

EE 235, Winter 2018, Homework 6: Fourier Series
Due Friday February 9, 2018 via Canvas Submission
Write down ALL steps for full credit

HW6 Topics:

- Fourier Series: Analysis, Synthesis, Properties, and LTI

HW6 Course Learning Goals Satisfied:

- Goal 1: Describe signals in different domains (time, frequency, and Laplace) and map characteristics in one domain to those in another.
- Goal 4: Analyze LTI system given different system representations (including input-output equations, impulse response, frequency response) and translate between these representations.

HW6 References: OWN Sections 3.2 - 3.5, 3.8

HW6 Problems (Total = 104 pts):

1. *Review* (16 pts)

(a) *Partial Fraction Expansion.* (2 pts)

$X(s) = \frac{-5}{s^2+2s+2}$. Using the cover-up method, show that $X(s) = -\frac{\frac{5}{2}j}{s+1+j} + \frac{\frac{5}{2}j}{s+1-j}$.

Solution. *Finding roots of denominator:*

$$s = -\frac{-2 \pm \sqrt{4-4(2)(1)}}{2} = -1 \pm j$$

Rewriting $X(s)$ as partial fractions:

$$X(s) = \frac{-5}{s^2+2s+2} = \frac{-5}{(s+1+j)(s+1-j)} = \frac{A}{s+1+j} + \frac{B}{s+1-j}$$

Finding A:

$$A = \left. \frac{-5}{(s+1+j)} \right|_{s=-1-j} = \frac{-5}{-1-j+1-j} = \frac{5}{2j} = -\frac{5}{2}j$$

Finding B:

$$B = A^* = \frac{5}{2}j$$

(b) *Partial Fraction Expansion.* (4 pts)

$X(s) = \frac{s+2}{s(s+1)^2(s+5)}$. Using the cover-up method.

Solution. *Rewriting $X(s)$ as partial fractions:*

$$X(s) = \frac{A}{s} + \frac{B1}{s+1} + \frac{B2}{(s+1)^2} + \frac{C}{s+5}$$

Finding A:

$$A = \left. \frac{s+2}{(s+1)^2(s+5)} \right|_{s=0} = \frac{2}{1(5)} = \frac{2}{5}$$

Finding C:

$$C = \left. \frac{s+2}{(s)(s+1)^2} \right|_{s=-5} = \frac{-3}{(-5)(16)} = \frac{3}{80}$$

Finding B2:

$$B2 = \left. \frac{s+2}{(s)(s+5)} \right|_{s=-1} = \frac{1}{(-1)(4)} = -\frac{1}{4}$$

Finding B1:

$$B1 = \frac{d}{ds} \left[\frac{s+2}{(s)(s+5)} \right] \Big|_{s=-1} = \frac{(s^2+5s)(1)-(s+2)(2s+5)}{(s^2+5s)^2} \Big|_{s=-1} = \frac{(1-5)(1)-(-1+2)(-2+5)}{(1-5)^2} = \frac{-4-3}{16} = -\frac{7}{16}$$

(c) *Magnitude and Phase Equation.* (2 pts)

Let $X = \frac{1}{\alpha - j\omega}$, where $\alpha > 0$. Evaluate the magnitude and phase of X . Show that $|X| = \frac{1}{\sqrt{\alpha^2 + \omega^2}}$ and $\angle X = \tan^{-1}(\frac{\omega}{\alpha})$.

Solution. *Magnitude: we can evaluate the magnitude by taking the magnitude of the numerators and denominators separately*

$$|X| = \frac{|1|}{|\alpha - j\omega|} = \frac{1}{\sqrt{\alpha^2 + (-\omega)^2}} = \frac{1}{\sqrt{\alpha^2 + \omega^2}}$$

Phase: we can evaluate phase by taking the phase of the numerator minus the phase of the denominator

$$\angle(X) = \angle(1) - \angle(\alpha - j\omega) = \arctan\left(\frac{0}{1}\right) - \arctan\left(\frac{-\omega}{\alpha}\right) = 0 - (-\arctan\left(\frac{\omega}{\alpha}\right)) = \arctan\left(\frac{\omega}{\alpha}\right).$$

- (d) *Signal Properties.* (4 pts)

$x(t) = \cos(t + \frac{\pi}{3})$. Evaluate P_∞ . Is $x(t)$ a power signal?

Show that the power of the signal is $P_\infty = \frac{1}{2}$, thus making $x(t)$ a power signal.

Hint: If $x(t)$ is periodic with fundamental period T_o , the power of $x(t)$, P_∞ is equivalent to the average power of $x(t)$ over any interval of length T_o : $P = \frac{1}{T_o} \int_0^{T_o} |x(t)|^2 dt$.

Solution. $P_\infty = \frac{1}{T_o} \int_0^{T_o} \cos^2(t + \frac{\pi}{3}) dt$

$$P_\infty = \frac{1}{2\pi} \int_0^{2\pi} \cos^2(t + \frac{\pi}{3}) dt$$

$$P_\infty = \frac{1}{2\pi} \left[\frac{t}{2} + \frac{\cos(2(t + \frac{\pi}{3}))}{4} \right]_0^{2\pi}$$

$$P_\infty = \frac{1}{2\pi} \left[\frac{2\pi}{2} + \frac{\cos(2(2\pi + \frac{\pi}{3}))}{4} - 0 - \frac{\cos(2(0 + \frac{\pi}{3}))}{4} \right]$$

$$P_\infty = \frac{1}{2}$$

$P_\infty < \infty$, so $x(t)$ is a power signal.

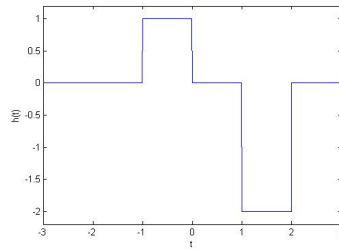
- (e) *Convolution.* (4 pts)

Let T denote an LTI system with impulse response $p(t+1) - 2p(t-1)$, then find and sketch $y(t) = T[p(-t/2)]$.

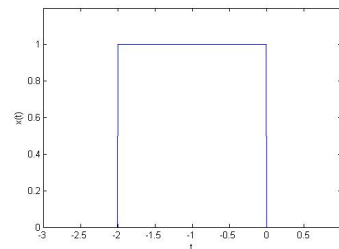
Hint: The pulse signal $p(t) = u(t) - u(t-1)$.

Solution. (We have sketched all the different cases here, but you don't need to give all these sketches in your solution as long as you work out the convolution correctly.)

The impulse response of the system is:



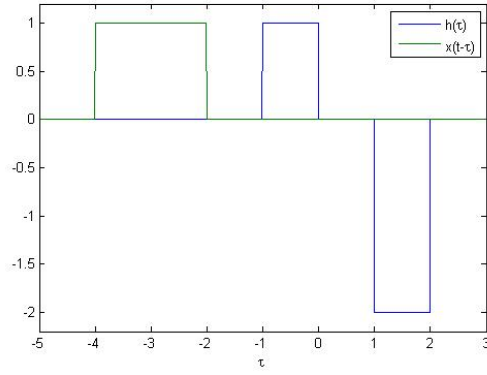
The input signal is:



The output signal is the convolution of the input signal and the impulse response:

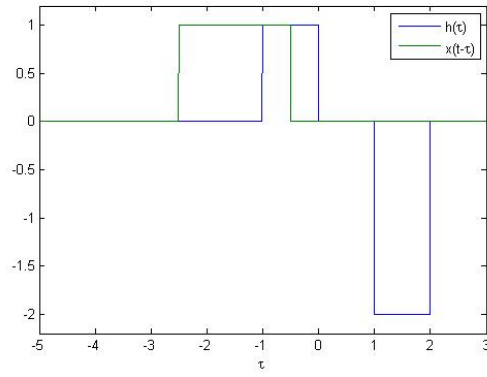
$$y(t) = h(t) * x(t) = \int_{-\infty}^{\infty} h(\tau)x(t-\tau)d\tau = \int_{-\infty}^{\infty} (p(\tau+1) - 2p(\tau-1))p\left(\frac{\tau-t}{2}\right)d\tau$$

When $t < -3$, as shown in the following figure, $y(t) = 0$ because there is not any overlap region between $h(t)$ and $x(t)$.



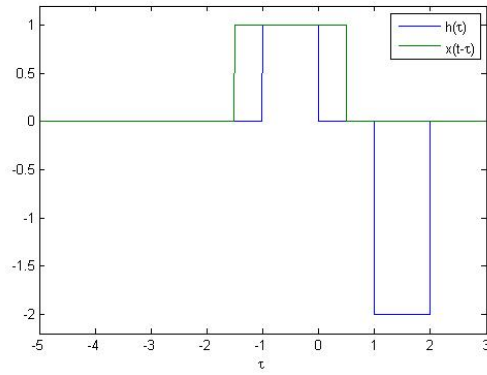
When $-3 \leq t < -2$, as shown in the following figure, the system output $y(t)$ is:

$$y(t) = \int_{-1}^t 1 d\tau = t + 3$$



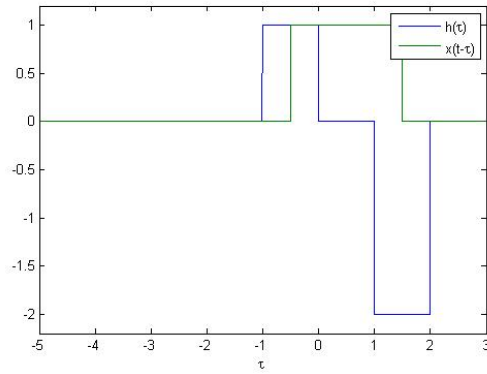
When $-2 \leq t < -1$, as shown in the following figure, the system output $y(t)$ is:

$$y(t) = \int_{-1}^0 1 d\tau = 1$$



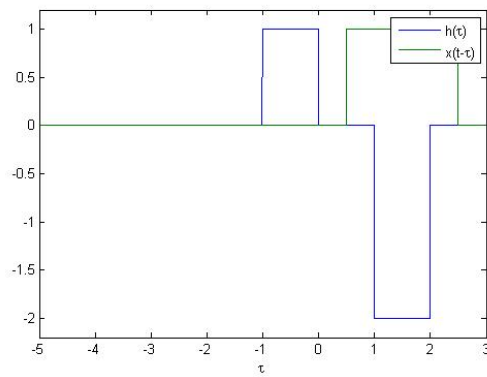
When $-1 \leq t < 0$, as shown in the following figure, the system output $y(t)$ is:

$$y(t) = \int_t^0 1 d\tau + \int_1^{t+2} -2 d\tau = -3t - 2$$



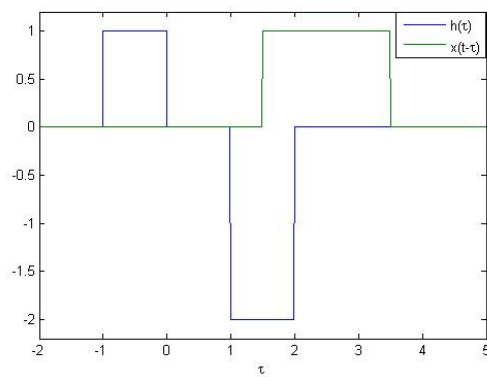
When $0 \leq t < 1$, as shown in the following figure, the system output $y(t)$ is:

$$y(t) = \int_1^2 -2d\tau = -2$$



When $1 \leq t < 2$, as shown in the following figure, the system output $y(t)$ is:

$$y(t) = \int_t^2 -2d\tau = 2t - 4$$

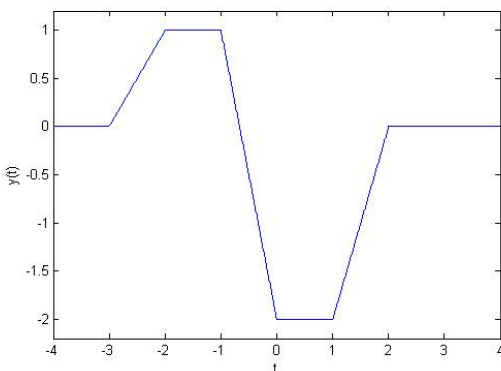


When $t \geq 2$, $y(t) = 0$ because there is not any overlap between the input signal and the system

impulse response.

$$y(t) = T[p(-t/2)] = \begin{cases} t+3, & -3 \leq t < -2 \\ 1, & -2 \leq t < -1 \\ -3t-2, & -1 \leq t < 0 \\ -2, & 0 \leq t < 1 \\ 2t-4, & 1 \leq t < 2 \\ 0, & \text{o.w.} \end{cases}$$

The plot is sketched as follows:



2. LTI System Description (14 pts)

Consider the following three LTI systems:

- T_1 : Has impulse response $h_1(t) = \begin{cases} 2, & -1 < t < 1 \\ 0, & \text{otherwise} \end{cases}$
- T_2 : Has step response $s_2(t) = 2u(t-1)$
- T_3 : Has input-output relationship $y_3(t) = x_3(t+2)$

(a) (4 pts) What is the step response $s_1(t)$ of system T_1 ?

Solution. $s_1(t) = \int_{-\infty}^t h_1(\tau) d\tau$

Case 1: $t < -1$

$$s_1(t) = \int_{-\infty}^t h_1(\tau) d\tau$$

Since $h_1(\tau) = 0$ from $\tau = -\infty$ to $\tau = t$ for this case, $s_1(t) = 0$

Case 2: $-1 < t < 1$

$$s_1(t) = \int_{-\infty}^t h_1(\tau) d\tau$$

Since $h_1(\tau) = 2$ only from $\tau = -1$ to $\tau = t$ for this case, $s_1(t) = \int_{-1}^t 2d\tau = 2t + 2$

Case 3: $t > 1$

$$s_1(t) = \int_{-\infty}^t h_1(\tau) d\tau$$

Since $h_1(\tau) = 2$ only from $\tau = -1$ to $\tau = 1$ for this case, $s_1(t) = \int_{-1}^1 2d\tau = 4u(t)$

(b) (4 pts) What is impulse response $h_2(t)$ of system T_2 ?

Solution. $h_2(t) = \frac{ds_2(t)}{dt} = \frac{2u(t-1)}{dt} = 2\delta(t-1)$

(c) (2 pts) What is the corresponding input-output relationship for system T_2 ? Show that $y_2(t) = 2x_2(t-1)$.

Solution. We can find the input-output relationship using convolution:

$$y(t) = x_2(t) * h(t) = x_2(t) * 2\delta(t-1) = 2x_2(t-1).$$

(d) (4 pts) What is the impulse response $h_3(t)$ of system T_3 ? What is the corresponding step response $s_3(t)$?

Solution. Using the definition of the impulse response: Let $x_3(t) = \delta(t)$
 $y(t) = T[\delta(t)] = \delta(t+2)$.
Therefore, $h_3(t) = \delta(t+2)$.
For step response:
 $s_3(t) = \int_{-\infty}^t h_3(\tau) d\tau = \int_{-\infty}^t \delta(\tau+2) d\tau = u(t+2) - u(-\infty+2)$
Therefore, $s_3(t) = u(t+2)$.

3. LTI System Interconnection and Properties (14 pts)

Consider the same LTI systems in Problem 2. Answer the following questions.

- (a) (2 pts) Is system T_2 BIBO stable? Using the impulse response test that we discussed in lecture, show that T_2 is BIBO stable with $\int_{-\infty}^{\infty} |h(t)| dt = 2$.

Solution. $\int_{-\infty}^{\infty} |h(t)| dt = \int_{-\infty}^{\infty} |2\delta(t-1)| dt = \int_{-\infty}^{\infty} 2\delta(t-1) dt = 2 \int_{-\infty}^{\infty} \delta(t-1) dt = 2(1) = 2$
Because the integral is finite, that means T_2 is BIBO stable.

- (b) (4 pts) Suppose T_1 and T_3 are connected in parallel. Is the overall system causal? Use the impulse response test that we discussed in lecture.

Solution. In parallel, $h(t) = h_1(t) + h_3(t) = \delta(t+2) + \begin{cases} 2, & -1 < t < 1 \\ 0, & \text{otherwise} \end{cases}$
Because $h(t) \neq 0$ for all $t < 0$, the overall system is not causal.

- (c) (4 pts) Suppose T_2 and T_3 are connected in parallel. Find the overall impulse response $h(t)$ and then find the overall output $y(t)$ when the input is $x(t) = \sin(t^2)$.

Solution. In parallel, $h(t) = h_2(t) + h_3(t) = 2\delta(t-1) + \delta(t+2)$
Computing the output:
 $y(t) = x(t) * h(t) = \sin(t^2) * [2\delta(t-1) + \delta(t+2)] = \boxed{2\sin(t^2 - 2t + 1) + \sin(t^2 + 4t + 4)}$.

- (d) (4 pts) Suppose T_1 and T_3 are connected in series. Is the system causal? Is the system BIBO stable? Use the impulse response tests.

Solution. In series, $h(t) = h_1(t) * h_3(t) = h_1(t) * \delta(t+2) = \begin{cases} 2, & -3 < t < -1 \\ 0, & \text{otherwise} \end{cases}$
For causality:
Because $h(t) \neq 0$ for all $t < 0$, the overall system is not causal.
For stability:
 $\int_{-\infty}^{\infty} |h(t)| dt = \int_{-3}^{-1} 2 dt = 4$
Because the integral is finite, this system is BIBO stable.

4. Fourier Series: Synthesis. (4 pts)

- (a) (2 pts) $w_o = \frac{\pi}{4}$ and $a_0 = -2$, $a_1 = a_{-1} = 1$, $a_2 = a_{-2}^* = \frac{1}{j}$, $a_3 = 2$, and $a_{-3} = -2$.
Using the synthesis equation, convert back to the time domain and show that:
 $x(t) = -2[1 - \cos(\frac{\pi}{4}t) - \sin(\frac{\pi}{2}t) - 2j \sin(\frac{3\pi}{4}t)]$

Solution. $x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_o t}$
 $x(t) = -2e^{-j\frac{3\pi}{4}t} - \frac{1}{j}e^{-j\frac{\pi}{2}t} + e^{j\frac{\pi}{4}t} - 2e^0 + e^{-j\frac{\pi}{4}t} + \frac{1}{j}e^{j\frac{\pi}{2}t} + 2e^{j\frac{3\pi}{4}t}$
 $x(t) = -2 + (e^{j\frac{\pi}{4}t} + e^{-j\frac{\pi}{4}t}) + \frac{1}{j}(e^{j\frac{\pi}{2}t} - e^{-j\frac{\pi}{2}t}) + 2(e^{j\frac{3\pi}{4}t} - e^{-j\frac{3\pi}{4}t})$
 $x(t) = -2[1 - \cos(\frac{\pi}{4}t) - \sin(\frac{\pi}{2}t) - 2j \sin(\frac{3\pi}{4}t)]$

- (b) (2 pts) $w_o = \frac{\pi}{4}$ and $a_1 = \frac{1}{2j}e^{j\frac{\pi}{4}}$, $a_{-1} = -\frac{1}{2j}e^{-j\frac{\pi}{4}}$.

Using the synthesis equation, convert back to the time domain and show that:

$$x(t) = \sin\left(\frac{\pi}{4}t + \frac{\pi}{4}\right)$$

Solution. $x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_o t}$

$$x(t) = -\frac{1}{2j}e^{-j\frac{\pi}{4}}e^{-j\frac{\pi}{4}t} + \frac{1}{2j}e^{j\frac{\pi}{4}}e^{j\frac{\pi}{4}t}$$

$$x(t) = \frac{1}{2j}e^{j(\frac{\pi}{4} + \frac{\pi}{4}t)} - \frac{1}{2j}e^{-j(\frac{\pi}{4} + \frac{\pi}{4}t)}$$

$$x(t) = \sin\left(\frac{\pi}{4}t + \frac{\pi}{4}\right)$$

5. (Fourier Series: Analysis) (20 pts) In the following problems, we practice analyzing signals and computing their Fourier Series coefficients:

- (a) Consider the continuous-time signal $x(t) = 2\cos(3t)\sin(t) - je^{-j8t} + e^{j6(t-3)}$.

- i. (4 pts) Show the Fourier Series representation of $x(t)$ by finding the fundamental frequency ω_0 and its Fourier Series coefficients a_k .

Hint: $\cos(A)\sin(B) = \frac{1}{2}[\sin(A+B) - \sin(A-B)]$

Solution. $x(t) = 2\cos(3t)\sin(t) - je^{-j8t} + e^{j6(t-3)} = \sin(4t) - \sin(2t) - je^{-j8t} + e^{j6(t-3)}$

$$T_0 = LCM\left(\frac{2\pi}{4}, \frac{2\pi}{2}, \frac{2\pi}{8}, \frac{2\pi}{6}\right) = \pi$$

$$\omega_0 = \frac{2\pi}{T_0} = \frac{2\pi}{\pi} = 2.$$

$$x(t) = \frac{1}{2j}e^{j4t} - \frac{1}{2j}e^{-j4t} - \frac{1}{2j}e^{j2t} + \frac{1}{2j}e^{-j2t} - je^{-j8t} + e^{-j18}e^{j6t}.$$

Hence,

$$a_{-4} = -j, a_{-2} = -\frac{1}{2j}, a_{-1} = \frac{1}{2j}, a_1 = -\frac{1}{2j}, a_2 = \frac{1}{2j}, a_3 = e^{-j18}, a_k = 0, \text{ otherwise.}$$

- ii. (2 pts) Using the result of the previous part, find the power of $x(t)$ using Parseval's Theorem.

Solution. $P_\infty = \sum_{k=-\infty}^{\infty} |a_k|^2 = 1 + \frac{1}{4} + \frac{1}{4} + 1 + \frac{1}{4} + \frac{1}{4} = 3$

- (b) Consider a signal $x(t) = \sin(3\pi t) + \cos(2\pi t)$. Answer the following questions about $x(t)$.

- i. (1 pt) What the fundamental frequency ω_0 of this signal?

Solution. $T_0 = LCM\left(\frac{2\pi}{3\pi}, \frac{2\pi}{2\pi}\right) = 2$. Therefore $w_0 = 2\pi/2 = \pi$ (rad/s).

- ii. (1 pt) Express $x(t)$ as a sum of complex exponentials using Euler's formula.

Solution. $x(t) = \frac{1}{2j}e^{j3\pi t} - \frac{1}{2j}e^{-j3\pi t} + \frac{1}{2}e^{j2\pi t} + \frac{1}{2}e^{-j2\pi t}$.

- iii. (2 pts) What are the coefficients a_k in the Fourier Series representation of $x(t)$?

Solution. Synthesis equation: $x(t) = \sum_{k=-\infty}^{\infty} a_k e^{j\omega_0 k t}$.

From solution to part (b), and the fact that $\omega_0 = \pi$, we have:

$$a_3 = 1/2j, a_{-3} = -1/2j, a_2 = 1/2, \text{ and } a_{-2} = 1/2. \text{ All other } a_k \text{'s are } 0.$$

- iv. (1 pt) The DC component of a signal is defined as its mean value. What is the DC component of this signal?

Solution. $a_0 = 0$ so the DC component is 0.

- (c) Consider the periodic signal described by $x(t) = \sum_{k=-\infty}^{\infty} \delta(t-2k) - \frac{1}{4} \sum_{k=-\infty}^{\infty} \delta(t+2k-1)$. Answer the following questions about this signal.

- i. (1 pt) Find the fundamental frequency, ω_0 .

Solution. Period = 2, $\omega_0 = \frac{2\pi}{2} = \pi$.

- ii. (4 pts) Find the DC value c_0 , and the Fourier series coefficients c_k for $k \neq 0$. Specify the value of c_k for even k and odd k .

Solution. We have,

$$c_0 = \frac{1}{2} \int_{-1/2}^{3/2} (\delta(t) - \frac{1}{4}\delta(t-1))dt = \frac{1}{2}(1 - 1/4) = 3/8.$$

For a general coefficient c_k , we have:

$$\begin{aligned} c_k &= \frac{1}{2} \int_{-1/2}^{3/2} (\delta(t) - \frac{1}{4}\delta(t-1))e^{-jk\pi t} dt \\ &= \frac{1}{2} \left(\int_{-1/2}^{3/2} \delta(t)e^{-jk\pi(0)} dt - \frac{1}{4} \int_{-1/2}^{3/2} \delta(t-1)e^{-jk\pi(-1)} dt \right) \\ &= \frac{1}{2} \left(1 - \frac{1}{4}e^{-jk\pi} \right) = \frac{1}{2} \left(1 - \frac{1}{4}(-1)^k \right) = \begin{cases} 3/8 & \text{if } k \text{ even} \\ 5/8 & \text{if } k \text{ odd} \end{cases} \end{aligned}$$

- (d) (4 pts) Consider a periodic signal of the form $x(t) = \begin{cases} 1 & \text{if } 0 \leq t < 4 \\ -1 & \text{if } 4 \leq t < 8 \end{cases}$, with period $T = 8$. Compute the Fourier series coefficients of this signal *using analysis formulas*.

Solution. We have:

$$\begin{aligned} a_k &= \frac{1}{8} \int_0^4 e^{-jk(\pi/4)t} dt - \frac{1}{8} \int_4^8 e^{-jk(\pi/4)t} dt \\ &= \frac{1}{8} \frac{e^{-jk(\pi/4)t}}{-jk(\pi/4)} \Big|_0^4 - \frac{1}{8} \frac{e^{-jk(\pi/4)t}}{-jk(\pi/4)} \Big|_4^8 \\ &= \frac{1}{2\pi jk} (1 - e^{-jk\pi}) + \frac{1}{2j\pi k} (e^{-2jk\pi} - e^{-jk\pi}) \\ &= \frac{1}{\pi jk} (1 - e^{-jk\pi}) \\ &= \frac{2e^{-jk(\pi/2)}}{2jk\pi} (e^{jk(\pi/2)} - e^{-jk(\pi/2)}) \\ &= \frac{2e^{-jk(\pi/2)}}{\pi k} \sin(k\pi/2) \\ &= e^{-jk\pi/2} \frac{\sin(k\pi/2)}{\pi k/2}. \end{aligned}$$

6. Fourier Series: Properties (6 pts)

- (a) Let $x(t)$ be a continuous-time periodic signal with fundamental frequency ω and Fourier coefficients a_k . Express the Fourier series coefficients of the following signals (call them b_k) in terms of a_k . Justify all your statements. Use the properties from Table 3.1 in the textbook.

- i. (2 pts) $y(t) = x(2-t) + x(t-1)$.

Solution. Apply time reversal and time shift properties to get $b_k = a_k e^{-jk\omega} + a_{-k} e^{-2jk\omega}$.

- ii. (2 pts) $y(t) = \text{Even}(x(t))$.

Solution. We have, $y(t) = \frac{1}{2}(x(t) + x(-t))$. By properties of amplitude scaling and time reversal, this means we have $b_k = \frac{1}{2}(a_k + a_{-k})$.

- iii. (2 pts) $y(t) = x(3t-1)$.

Solution. By time-shift property, $b_k = e^{-jk\omega} a_k$. Note, even though the Fourier series coefficients only have a phase shift, the overall Fourier series representation also encodes the new frequency of the signal.

7. Fourier Series: Parseval's Relation and LTI (30 pts)

- (a) (2 pts) Suppose a signal $x(t)$ has Fourier Series representation $\omega_o = 2, a_5 = a_{-5} = -\frac{1}{3}, a_3 = a_{-3} = \frac{1}{3}, a_2 = a_{-2} = \frac{j}{\pi}$. Compute the average power of the signal $x(t)$.
Show that $P = \frac{4}{9} + \frac{2}{\pi^2}$

Solution.

$$P = \sum_{k=-\infty}^{\infty} |a_k|^2 = \left| -\frac{1}{3} \right|^2 + \left| -\frac{1}{3} \right|^2 + \left| \frac{1}{3} \right|^2 + \left| -\frac{1}{3} \right|^2 + \left| \frac{j}{\pi} \right|^2 + \left| -\frac{j}{\pi} \right|^2$$

$$P = \frac{1}{9} + \frac{1}{9} + \frac{1}{9} + \frac{1}{9} + \frac{1}{\pi^2} + \frac{1}{\pi^2} = \boxed{\frac{4}{9} + \frac{2}{\pi^2}}$$

- (b) (4 pts) Suppose a signal $x(t)$ has Fourier Series representation $\omega_o = 2$ and $a_k = \begin{cases} \frac{1}{2}jk, & |k| < 3 \\ 0, & \text{otherwise} \end{cases}$

Compute the average power of the signal $x(t)$.

Solution.

The only nonzero terms in a_k are:

$$a_{-2} = -j$$

$$a_{-1} = -\frac{1}{2}j$$

$$a_0 = 0$$

$$a_1 = \frac{1}{2}j$$

$$a_2 = j$$

$$P = \sum_{k=-\infty}^{\infty} |a_k|^2 = |-j|^2 + \left| -\frac{1}{2}j \right|^2 + \left| -\frac{1}{2}j \right|^2 + |j|^2$$

$$P = 1 + \frac{1}{4} + 1 + \frac{1}{4} + 1 = 2 + \frac{1}{2} \boxed{\frac{5}{2}}$$

- (c) (4 pts) Suppose a signal with Fourier Series representation $\omega_o = 2, a_5 = a_{-5} = -\frac{1}{3}, a_3 = a_{-3} = \frac{1}{3}, a_2 = a_{-2} = \frac{j}{\pi}$ is input to an LTI system with frequency response

$$H(\omega) = \begin{cases} \omega, & 0 < \omega < 8 \\ -\omega, & -8 < \omega < 0 \\ 0, & \text{otherwise} \end{cases}$$

Find the output Fourier Series coefficients b_k and the corresponding output signal $y(t)$

Show that the final output you get is $y(t) = 4 \cos(6t) - \frac{8}{\pi} \sin(4t)$

Solution.

$$b_k = H(jk\omega_o)a_k = H(j2k)a_k$$

$$b_5 = H(j10)a_5 = 0$$

$$b_{-5} = H(j10)a_5 = 0$$

$$b_3 = H(j6)a_3 = (6)(1/3) = 2$$

$$b_{-3} = H(-j6)a_{-3} = (-(-6))(1/3) = 2$$

$$b_2 = H(j4)a_2 = (4)(j/\pi) = \frac{4j}{\pi}$$

$$b_{-2} = H(-j4)a_{-2} = (-(-4))(-j/\pi) = -\frac{4j}{\pi}$$

$$\boxed{b_3 = 2, b_{-3} = 2, b_2 = \frac{4j}{\pi}, b_{-2} = -\frac{4j}{\pi}}$$

Synthesize to find output in time:

$$y(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk2t} = 2e^{j6t} + 2e^{-j6t} + \frac{4j}{\pi}e^{j4t} - \frac{4j}{\pi}e^{-j4t} = 2[2 \cos(6t)] + \frac{4j}{\pi}[2j \sin(4t)] = \boxed{4 \cos(6t) - \frac{8}{\pi} \sin(4t)}$$

- (d) (4 pts) Suppose a signal with Fourier Series representation $\omega_o = 2$ and $a_k = \begin{cases} \frac{1}{2}jk, & |k| < 3 \\ 0, & \text{otherwise} \end{cases}$ is input to an LTI system with frequency response

$$H(\omega) = \begin{cases} 2, & 10 < |\omega| < 14 \\ 0, & \text{otherwise} \end{cases}$$

Find the output Fourier Series coefficients b_k and the corresponding output signal $y(t)$

Solution.

The only nonzero terms in a_k are:

$$a_{-2} = -j$$

$$a_{-1} = -\frac{1}{2}j$$

$$a_0 = 0$$

$$a_1 = \frac{1}{2}j$$

$$a_2 = j$$

Calculating output coefficients:

$$b_k = H(jk\omega_o)a_k = H(j2k)a_k$$

$$b_{-2} = H(-j4)a_{-2} = 0(-j) = 0$$

$$b_{-1} = H(-j2)a_{-1} = 0(-1/2) = 0$$

$$b_0 = H(j0)a_0 = 0(0) = 0$$

$$b_1 = H(j2)a_2 = 0(1/2) = 0$$

$$b_2 = H(j4)a_4 = 0(j) = 0$$

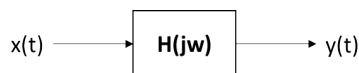
$$\boxed{b_k = 0 \text{ for all } n}$$

Synthesize to find output in time:

$$y(t) = \sum_{n=-\infty}^{\infty} Y_n e^{jn6t} = \boxed{0}$$

(e) *Fourier Series.*

Consider the following LTI system:



Suppose the input to the system is given by: $x(t) = 2\cos(4t) + je^{j2t}$.

Also, suppose the LTI system has the frequency response $H(jw) = \begin{cases} 2 & -2 < w < 10 \\ 0 & \text{otherwise} \end{cases}$.

- i. (4 pts) Transform the input signal $x(t)$ into its Fourier Series representation by finding the fundamental frequency w_o and the Fourier Series coefficients a_k .

Solution.

$$T_o = LCM(\frac{2\pi}{4}, \frac{2\pi}{2}) = \pi \rightarrow w_o = \frac{2\pi}{T_o} = \frac{2\pi}{\pi} = \boxed{2}$$

$$x(t) = 1e^{j4t} + 1e^{-j4t} + je^{j2t}$$

$$a_2 = \boxed{1}, a_{-2} = \boxed{1}, a_1 = \boxed{j}, a_k = \boxed{0} \text{ otherwise.}$$

- ii. (4 pts) Find the output Fourier Series coefficients b_k .

Solution.

$$b_k = a_k H(jkw_o) = a_k H(jk2)$$

$$b_2 = (1)H(j4) = \boxed{2}$$

$$b_{-2} = (1)H(-j4) = \boxed{0}$$

$$b_1 = (j)H(j2) = \boxed{2j}$$

$$b_k = \boxed{0} \text{ otherwise.}$$

- iii. (4 pts) Using your results from (b), find the output signal $y(t)$.

Solution.

$$\begin{aligned} y(t) &= \sum_{k=-\infty}^{\infty} b_k e^{jkw_o t} \\ &= 2e^{j(2)(2)t} + 2je^{j(1)(2)t} \\ &= \boxed{2e^{j4t} + 2je^{j2t}} \end{aligned}$$

- iv. (4 pts) What is the average power of the input, which we can denote as P_{in} ? What is the average power of the output, which we can denote as P_{out} ?

Solution.

$$\begin{aligned} P_{in} &= \sum_{k=-\infty}^{\infty} |a_k|^2 = |1|^2 + |1|^2 + |j|^2 = 1 + 1 + 1 = \boxed{3} \\ P_{out} &= \sum_{k=-\infty}^{\infty} |b_k|^2 = |2|^2 + |2j|^2 = 4 + 4 = \boxed{8} \end{aligned}$$

8. *Homework Self-Reflection* (10 pts) After completing your homework, go to the following link to rate your skill or concept understanding level for each item listed. Your self-reflection must be completed by the due date. All submissions are time-stamped, so please give yourself plenty of time to complete and submit your self-reflection.

<http://bit.ly/2DNFX0i>