.0340, ..., 0.2979, 0.0118, -0.0658],
             [0.3455, -0.1725, 0.2791, ..., 0.3818, -0.0107, -0.2146],
             [0.4592, 0.1558, 0.0924, ..., 0.4541, 0.1828, 0.0899],
             [-0.1451, 0.3672, -0.1604, ..., 0.4152, 0.1399, 0.0320],
             [0.5077, 0.1205, 0.1281, ..., 0.2762, -0.1545, -0.0600],
             [0.2511, 0.1209, 0.2638, ..., 0.5946, 0.0303, -0.0083]],
            grad_fn=<AddmmBackward0>)
     Outputs shape: torch.Size([128, 10])
     Sample outputs:
      tensor([[-0.2234, 0.2386, -0.0340, -0.1299, 0.1609, 0.2886, 0.0154,
     0.2979,
               0.0118, -0.0658,
             [0.3455, -0.1725, 0.2791, -0.0059, -0.0450, 0.2795, 0.2659, 0.3818,
              -0.0107, -0.2146]])
     0.3 Softmax function
[34]: ## Apply softmax for each output row
      probs = F.softmax(outputs, dim = 1)
      ## chaecking at sample probabilities
      print("Sample probabilities:\n", probs[:2].data)
      # print(preds)
      # print("\n")
      # print(max_probs)
     Sample probabilities:
      tensor([[0.0745, 0.1183, 0.0900, 0.0818, 0.1094, 0.1243, 0.0946, 0.1255,
     0.0943,
              0.0872],
             [0.1238, 0.0737, 0.1158, 0.0871, 0.0838, 0.1159, 0.1143, 0.1283, 0.0867,
              0.0707]])
```

#### 0.4 Evaluation Metric and Loss Function

```
[35]: # accuracy calculation
    def accuracy(outputs, labels):
        _, preds = torch.max(outputs, dim = 1)
        return(torch.tensor(torch.sum(preds == labels).item()/ len(preds)))

print("Accuracy: ", accuracy(outputs, labels))
print("\n")
    loss_fn = F.cross_entropy
print("Loss Function: ",loss_fn)
print("\n")
## Loss for the current batch
loss = loss_fn(outputs, labels)
print(loss)
```

Accuracy: tensor(0.1641)

Loss Function: <function cross\_entropy at 0x7f2f26975d00>

tensor(2.3216, grad\_fn=<NllLossBackward0>)

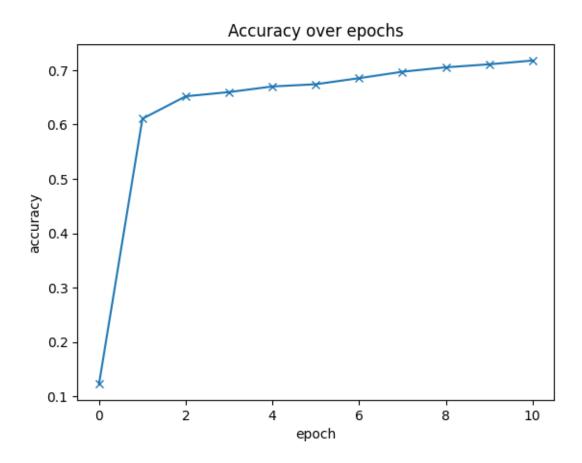
## 0.5 Cross-Entropy

```
[36]: # We put all of the above:
      class MnistModel(nn.Module):
          def __init__(self):
               super().__init__()
              self.linear = nn.Linear(input_size, num_classes)
          def forward(self, xb):
              xb = xb.reshape(-1, 784)
              out = self.linear(xb)
              return(out)
          # We add extra methods
          def training_step(self, batch):
               # when training, we compute the cross entropy, which help us update_{\sqcup}
       \hookrightarrow weights
              images, labels = batch
              out = self(images) ## Generate predictions
              loss = F.cross_entropy(out, labels) ## Calculate the loss
              return(loss)
          def validation_step(self, batch):
              images, labels = batch
```

```
out = self(images) ## Generate predictions
        loss = F.cross_entropy(out, labels) ## Calculate the loss
        # in validation, we want to also look at the accuracy
        # idealy, we would like to save the model when the accuracy is the
 \hookrightarrow highest.
        acc = accuracy(out, labels) ## calculate metrics/accuracy
        return({'val_loss':loss, 'val_acc': acc})
    def validation_epoch_end(self, outputs):
        # at the end of epoch (after running through all the batches)
        batch_losses = [x['val_loss'] for x in outputs]
        epoch_loss = torch.stack(batch_losses).mean()
        batch_accs = [x['val_acc'] for x in outputs]
        epoch_acc = torch.stack(batch_accs).mean()
        return({'val loss': epoch_loss.item(), 'val acc' : epoch_acc.item()})
    def epoch_end(self, epoch,result):
        # log epoch, loss, metrics
        print("Epoch [{}], val_loss: {:.4f}, val_acc: {:.4f}".format(epoch, ___

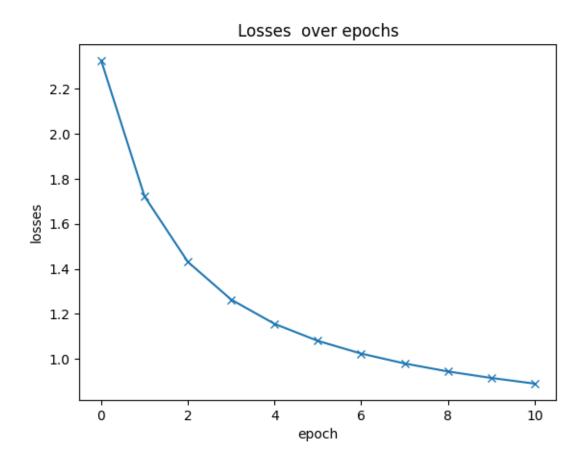
¬result['val_loss'], result['val_acc']))
# we instantiate the model
model = MnistModel()
# a simple helper function to evaluate
def evaluate(model, data_loader):
    # for batch in data loader, run validation step
    outputs = [model.validation_step(batch) for batch in data_loader]
    return(model.validation_epoch_end(outputs))
# actually training
def fit(epochs, lr, model, train_loader, val_loader, opt_func = torch.optim.
 ⇒SGD):
    history = []
    optimizer = opt_func(model.parameters(), lr)
    for epoch in range(epochs):
        ## Training Phase
        for batch in train loader:
            loss = model.training_step(batch)
            loss.backward() ## backpropagation starts at the loss and goes_
 →through all layers to model inputs
            optimizer.step() ## the optimizer iterate over all parameters_
 ⇔(tensors); use their stored grad to update their values
            optimizer.zero_grad() ## reset gradients
        ## Validation phase
        result = evaluate(model, val_loader)
```

```
model.epoch_end(epoch, result)
              history.append(result)
          return(history)
[37]: # test the functions, with a randomly initialized model (weights are random, e.
       \hookrightarrow g., untrained)
      result0 = evaluate(model, val_loader)
      result0
[37]: {'val_loss': 2.325157642364502, 'val_acc': 0.12321993708610535}
[38]: # let's train for 10 epochs
      history1 = fit(10, 0.001, model, train_loader, val_loader)
     Epoch [0], val loss: 1.7219, val acc: 0.6107
     Epoch [1], val_loss: 1.4309, val_acc: 0.6520
     Epoch [2], val loss: 1.2635, val acc: 0.6597
     Epoch [3], val_loss: 1.1558, val_acc: 0.6701
     Epoch [4], val_loss: 1.0801, val_acc: 0.6741
     Epoch [5], val_loss: 1.0237, val_acc: 0.6853
     Epoch [6], val_loss: 0.9798, val_acc: 0.6972
     Epoch [7], val_loss: 0.9444, val_acc: 0.7053
     Epoch [8], val_loss: 0.9155, val_acc: 0.7108
     Epoch [9], val_loss: 0.8904, val_acc: 0.7178
[39]: |# we combine the first result (no training) and the training results of 5_{\square}
       ⇔epoches
      # plotting accuracy
      history = [result0] + history1
      accuracies = [result['val_acc'] for result in history]
      plt.plot(accuracies, '-x')
      plt.xlabel('epoch')
      plt.ylabel('accuracy')
      plt.title('Accuracy over epochs')
[39]: Text(0.5, 1.0, 'Accuracy over epochs')
```



```
[40]: # plotting losses
history = [result0] + history1
losses = [result['val_loss'] for result in history]
plt.plot(losses, '-x')
plt.xlabel('epoch')
plt.ylabel('losses')
plt.title('Losses over epochs')
```

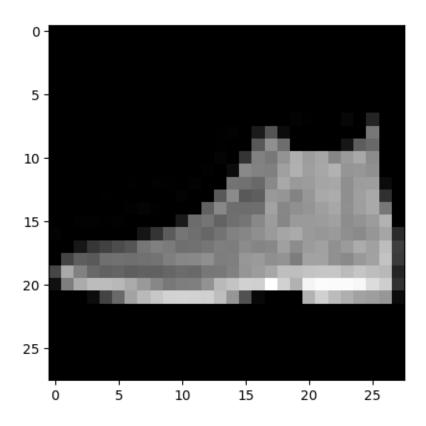
[40]: Text(0.5, 1.0, 'Losses over epochs')



## 0.6 Final check using the (held-out) test dataset.

We will first load the test dataset (from MNIST) and individually check the prediction made by the model. And then, we will put through all images in the test dataset to obtain the final accuracy

Shape: torch.Size([1, 28, 28])
Label: 9



```
[42]: def predict_image(img, model):
    xb = img.unsqueeze(0)
    yb = model(xb)
    _, preds = torch.max(yb, dim = 1)
    return(preds[0].item())

[43]: img, label = test_dataset[0]
    print('Label:', label, ', Predicted :', predict_image(img, model))

Label: 9 , Predicted : 9

[44]: # the final check on the test dataset (not used in any training)
    test_loader = DataLoader(test_dataset, batch_size = 256, shuffle = False)
    result = evaluate(model, test_loader)
    result

[44]: {'val_loss': 0.8996326327323914, 'val_acc': 0.708691418170929}
```

# 1 Convolutional Neural Network (CNN)

```
[45]: # We construct a fundamental CNN class.
      class CNN(nn.Module):
          def init (self):
              super(CNN, self).__init__()
              self.conv1 = nn.Sequential(
                  nn.Conv2d(
                      in_channels=1,
                      out_channels=16,
                      kernel_size=5,
                      stride=1,
                      padding=2,
                  ),
                  nn.ReLU(),
                  nn.MaxPool2d(kernel_size=2),
              )
              self.conv2 = nn.Sequential(
                  nn.Conv2d(16, 32, 5, 1, 2),
                  nn.ReLU(),
                  nn.MaxPool2d(2),
              # fully connected layer, output 10 classes
              self.out = nn.Linear(32 * 7 * 7, 10)
          def forward(self, x):
              x = self.conv1(x)
              x = self.conv2(x)
              # flatten the output of conv2 to (batch_size, 32 * 7 * 7)
              x = x.view(x.size(0), -1)
              output = self.out(x)
              return output, x # return x for visualization
      cnn = CNN()
      print(cnn)
     CNN (
       (conv1): Sequential(
         (0): Conv2d(1, 16, kernel size=(5, 5), stride=(1, 1), padding=(2, 2))
         (1): ReLU()
         (2): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil_mode=False)
       )
       (conv2): Sequential(
         (0): Conv2d(16, 32, kernel_size=(5, 5), stride=(1, 1), padding=(2, 2))
         (1): ReLU()
         (2): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil mode=False)
       )
```

```
(out): Linear(in_features=1568, out_features=10, bias=True)
     )
[46]: loss_func = nn.CrossEntropyLoss()
      loss func
      # unlike earlier example using optim.SGD, we use optim.Adam as the optimizer
      # lr(Learning Rate): Rate at which our model updates the weights in the cells
      ⇔each time back-propagation is done.
      optimizer = optim.Adam(cnn.parameters(), lr = 0.01)
      optimizer
[46]: Adam (
     Parameter Group 0
          amsgrad: False
          betas: (0.9, 0.999)
          capturable: False
          decoupled_weight_decay: False
          differentiable: False
          eps: 1e-08
          foreach: None
          fused: None
          lr: 0.01
         maximize: False
         weight_decay: 0
      )
 []: | # train_data, validation_data = random_split(fmnist_dataset, [50000, 10000])
      # ## Print the length of train and validation datasets
      # print("length of Train Datasets: ", len(train_data))
      # print("length of Validation Datasets: ", len(validation_data))
      # batch_size = 128
      # train_loader = DataLoader(train_data, batch_size, shuffle = True)
      # val loader = DataLoader(validation_data, batch_size, shuffle = False)
      from torch.autograd import Variable
      def train(num_epochs, cnn, loaders):
          cnn.train()
          optimizer = optim.Adam(cnn.parameters(), lr = 0.01)
          loss_func = nn.CrossEntropyLoss()
          # Train the model
          total_step = len(loaders)
          for epoch in range(num_epochs):
              for i, (images, labels) in enumerate(loaders):
```

```
# gives batch data, normalize x when iterate train_loader
           b_x = Variable(images)
                                    # batch x
           b_y = Variable(labels)
                                    # batch y
           output = cnn(b_x)[0]
           loss = loss_func(output, b_y)
           # clear gradients for this training step
           optimizer.zero_grad()
           # backpropagation, compute gradients
           loss.backward()
           # apply gradients
           optimizer.step()
           if (i+1) \% 100 == 0:
               print ('Epoch [{}/{}], Step [{}/{}], Loss: {:.4f}'.format(epoch | ...
4+ 1, num_epochs, i + 1, total_step, loss.item()))
               pass
      pass
  pass
```

```
[48]: # instiate the CNN model
cnn = CNN()
# for testing purpose, we calculate the accuracy of the initial
cnn.eval()
with torch.no_grad():
    correct = 0
    total = 0
    for images, labels in train_loader:
        test_output, last_layer = cnn(images)
        pred_y = torch.max(test_output, 1)[1].data.squeeze()
        accuracy = (pred_y == labels).sum().item() / float(labels.size(0))
        pass
print('Accuracy of the model on the 10000 test images: %.2f' % accuracy)
```

Accuracy of the model on the 10000 test images: 0.19

```
[49]: train(num_epochs=5, cnn=cnn, loaders=train_loader)
```

```
Epoch [1/5], Step [100/391], Loss: 0.5404

Epoch [1/5], Step [200/391], Loss: 0.2914

Epoch [1/5], Step [300/391], Loss: 0.2988

Epoch [2/5], Step [100/391], Loss: 0.3219

Epoch [2/5], Step [200/391], Loss: 0.2439

Epoch [2/5], Step [300/391], Loss: 0.2370

Epoch [3/5], Step [100/391], Loss: 0.3342

Epoch [3/5], Step [200/391], Loss: 0.2703

Epoch [3/5], Step [300/391], Loss: 0.2695
```

```
Epoch [4/5], Step [100/391], Loss: 0.2814
Epoch [4/5], Step [200/391], Loss: 0.2218
Epoch [4/5], Step [300/391], Loss: 0.2696
Epoch [5/5], Step [100/391], Loss: 0.2278
Epoch [5/5], Step [200/391], Loss: 0.3272
Epoch [5/5], Step [300/391], Loss: 0.3563
```

## 2 Evaluate the model on test data

```
[50]: # Test the model, after the training
cnn.eval()
with torch.no_grad():
    correct = 0
    total = 0
    for images, labels in train_loader:
        test_output, last_layer = cnn(images)
        pred_y = torch.max(test_output, 1)[1].data.squeeze()
        accuracy = (pred_y == labels).sum().item() / float(labels.size(0))
        pass
print('Test Accuracy of the model on the 10000 test images: %.2f' % accuracy)
```

Test Accuracy of the model on the 10000 test images: 0.89

```
[51]: # Test the model, after the training
    cnn.eval()
    with torch.no_grad():
        correct = 0
        total = 0
        for images, labels in test_loader:
            test_output, last_layer = cnn(images)
            pred_y = torch.max(test_output, 1)[1].data.squeeze()
            accuracy = (pred_y == labels).sum().item() / float(labels.size(0))
            pass
    print('Test Accuracy of the model on the 10000 test images: %.2f' % accuracy)
```

Test Accuracy of the model on the 10000 test images: 0.94

Run inference on individual images

```
[52]: sample = next(iter(test_loader))
imgs, lbls = sample

actual_number = lbls[:10].numpy()
actual_number

test_output, last_layer = cnn(imgs[:10])
pred_y = torch.max(test_output, 1)[1].data.numpy().squeeze()
print(f'Prediction number: {pred_y}')
```

print(f'Actual number: {actual\_number}')

Prediction number: [9 2 1 1 0 1 4 6 5 7]
Actual number: [9 2 1 1 6 1 4 6 5 7]