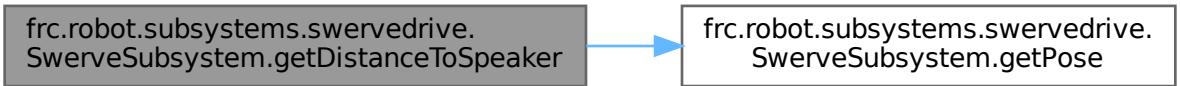
frc.robot.subsystems.swervedrive.
SwerveSubsystem.getDistanceToSpeaker
frc.robot.subsystems.swervedrive.
SwerveSubsystem.getPose