

EE 235, Winter 2018
Homework 3: Continuous-Time Systems
 (Due Friday January 19, 2018 by 12:30pm via Canvas Submission)
 Write down *ALL* steps for full credit

HW3 Topics:

- System Properties: C, S, I, TI

HW3 Course Learning Goals Satisfied:

- Goal 1: Describe signals in different domains (time).
- Goal 2: Understand the implications of different system properties and how to test for them.

HW3 References:

- OWN Sections 1.4, 1.5, 1.6

HW3 Problems (Total = 106 pts):

1. *Review*

- (a) *Complex Numbers.* (2 pts) In Ch.3, you will need to be comfortable working with equations with complex numbers and terms. Here is one problem for you to practice your skills. Consider the following equation where s is complex:

$$H(s) = 3e^{2s}$$

Using $H(s)$ above, evaluate and simplify as much as possible the following equation $y(t) = \frac{1}{2}H(j5)e^{j5t} + \frac{1}{2}H(-j5)e^{-j5t}$. *Hint: Use Euler's formulas.*

Solution. $y(t) = \frac{1}{2}H(j5)e^{j5t} + \frac{1}{2}H(-j5)e^{-j5t}$

$$y(t) = \frac{1}{2}(3e^{2(j5)})e^{j5t} + \frac{1}{2}(3e^{2(-j5)})e^{-j5t}$$

$$y(t) = 3[\frac{1}{2}e^{j(5t+10)} + \frac{1}{2}e^{-j(5t+10)}]$$

$$y(t) = 3 \cos(5t + 10)$$

- (b) *Integration* We will use this problem to continue practice doing multivariable integration. In Ch.2, you will need to evaluate a so-called running integral where the upper bound is a variable as shown below:

$$s(t) = \int_{-\infty}^t h(\tau) d\tau$$

Because t is a variable and changing values, the answer for $s(t)$ will also be a function of t – that is, for different regions of t , you will get a different equation for $s(t)$. See Supplementary Notes for an example. Evaluate the integral above for the following cases:

i. (2 pts) $h(\tau) = \begin{cases} 3, & \tau > -1 \\ 0, & \tau < -1 \end{cases}$

Show that $s(t) = \begin{cases} 0, & t < -1 \\ 3(t+1), & t > -1 \end{cases}$

Solution.

Case 1, $t < -1$: Note in this case $h(\tau) = 0$, so we will use that value for the integral

$$s(t) = \int_{-\infty}^t 0 d\tau = 0$$

Case 2, $t > -1$: Note in this case, the running integral needs to take into account two cases for $h(\tau)$ so we will need to split up the integral and integrate from $[-\infty, -1]$ and $[-1, t]$

$$s(t) = \int_{-\infty}^{-1} 0 d\tau + \int_{-1}^t 3 d\tau = 3(t+1)$$

In summary, we have: $s(t) = \begin{cases} 0, & t < -1 \\ 3(t+1), & t > -1 \end{cases}$

ii. (4 pts) $h(\tau) = \begin{cases} 0, & \tau > 0 \\ e^{2\tau}, & \tau < 0 \end{cases}$

Solution.

Case 1, $t < 0$: Note in this case $h(\tau) = e^{2\tau}$, so we will use that value for the integral

$$s(t) = \int_{-\infty}^t e^{2\tau} d\tau = \frac{1}{2} e^{2t}$$

Case 2, $t > 0$: Note in this case, the running integral needs to take into account two cases for $h(\tau)$ so we will need to split up the integral and integrate from $[-\infty, 0]$ and $[0, t]$ $s(t) = \int_{-\infty}^0 e^{2\tau} d\tau + \int_0^t 0 d\tau = \frac{1}{2}[e^0 - e^{-\infty}] + 0 = \frac{1}{2}$

In summary, we have: $s(t) = \begin{cases} \frac{1}{2} e^{2t}, & t < 0 \\ \frac{1}{2}, & t > 0 \end{cases}$

(c) Periodicity and Even/Odd. (4 pts)

Let $z(t) = \sin^3(4t) + e^{-j6t}$. Find the odd $z_0(t)$ part of $z(t)$. Is the odd part of $z(t)$ periodic?

Solution. $z_0(t) = \frac{z(t) - z(-t)}{2} = \sin^3(4t) + j \sin(6t)$

$$T_1 = \frac{2\pi}{4} = \frac{\pi}{2}$$

$$T_2 = \frac{2\pi}{6} = \frac{\pi}{3}$$

$$T_0 = LCM(T_1, T_2) = LCM\left(\frac{\pi}{2}, \frac{\pi}{3}\right) = \pi$$

2. Energy and Power

(a) (2 pts) $x(t) = e^{-at}u(-t)$, $a > 0$. Evaluate E_∞ and P_∞ . Is $x(t)$ an energy signal or a power signal? Show that $x(t)$ is not an energy signal and not a power signal.

Solution.

$$u(-t) = \begin{cases} 1 & t \leq 0 \\ 0 & t > 0 \end{cases}$$

$$E_\infty = \int_{-\infty}^0 x(t)^2 dt$$

$$E_\infty = \int_{-\infty}^0 e^{-2at} dt$$

$$E_\infty = -\frac{1}{2a} e^{-2at} \Big|_{-\infty}^0$$

$$E_\infty = \infty$$

So, $x(t)$ is not an energy signal.

$$P_\infty = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x(t)^2 dt$$

$$P_\infty = \lim_{T \rightarrow \infty} \frac{1}{T} \left(-\frac{1}{2a} e^{-2at} \right) \Big|_{-T/2}^0$$

$$P_\infty = \lim_{T \rightarrow \infty} \frac{e^{aT} - 1}{2aT} = \frac{e^\infty - 1}{\infty} = \infty$$

Therefore, $x(t)$ is not a power signal

(b) (2 pts) Find the energy E_∞ and power P_∞ of the signal $x(t) = \cos^2(2t)$. Is this an energy signal or a power signal? Show that $x(t)$ has infinite energy but finite power with $P_\infty = \frac{3}{8}$, so hence it is a power signal.

Hint: The power of a periodic signal can be calculated from the power in one period.

Solution.

$$E_\infty = \int_{-\infty}^{\infty} |f(t)|^2 dt = \int_{-\infty}^{\infty} \cos^4(2t) dt$$

Since the area under $\cos^4(2t)$ is infinite, this is not an energy signal.

The power of a periodic signal can be calculated from the power in one period:

$$P_\infty = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |f(t)|^2 dt$$

If it is a periodic signal

$$\begin{aligned}
P_\infty &= \lim_{kT \rightarrow +\infty} \frac{1}{kT} \int_{-kT/2}^{kT/2} |f(t)|^2 dt \\
&= \lim_{kT \rightarrow +\infty} \frac{1}{kT} k \int_{-T/2}^{T/2} |f(t)|^2 dt \\
&= \lim_{kT \rightarrow +\infty} \frac{1}{T} \int_{-T/2}^{T/2} |f(t)|^2 dt \\
&= \frac{1}{T} \int_{-T/2}^{T/2} |f(t)|^2 dt
\end{aligned}$$

So, the power of this signal is

$$\begin{aligned}
P_\infty &= \frac{2}{2\pi} \int_{-\pi/2}^{\pi/2} \cos^4(2t) dt \\
&= \frac{1}{\pi} \int_{-\pi/2}^{\pi/2} \frac{3}{8} + \frac{1}{2} \cos(4t) + \frac{1}{8} \cos(8t) dt \\
&= \frac{1}{\pi} \left(\frac{3}{8} t + \frac{1}{8} \sin(4t) + \frac{1}{64} \sin(8t) \right) \Big|_{t=-\pi/2}^{t=\pi/2} \\
&= \frac{1}{\pi} \frac{3\pi}{8} = \frac{3}{8}
\end{aligned}$$

Because $0 < P_\infty < \infty$, this is a power signal.

- (c) (4 pts) Find the energy E_∞ and power P_∞ of the signal $x(t)$ is defined as below. Is this an energy signal or a power signal?

$$x(t) = \begin{cases} t+1 & -1 < t < 0 \\ -t+1 & 0 \leq t < 1 \\ 0 & \text{otherwise} \end{cases}$$

Solution.

$$E_\infty = \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-1}^0 (t+1)^2 dt + \int_0^1 (-t+1)^2 dt = \int_{-1}^0 t^2 + 2t + 1 dt + \int_0^1 t^2 - 2t + 1 dt = \frac{1}{3} + \frac{1}{3} = \frac{2}{3}.$$

Hence, the energy of $x(t)$ is $\frac{2}{3}$.

$$P_\infty = \lim_{T \rightarrow +\infty} \frac{1}{T} \times \frac{2}{3} = 0$$

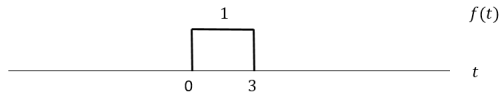
Hence this is an energy signal.

3. Unit Step and Unit Impulse

- (a) Graph the following sum of unit step functions. See HW3 Supplementary Notes for extra assistance, if needed.

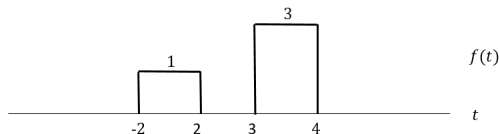
- i. (2 pts) $f(t) = u(t) - u(t-3)$

Solution.



- ii. (2 pts) $f(t) = u(t+2) - u(t-2) + 3u(t-3) - 3u(t-4)$

Solution.



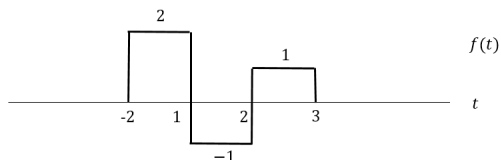
- (b) Consider the following signal:

$$f(t) = -u(t-3) - 3u(t-1) + 2u(t+2) + 2u(t-2)$$

- i. (2 pts) Graph $f(t)$

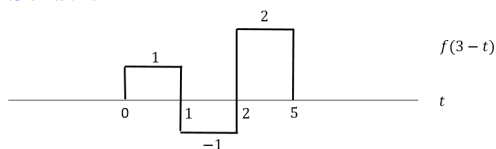
Solution.

$$\text{Reordering terms: } f(t) = 2u(t+2) - 3u(t-1) + 2u(t-2) - u(t-3)$$



ii. (2 pts) Graph $f(3 - t)$

Solution.



(c) Given the following piecewise function, rewrite each function in terms of the unit step function. See HW3 Supplementary Notes for extra assistance, if needed.

i. (2 pts) $f(t) = \begin{cases} 3, & 2 < t < 4 \\ 0, & \text{otherwise} \end{cases}$

Solution.

$$f(t) = \begin{cases} 3, & 2 < t < 4 \\ 0, & \text{otherwise} \end{cases} = 3 \cdot \begin{cases} 1, & 2 < t < 4 \\ 0, & \text{otherwise} \end{cases} = \boxed{3[u(t-2) - u(t-4)]}$$

ii. (2 pts) $f(t) = \begin{cases} -2, & -3 < t < -1 \\ 4, & 5 < t < 7 \\ 0, & \text{otherwise} \end{cases}$

Solution.

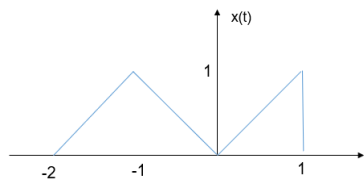
$$f(t) = \begin{cases} -2, & -3 < t < -1 \\ 4, & 5 < t < 7 \\ 0, & \text{otherwise} \end{cases} = -2 \cdot \begin{cases} 1, & -3 < t < -1 \\ 0, & \text{otherwise} \end{cases} + 4 \cdot \begin{cases} 1, & 5 < t < 7 \\ 0, & \text{otherwise} \end{cases} = \boxed{-2[u(t+3) - u(t+1)] + 4[u(t-5) - u(t-7)]}$$

(d) (2 pts) Show that the following statement is true. $\int_{-\infty}^0 [2\delta(t+3) + 3\delta(t-1)]dt = 2$

Solution.

$$\int_{-\infty}^0 2\delta(t+3) + 3\delta(t-1)dt = \int_{-\infty}^0 2\delta(t+3)dt + \int_{-\infty}^0 3\delta(t-1)dt = 2 + 0 = 2$$

(e) (4 pts) Consider $x(t)$ below:



Simplify the following: $x(t)x(-t)[\delta(t-0.5) + \delta(t+1.5)]$.

Solution.

$$x(0.5)x(-0.5)\delta(t-0.5) + x(0.5)x(-0.5)\delta(-1.5) = 0.5 \times 0.5\delta(t-0.5) + 0 = 0.25\delta(t-0.5).$$

- (f) (2 pts) Evaluate $\int_{-\infty}^{\infty} \tau^2 \delta(\tau + 1) d\tau$. Show that the answer is 1.

Solution.

$$\int_{-\infty}^{\infty} \tau^2 \delta(\tau + 1) d\tau = (-1)^2 = 1$$

4. *Causal.*

Consider the following input-output relationships of a system:

- (a) (2 pts) $y(t) = x(t - 3) - x(3 - t)$. Is the system causal? Show that the system is *not* causal.

Solution. *The system is not causal because $x(3 - t)$ can depend on future values of input $x(t)$, e.g. $y(-3) = x(-6) - x(6)$.*

- (b) (4 pts) $y(t) = x(t/4)$. Is the system causal?

Solution. *The system is not causal because $y(t)$ depends on future values of the input: $y(-4) = x(-1)$.*

- (c) (2 pts) $y(t) = \frac{dx(t)}{dt}$. Is the system causal? Show that the system is causal.

Solution. *The system is causal because the derivative depends only on present values of t .*

- (d) (4 pts) $y(t) = \cos(2t)x(t - 7) + \sin(t)x(t - 1)$. Is the system causal?

Solution. *The system is causal because $x(t - 7)$ and $x(t - 1)$ depend on only present or past values of t .*

- (e) (4 pts) The input-output relationship is given as:
 $y(t) = x(t + 3a - 2b + 4)$. Given input-output relationship, determine the values of b in terms of a that will make the system causal.

Solution. *To make the system causal, we have to make $3a - 2b + 4 \leq 0$. Hence, $3a - 2b + 4 \leq 0$*

$$3a + 4 \leq 2b. \quad \boxed{b \geq \frac{3a + 4}{2}}.$$

5. *Stable.*

Consider the following input-output relationships of a system:

- (a) (2 pts) $y(t) = x(t)(x(t - k))$ where k is a real number. Is the system stable?
 Show that the system is stable by showing that it has a constant upper bound.

Solution. *Assume $|x(t)| \leq M$ for all time t . Therefore $|y(t)| = |x(t)||x(t - k)| \leq M^2$. Since M^2 is a constant the system is stable.*

- (b) (2 pts) $y(t) = \int_t^{2t} x(\tau) d\tau$. Is the system stable?
 Show that the system is *not* stable by showing that it has no constant upper bound.

Solution. *Assume $|x(t)| \leq M$. Therefore $|y(t)| = \left| \int_t^{2t} x(\tau) d\tau \right| \leq \left| \int_t^{2t} M d\tau \right| = Mt$. $\lim_{t \rightarrow \infty} Mt$ is not bounded, so the system is not stable.*

- (c) (4 pts) $y(t) = \int_{10}^{300} x(\tau) d\tau$. Is the system stable?

Solution. *Assume $|x(t)| \leq M$ for all t . Therefore $|y(t)| = \left| \int_{10}^{300} x(\tau) d\tau \right| \leq \int_{10}^{300} M d\tau \leq 290M$. Since $290M$ is a constant the system is stable.*

- (d) (4 pts) $y(t) = \frac{d}{dt}(x(t) - t^2)$. Is the system stable? Hint: find the counter-example.

Solution. Counter example: $x(t) = u(t)$

$$y(t) = \frac{du(t)}{dt} - 2t = \delta(t) - 2t$$

Input $u(t)$ is bounded, but output $y(t)$ is ∞ when $t = 0$, so the system is not stable.

6. *Invertible.*

Given the following input-output relationships of different systems find out if the system is invertible or not; if so, derive the inverse. Justify your answer in both cases.

- (a) (2 pts) $y(t) = x(t/3)$. Is this system invertible?

Show that it is.

Solution. The system represented by $y(t) = x(t/3)$ is invertible, because we can recover $x(t)$ given $y(t)$ as follows: let $t' = t/3$. Then $x(t') = y(3t')$.

- (b) (2 pts) $y(t) = \begin{cases} x^3(t) & t > 2 \\ 0 & \text{otherwise} \end{cases}$. Is this system invertible?

Show that it is NOT invertible.

Solution. The system represented by $y(t) = \begin{cases} x^3(t) & t > 2 \\ 0 & \text{otherwise} \end{cases}$ is not invertible. This is because for $t \leq 2$, we can't recover $x(t)$ from zero.

- (c) (4 pts) $y(t) = tx(t)$. Is this system invertible?

Solution. No, the system is not invertible. Both $x(t) = \delta(t)$ and $x(t) = 2\delta(t)$ give the same output, $y(t) = 0$.

- (d) (4 pts) $y(t) = (x(t))^k$, where k is an integer. Is the system invertible?

Hint: Think of two cases, one when k is odd, second when k is even. It might help to draw a picture of $(x(t))^k$ for a couple of small values of k to guess what the answer might be; once you guess it, you can prove invertibility or non-invertibility for each of the two cases.

Solution. We have two cases. When k is even, $x(t)$ and $-x(t)$ produce the same output because $(-1)^k = 1$ for even value of k ; therefore in this case, the system is not invertible. On the other hand, when k is odd, the system is invertible, since we can recover x by the formula $x(t) = (y(t))^{1/k}$.

- (e) (2 pts) $y(t) = \begin{cases} x(t-7) & t > 1 \\ 8x(t) & t \leq 1 \end{cases}$. Is this system invertible or not?

Show that it is invertible.

Solution. This is an invertible system, as can be seen by the following inverse function:

$$x(t) = \begin{cases} y(t+7) & t > 1 \\ \frac{1}{8}y(t) & t \leq 1 \end{cases}.$$

7. *Time-Invariance.*

Given input-output relationship of a system, prove whether system is time-invariant.

- (a) (2 pts) Consider the system $y(t) = x(5t) + \sin(x(t))$. Is this system time-invariant?

Solution. We have,

$$\begin{aligned} y(t - t_0) &= x(5(t - t_0)) + \sin(x(t - t_0)). \\ &= x(5t - 5t_0) + \sin(x(t - t_0)). \end{aligned} \tag{1}$$

Next,

$$\mathcal{T}(x(t - t_0)) = x(5t - t_0) + \sin(x(t - t_0)). \tag{2}$$

In general, the right hand sides of Equation 1 and 2 are not equal. Therefore this system is not time-invariant.

- (b) Consider a system \mathcal{T} with input $x(t)$ and output $y(t)$ related by:

$$y(t) = x(t)\{g(t) + g(t-1)\}$$

- i. (2 pts) If $g(t) = 1$ for all t , show that \mathcal{T} is time-invariant using the time-invariance test from lecture.

Solution. For $g(t) = 1$, $y(t) = x(t)\{1 + 1\} = 2x(t)$.

$$y(t - t_0) = 2x(t - t_0)$$

$$\text{Let } x_1(t) = x(t - t_0)$$

$$y_1(t) = \mathcal{T}1(t) = 2x_1(t) = 2x(t - t_0) = y(t - t_0)$$

The system \mathcal{T} is time invariant.

- ii. (2 pts) If $g(t) = t$, show that \mathcal{T} is not time-invariant by using the time-invariance test from lecture.

Solution. For $g(t) = t$, $y(t) = x(t)\{2t - 1\} = (2t - 1)x(t)$.

$$y(t - t_0) = (2t - 2t_0 - 1)x(t - t_0)$$

$$\text{Let } x_1(t) = x(t - t_0)$$

$$y_1(t) = \mathcal{T}x_1(t) = (2t - 1)x_1(t) = (2t - 1)x(t - t_0) \neq y(t - t_0)$$

The system \mathcal{T} is not time invariant.

- (c) (2 pts) Consider the system \mathcal{T} where $y(t) = \mathcal{T}(x(t)) = x(\sin(t))$. Is this time-invariant?

Solution. *We have,*

$$y(t - t_0) = x(\sin(t - t_0)). \quad (3)$$

Also,

$$\mathcal{T}(x(t - t_0)) = x(\sin(t) - t_0). \quad (4)$$

The right hand sides of Equations 3 and 4 are not the same, in general. So this is a time-varying system.

8. *Homework Self-Reflection* (10 pts) After completing your homework, go to the following link to rate your skill or concept understanding level for each item listed. Your self-reflection must be completed by the due date. All submissions are time-stamped, so please give yourself plenty of time to complete and submit your self-reflection.

<http://bit.ly/2CVDofA>