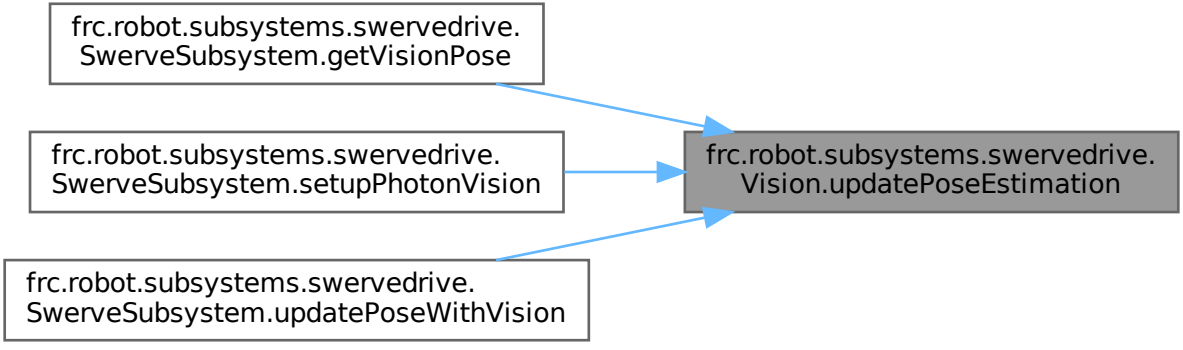
frc.robot.subsystems.swervedrive.
SwerveSubsystem.getVisionPose
frc.robot.subsystems.swervedrive.
SwerveSubsystem.setupPhotonVision
frc.robot.subsystems.swervedrive.
SwerveSubsystem.updatePoseWithVision
frc.robot.subsystems.swervedrive.
Vision.updatePoseEstimation