

# Build A Rocket



$x1$

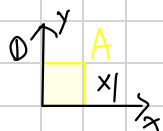


$x3$

$T(tx, ty)$  平移

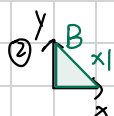
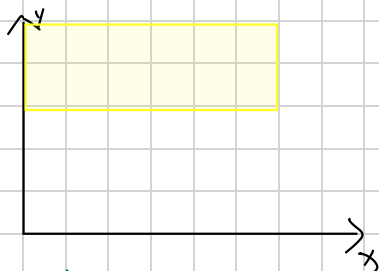
$S(sx, sy)$  缩放

$R(theta)$  绕原点旋转 (逆)



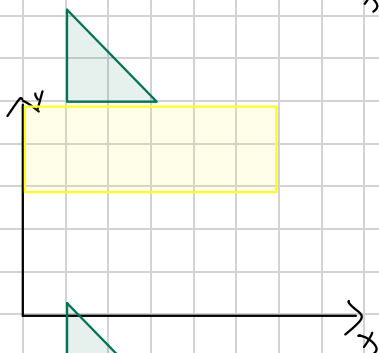
$S(6, 2) A$

$T(0, 3) A$



$S(2, 2) B \rightarrow$

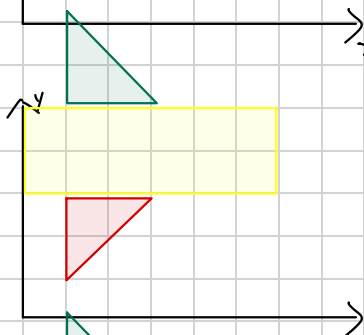
$T(1, 5) B$



$R(\frac{3}{2}\pi) C$

$S(2, 2) C \Rightarrow$

$T(1, 3) C$



$R(\frac{3}{4}\pi) D$

$S(\sqrt{2}, \sqrt{2}) D$

$T(7, 4) D$

