

Summary of Rules for Error Propagation

Suppose you measure some quantities a, b, c, \dots with uncertainties $\delta a, \delta b, \delta c, \dots$. Now you want to calculate some other quantity Q which depends on a and b and so forth. What is the uncertainty in Q ? The answer can get a little complicated, but it should be no surprise that the uncertainties $\delta a, \delta b$, etc. “propagate” to the uncertainty of Q . Here are some rules which you will occasionally need; all of them assume that the quantities a, b , etc. have errors which are *uncorrelated* and *random*.¹

1. Addition or subtraction: If

$$Q = a + b + \dots + c - (x + y + \dots + z)$$

then

$$\delta Q = \sqrt{(\delta a)^2 + (\delta b)^2 + \dots + (\delta c)^2 + (\delta x)^2 + (\delta y)^2 + \dots + (\delta z)^2}.$$

2. Multiplication or division: If

$$Q = \frac{ab\dots c}{xy\dots z}$$

then

$$\frac{\delta Q}{|Q|} = \sqrt{\left(\frac{\delta a}{a}\right)^2 + \left(\frac{\delta b}{b}\right)^2 + \dots + \left(\frac{\delta c}{c}\right)^2 + \left(\frac{\delta x}{x}\right)^2 + \left(\frac{\delta y}{y}\right)^2 + \dots + \left(\frac{\delta z}{z}\right)^2}.$$

3. Measured quantity times exact number: If A is known exactly (e.g. $A = 2$ or $A = \pi$) and

$$Q = Ax$$

then

$$\delta Q = |A| \delta x$$

or equivalently

$$\frac{\delta Q}{|Q|} = \frac{\delta x}{|x|}$$

4. Uncertainty in a power: If n is an exact number and

$$Q = x^n$$

then

$$\frac{\delta Q}{|Q|} = |n| \frac{\delta x}{|x|}.$$

5. General formula for error propagation: If $Q = Q(x)$ is any function of x , then

$$\delta Q = \left| \frac{dQ}{dx} \right| \delta x.$$

¹These rules can all be derived from the Gaussian equation for normally-distributed errors, but you are not expected to be able to derive them, merely to be able to use them.