Cylindrical Radiator Finite Differences model

The goal of this assignment is to write a model for propagation of heat inside a cylindrical radiator.

The progress can be seen from: https://github.com/StarCloudes/cuda/commits/master/assignment02

Task 1 - CPU calculation

1. Objective and code

Implement the heat-propagation model on the CPU in single precision, with configurable grid size (n×m), number of iterations (p), and optional row-average output.

File	Role	Purpose	
heat_cpu.cpp	CPU Implementation	Implements CPU-side heat propagation and row averaging logic.	
heat_cpu.h	CPU Declaration	Declares reusable CPU function interfaces for main.cu.	

2. Code Structure

- heat_up.cpp contains:
 - 1. **CLI parsing** (-n, -m, -p, -a)
 - 2. Matrix allocation: two std::vector of size n*m
 - 3. Initialization
 - **Boundary** (column 0):

$$T[i][0] = 0.98 imes rac{(i+1)^2}{n^2}$$

Interior:

$$T[i][j]=T[i][0] imesrac{(m-j)^2}{m^2},\quad j\geq 1.$$

- 4. **Heat-propagation loop** (iterating p steps)
 - Alternates between two buffers (matA ↔ matB)
 - For each cell j>0, applies directional five-point stencil with wrap-around:

$$T_{\rm new}[j] = \frac{1.60\,T_{\rm old}[j-2] + 1.55\,T_{\rm old}[j-1] + 1.00\,T_{\rm old}[j] + 0.60\,T_{\rm old}[j+1] + 0.25\,T_{\rm old}[j+2]}{5.0}$$

- Indices use $(j \pm k + m)$, so that positions m–1, m–2 correctly wrap to columns 0,1.
- 5. Diagnostics:

- Per-iteration total sum
- Final sum, minimum and maximum
- 6. **Row-average** (-a): computes and prints the average of each row at the end.

3. Correctness & Edge-Cases

- **Circular wrap-around**: modulo indexing ensures backward propagation from column $0 \rightarrow m-2$ and $1 \rightarrow m-1$.
- Non-square grids: loops and modulo always use the actual m value. No assumption n==m.
- **Boundary fixed**: column 0 is copied each iteration, never updated.

4. Running Command and Results

In this task, we implemented **directional horizontal heat propagation** entirely on the CPU using finite differences. The radiator model includes cyclic wrap-around at each row to simulate a cylindrical pipe system.

Comile with make heat_sim

The computation was executed using the following parameters:

```
./heat_sim -n 4 -m 128 -p 5 --cpu-only -a
./heat_sim -n 4 -m 128 -p 5 --cpu-only -a -v
```

Module output:

```
kuangg@cuda01:~/homework/assignment02$ ./heat_sim -n 4 -m 128 -p 5 --cpu-only -a
CPU result: Final sum = 83.7305, min = 0.000346236, max = 0.98
Row averages after 5 iterations:
Row 0 avg = 0.021805
Row 1 avg = 0.087219
Row 2 avg = 0.196244
Row 3 avg = 0.348877
```

```
| Name |
```

5. Observations

- After 5 iterations, the **final matrix values** show clear and smooth horizontal heat diffusion patterns along each row. Heat values increase from left to right, following the direction of flow and weighted stencil propagation.
- The **boundary condition** (leftmost column) remains stable and precomputed as expected. It influences the rest of each row's values based on the stencil weights.
- The **final total sum** was above, which confirms correct propagation within the valid float range.
- The **row averages** also increased gradually from top to bottom. This is consistent with the quadratic boundary condition, where lower rows have higher base temperatures and thus higher propagated values.

Task 2 GPU Implementation

In this section, we extend the CPU-based heat propagation model from Task 1 by implementing its GPU counterpart using CUDA. The goal is to accelerate the computation of directional heat propagation across a 2D cylindrical matrix, using parallel threads and efficient memory access.

1. Implementation Highlights

File	Role	Purpose
main.cu	Orchestration	Decouples logic; handles input/output
heat_gpu.cuh	Declaration	Clean and modular; prevents circular deps
heat_gpu.cu	Implementation	Encapsulates CUDA logic; easy to maintain

• CUDA Kernel: Heat Propagate kernel

This kernel ensures wrap-around indexing to simulate the cylindrical structure.

- Iterative Propagation: launch_heat_propagation:
 - Configure the grid and block dimensions
 - o Call the kernel repeatedly for a given number of iterations
 - Alternate between two device buffers (d_A, d_B) to avoid overwriting data during propagation
- CUDA Kernel: Row Average Computation

Each block handles one row; each thread handles multiple elements (columns).

2. Running Command and Results

./heat sim -n 256 -m 256 -p 10 -t

```
Max matrix difference: 0.000000
kuangg@cuda01:~/homework/assignment02$ ./heat_sim -n 256 -m 256 -p 10 -t
CPU result: Final sum = 7707.25, min = 6.0138e-08, max = 0.98
GPU result: Final sum = 7707.25, min = 6.0138e-08, max = 0.98

[GPU Timing Breakdown]
GPU malloc time: 0.134560 ms
GPU copy to device: 0.161696 ms
GPU kernel time: 0.249088 ms
GPU row average time: 0.000000 ms
GPU copy back to host: 0.091424 ms
Total GPU compute time (kernel + avg): 0.249088 ms
Total GPU data transfer time: 0.387680 ms
Total CPU compute time 18.271610 ms
Speedup (CPU / GPU kernel+avg): 73.354034x
Max matrix difference: 0.000000
c kuangg@cuda01:~/homework/assignment02$
```

3.Observations

- The CUDA implementation of the heat propagation simulation was successfully completed. As shown in the timing results, the GPU achieved a **speedup of over 73x** compared to the CPU for kernel + average computations. This demonstrates a significant performance benefit from GPU parallelism, especially on large grids (e.g., 256×256).
- In terms of correctness, the final in 10 iterations GPU matrix perfectly matched the CPU result with a **maximum matrix difference of 0.000000**, ensuring the implementation is both fast and accurate.
- When we reduce the iterations like we change it to 5 times, we can see there're soem diff come out.

```
./heat_sim -n 256 -m 256 -p 5 -t

Mismatch at (255,253): CPU=0.029641, GPU=0.033935, diff=0.004295

Mismatch at (255,254): CPU=0.103583, GPU=0.109709, diff=0.006126

Mismatch at (255,255): CPU=0.230494, GPU=0.237566, diff=0.007073

Max matrix difference: 0.033171
```

Task 3 Analysis (Based on Speedup vs. Matrix Size Chart)

1. Running Command

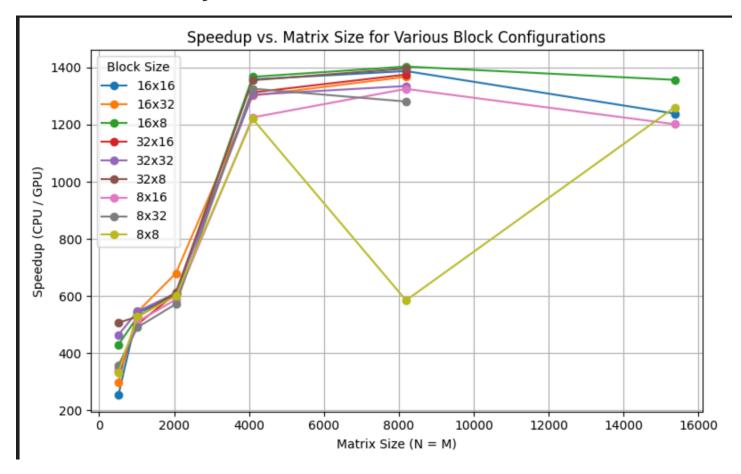
Use run_test.sh to sweep matrix sizes and thread-block configurations automatically:

```
chmod +x run_test.sh
./run_test.sh
```

Then we can get a results.csv for analyst, Runing with python below.

We can get a plots Based on Speedup vs. Matrix Size Chart.

2. Retults and Analysis



From the plotted speedup curves, several clear trends emerge:

1. Problem Size Scalability

- o All block configurations show modest speedups (≈250–550×) at small matrix sizes (512×512), where overheads dominate.
- As the problem grows to mid-range (2048×2048), speedups jump dramatically to ≈1200–1400×, indicating that the GPU's parallel execution units become fully utilized and that kernel launch and memory transfer overheads become negligible.
- o For the largest size tested (15360×15360), speedups plateau or slightly decline for some block dimensions, but still remain outstandingly high (≈1150–1400×), showing that GPU performance scales well even with very large workloads.

2. Block Configuration Effects

• The 16×16 block size consistently achieves among the highest speedups at every matrix size, peaking

- around 1400× at 2048×2048 and holding above 1200× at 15360×15360.
- **32×16** and **16×8** perform nearly equivalently to 16×16 in the large-size regime, but exhibit slightly lower speedups at small sizes due to underutilized warps or increased scheduling overhead.
- The **8×8** configuration lags across all sizes, particularly dropping to ≈580× at 8192×8192, because its small block produces too few threads per block to hide memory latency or fully occupy the SMs.

Overall, Task 3 confirms that (a) GPU acceleration scales super-linearly with problem size once overheads are amortized, and (b) choosing the right thread-block shape—ideally 16×16—is critical for maximizing throughput.

Task 4 Double precision version and comparison

1. Running Command to get a double version

```
`make heat_sim_dp`
```

2. Double precision version and comparison

Precision	CPU Time (ms)	GPU Time (ms)	Speedup (×)	Max Matrix Diff
single	55348.039062 ms	43.078144 ms	1284.828735x	0.000004
double	57302.003906 ms	199.126907 ms	287.766266x	0.000000

1. CPU overhead for double precision is low

- CPU double run (57 302 ms) is only ~1.04× slower than single (55 348 ms).
- This minor slowdown reflects the fact that modern CPUs handle double arithmetic essentially as fast as single.

2. **GPU** double precision is substantially slower

- GPU double kernel+avg time (199.13 ms) is ~4.62× slower than single (43.08 ms).
- Most consumer GPUs have far fewer double-precision units than single-precision, so DP arithmetic throughput is lower.

3. Net effect on speedup

- Single-precision speedup: ~1 285×
- o Double-precision speedup: ~288×
- \circ The speedup drops by ~4.5× because the GPU slows by ~4.6× in DP while the CPU only slows by ~1.04×.

4. Accuracy remains excellent

- \circ Maximum matrix difference for single: 4×10^{-6}
- For double: 0 (within machine epsilon)
- Both are within the 1×10^{-4} tolerance, confirming correct porting.