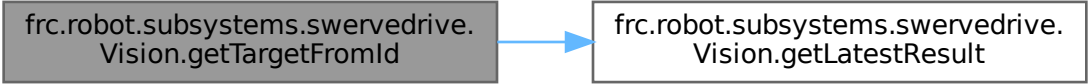


```
frc.robot.subsystems.swervedrive.  
Vision.getTargetFromId
```



```
graph LR; A[frc.robot.subsystems.swervedrive.  
Vision.getTargetFromId] --> B[frc.robot.subsystems.swervedrive.  
Vision.getLatestResult]
```

```
frc.robot.subsystems.swervedrive.  
Vision.getLatestResult
```