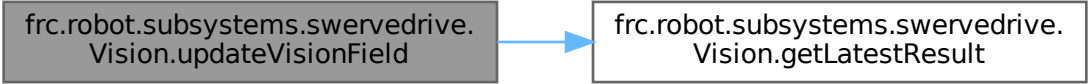


```
frc.robot.subsystems.swervedrive.  
Vision.updateVisionField
```



```
graph LR; A[frc.robot.subsystems.swervedrive.  
Vision.updateVisionField] --> B[frc.robot.subsystems.swervedrive.  
Vision.getLatestResult];
```

A diagram showing a call to `Vision.updateVisionField` in the `frc.robot.subsystems.swervedrive` package. A blue arrow points from this call to the `Vision.getLatestResult` method in the same package.

```
frc.robot.subsystems.swervedrive.  
Vision.getLatestResult
```