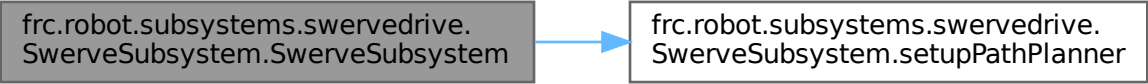


```
frc.robot.subsystems.swervedrive.  
SwerveSubsystem.SwerveSubsystem
```



```
graph LR; A[frc.robot.subsystems.swervedrive.SwerveSubsystem] --> B[frc.robot.subsystems.swervedrive.SwerveSubsystem.setupPathPlanner]
```

A diagram showing a call to the `SwerveSubsystem.setupPathPlanner` method. A gray box on the left contains the text `frc.robot.subsystems.swervedrive.SwerveSubsystem`. A blue arrow points from this box to a white box on the right, which contains the text `frc.robot.subsystems.swervedrive.SwerveSubsystem.setupPathPlanner`.

```
frc.robot.subsystems.swervedrive.  
SwerveSubsystem.setupPathPlanner
```