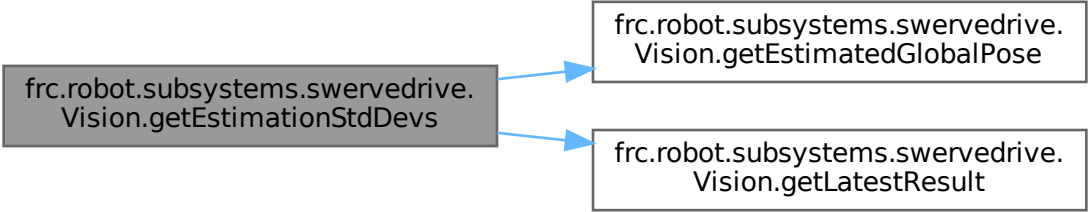


frc.robot.subsystems.swervedrive.
Vision.getEstimationStdDevs



```
graph LR; A[frc.robot.subsystems.swervedrive.Vision.getEstimationStdDevs] --> B[frc.robot.subsystems.swervedrive.Vision.getEstimatedGlobalPose]; A --> C[frc.robot.subsystems.swervedrive.Vision.getLatestResult];
```

The diagram illustrates a method call. A grey box on the left contains the text 'frc.robot.subsystems.swervedrive.Vision.getEstimationStdDevs'. Two blue arrows originate from the right side of this box. The top arrow points to a white box containing 'frc.robot.subsystems.swervedrive.Vision.getEstimatedGlobalPose'. The bottom arrow points to another white box containing 'frc.robot.subsystems.swervedrive.Vision.getLatestResult'.

frc.robot.subsystems.swervedrive.
Vision.getEstimatedGlobalPose

frc.robot.subsystems.swervedrive.
Vision.getLatestResult