浙江水学

本科实验报告

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浙江大学操作系统实验报告

实验名称: fork 机制

电子邮件地址: ___手机: __.

实验地点: <u>线上</u>实验日期: <u>2024</u>年<u>01</u>月<u>03</u>日

一、实验目的和要求

本实验的要求是:为 task 加入 fork 机制,支持通过 fork 创建用户态 task。

二、实验过程

我们考虑实现 fork()机制。

修改 task_init(), 使得本环节只创建一个内核线程。

修改 entry.S,增加一个__ret_from_fork 入口。

```
1 # arch/riscv/kernel/entry.S
2 _traps:
3 ...
4 call trap_handler
5 .global __ret_from_fork
6 __ret_from_fork:
7 ...
```

我们维护一个全局变量 num_of_task,用于表示目前创建的线程数量。 这个变量同时会在调度算法中造成一些改动。

实现 sys_clone(),其中的一些关键逻辑是: 子线程的 regs 在 task_struct 中的偏移应当与父线程一致,我们由此可以得到子线程的 regs; 子线程在被创建后并不会经由 trap_handler()返回,因此要在这里就将它的 sepc 移动到下一条指令的地址处; 在建立映射时,遍历其 vma,对 vma 的每一页检索它是否在页表内,如果在说明在父线程中已经建立映射,我们对子线程建立映射; 我们不必专门关注子线程的用户态栈,因为它也是 vma 之一。

至此,我们已经实现了 fork 机制,随实验提供的 4 个 main()输出结果将在 后面 4 页中依序列出。

不包含 fork()的 main()每个线程在创建时会产生 3 次缺页异常。这四个线程一共产生了 12 次缺页异常。

包含 fork()的第一个 main()在第一个线程产生 3 次缺页异常, 之后的子线程 会产生 1 次缺页异常(Load Page Fault)。这两个线程一共产生了 4 次缺页异常。

包含 fork()的第二个 main()在第一个线程产生 3 次缺页异常,之后的子线程不产生缺页异常。这两个线程一共产生了 3 次缺页异常。

包含 fork()的第三个 main()在第一个线程产生 3 次缺页异常,之后的子线程不产生缺页异常。这四个线程一共产生了 3 次缺页异常。

```
...proc_init done!
2023[S-Mode] Hello RISC-V
SWITCH TO [pid=1 counter=4 priority=37]
[S] Supervisor Page Fault, cause: 0x0000
[PID = 1] is running, variable: 1
[PID = 1] is running, variable: 2
[PID = 1] is running, variable: 2
[PID = 1] is running, variable: 4
[PID = 1] is running, variable: 5
[PID = 1] is running, variable: 6
[PID = 1] is running, variable: 7
[PID = 1] is running, variable: 8
[PID = 1] is running, variable: 9
[PID = 1] is running, variable: 9
                                                                                                                        0000000000000, stval: 0x0000000000100e8, sepc: 0x0000000
0000000000000, stval: 0x000003ffffffff8, sepc: 0x0000000
00000000000000, stval: 0x00000000011880, sepc: 0x0000000
SWITCH TO [pid=1 counter=1 priority=37]

[PID = 1] is running, variable: 11

[PID = 1] is running, variable: 12

[PID = 1] is running, variable: 13
[PIO = 1] is Tunhing, variable: S

SMITCH TO [pid=2 counter=4 priority=88]

[PID = 2] is running, variable: 25

[PID = 2] is running, variable: 26

[PID = 2] is running, variable: 28

[PID = 2] is running, variable: 28

[PID = 2] is running, variable: 30

[PID = 2] is running, variable: 31

[PID = 2] is running, variable: 32

[PID = 2] is running, variable: 33

[PID = 2] is running, variable: 34
 SMITCH TO [pid=4 counter=4 priority=66]
[PID = 4] is running, variable: 14
[PID = 4] is running, variable: 15
[PID = 4] is running, variable: 16
[PID = 4] is running, variable: 16
[PID = 4] is running, variable: 17
[PID = 4] is running, variable: 18
[PID = 4] is running, variable: 29
[PID = 4] is running, variable: 21
[PID = 4] is running, variable: 22
[PID = 4] is running, variable: 23
[PID = 4] is running, variable: 23
[PID = 4] is running, variable: 24
 SWITCH TO [pid=3 counter=10 priority=52]
[PID = 3] is running, variable: 22
```

```
...proc_init done!
2023[S-Mode] Hello RISC-V
 SWITCH TO [pid=1 counter=4 priority=37]
[S] Supervisor Page Fault, cause: 0x0000000000000000, stval: 0x000000000100e8, sepc: 0x0000000000100e8
[S] Supervisor Page Fault, cause: 0x000000000000000, stval: 0x0000003ffffffff8, sepc: 0x000000000010158
 FORK [pid=2 counter=4 priority=37]
 [S] Supervisor Page Fault, cause: 0x00000000000000000, stval: 0x000000000011978, sepc: 0x0000000000101f0
 [U-PARENT] pid: 1 is running!, global_variable: 0
[U-PARENT] pid: 1 is running!, global_variable: 1
[U-PARENT] pid: 1 is running!, global_variable: 1 [U-PARENT] pid: 1 is running!, global_variable: 2 [U-PARENT] pid: 1 is running!, global_variable: 3 [U-PARENT] pid: 1 is running!, global_variable: 4 [U-PARENT] pid: 1 is running!, global_variable: 5 [U-PARENT] pid: 1 is running!, global_variable: 6 [U-PARENT] pid: 1 is running!, global_variable: 7
 [U-PARENT] pid: 1 is running!, global_variable: 8
[U-PARENT] pid: 1 is running!, global_variable: 9
[U-PARENT] pid: 1 is running!, global_variable: 10
 SWITCH TO [pid=2 counter=4 priority=37]
 [S] Supervisor Page Fault, cause: 0x0000000000000000, stval: 0x00000000011978, sepc: 0x00000000001018c
 [U-CHILD] pid: 2 is running!, global_variable: 0
 [U-CHILD] pid: 2 is running!, global_variable:
 [U-CHILD] pid: 2 is running!, global_variable:
 [U-CHILD] pid: 2 is running!, global_variable:
 [U-CHILD] pid: 2 is running!, global_variable: 4
 [U-CHILD] pid: 2 is running!, global_variable: 5
 [U-CHILD] pid: 2 is running!, global_variable: 6
 [U-CHILD] pid: 2 is running!, global_variable:
 [U-CHILD] pid: 2 is running!, global_variable: 8
 [U-CHILD] pid: 2 is running!, global_variable: 9
 [U-CHILD] pid: 2 is running!, global_variable: 10
 SWITCH TO [pid=1 counter=1 priority=37]
[U-PARENT] pid: 1 is running!, global_variable: 11
[U-PARENT] pid: 1 is running!, global_variable: 12
[U-PARENT] pid: 1 is running!, global_variable: 13
 SWITCH TO [pid=2 counter=4 priority=37]
 [U-CHILD] pid: 2 is running!, global_variable: 11
 [U-CHILD] pid: 2 is running!, global_variable: 12
 [U-CHILD] pid: 2 is running!, global_variable: 13
 [U-CHILD] pid: 2 is running!, global_variable: 14
[U-CHILD] pid: 2 is running!, global_variable: 15
[U-CHILD] pid: 2 is running!, global_variable: 16
 [U-CHILD] pid: 2 is running!, global_variable: 17
[U-CHILD] pid: 2 is running!, global_variable: 18
[U-CHILD] pid: 2 is running!, global_variable: 19
[U-CHILD] pid: 2 is running!, global_variable: 20
[U-CHILD] pid: 2 is running!, global_variable: 20 [U-CHILD] pid: 2 is running!, global_variable: 21 [U-CHILD] pid: 2 is running!, global_variable: 22 [U-CHILD] pid: 2 is running!, global_variable: 23 [U-CHILD] pid: 2 is running!, global_variable: 24 [U-CHILD] pid: 2 is running!, global_variable: 25 [U-CHILD] pid: 2 is running!, global_variable: 26 [U-CHILD] pid: 2 is running!, global_variable: 27 [U-CHILD] pid: 2 is running!, global_variable: 27 [U-CHILD] pid: 2 is running!, global_variable: 29 [U-CHILD] pid: 2 is running!, global_variable: 30 [U-CHILD] pid: 2 is running!, global_variable: 30 [U-CHILD] pid: 2 is running!, global_variable: 31
[U-CHILD] pid: 2 is running!, global_variable: 31
[U-CHILD] pid: 2 is running!, global_variable: 32
 SWITCH TO [pid=1 counter=10 priority=37]
U-PARENT] pid: 1 is running!, global_variable: 14
[U-PARENT] pid: 1 is running!, global_variable: 15
[U-PARENT] pid: 1 is running!, global_variable: 16
[U-PARENT] pid: 1 is running!, global_variable: 17
[U-PARENT] pid: 1 is running!, global_variable: 18
[U-PARENT] pid: 1 is running!, global_variable: 19
[U-PARENT] pid: 1 is running!, global_variable: 18 [U-PARENT] pid: 1 is running!, global_variable: 19 [U-PARENT] pid: 1 is running!, global_variable: 20 [U-PARENT] pid: 1 is running!, global_variable: 21 [U-PARENT] pid: 1 is running!, global_variable: 23 QEMU: Terminated
```

```
.proc_init done!
 2023[S-Mode] Hello RISC-V
 SWITCH TO [pid=1 counter=4 priority=37]
[S] Supervisor Page Fault, cause: 0x00000000000000000, stval: 0x0000000000100e8, sepc: 0x0000000000100e8
 [U] pid: 1 is running!, global_variable: 2
 FORK [pid=2 counter=4 priority=37]
FORK [pid=2 counter=4 priority=37]
[U-PARENT] pid: 1 is running!, global_variable: 3
[U-PARENT] pid: 1 is running!, global_variable: 4
[U-PARENT] pid: 1 is running!, global_variable: 5
[U-PARENT] pid: 1 is running!, global_variable: 6
[U-PARENT] pid: 1 is running!, global_variable: 7
[U-PARENT] pid: 1 is running!, global_variable: 8
[U-PARENT] pid: 1 is running!, global_variable: 9
[U-PARENT] pid: 1 is running!, global_variable: 10
[U-PARENT] pid: 1 is running!, global_variable: 11
[U-PARENT] pid: 1 is running!, global_variable: 12
[U-PARENT] pid: 1 is running!, global_variable: 13
 SWITCH TO [pid=2 counter=4 priority=37]
 [U-CHILD] pid: 2 is running!, global_variable: 3
[U-CHILD] pid: 2 is running!, global_variable: 4
 [U-CHILD] pid: 2 is running!, global_variable: 5
[U-CHILD] pid: 2 is running!, global_variable: 6
 [U-CHILD] pid: 2 is running!, global_variable: 7
[U-CHILD] pid: 2 is running!, global_variable: 8
[U-CHILD] pid: 2 is running!, global_variable: 9
[U-CHILD] pid: 2 is running!, global_variable: 10
 [U-CHILD] pid: 2 is running!, global_variable: 11
[U-CHILD] pid: 2 is running!, global_variable: 12
[U-CHILD] pid: 2 is running!, global_variable: 13
 SWITCH TO [pid=1 counter=1 priority=37]
[U-PARENT] pid: 1 is running!, global_variable: 14
[U-PARENT] pid: 1 is running!, global_variable: 15
[U-PARENT] pid: 1 is running!, global_variable: 16
SWITCH TO [pid=2 counter=4 priority=37]
[U-CHILD] pid: 2 is running!, global_variable: 14
[U-CHILD] pid: 2 is running!, global_variable: 15
[U-CHILD] pid: 2 is running!, global_variable: 15
[U-CHILD] pid: 2 is running!, global_variable: 17
[U-CHILD] pid: 2 is running!, global_variable: 18
[U-CHILD] pid: 2 is running!, global_variable: 19
[U-CHILD] pid: 2 is running!, global_variable: 20
[U-CHILD] pid: 2 is running!, global_variable: 20
[U-CHILD] pid: 2 is running!, global_variable: 22
[U-CHILD] pid: 2 is running!, global_variable: 23
[U-CHILD] pid: 2 is running!, global_variable: 24
[U-CHILD] pid: 2 is running!, global_variable: 25
[U-CHILD] pid: 2 is running!, global_variable: 25
[U-CHILD] pid: 2 is running!, global_variable: 26
[U-CHILD] pid: 2 is running!, global_variable: 27
[U-CHILD] pid: 2 is running!, global_variable: 28
[U-CHILD] pid: 2 is running!, global_variable: 28
 SWITCH TO [pid=2 counter=4 priority=37]
 [U-CHILD] pid: 2 is running!, global_variable: 29 [U-CHILD] pid: 2 is running!, global_variable: 39 [U-CHILD] pid: 2 is running!, global_variable: 31 [U-CHILD] pid: 2 is running!, global_variable: 32 [U-CHILD] pid: 2 is running!, global_variable: 32
 [U-CHILD] pid: 2 is running!, global_variable: 33
[U-CHILD] pid: 2 is running!, global_variable: 34
[U-CHILD] pid: 2 is running!, global_variable: 35
 SWITCH TO [pid=1 counter=10 priority=37]
 [U-PARENT] pid: 1 is running!, global_variable: 17

[U-PARENT] pid: 1 is running!, global_variable: 18

[U-PARENT] pid: 1 is running!, global_variable: 19

[U-PARENT] pid: 1 is running!, global_variable: 20

[U-PARENT] pid: 1 is running!, global_variable: 21
```

```
...proc_init done!
2023[S-Mode] Hello RISC-V
   [U] pid: 1 is running!, global_variable: 12
SMITCH TO [pid=2 counter=4 priority=37]
[U] pid: 2 is running!, global_variable: 1
FORK [pid=4 counter=4 priority=37]
[U] pid: 2 is running!, global_variable: 2
[U] pid: 2 is running!, global_variable: 3
[U] pid: 2 is running!, global_variable: 4
[U] pid: 2 is running!, global_variable: 5
[U] pid: 2 is running!, global_variable: 6
[U] pid: 2 is running!, global_variable: 6
[U] pid: 2 is running!, global_variable: 7
[U] pid: 2 is running!, global_variable: 9
[U] pid: 2 is running!, global_variable: 9
[U] pid: 2 is running!, global_variable: 11
[U] pid: 2 is running!, global_variable: 12
[U] pid: 2 is running!, global_variable: 12
   [U] pid: 2 is running!, global_variable:
SWITCH TO [pid=3 counter=4 priority=37]
[U] pid: 3 is running!, global_variable:
      [U] pid: 4 is running!, global_variable: 12
SMITCH TO [pid=4 conning!, global_variable: 2
[U] pid: 4 is running!, global_variable: 3
[U] pid: 4 is running!, global_variable: 3
[U] pid: 4 is running!, global_variable: 4
[U] pid: 4 is running!, global_variable: 6
[U] pid: 4 is running!, global_variable: 6
[U] pid: 4 is running!, global_variable: 8
[U] pid: 4 is running!, global_variable: 9
[U] pid: 4 is running!, global_variable: 11
[U] pid: 4 is running!, global_variable: 11
[U] pid: 4 is running!, global_variable: 12
            SWITCH TO [pid=1 counter=1 priority=37]
[U] pid: 1 is running!, global_variable: 13
[U] pid: 1 is running!, global_variable: 14
[U] pid: 1 is running!, global_variable: 15
   [U] pid: 1 is running!, global_variable:
SWITCH TO [pid=2 counter=4 priority=37]
[U] pid: 2 is running!, global_variable:
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    20
21
22
23
      [U] pid: 2 is running!, global_variable:
SMITCH TO [pid=4 counter=4 priority=37]
[U] pid: 4 is running!, global_variable:
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 13
14
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16
17
18
19
20
21
22
23
[U] pid: 4 is running!, global_variable: :
SWITCH TO [pid=3 counter=10 priority=37]
[U] pid: 3 is running!, global_variable: :
[U] pid: 3 is running!
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    13
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```

三、讨论和心得

在这里, 想高度赞扬 lab6 指导书, 感觉这一篇写得非常清楚, 也很有对话感, 注释指导得也很清晰。

本次实验基本没有遇到什么问题,除了在根据父线程建立映射那里稍有卡顿外,其余部分跟着指导走非常顺利。特别想提到的是,在运行时我发现每产生一个新子线程时会报一次 Instruction Page Fault——经检查,是在建立映射时权限设置错误。

四、思考题

1. 参考 task_init 创建一个新的 task, 将 parent task 的整个页复制到新创建的 task struct 页上, 这一步复制了哪些东西?

结合 task_struct 的结构,这一步应当复制了以下所有成员。同时,还有 task 高地址的进程栈的内容也在这一步被复制。

2. 将 thread.ra 设置为 __ret_from_fork, 并正确设置 thread.sp。仔细想想,这个应该设置成什么值?可以根据 child task 的返回路径来倒推。

我们根据 child task 的返回路径,即__switch_to->__ret_from_fork(in _traps)->user program,加上__switch_to 中并没有使用 sp 作为栈指针进行操作,而是在 ret from fork 中发生了第一次将 sp 作为栈指针进行栈操作。因此,需要将

thread.sp 设置为在__ret_from_fork 中预期的栈顶指针。

容易得到,此时 sp 应当指向 regs 的顶端,即 thread.sp 应当指向子线程的 regs 的顶端,而根据子线程和父线程的 regs 在其 task_struct 中的偏移应当相同,我们可以通过如下方式计算得到 thread.sp 的值:

```
1 struct pt_regs* child_regs = (struct pt_regs*)((uint64)task[new_task_index] + ((uint64)regs -PGROUNDDOWN((uint64)regs)));
2 task[new_task_index]->thread.sp = (uint64)child_regs;
```

3. 利用参数 regs 来计算出 child task 的对应的 pt_regs 的地址,并将其中的 a0, sp, sepc 设置成正确的值。为什么还要设置 sp?

在稍后的__ret_from_fork 中,我们会从 regs 中恢复所有寄存器的值。上题中设置 sp,是为了在__ret_from_fork 中能够在正确的栈上进行操作,本题中设置 sp 是为了在 ret from fork 恢复寄存器值后 sp 仍能保持正确。

如下图所示,在_traps 中,trap_handler 调用前后也发生了一次 sp 的存取。如果只将上题的 sp 做设置而不设置本题中的 sp,从栈上恢复的仍然是从父线程中复制过来的值。

```
1 # arch/riscv/kernel/entry.S
2 _traps:
3 ...
4 _traps_start:
5 # 1. save 32 registers and sepc to stack
6 addi sp, sp, -8*37
7 ...
8 sd x2, 16(sp)
9 ...
10 call trap_handler
11
12 .global __ret_from_fork
13 __ret_from_fork:
14 ...
15 ld x2, 16(sp)
16 addi sp, sp, 8*37
```