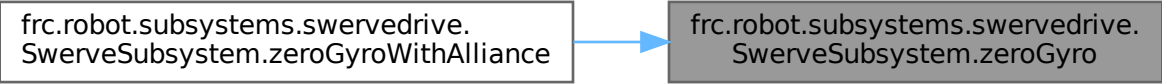


```
frc.robot.subsystems.swervedrive.  
SwerveSubsystem.zeroGyroWithAlliance
```



```
graph LR; A["frc.robot.subsystems.swervedrive.  
SwerveSubsystem.zeroGyroWithAlliance"] --> B["frc.robot.subsystems.swervedrive.  
SwerveSubsystem.zeroGyro"]
```

```
frc.robot.subsystems.swervedrive.  
SwerveSubsystem.zeroGyro
```