

# FLIGHT DYNAMICS

**077BAS005 BIBEK YONZAN**

**077BAS023 MANISH TAJPURIYA**

**077BAS042 SIMONKRITH LAMICHHANE**

**077BAS043 SIMRAN PAUDEL**

**FL** YING FOX

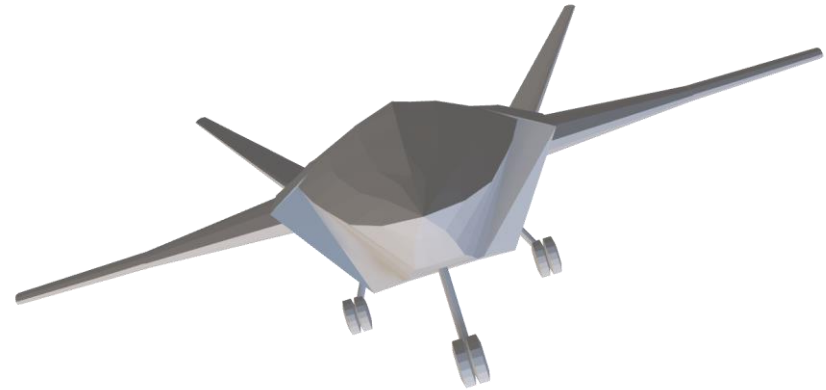
# FLYING FOX

- Unmanned
- Multirole
- High speed
- High maneuverability
- Combat Aerial Vehicle



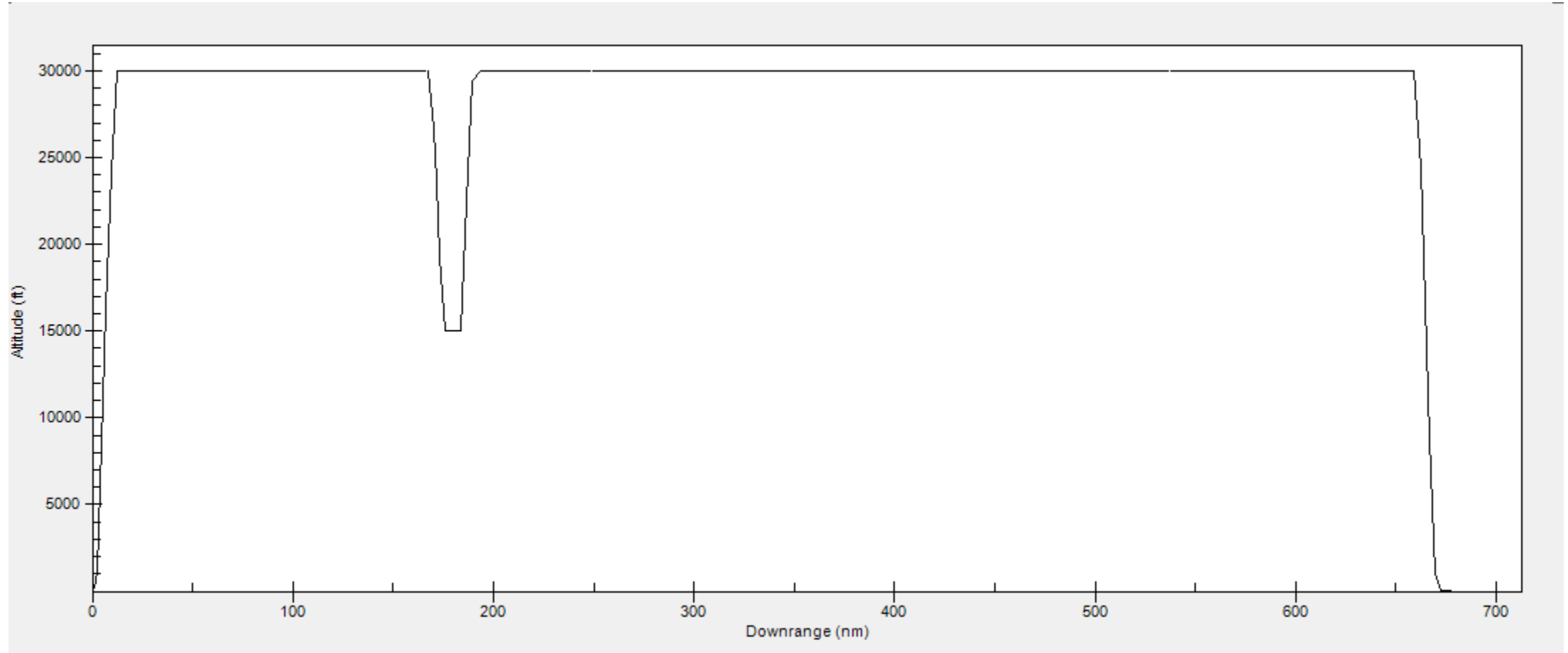
# FLYING FOX

- Unmanned
  - Multirole
  - High speed
  - High maneuverability
  - Combat Aerial Vehicle
- 
- Surveillance
  - Reconnaissance
  - Wingman



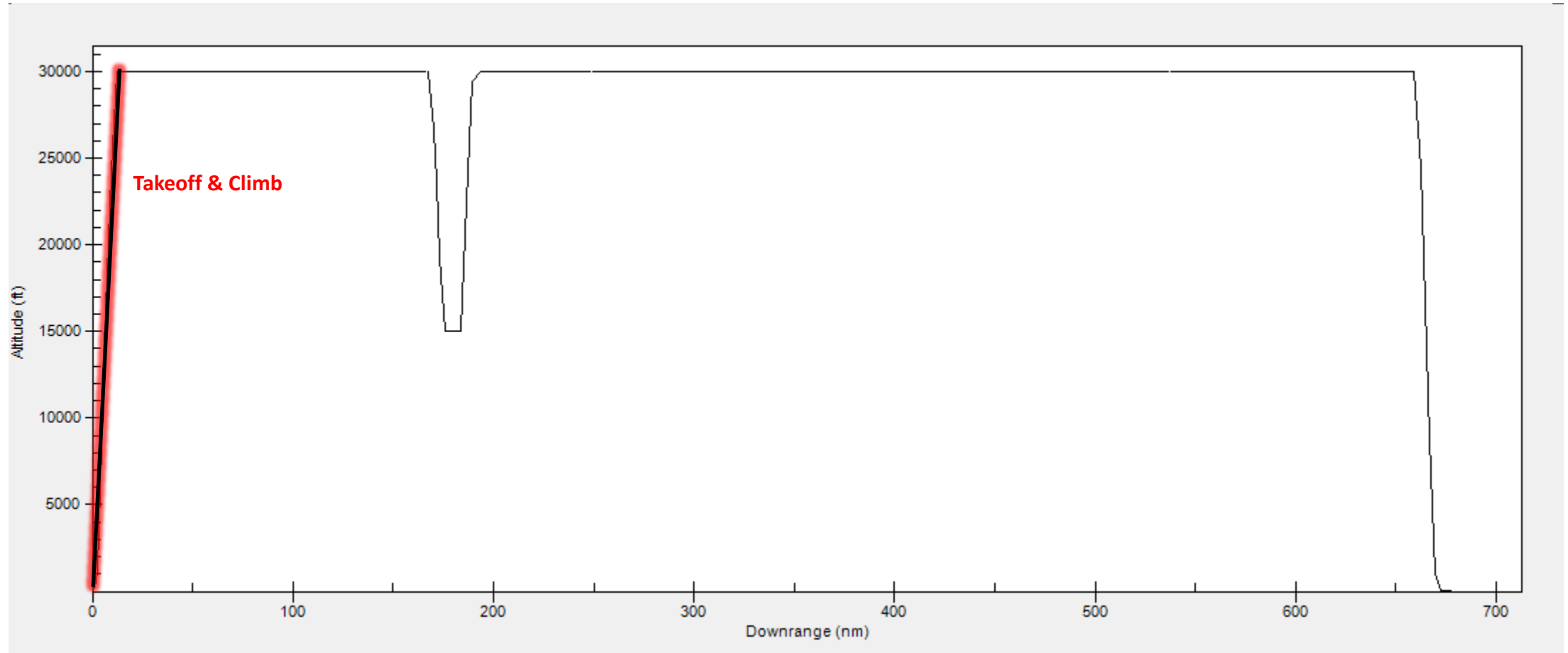
# FLYING FOX

## MISSION PROFILE



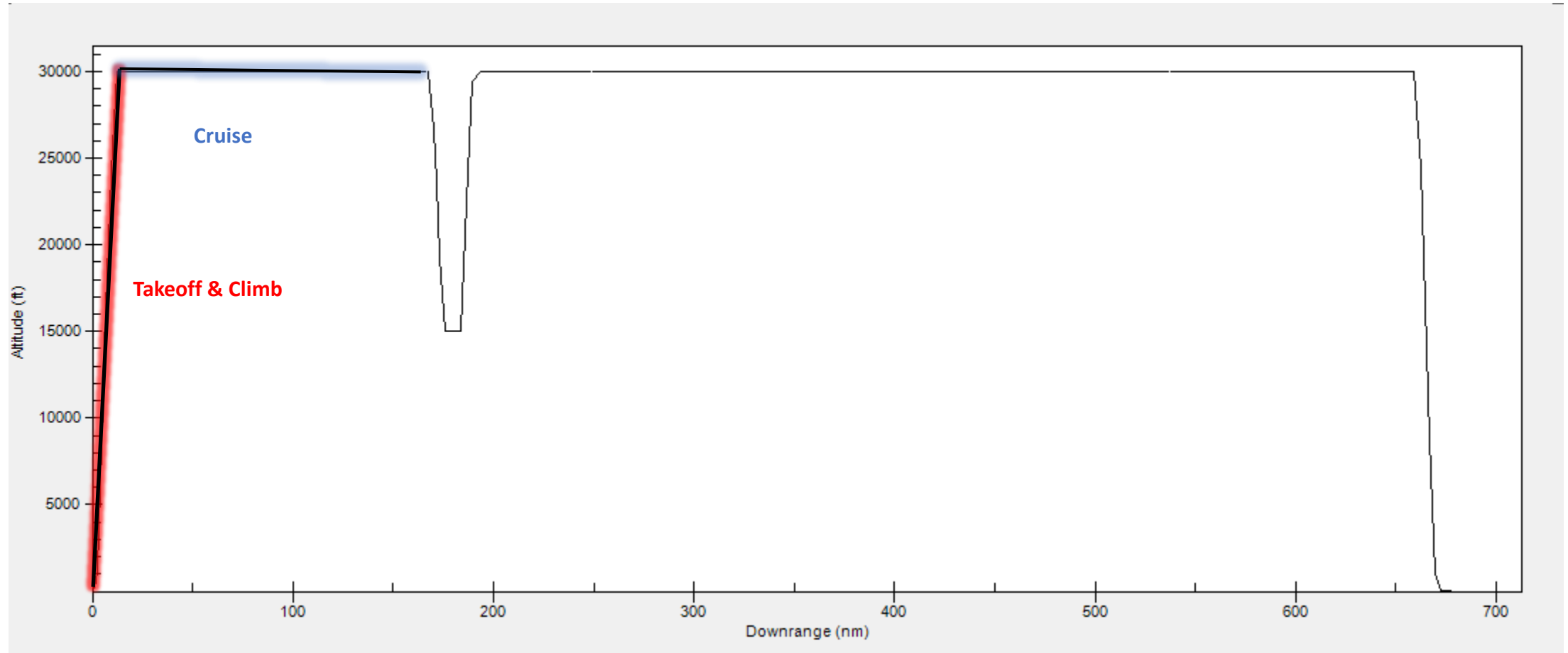
# FLYING FOX

## MISSION PROFILE



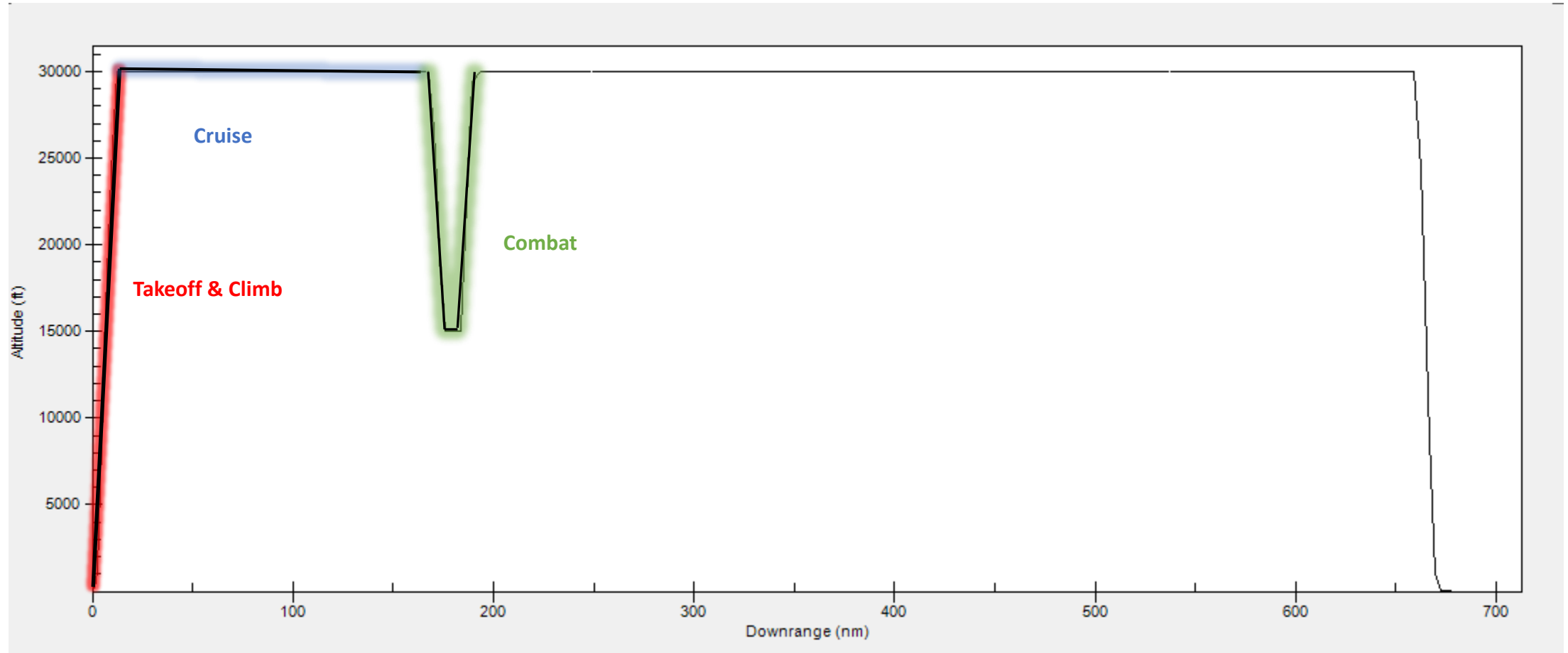
# FLYING FOX

## MISSION PROFILE



# FLYING FOX

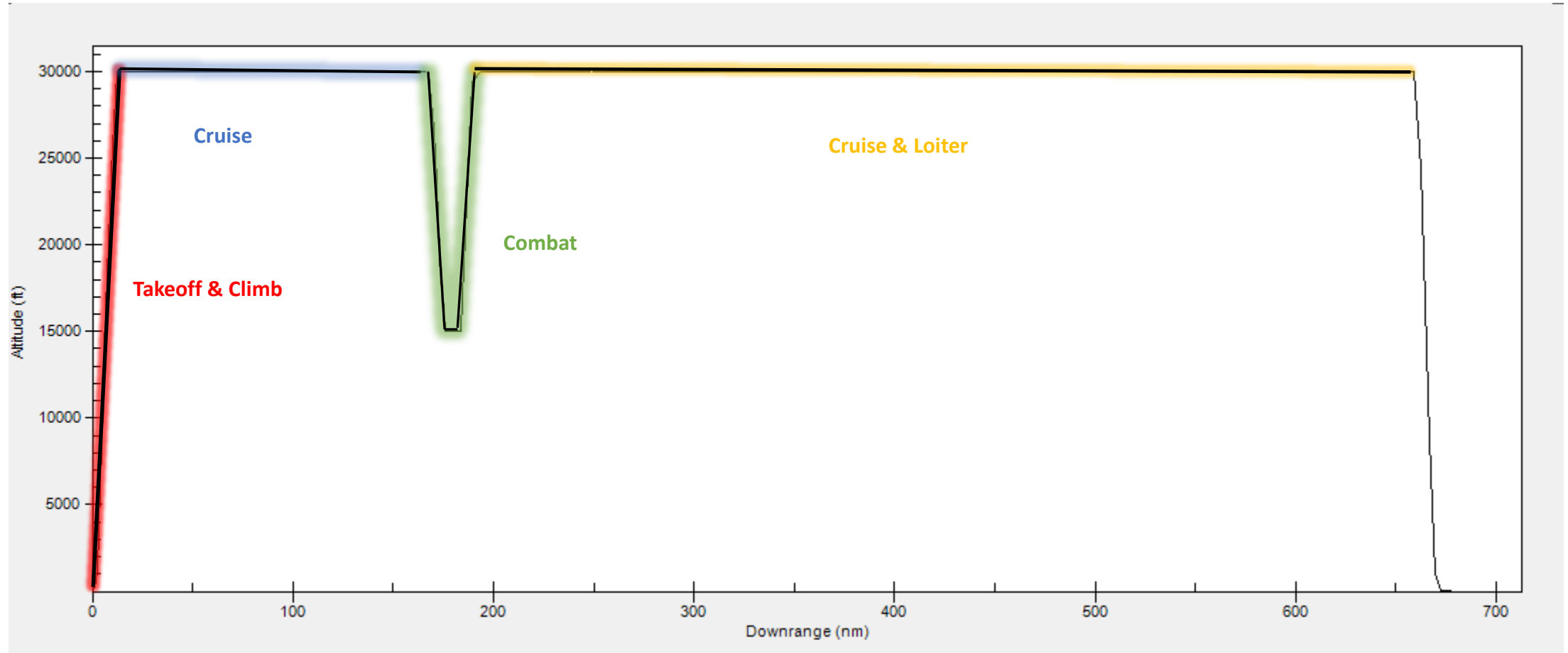
## MISSION PROFILE





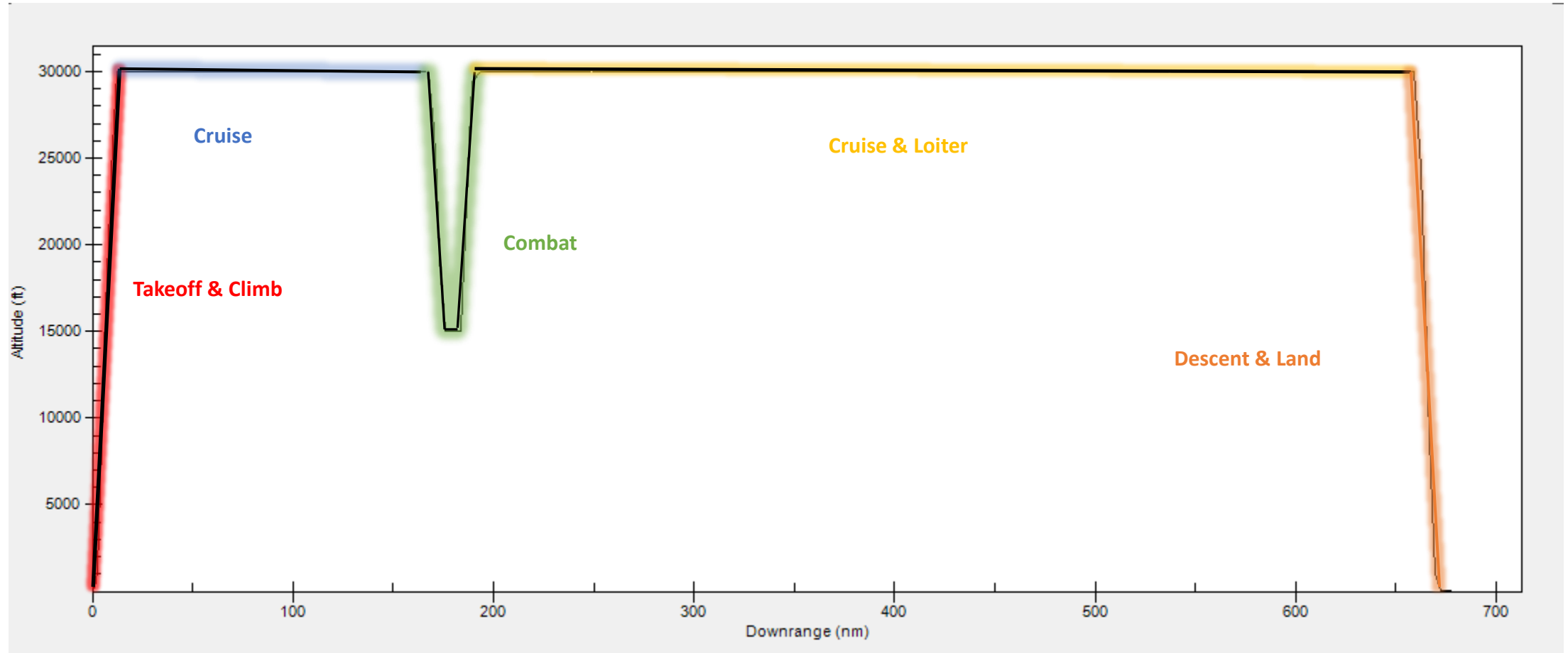
# FLYING FOX

## MISSION PROFILE



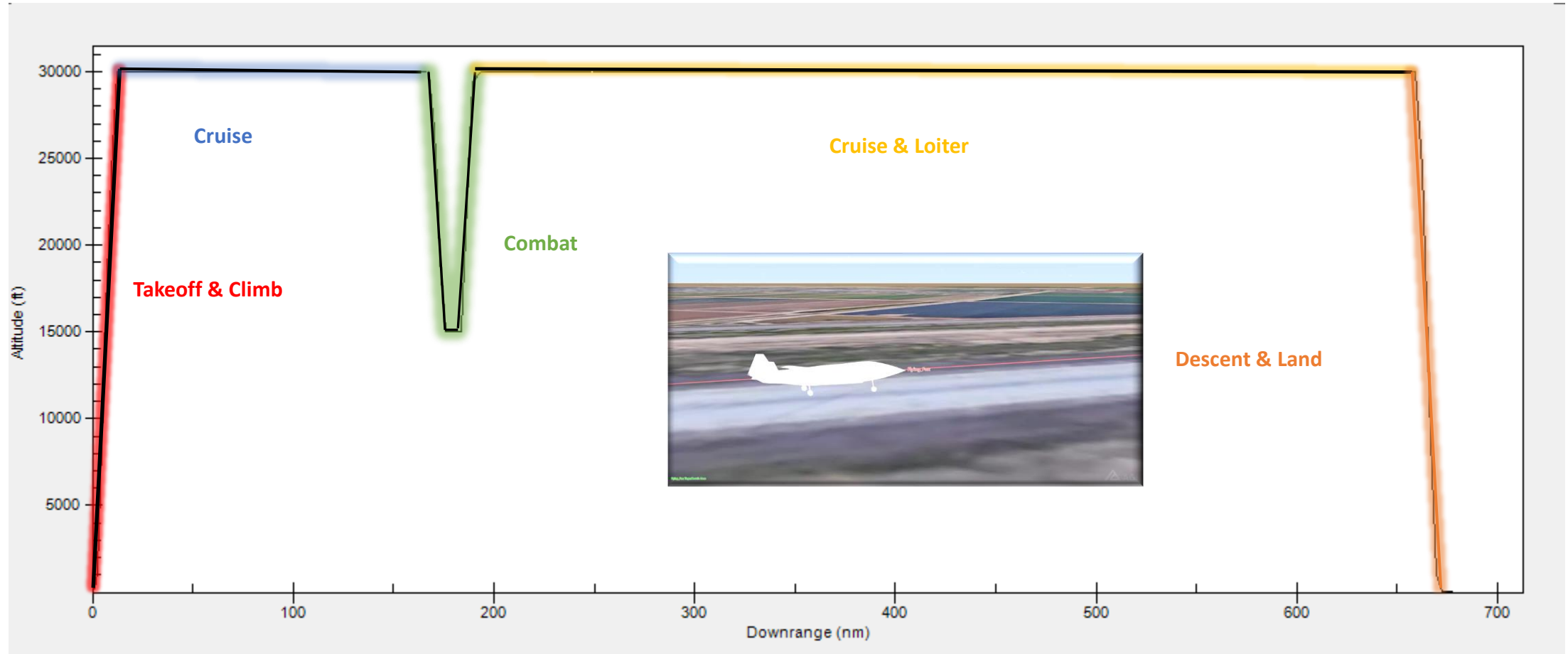
# FLYING FOX

## MISSION PROFILE

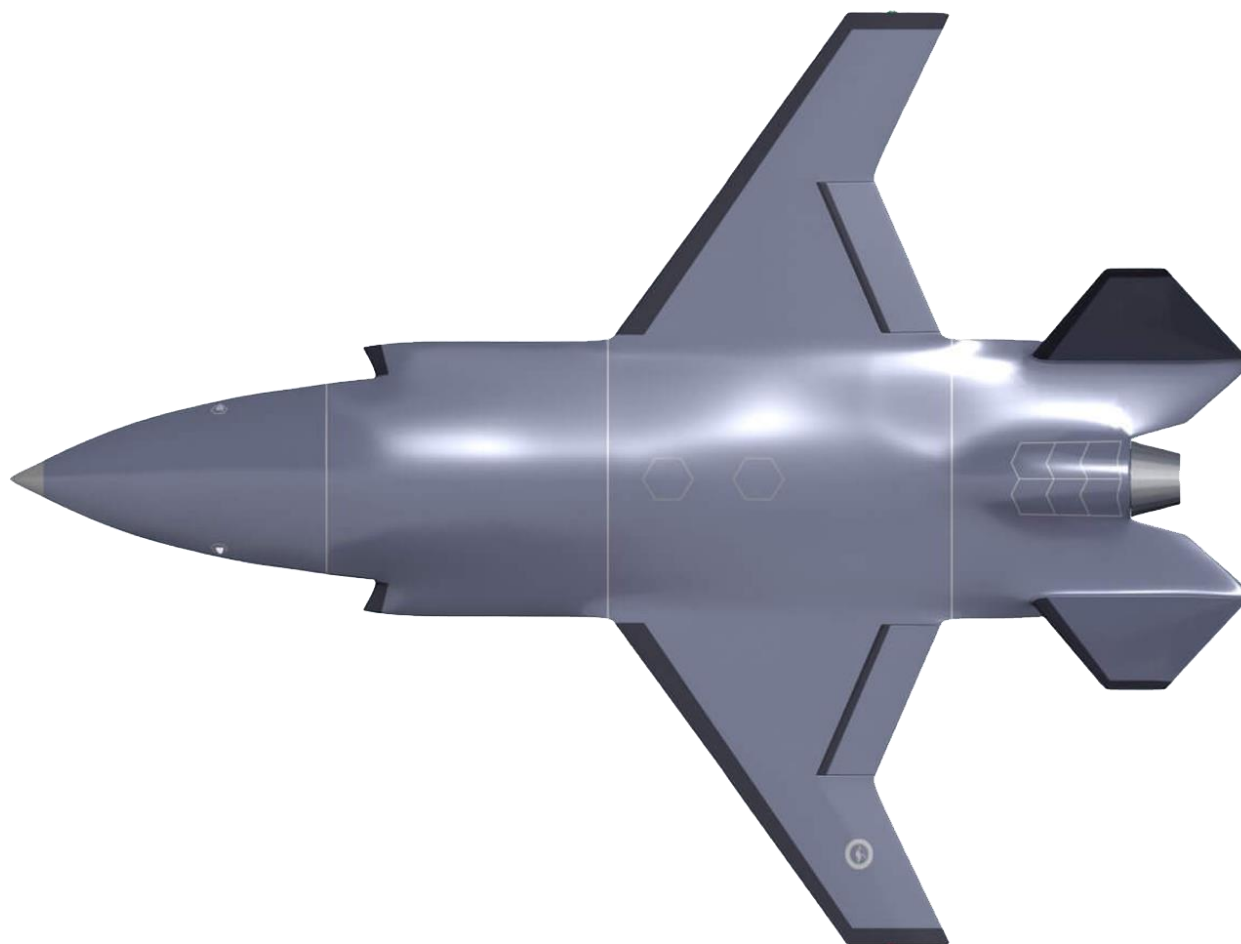


# FLYING FOX

## MISSION PROFILE



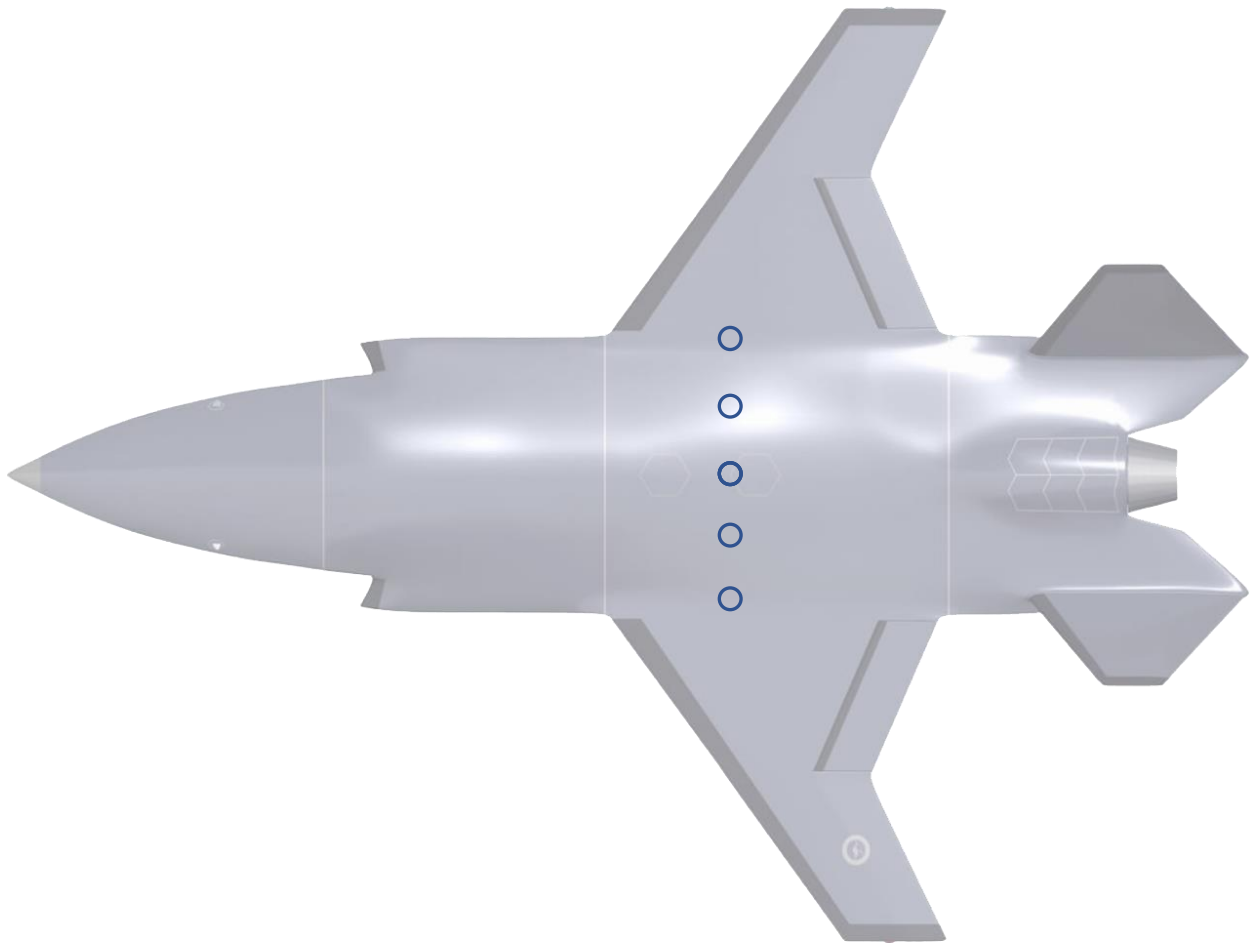
# PLANEMAKER



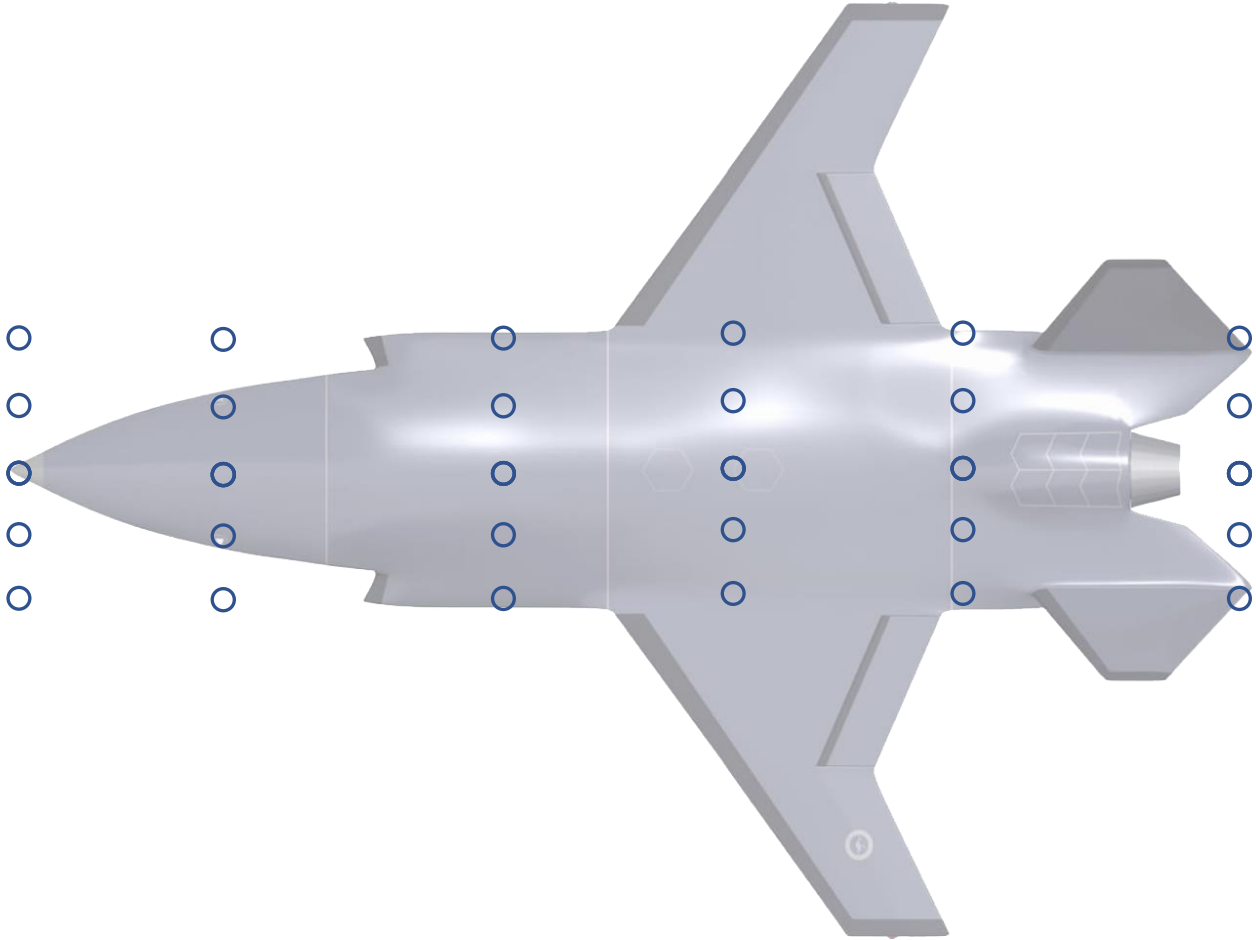
PLANEMAKER



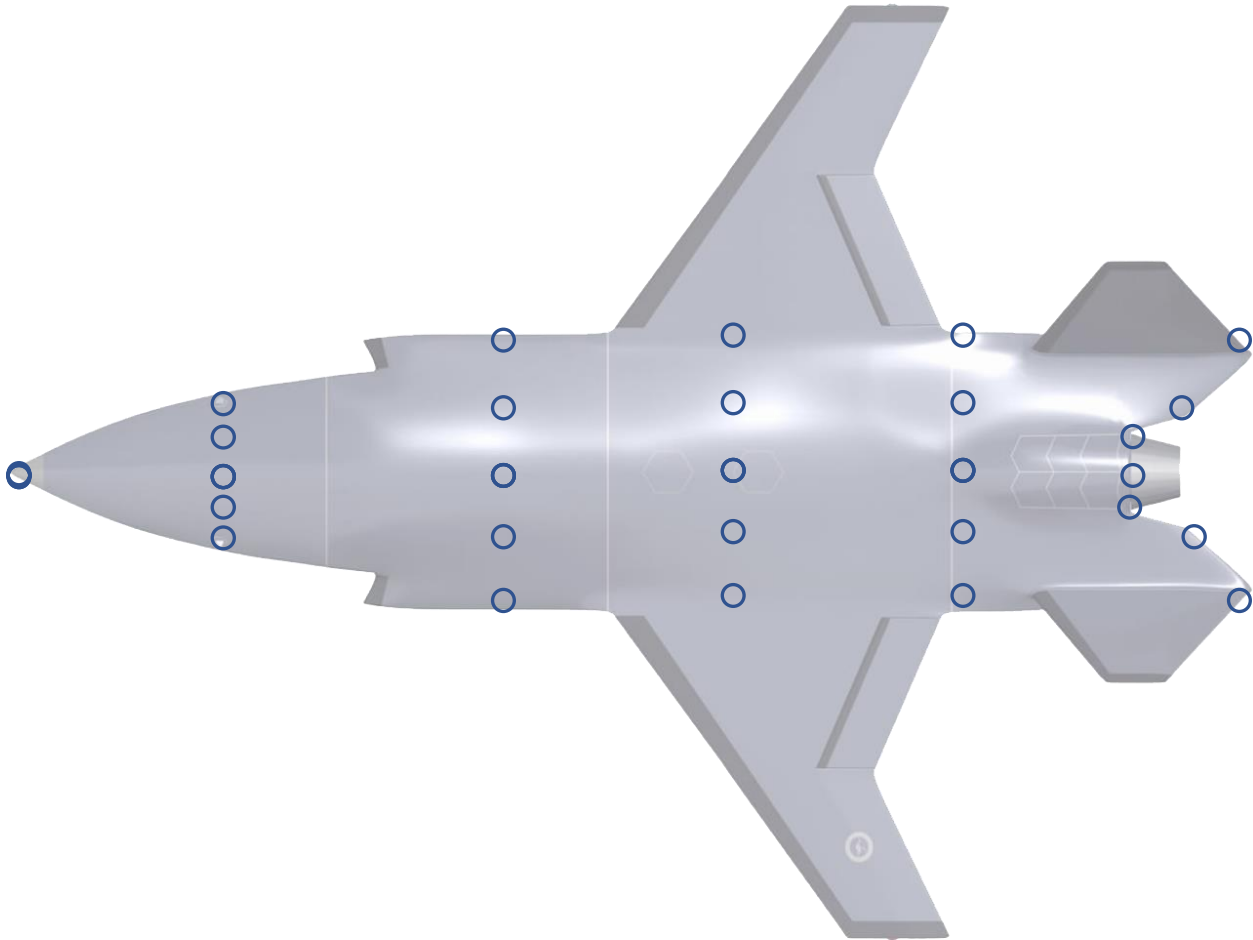
PLANEMAKER



PLANEMAKER

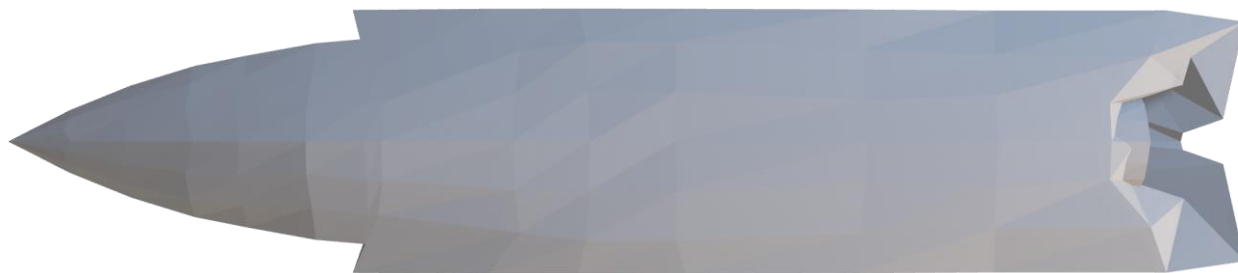


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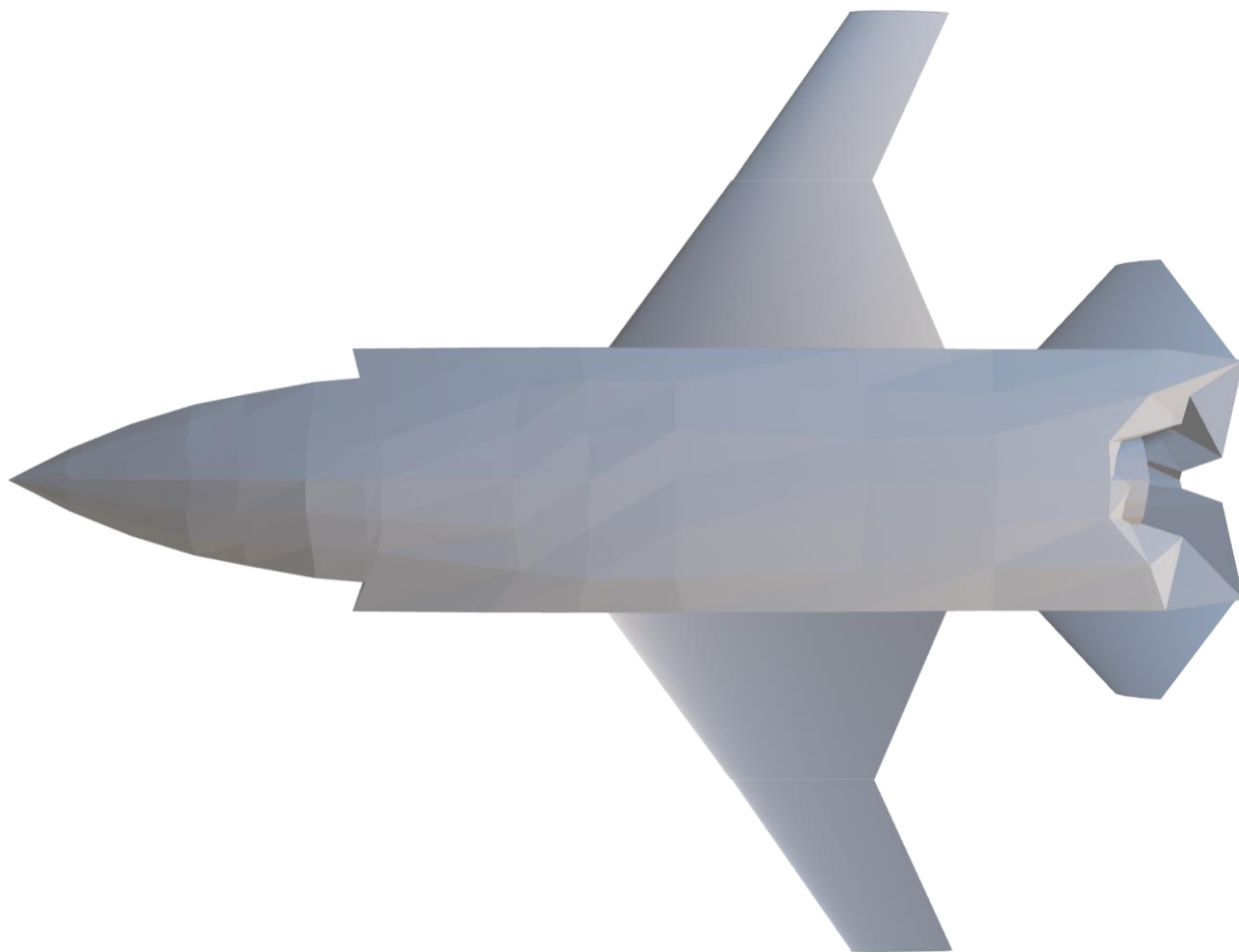




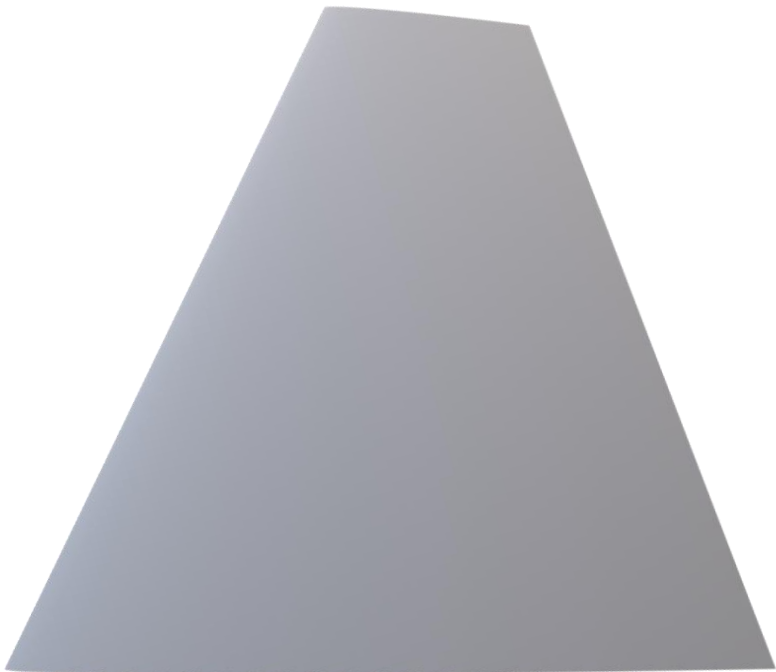
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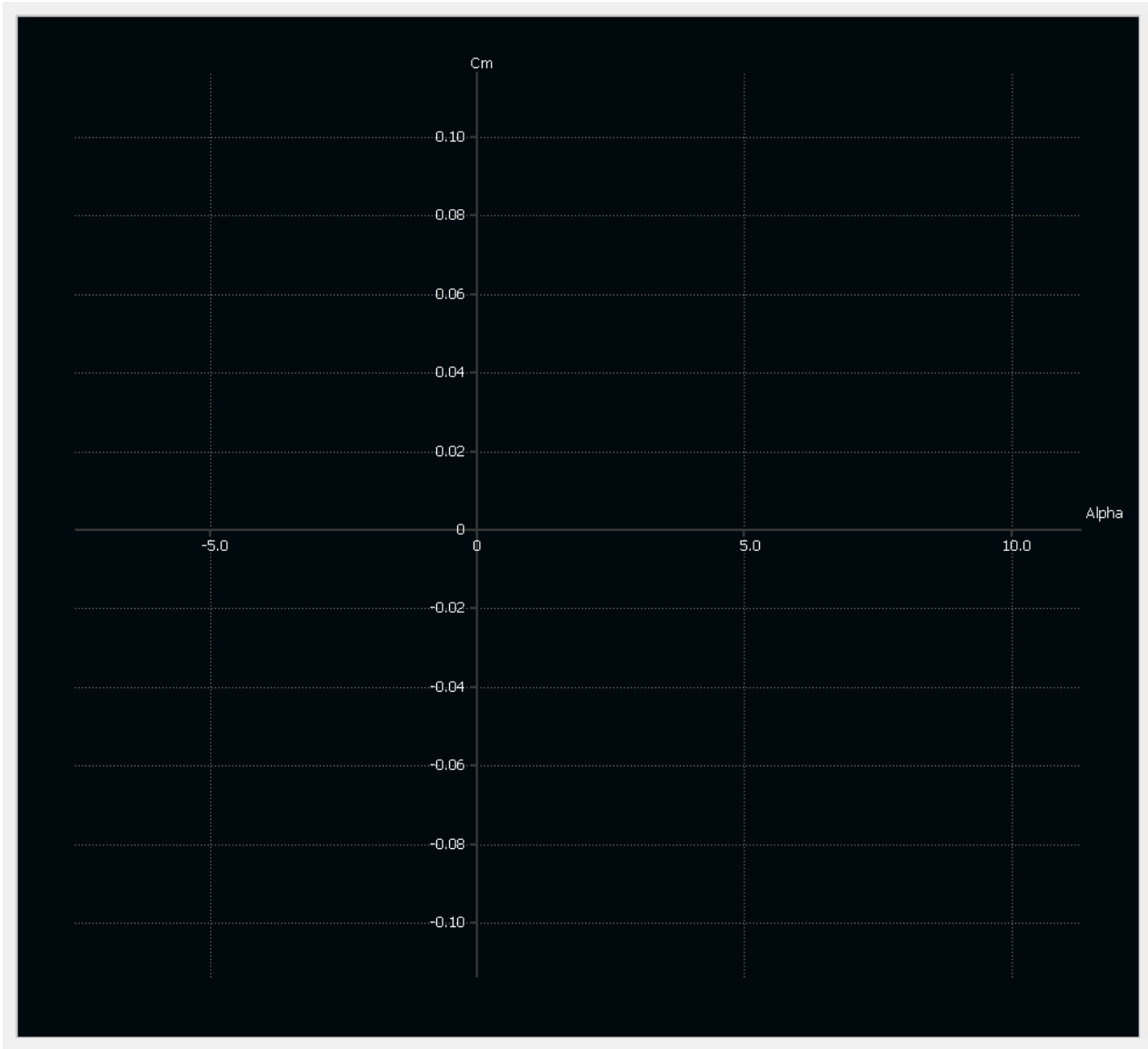
# PLANEMAKER



XFLR5 ANALYSIS

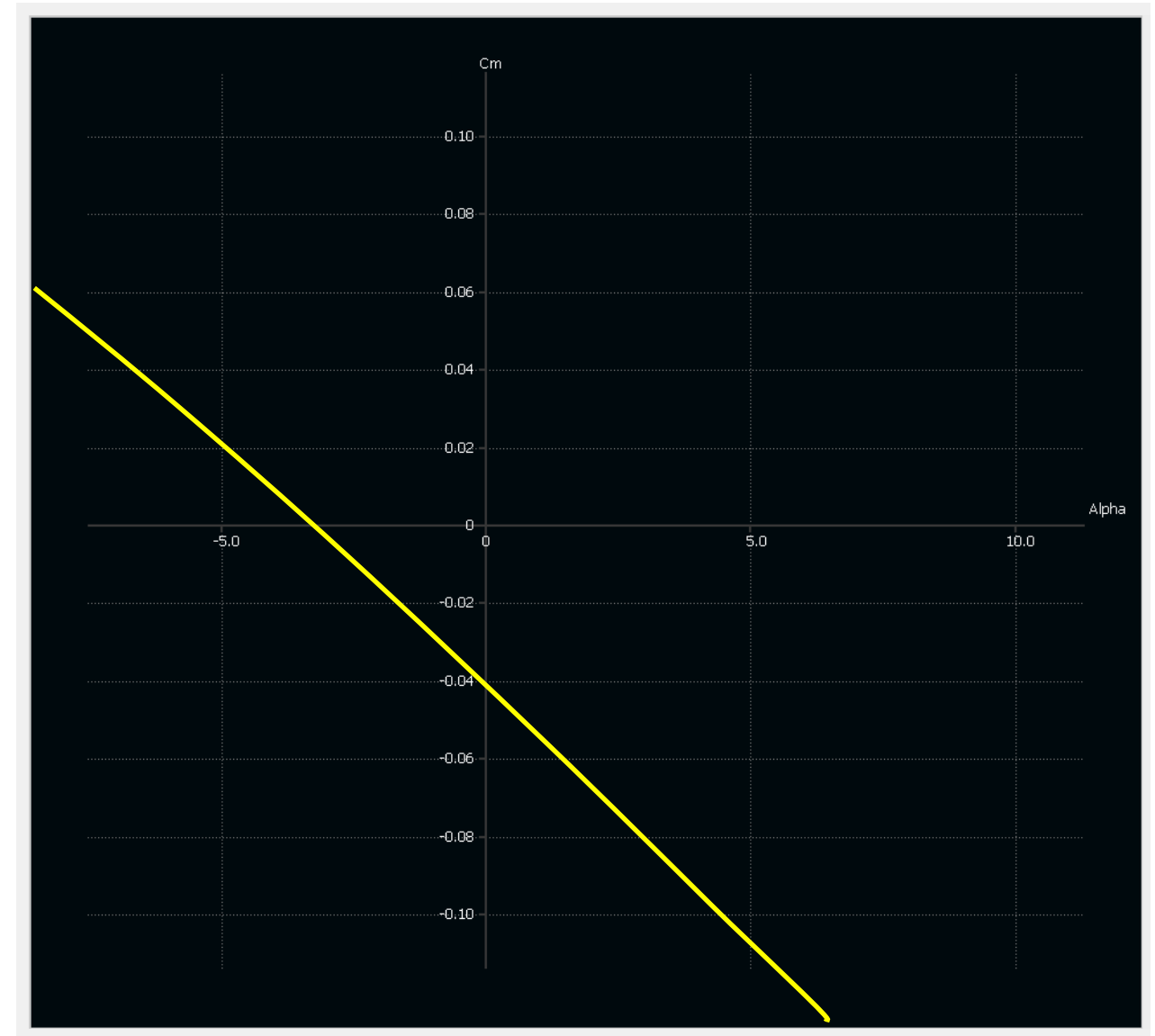


Tail Configuration



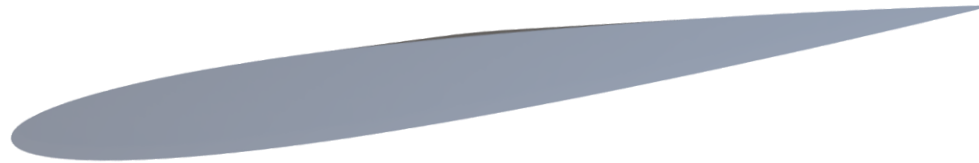
Graph Cm vs  $\alpha$

# XFLR5 ANALYSIS

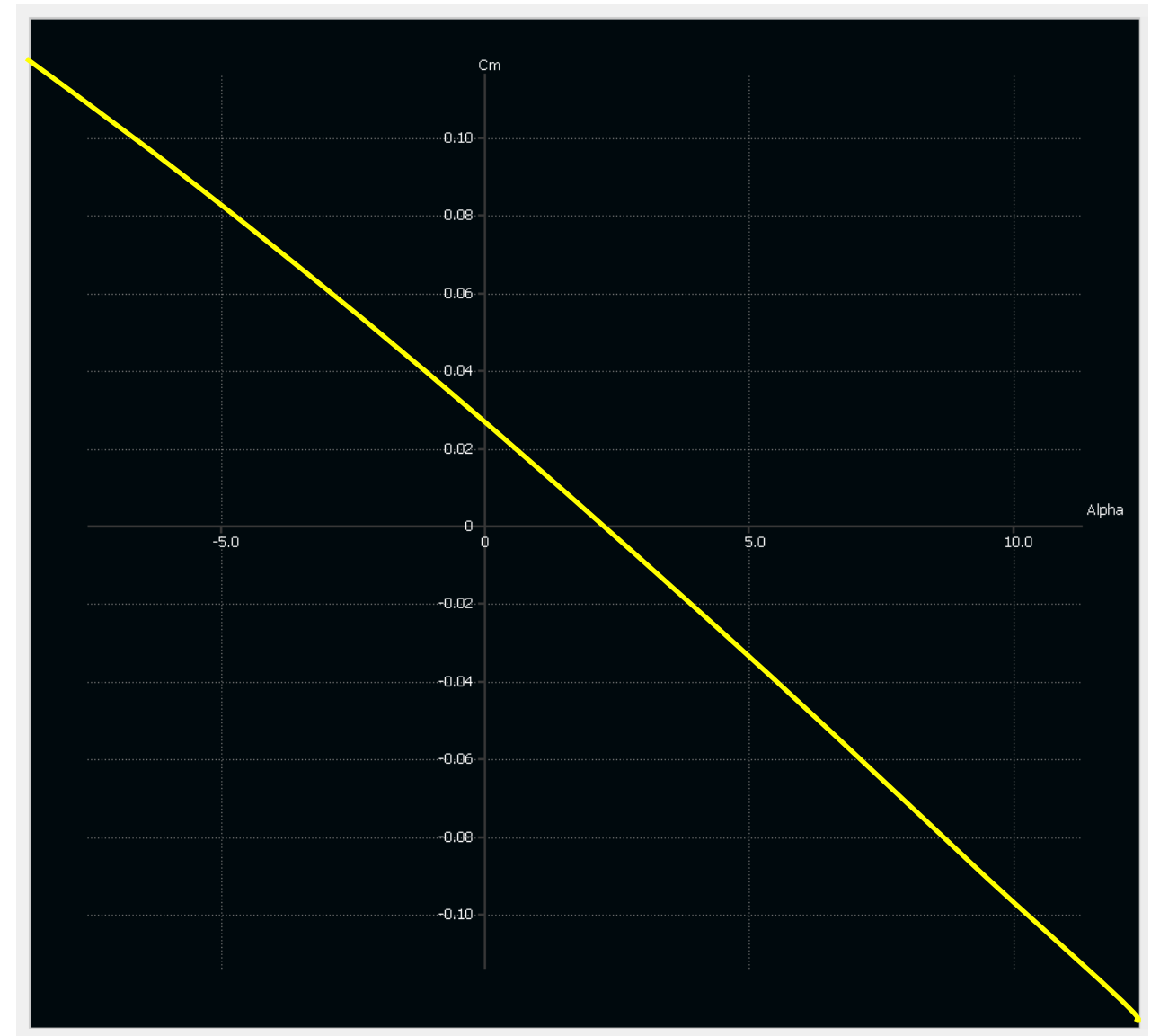


Graph Cm vs  $\alpha$  [Unstable]

## XFLR5 ANALYSIS



**-ve 8 °angle of incidence**



**Graph  $C_m$  vs  $\alpha$  [stable]**

# XFLR5 ANALYSIS

## Airfoil Selection

- High stability
- Low drag
- Symmetric



0009

# XFLR5 ANALYSIS

## Airfoil Selection

- High stability
  - Low drag
  - Symmetric
- 
- Good stability
  - Enhanced lift
  - Delay drag rise



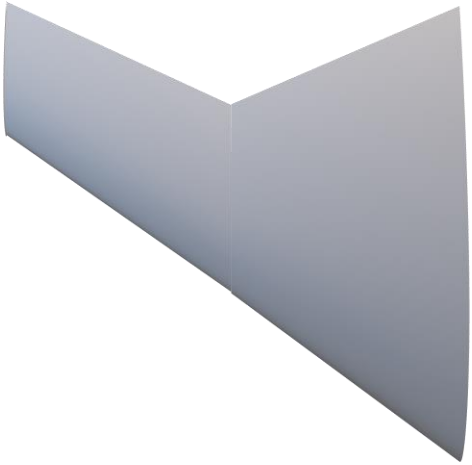
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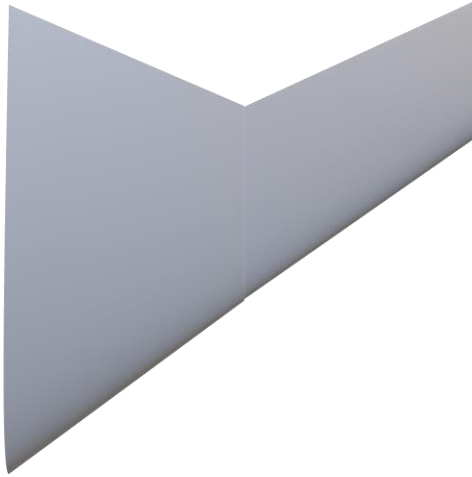
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# XFLR5 ANALYSIS

## Configuration



Swept Wing

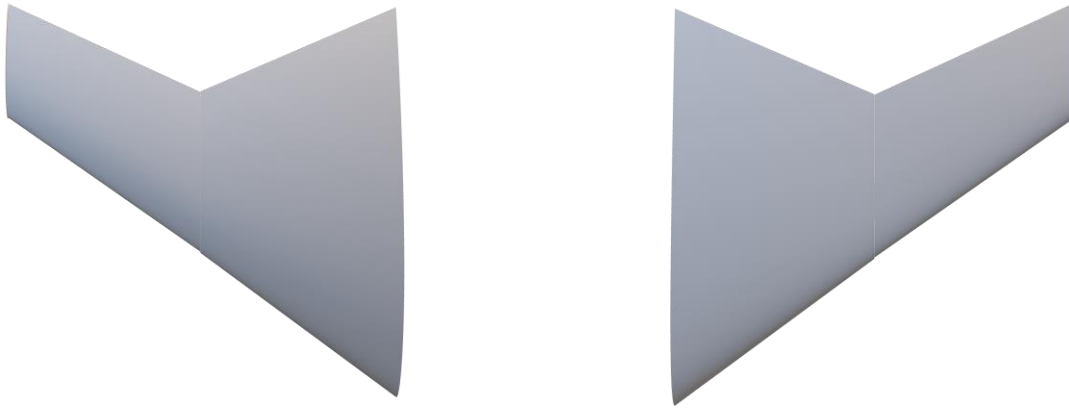


V tail



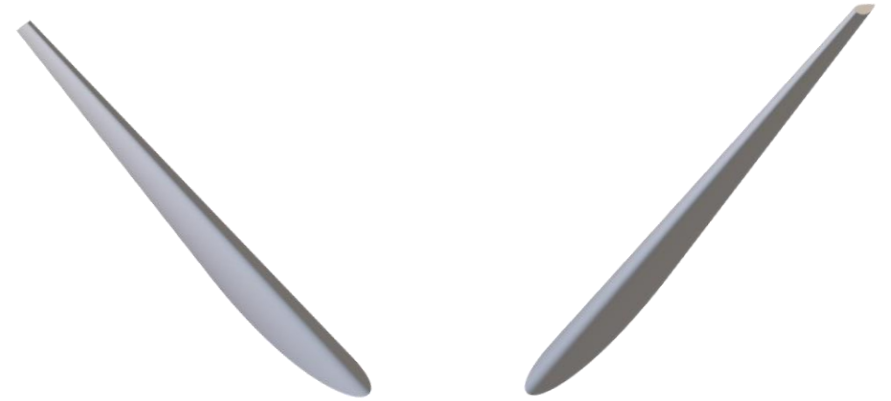
# XFLR5 ANALYSIS

## Configuration



**Swept Wing**

- Reduces adverse effects of transonic & supersonic flow
- Increase Divergence Mach number
- High maneuverability with low aspect ratio



**V tail**

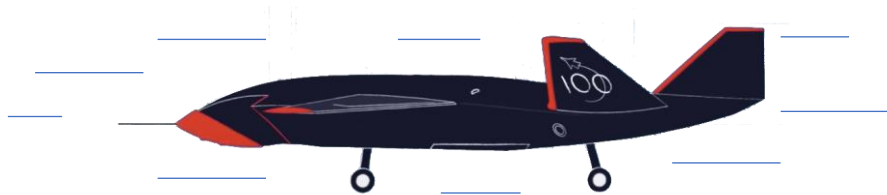
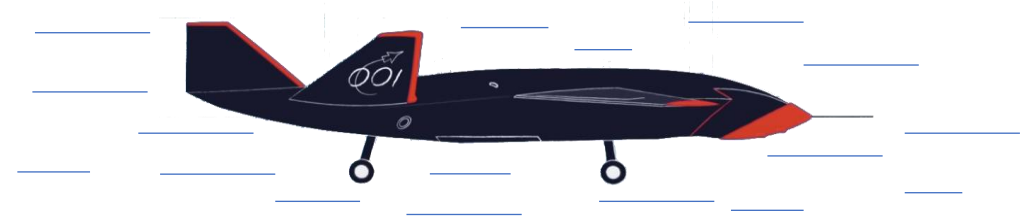
- Reduced Interference Drag
- Reduced weight than conventional tail configuration
- Enhanced Maneuverability

# STABILITY TEST

## High Altitude High Speed [Mode H]

Altitude – 44,000 ft (above MSL)

Speed – 171 knots (IAS)



## Low Altitude Low Speed [Mode L]

Altitude – 16,000 ft (above MSL)

Speed – 155 knots (IAS)



# **STABILITY TEST**

## **High Altitude High Speed [Mode H]**

**Altitude – 44,000 ft (above MSL)**

**Speed – 171 knots (IAS)**

## **Low Altitude Low Speed [Mode L]**

**Altitude – 16,000 ft (above MSL)**

**Speed – 155 knots (IAS)**

## STABILITY TEST

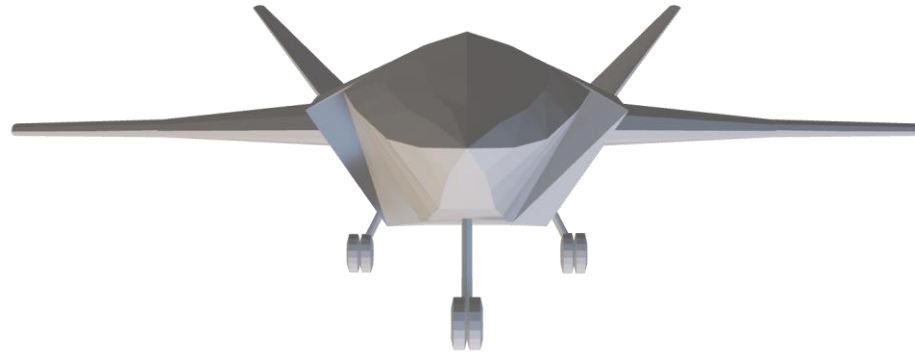
### Spiral Mode

High Altitude High Speed [Mode H]

Low Altitude Low Speed [Mode L]

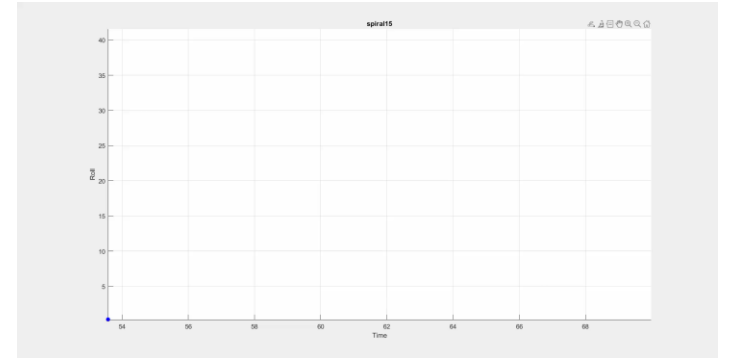
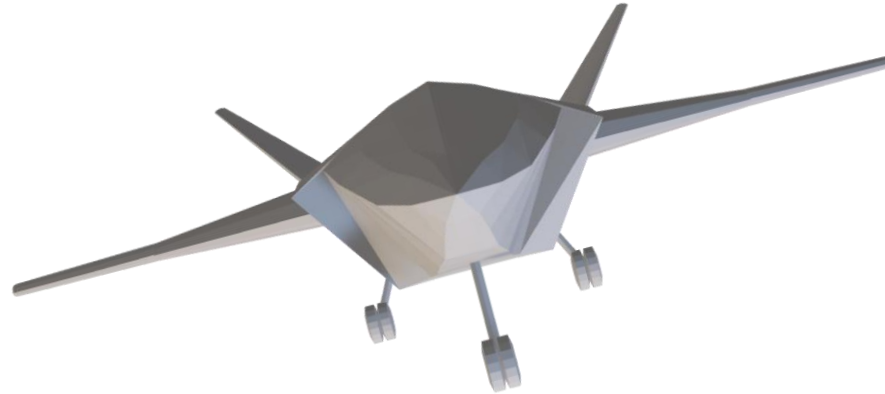
# STABILITY TEST

**Spiral Mode**



# STABILITY TEST

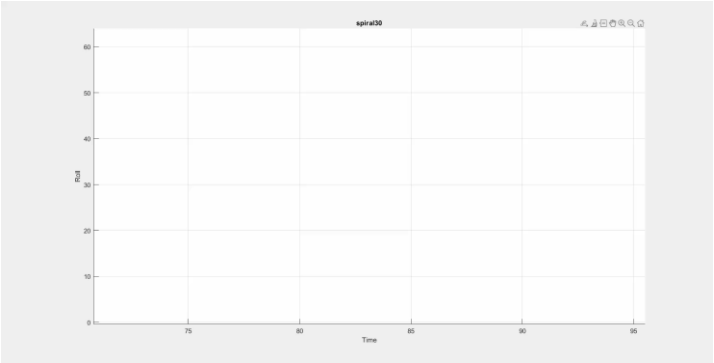
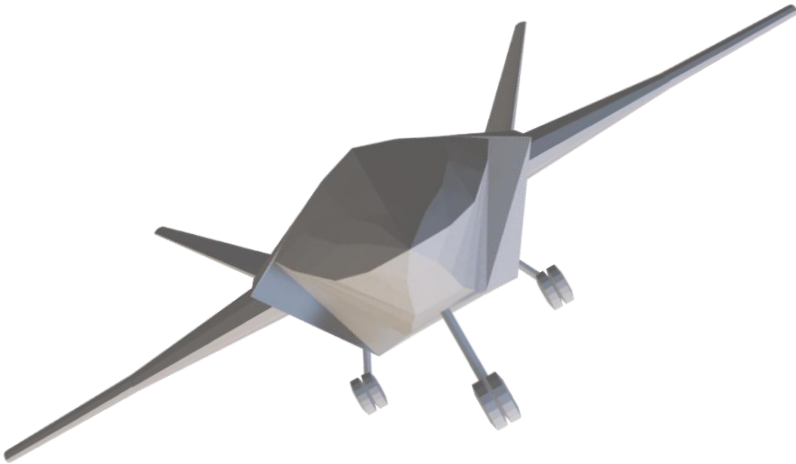
## Spiral Mode



$15^\circ$

STABILITY TEST

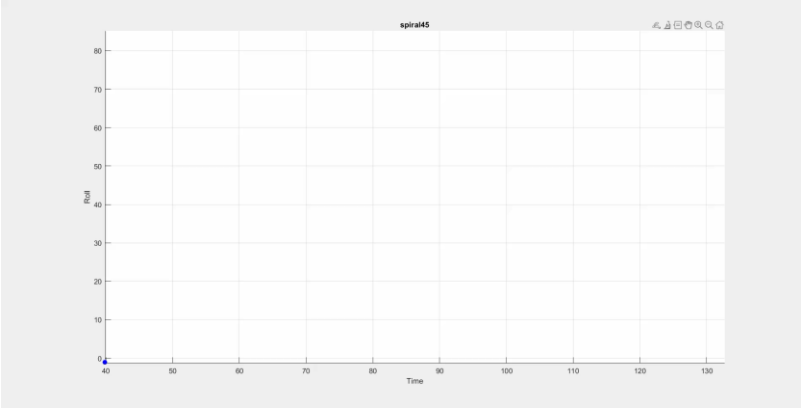
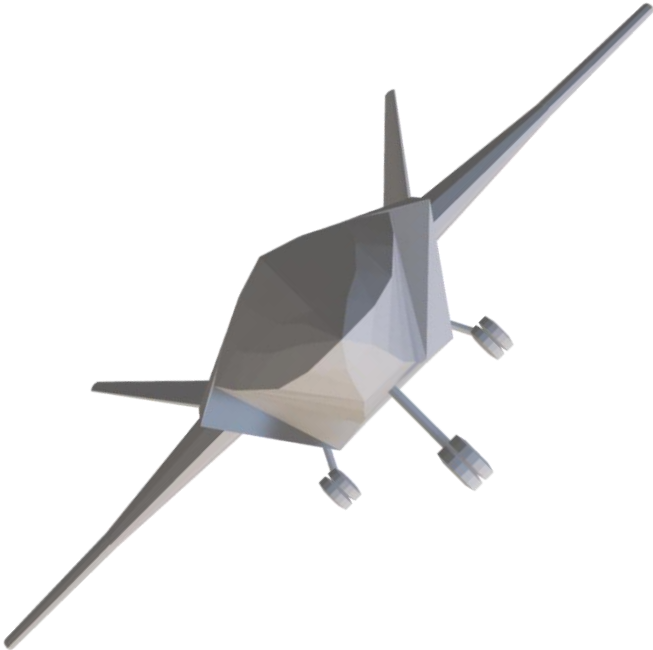
Spiral Mode



30°

STABILITY TEST

Spiral Mode



45°



## STABILITY TEST

### Spiral Mode

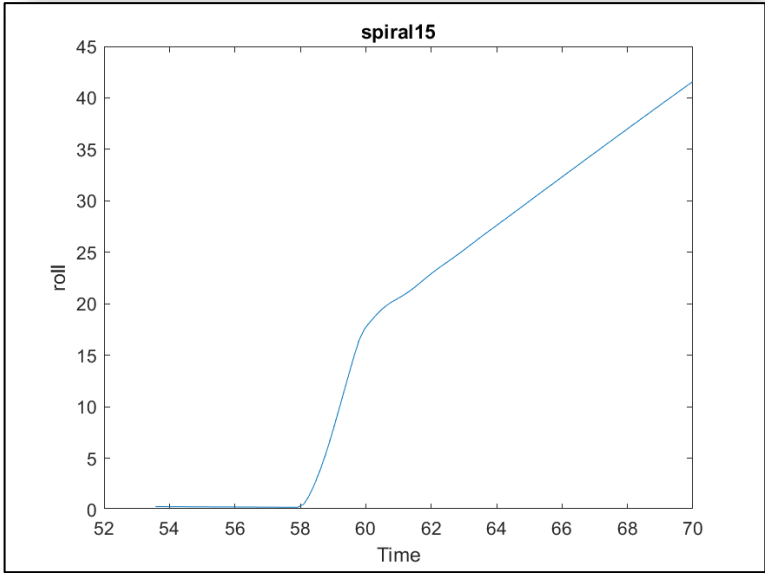
High Altitude High Speed [Mode H]

Low Altitude Low Speed [Mode L]

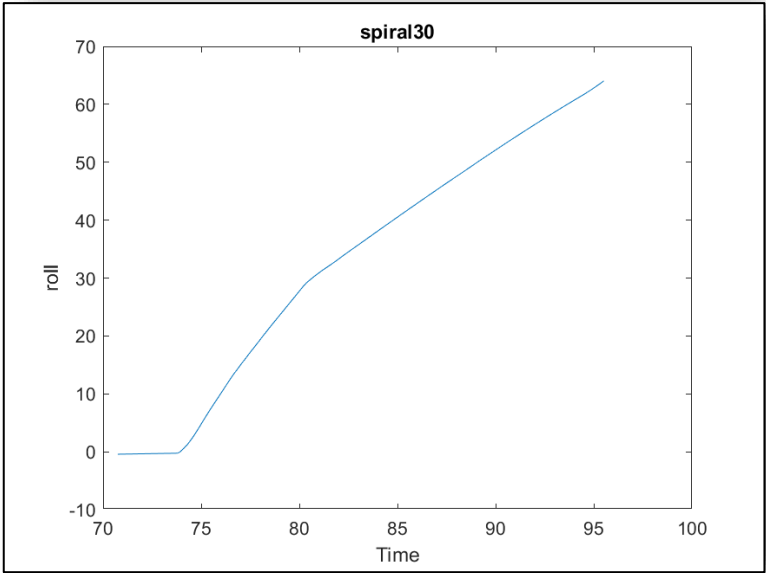
# STABILITY TEST

## Spiral Mode

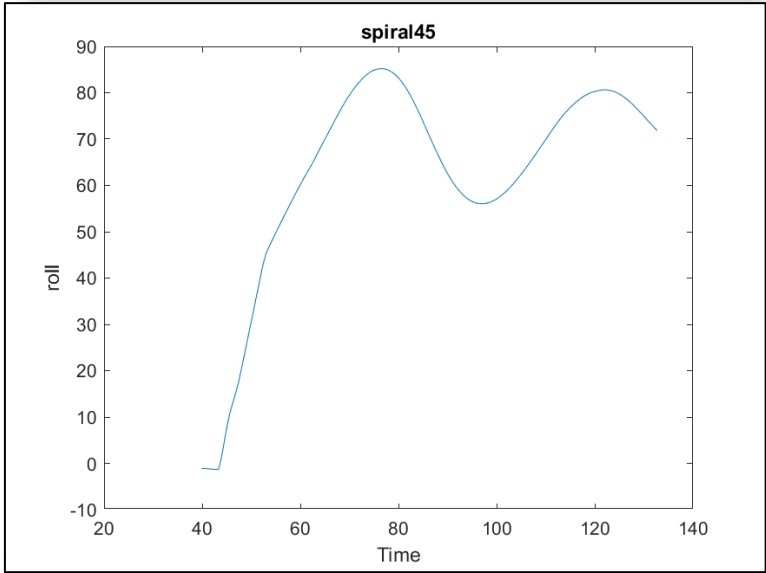
[Mode H]



15°



30°



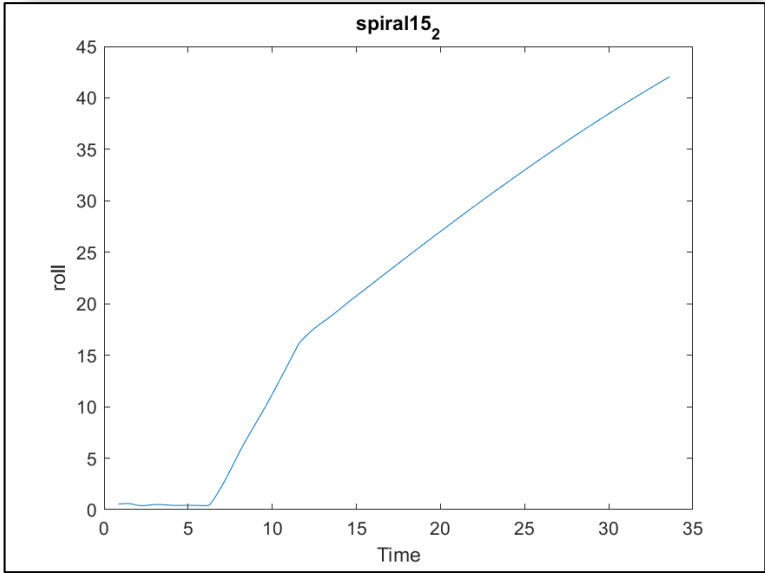
45°

Graph Roll vs Time

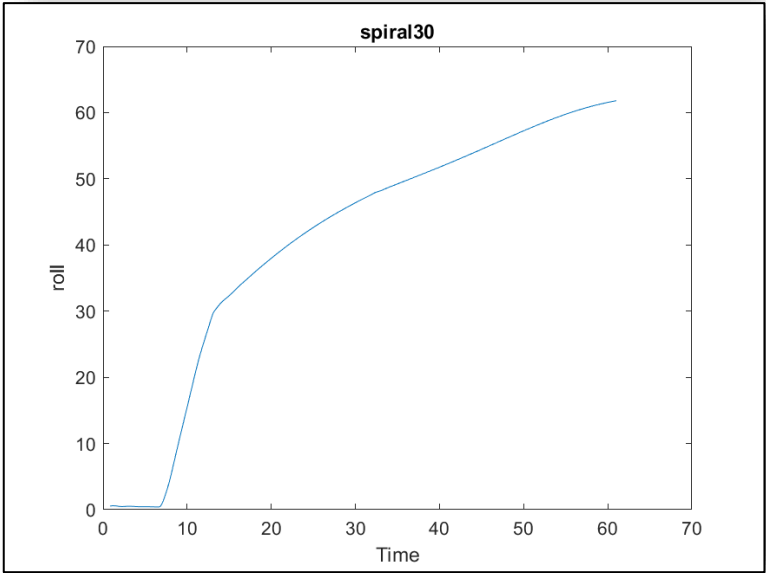
# STABILITY TEST

## Spiral Mode

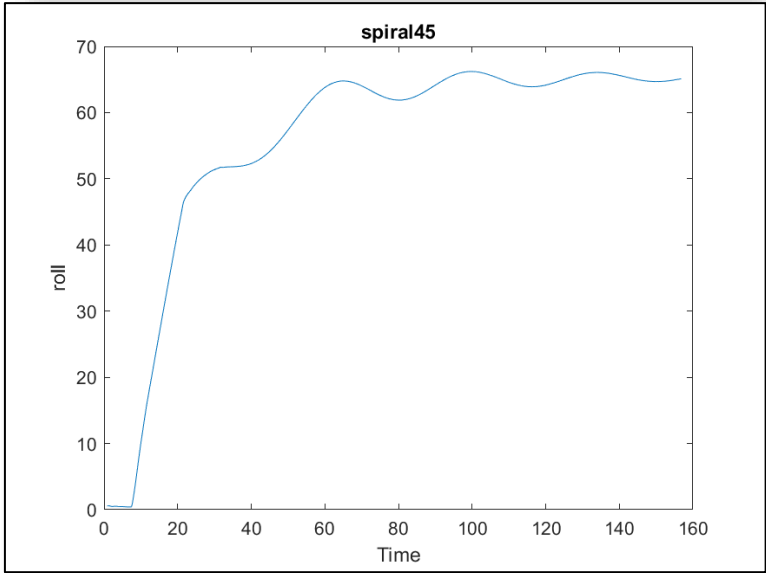
[Mode L]



15°



30°

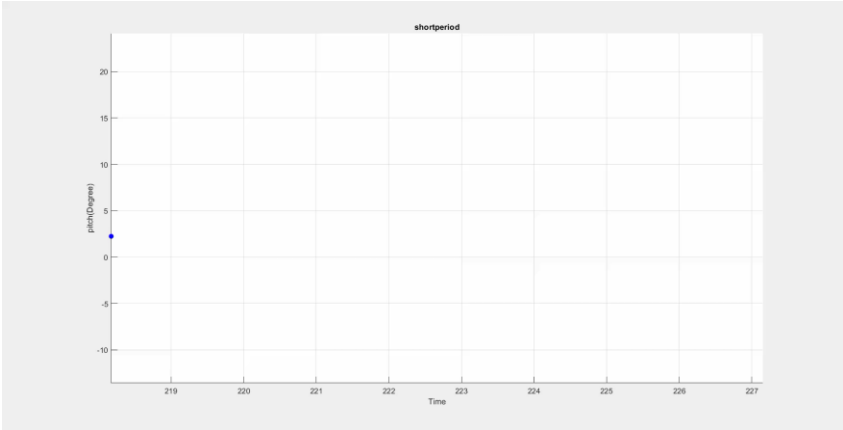
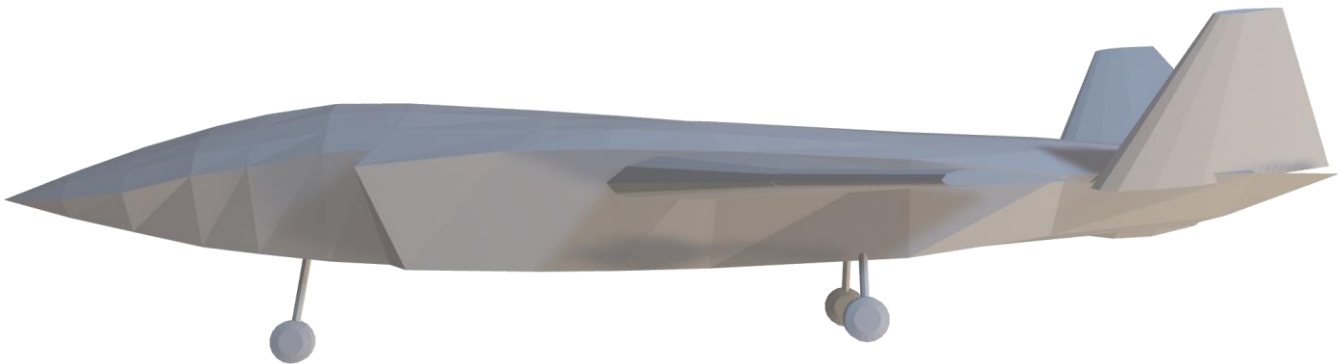


45°

Graph Roll vs Time

STABILITY TEST

Short Period Mode



Pitch Doublet

# STABILITY TEST

## Short Period Mode

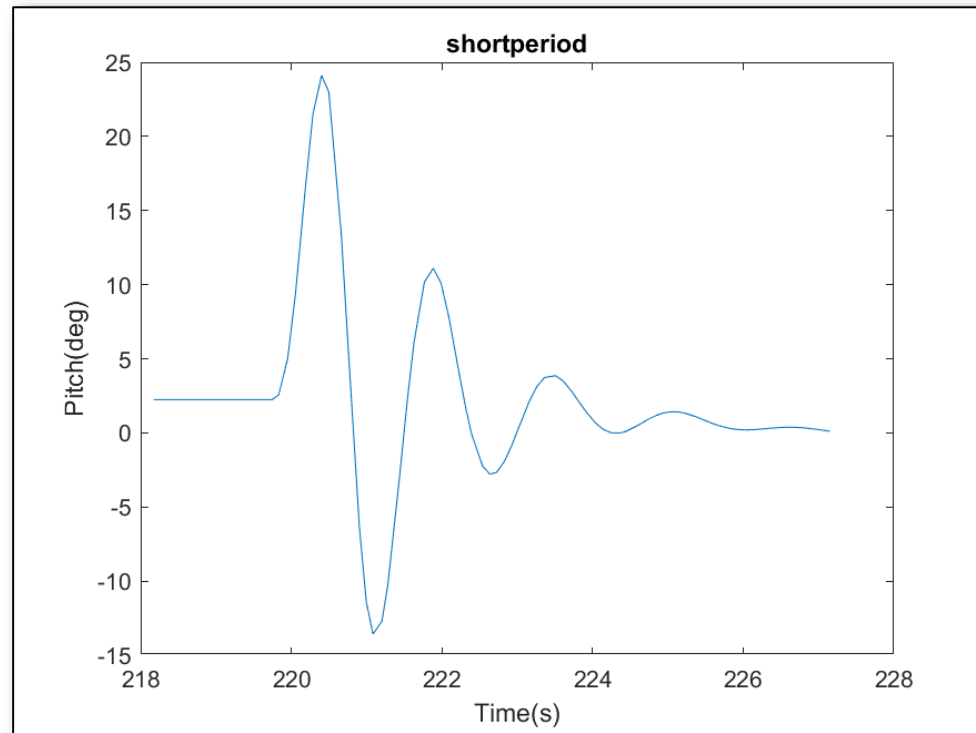
High Altitude High Speed [Mode H]

Low Altitude Low Speed [Mode L]

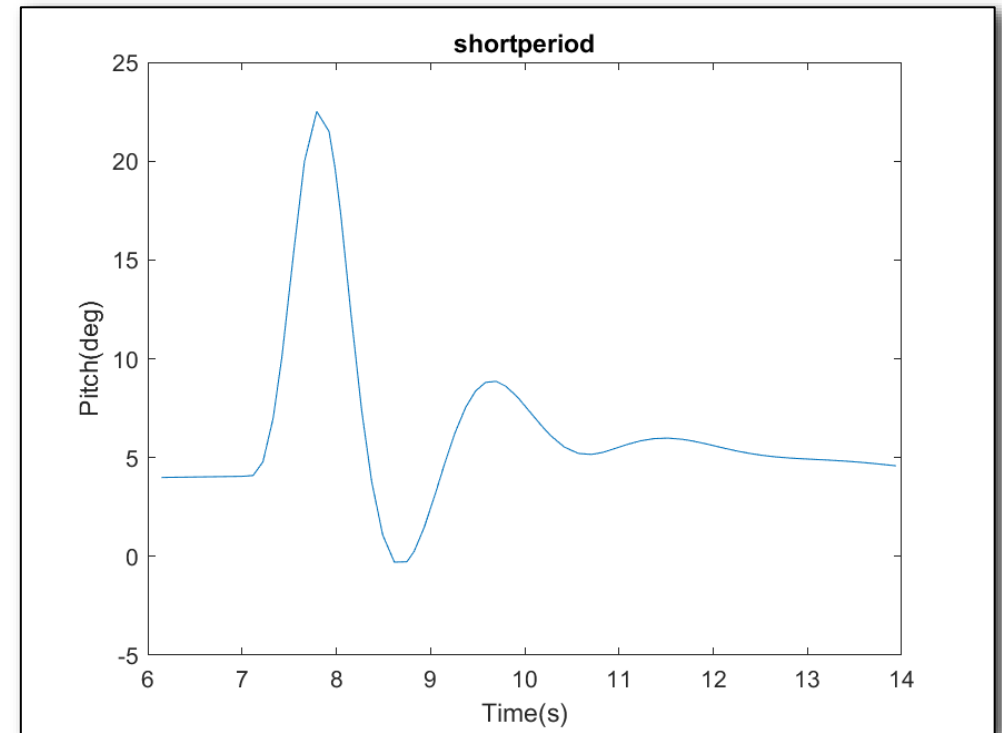
# STABILITY TEST

## Short Period Mode

[Mode H]



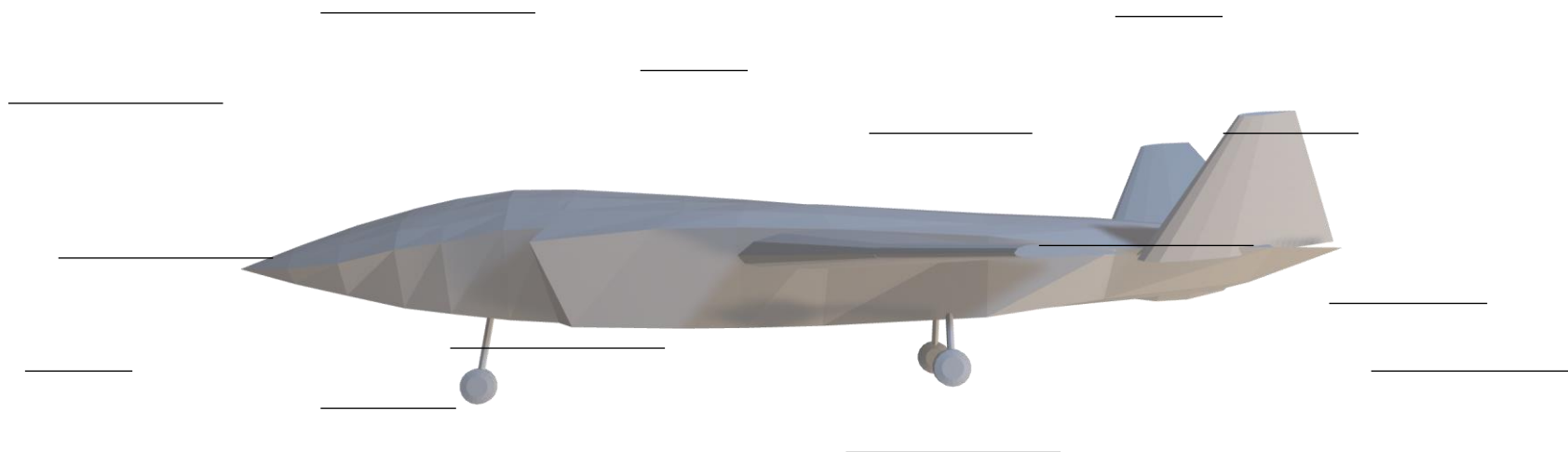
[Mode L]



Graph Pitch vs Time

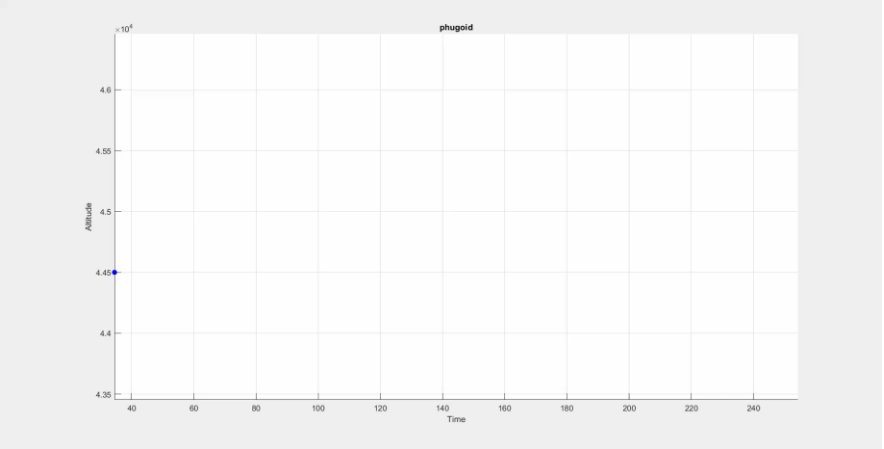
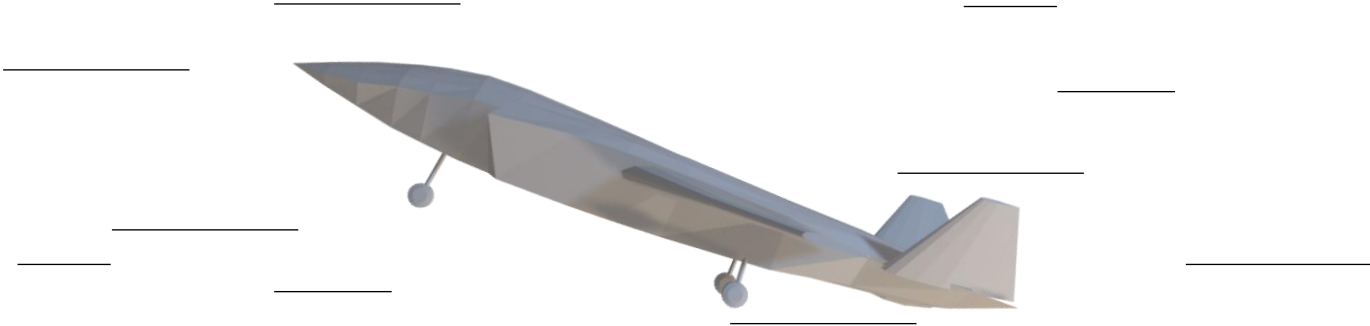
# STABILITY TEST

## Phugoid Mode



STABILITY TEST

Phugoid Mode



20° Nose Up , 10% decrease in velocity



# STABILITY TEST

## Phugoid Mode

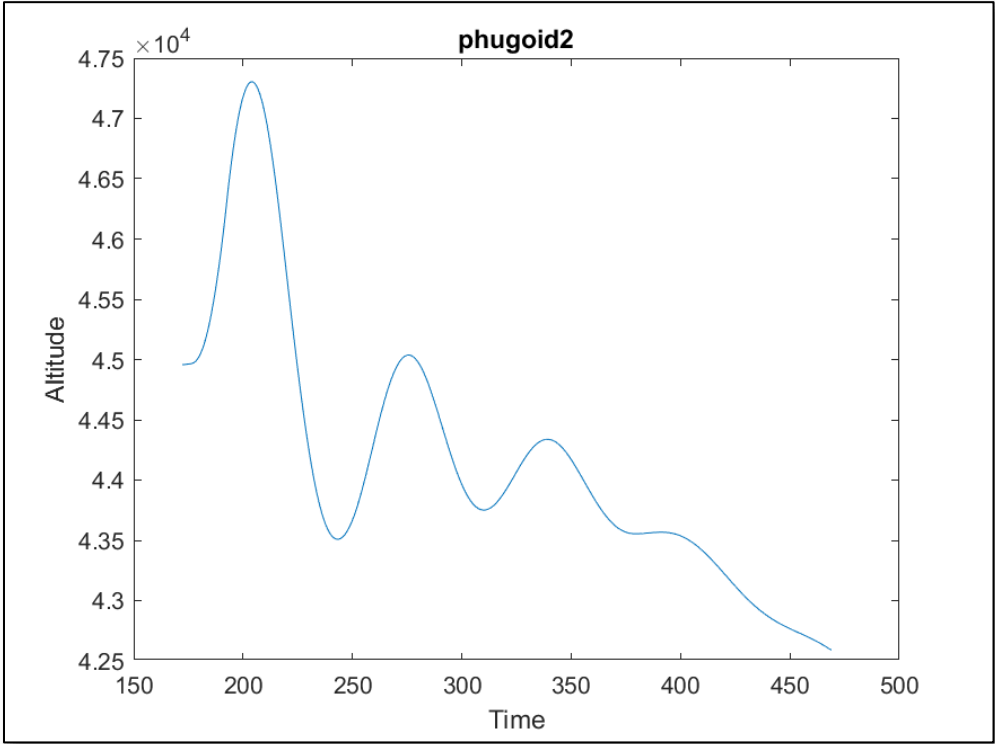
High Altitude High Speed [Mode H]

Low Altitude Low Speed [Mode L]

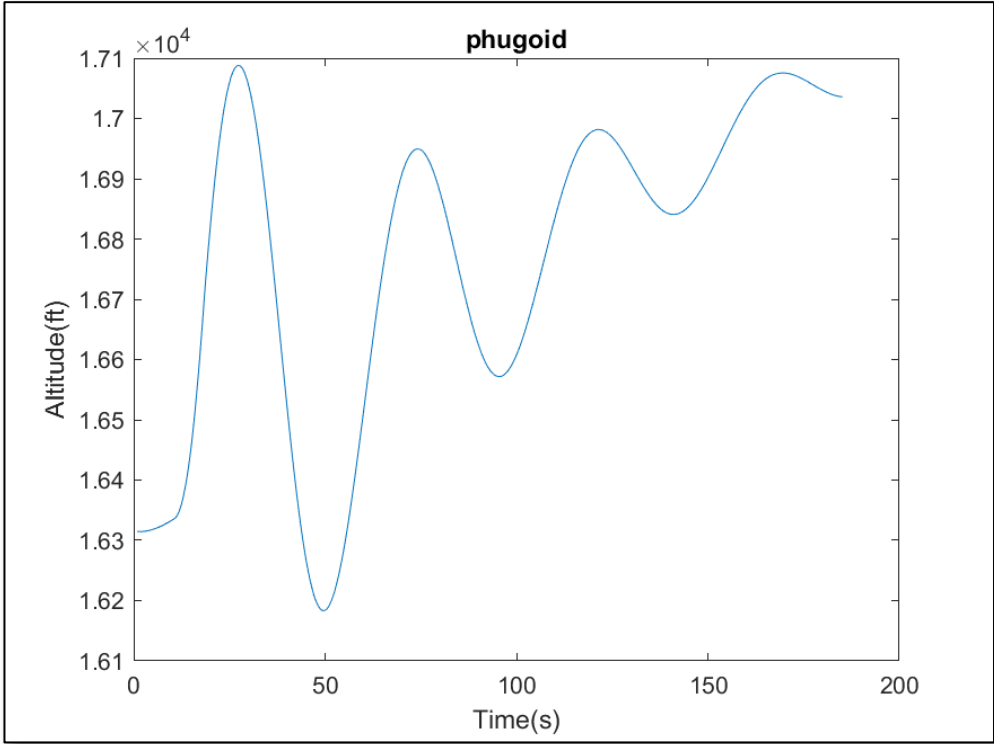
# STABILITY TEST

## Phugoid Mode

[Mode H]



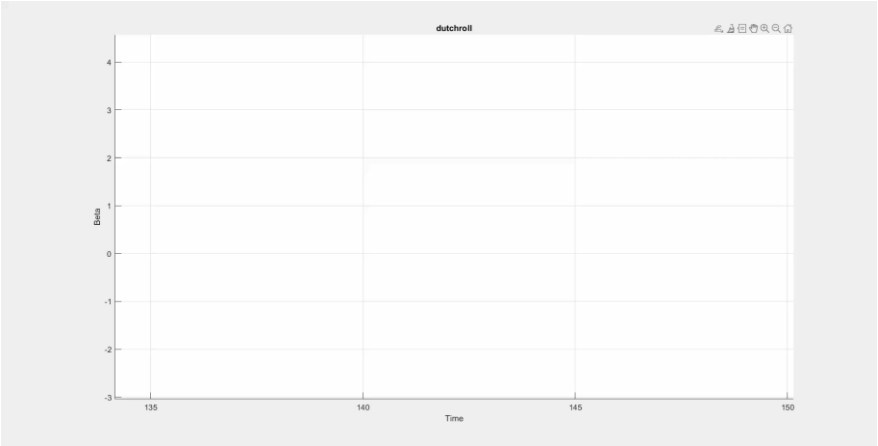
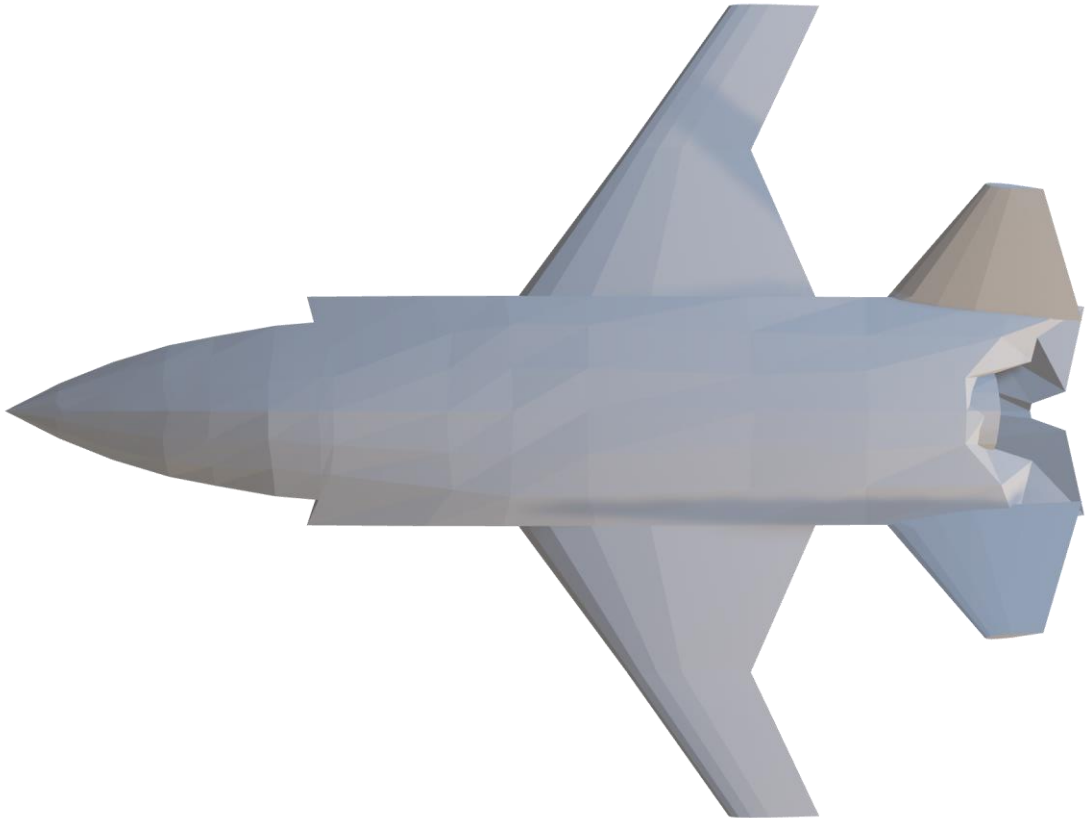
[Mode L]



Graph Altitude vs Time

STABILITY TEST

Dutch Roll



Rudder Doublet

**STABILITY TEST**

**Dutch Roll**

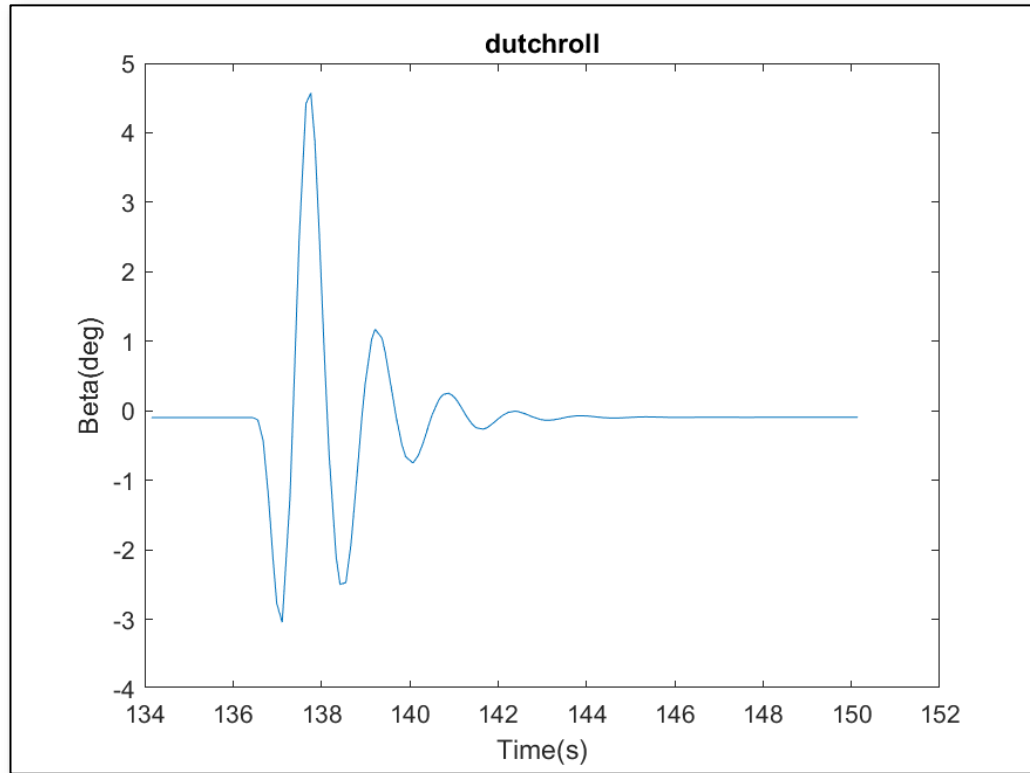
**High Altitude High Speed      [Mode H]**

**Low Altitude Low Speed      [Mode L]**

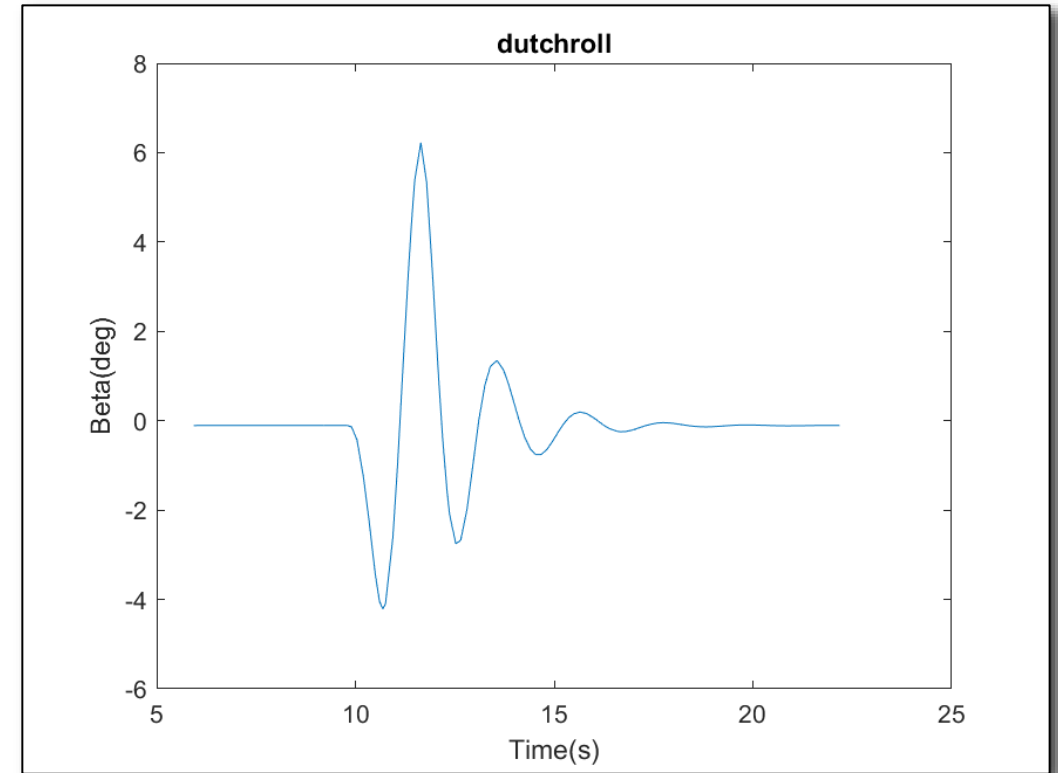
# STABILITY TEST

## Dutch Roll

[Mode H]



[Mode L]



Graph  $\beta$  vs Time