

frc.robot.Robot.autonomousInit

```
graph LR; A[frc.robot.Robot.autonomousInit] --> B[frc.robot.RobotContainer.get AutonomousCommand]; A --> C[frc.robot.RobotContainer.set MotorBrake];
```

frc.robot.RobotContainer.get  
AutonomousCommand

frc.robot.RobotContainer.set  
MotorBrake