Pynigma

Cédric Laubacher, Tao Grenkowski 4e, Kantonsschule Alpenquai Luzern

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Abstract. Pynigma is an easily comprehensible Enigma Emulator written in Python 3 Source code is available on Github under https://github.com/Starbix/

 ${\tt pynigma}$

Website: https://starbix.github.io/pynigma License: GNU General Public License v3.0

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1 Introduction

Our goal was to write a script or program that allows us to simulate the encryption of an Enigma M3 (and also M4 with certain settings). We decided on doing this, because we didn't want to write an only mathematical program and because cryptography is a very interesting and important topic. We got our inspiration from the movies "Enigma (2001)" and "The Imitation Game (2014)" because we recently watched them and made us realize how important cryptography and cracking its code can be.

Encryption has also never been more relevant. Because a huge amount of data gets transferred through the internet, people try to steal that data. That's why encryption is being used.

2 Theory

The Enigma machine is an electro-mechanical device. It is mechanically operated, with an electric signal passed through wires and various mechanical parts. The easiest way to explain the mechanics is to follow the journey of a single letter from keyboard to lampboard.

The diagram below (Figure 1) shows the path the signal takes from pressing the letter 'T' on the keyboard to the 'G' lamp lighting up.

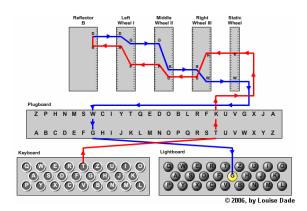


Fig. 1. [1] How one letter is changed into another letter at each stage as it passes through an Enigma machine.

When the letter 'T' is pressed on the keyboard it creates an electric signal that goes through the Enigma machine wiring that will end with a lamp flashing on the lampboard.

First, the current flows through the plugboard. Here the signal is connected to the 'T' input on the plugboard. Some of the letters on the plugboard will be wired up to other letters (the plugs). If the 'T' input is not plugged to another

letter then our signal will pass straight to the 'T output. Here though the 'T' is plugged to the 'K', so the signal comes out of the 'K' output.

The plugboard isn't implemented in pynigma at the moment, however it can always be added. The source code is located on Github on https://github.com/Starbix/pynigma

Then the signal pass through three rotors (there are five available). Each of them is wired differently, so the output will be different. The first one gets rotated every letter, which will also scramble the signal even more. The others also rotate, but based on notches. It works just like a clock.

The reflector takes the input and reflects back the electrical signal for its return through the rotors. The reflector takes the letter and converts it to a different one, just like the plugboard. There are 5 different reflectors.

The reflector is important because it just wouldn't work if it got reflected the same way as no current could flow. (This is also the Enigma's biggest flaw.)

The reflected signal now passes back through the rotors, which work in exactly the same way in reverse.

The final stop is the lampboard, where the plugboard output is connected to the corresponding lamp for that letter. In our example, the letter 'G' lights up meaning the original letter 'T' is encrypted as 'G'.

The Enigma machine operator notes down the output letter and then enters the next letter in the message, and so on for every letter in the message.

2.1 Numbers



Fig. 2. [3] An Enigma keyboard showing the letters used as numbers.

To include numbers in your message, you first need to indicate that you are about to use a number by entering the letter "Y" before each number. The numbers itself are replaced with letters just like in the picture above (Figure 2). So, to encode the number 5 in your message you would type in "YT", the number 6 would be "YZ", and 42 would be "YRW".

2.2 Strength

The enigma was extremely secure for it's time. Yet it's code still got cracked. That's because of some flaws the enigma has. One of them is that a letter can't get encrypted to itself, one option less may not sound like much, but it is. Another flaw was that the Nazis had the rule that no same rotor order should be the same

in one month, this lead to worse security. Another flaw is that encrypting works the exact same ways as decrypting. [2] and [5]

3 Implementation

The program is easily readable and understandable, so to understand how it works, just take a look at the source code.

3.1 Initialization

So first we import some needed libraries. Then we define a class based on the OS. This is needed because Windows isn't POSIX compliant and it wouldn't look correct otherwise. Then we need to define all of the rotors and reflectors. [3] Then the script gets all of the inputs from the user and check if they are valid and reacts accordingly. The program then makes the input uppercase and converts it into a list. Some functions then are defined and the rotors get shifted into the initial position given by the user.

3.2 Main program

Now comes the real program. The for-loop runs once for every letter in the input.

```
for i in range(0, len(textArray)):
    firstRotor = shift(firstRotor, 1)
```

The first rotor gets shifted for every key "pressed".

Then it checks whether the turnover notch position is reached or not and shifts the next rotor if it is. Then the reverse rotors get generated.

Here's the most important part of this script.

```
print(colors.GREEN + colors.BOLD +
firstRotorReversed[ABC.index(
  secondRotorReversed[ABC.index(
  thirdRotorReversed[ABC.index(
  reflector[ABC.index(
  thirdRotor[ABC.index(
  secondRotor[ABC.index(
  firstRotor[ABC.index(
  textArray[i])])])])])])])
+ colors.ENDC, end="")
```

It takes the current letter that needs to get converted and then gets the position of it in the alphabet, for example for the letter 'C' it's 2 (lists start counting at 0). Then that position becomes the new letter because the third letter of the first rotor is for example 'M'. Then that letter becomes a new letter because of the second rotor and so on. In the end we get one letter for each print command. The ', end=""' is used because each character would be printed on a new line.

4 Results

4.1 How to get the code

First, you need to install git, this is preinstalled on most OSs, if not just head to this website https://git-scm.com and install it.

To get the code, enter the following commands:

```
git clone https://github.com/Starbix/pynigma
```

Now there should be a directory called pynigma which contains the script.

4.2 How to execute the code

To execute the program simply enter the directory and execute main.py

```
cd pynigma
./main.py
```

You will now see the following output where you can input the settings just like in the following example.

```
Choose the second rotor (each rotor can only be used once) \rightarrow [I/II/III/IV/V/VI/VIII] VII Choose the third rotor (each rotor can only be used once) \rightarrow [I/II/III/IV/V/VI/VIII] V Choose the position of the first rotor [1-26] 8 Choose the position of the second rotor [1-26] 24 Choose the position of the third rotor [1-26] 1 Choose reflector [A/B/C/B_thin/C_thin] A Please type your text you want to decode or encode. Use 'X' as \rightarrow space or a stop.
```

ALLEXXFOLGENDESISTSOFORTBEKANNTZUGEBENXXICHHABEFOLGELNDEBEFEHLERHALTENXXJANSTELLE

DESBISHERIGENREICHSMARSCHALLSJGOERINGJSETZTDERFUEHRERSIEYHERRGROSSADMIRAL
YALSSEINENNACHFOLGEREINXSCHRIFTLICHEVOLLMACHTUNTERWEGSXABSOFORTSOLLENSIES
AEMTLICHEMASSNAHMENVERFUEGENYDIESICHAUSDERGEGENWAERTIGENLAGEERGEBENXGEZX
REICHSLEITEIRKTULPEKKJBORMANNJ

UDHQYWALZPPEMKXCAMLAUSNSKVTWOMXCICDKQLBGKQLFDKCTXBTTZZKGICTSTNQKYKXJGAJNYHLXGBC HDCIISNVNRADILWICLAUCQWWTWAUKQOOHUFYMVKFKZOAXZMSWOYZLGHJROUGNVIAWFKQJGIZXRWUSGH CKYRKXPUSLNSDIOCAMTBTUWWEBOGTKFGLDGHYYHDYWCEQCACUPJYOZATZDRQAWXBLHULGSQBQQZZWRB LDBPPCKTQKHECZCJNCAUOFKSBPZXOLYFMWYSZIGRBNFSSVVPBQZXSORGHSCKBJDUOSWUXTCPVBOMUCQ KYHAZDSNQDEJQ

```
$ python3 main.py
Choose the first rotor (each rotor can only be used once)

→ [I/II/III/IV/V/VI/VII] II
```

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```
Choose the second rotor (each rotor can only be used once) \hookrightarrow [I/II/III/IV/V/VI/VIII] VII Choose the third rotor (each rotor can only be used once) \hookrightarrow [I/II/III/IV/V/VI/VII/VIII] V Choose the position of the first rotor [1-26] 8 Choose the position of the second rotor [1-26] 24 Choose the position of the third rotor [1-26] 1 Choose reflector [A/B/C/B_thin/C_thin] A Please type your text you want to decode or encode. Use 'X' as \hookrightarrow space or a stop.
```

UDHQYWALZPPEMKXCAMLAUSNSKVTWOMXCICDKQLBGKQLFDKCTXBTTZZKGICTSTNQKYKXJGAJNYHLXGBC HDCIISNVNRADILWICLAUCQWWTWAUKQOOHUFYMVKFKZOAXZMSWOYZLGHJROUGNVIAWFKQJGIZXRWUSGH CKYRKXPUSLNSDIOCAMTBTUWWEBOGTKFGLDGHYYHDYWCEQCACUPJYOZATZDRQAWXBLHULGSQBQQZZWRB LDBPPCKTQKHECZCJNCAUOFKSBPZXOLYFMWYSZIGRBNFSSVVPBQZXSORGHSCKBJDUOSWUXTCPVBOMUCQ KYHAZDSNQDEJQ

ALLEXXFOLGENDESISTSOFORTBEKANNTZUGEBENXXICHHABEFOLGELNDEBEFEHLERHALTENXXJANSTELLE

DESBISHERIGENREICHSMARSCHALLSJGOERINGJSETZTDERFUEHRERSIEYHERRGROSSADMIRAL

YALSSEINENNACHFOLGEREINXSCHRIFTLICHEVOLLMACHTUNTERWEGSXABSOFORTSOLLENSIES

AEMTLICHEMASSNAHMENVERFUEGENYDIESICHAUSDERGEGENWAERTIGENLAGEERGEBENXGEZX

REICHSLEITEIRKTULPEKKJBORMANNJ

So the output is this again:

An Alle:

```
Folgendes ist sofort bekanntzugeben:
Ich habe folgende Befehl erhalten:
'Anstelle des bisherigen Reichsmarschalls 'Göring' setzt der Führer
Sie, Herr Großadmiral, als seinen Nachfolger ein.
Schriftlische Vollmacht unterwegs.
Ab sofort sollen Sie sämtliche Maßnahmen verfügen,
die sich aus die gegenwärtigen Lage ergeben.
Gez. Reichsleiter (Tulpe) 'Bormann'
```

As you can see the program works as expected and encrypts and decrypts correctly.

5 Discussion

5.1 What we learned

This project was quite fun and we learned a lot. For example was this a great opportunity to learn git (https://git-scm.com), a distributed version control system, and Github (https://github.com), a hosting site for said version control system and more e.g. Issues (bug reports, feature requests) and branching for easy development.

But not only that, we also setup a simple website which is available under https://starbix.github.io/pynigma.

We also took a look at different lincenses such as MIT and GPL 3.0 (which we use in this project) and pep8 which is a style guide for Python code (our code is pep8 compliant).

And we also learned a bit of LATEX as one can probably see.

5.2 Initial problems

The biggest problem in the beginning was the question how we want to represent the input and how we can easily convert it. Fortunately we decided on using lists for that, which saved us a lot of hassle in later development. Also fully understanding how the Enigma works was challenging, but after some really helpful websites and videos [1] and [5] it was much clearer how we need to write the program.

5.3 Application

This program can be used for encrypting and decrypting text, not for exchanging nuclear launch codes of course. We actually also wanted to make this program able to directly take a file's content and encrypt it to another file using the redirect (>) function of UNIX OSs. Unfortunately we didn't have time for that, but maybe we add this functionality to Github in the future if we feel like it.

Bibliography

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- [4] Colors and more in print for python. https://stackoverflow.com/questions/287871/print-in-terminal-with-colors-using-python.
- [1] How enigma machines work. http://enigma.louisedade.co.uk/howitworks.html, Accessed: 2017-06-19.
- [2] How secure the enigma is. http://www.ostfalia.de/cms/de/pws/seutter/kryptologie/enigma/Sicherheit/Sicherheit/sicherheit2. html, Accessed: 2017-06-19.
- [3] Numbers in enigma. http://enigma.louisedade.co.uk/help.html, Accessed: 2017-06-19.

6 Attachment

```
#!/usr/bin/env python3
2
    import sys
    import string
    import os
5
    # use colors class for better input and output, while still
     \hookrightarrow supporting NT based OSs
    if os.name == "posix":
         class colors:
9
             HEADER = '\033[95m']
10
             BLUE = ' \033[94m']
11
             GREEN = ' \setminus 033 [92m']
12
             WARNING = ' \setminus 033[93m']
13
             RED = ' \033[91m']
             ENDC = ' \033[Om']
15
             BOLD = ' \setminus 033[1m']
16
             UNDERLINE = '\033[4m'
17
    else:
18
         class colors:
19
             HEADER = ''
20
             BLUE = ''
21
             GREEN = ''
22
             WARNING = ''
23
             RED = 11
24
             ENDC = ''
```

```
BOLD = ''
26
             UNDERLINE = ''
27
    # Alphabet list for converting input letters to numbers
29
    ABC = list(string.ascii_uppercase)
30
    # define the Walzen
    I = ['E', 'K', 'M', 'F', 'L', 'G', 'D', 'Q', 'V', 'Z', 'N', 'T',
33
        'O', 'W',
                    'Y', 'H', 'X', 'U', 'S', 'P', 'A', 'I', 'B', 'R',

    'C',
             'J']
    II = ['A', 'J', 'D', 'K', 'S', 'I', 'R', 'U', 'X', 'B', 'L', 'H',
    \hookrightarrow 'W', 'T', 'M', 'C', 'Q', 'G', 'Z', 'N', 'P', 'Y', 'F', 'V',
    → '0', 'E']
    III = ['B', 'D', 'F', 'H', 'J', 'L', 'C', 'P', 'R', 'T', 'X', 'V',
    \hookrightarrow 'Z', 'N', 'Y', 'E', 'I', 'W', 'G', 'A', 'K', 'M', 'U', 'S',
    → 'Q', '0']
    IV = ['E', 'S', 'O', 'V', 'P', 'Z', 'J', 'A', 'Y', 'Q', 'U', 'I',

→ 'R', 'H', 'X', 'L', 'N', 'F', 'T', 'G', 'K', 'D', 'C', 'M',
    \hookrightarrow 'W', 'B']
    V = ['V', 'Z', 'B', 'R', 'G', 'I', 'T', 'Y', 'U', 'P', 'S', 'D',
    → 'N', 'H', 'L', 'X', 'A', 'W', 'M', 'J', 'Q', 'O', 'F', 'E',
    \hookrightarrow 'C', 'K']
    VI = ['J', 'P', 'G', 'V', 'O', 'U', 'M', 'F', 'Y', 'Q', 'B', 'E',
    \label{eq:continuous} \ \hookrightarrow \ \ ^{1}\text{N'}, \ ^{1}\text{H'}, \ ^{1}\text{Z'}, \ ^{1}\text{R'}, \ ^{1}\text{D'}, \ ^{1}\text{K'}, \ ^{1}\text{A'}, \ ^{1}\text{S'}, \ ^{1}\text{X'}, \ ^{1}\text{L'}, \ ^{1}\text{I'}, \ ^{1}\text{C'},
    \hookrightarrow 'T', 'W']
    VII = ['N', 'Z', 'J', 'H', 'G', 'R', 'C', 'X', 'M', 'Y', 'S', 'W',
    → 'B', 'O', 'U', 'F', 'A', 'I', 'V', 'L', 'P', 'E', 'K', 'Q',
    \hookrightarrow 'D'. 'T']
    VIII = ['F', 'K', 'Q', 'H', 'T', 'L', 'X', 'O', 'C', 'B', 'J',
    \hookrightarrow 'S', 'P', 'D', 'Z', 'R', 'A', 'M', 'E', 'W', 'N', 'I', 'U',
    \rightarrow 'Y', 'G', 'V']
    # beta and gamma were used in the Enigma M4
    beta = ['L', 'E', 'Y', 'J', 'V', 'C', 'N', 'I', 'X', 'W', 'P',
    \hookrightarrow 'B', 'Q', 'M', 'D', 'R', 'T', 'A', 'K', 'Z', 'G', 'F', 'U',
    → 'H', 'O', 'S']
    gamma = ['F', 'S', 'O', 'K', 'A', 'N', 'U', 'E', 'R', 'H', 'M',
    -

→ 'B', 'T', 'I', 'Y', 'C', 'W', 'L', 'Q', 'P', 'Z', 'X', 'V',

    'G', 'J', 'D']

    A = ['E', 'J', 'M', 'Z', 'A', 'L', 'Y', 'X', 'V', 'B', 'W', 'F',
              'R', 'Q', 'U', 'O', 'N', 'T', 'S', 'P', 'I', 'K', 'H',

    'G', 'D']

   B = ['Y', 'R', 'U', 'H', 'Q', 'S', 'L', 'D', 'P', 'X', 'N', 'G',
    \hookrightarrow 'O', 'K', 'M', 'I', 'E', 'B', 'F', 'Z', 'C', 'W', 'V', 'J',
     \hookrightarrow 'A', 'T']
```

```
C = ['F', 'V', 'P', 'J', 'I', 'A', 'O', 'Y', 'E', 'D', 'R', 'Z',
        \label{eq:continuous} \ \hookrightarrow \ \ 'X', \ 'W', \ 'G', \ 'C', \ 'T', \ 'K', \ 'U', \ 'Q', \ 'S', \ 'B', \ 'N', \ 'M',
        \hookrightarrow 'H', 'L']
       B_{thin} = ['E', 'N', 'K', 'Q', 'A', 'U', 'Y', 'W', 'J', 'I', 'C',

→ '0', 'P', 'B', 'L', 'M', 'D', 'X', 'Z', 'V', 'F', 'T', 'H',

    'R', 'G', 'S']

       C_thin = ['R', 'D', 'O', 'B', 'J', 'N', 'T', 'K', 'V', 'E', 'H',
        \label{eq:continuous} \ \hookrightarrow \ \ ^{1}M^{\, +}, \ ^{1}L^{\, +}, \ ^{1}F^{\, +}, \ ^{1}C^{\, +}, \ ^{1}W^{\, +}, \ ^{1}Z^{\, +}, \ ^{1}A^{\, +}, \ ^{1}X^{\, +}, \ ^{1}G^{\, +}, \ ^{1}Y^{\, +}, \ ^{1}I^{\, +}, \ ^{1}P^{\, +}, \ ^{1}H^{\, +}, \ ^{1}
        → 'S', 'U', 'Q']
       # get input from user
       firstRotor = eval(input("Choose the " + colors.BOLD + "first " +

→ colors.ENDC + "rotor (each rotor can only be used once)

        # use static rotor for correct turning
       firstRotorStatic = firstRotor
53
       secondRotor = eval(input("Choose the " + colors.BOLD + "second " +

→ colors.ENDC + "rotor (each rotor can only be used once)

        secondRotorStatic = secondRotor
       thirdRotor = eval(input("Choose the " + colors.BOLD + "third " +

→ colors.ENDC + "rotor (each rotor can only be used once)

        # fourthRotor for Enigma M4
       # check if every Rotor is only used once
       if firstRotor == secondRotor or firstRotor == thirdRotor or

→ secondRotor == thirdRotor:
               print(colors.RED + "Each rotor can only be used once" +
60
                sys.exit(1)
61
       # get the initial positions of the rotors
62
       firstRotorPosition = eval(input("Choose the position of the " +

    colors.BOLD + "first " + colors.ENDC + "rotor [1-26] ")) - 1

       if 0 > firstRotorPosition or firstRotorPosition > 25:
               print(colors.WARNING + "Choose a value between 1 and 26" +
65

→ colors.ENDC)

               firstRotorPosition = eval(input("Choose the position of the "
                 + colors.BOLD + "first " + colors.ENDC + "rotor [1-26] "))
                if 0 > firstRotorPosition or firstRotorPosition > 25:
67
                        print(colors.RED + "Choose a value between 1 and 26" +

→ colors.ENDC)

                       sys.exit(1)
69
       secondRotorPosition = eval(input("Choose the position of the " +

    colors.BOLD + "second " + colors.ENDC + "rotor [1-26] ")) - 1
```

```
if 0 > secondRotorPosition or secondRotorPosition > 25:
        print(colors.WARNING + "Choose a value between 1 and 26" +
72
         \hookrightarrow colors.ENDC)
        secondRotorPosition = eval(input("Choose the position of the "
73
         → + colors.BOLD + "second " + colors.ENDC + "rotor [1-26]

→ ")) - 1

        if 0 > secondRotorPosition or secondRotorPosition > 25:
            print(colors.RED + "Choose a value between 1 and 26" +
75

→ colors.ENDC)

            sys.exit(1)
    thirdRotorPosition = eval(input("Choose the position of the " +

    colors.BOLD + "third " + colors.ENDC + "rotor [1-26] ")) - 1

    if 0 > thirdRotorPosition or thirdRotorPosition > 25:
78
        print(colors.WARNING + "Choose a value between 1 and 26" +

→ colors.ENDC)

        thirdRotorPosition = eval(input("Choose the position of the "
80

    + colors.BOLD + "third " + colors.ENDC + "rotor [1-26] "))

        if 0 > thirdRotorPosition or thirdRotorPosition > 25:
81
            print(colors.RED + "Choose a value between 1 and 26" +
82

→ colors.ENDC)

            sys.exit(1)
    # let the user choose the reflector
    reflector = eval(input("Choose reflector [A/B/C/B_thin/C_thin] "))
85
86
    # input text from user
    input = input("Please type your text you want to decode or encode.
    → Use 'X' as space or a stop. ")
    # convert text to only upper case letters
    input = input.upper()
91
    # check for numbers in input
92
    if len(set(string.digits).intersection(input)) > 0:
        print(colors.RED + colors.BOLD + "Refer to the README. Don't
94

    use digits")

        if (' ' in input):
95
            print("and no space!")
        print(colors.ENDC)
        sys.exit(1)
98
    # convert input to list
99
    textArray = list(input)
101
102
    # define reverse function for the way "back"
103
    def reverse(array):
```

```
reverseRotor = []
105
        for s in range(0, 26):
106
            reverseRotor.append(ABC[array.index(ABC[s])])
        return reverseRotor
108
109
110
    # define shift function for shifting the rotors
111
    def shift(array, int):
112
        return array[int:] + array[:int]
113
114
115
    # shift to initial positions
116
    firstRotor = shift(firstRotor, firstRotorPosition)
117
    secondRotor = shift(secondRotor, secondRotorPosition)
    thirdRotor = shift(thirdRotor, thirdRotorPosition)
119
120
    # run code once for every letter in the input
121
    for i in range(0, len(textArray)):
122
123
         # initial shift
124
        firstRotor = shift(firstRotor, 1)
125
         # check if any rotor is at the turnover notch position
        if firstRotorStatic == I:
127
             if firstRotor[0] == 'U':
128
                 secondRotor = shift(secondRotor, 1)
129
        elif firstRotorStatic == II:
             if firstRotor[0] == 'I':
131
                 secondRotor = shift(secondRotor, 1)
132
        elif firstRotorStatic == III:
133
             if firstRotor[0] == 'U':
134
                 secondRotor = shift(secondRotor, 1)
135
        elif firstRotorStatic == IV:
136
             if firstRotor[0] == 'U':
137
                 secondRotor = shift(secondRotor, 1)
138
        elif firstRotorStatic == V:
139
             if firstRotor[0] == 'V':
140
                 secondRotor = shift(secondRotor, 1)
141
    # some rotors have two turnover positions
        elif firstRotorStatic == VI:
143
             if firstRotor[0] == 'J' or firstRotor[0] == 'H':
144
                 secondRotor = shift(secondRotor, 1)
145
        elif firstRotorStatic == VII:
146
             if firstRotor[0] == 'N' or firstRotor[0] == '0':
147
                 secondRotor = shift(secondRotor, 1)
148
        elif firstRotorStatic == VIII:
```

```
if firstRotor[0] == 'F' or firstRotor[0] == 'D':
150
                 secondRotor = shift(secondRotor, 1)
151
        elif firstRotorStatic == beta:
            if firstRotor[0] == 'P':
153
                 secondRotor = shift(secondRotor, 1)
154
        elif firstRotorStatic == gamma:
            if firstRotor[0] == 'P':
                 secondRotor = shift(secondRotor, 1)
157
        elif secondRotorStatic == I:
158
            if secondRotor[0] == 'U':
159
                 thirdRotor = shift(thirdRotor, 1)
160
        elif secondRotorStatic == II:
161
            if secondRotor[0] == 'I':
162
                 thirdRotor = shift(thirdRotor, 1)
        elif secondRotorStatic == III:
164
            if secondRotor[0] == 'U':
165
                 thirdRotor = shift(thirdRotor, 1)
166
        elif secondRotorStatic == IV:
167
            if secondRotor[0] == 'U':
168
                 thirdRotor = shift(thirdRotor, 1)
169
        elif secondRotorStatic == V:
170
            if secondRotor[0] == 'V':
                 thirdRotor = shift(thirdRotor, 1)
172
        elif secondRotorStatic == VI:
173
            if secondRotor[0] == 'J' or secondRotor[0] == 'H':
174
                 thirdRotor = shift(thirdRotor, 1)
        elif secondRotorStatic == VII:
176
            if secondRotor[0] == 'N' or secondRotor[0] == '0':
177
                 thirdRotor = shift(thirdRotor, 1)
        elif secondRotorStatic == VIII:
            if secondRotor[0] == 'F' or secondRotor[0] == 'D':
180
                 thirdRotor = shift(thirdRotor, 1)
181
        elif secondRotorStatic == beta:
182
            if secondRotor[0] == 'P':
183
                 thirdRotor = shift(thirdRotor, 1)
184
    # reverse the rotors
185
        firstRotorReversed = reverse(firstRotor)
        secondRotorReversed = reverse(secondRotor)
        thirdRotorReversed = reverse(thirdRotor)
188
189
    # most important piece of the script
    # it basically takes the position of the letter in the list which
    → then gets passed through the rotors, reflector and reverse
       rotors
```

Pynigma 15