Sample Solution for Problem Set 12

Data Structures and Algorithms, Fall 2020

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Algorithm Overview: Use dynamic programming. Let dp[i][j] = True means wee can parenthesize S[i....j] to make the value be True. Then we have the transition function:

$$dp[i][j] = \bigvee_{i \le k \le j, S[k] \in \{\land, \lor, \oplus\}} dp[i][k-1]S[k]dp[k+1][j]$$

$$\tag{1}$$

Implementation: We use a simple down-top dynamic programming. Initialize dp[i][i] = S[i] for all even i. Then do the following loop

• For
$$k=2,4,6,8,...$$
 until $k=2n$, do
$$-\text{ For } i=0,2,4,6,... \text{ until } i+k=2n, \text{ let } j=i+k, \text{ do}$$

$$*dp[i][j]=\bigvee_{i\leq k\leq j,S[k]\in\{\land,\lor,\oplus\}}dp[i][k-1]S[k]dp[k+1][j]$$

Complexity: $O(n^3)$. Recall that the complexity of dynamic programming is the number of states $(O(n^2))$ times the complexity for transition function (O(n)).

Let $f_{max}(i)$ represent the largest product in the subarrays ending with i, and $f_{min}(i)$ represent the smallest product in the subarrays ending with i.

Algorithm 1: LargestProduct(A, i, j)

```
1 f_{max} = f_{min} = ans = 1;

2 for i = 1 to n do

3 | temp = f_{max};

4 | f_{max} = \max(A[i], f_{max} * A[i], f_{min} * A[i]);

5 | f_{min} = \min(A[i], temp * A[i], f_{min} * A[i]);

6 | ans = \max(ans, f_{max});

7 end

8 return ans;
```

First sort all the points based on their x coordinate. To index our subproblem, we will give the rightmost point for both the path going to the left and the path going to the right. Then, we have that the desired result will be the subproblem indexed by v, where v is the rightmost point. Suppose by symmetry that we are further along on the left-going path, that the leftmost path is going to the ith one and the right going path is going until the jth one. Then, if we have that i > j + 1, then we have that the cost must be the distance from the i - 1st point to the ith plus the solution to the subproblem obtained where we replace i with i - 1. There can be at most $O(n^2)$ of these subproblem, but solving them only requires considering a constant number of cases. The other possibility for a subproblem is that $j \le i \le j + 1$. In this case, we consider for every k from 1 to j the subproblem where we replace i with k plus the cost from kth point to the ith point and take the minimum over all of them. This case requires considering O(n) things, but there are only O(n) such cases. So, the final runtime is $O(n^2)$.

- (a) To index the subproblem, we will give the first k items from the item list and the maximum weight of current knapsack. There can be at most O(nW) of these subproblem. For each item, we can decide to put it in or not. If we put the ist item in, we need to prepare w_i weight for it and earn v_i value. The value is v_i plus the solution to the subproblem with the first i-1 items, and $W-w_i$ capacity. Otherwise, the value is as same as the solution to the subproblem with the first i-1 items, and W capacity. We take the maximum value from the two choices for each item.
- (b) No since W can increase exponential as input length.

From the definition, there is an algorithm A_1 solves L_1 in $O(n^{k_1})$, and A_2 solves L_2 in $O(n^{k_2})$.

5.1 $L_1 \cup L_2$

Algorithm 2: $A_3(x)$ 1 if $A_1(x)$ then 2 | return true; 3 end 4 if $A_2(x)$ then 5 | return true; 6 end 7 return false;

 A_3 solves $L_1 \cup L_2$ in $O(n^{\max(k_1,k_2)})$, so $L_1 \cup L_2 \in P$.

5.2 $L_1 \cap L_2$

Algorithm 3: $A_3(x)$ 1 if $A_1(x)$ then 2 | if $A_2(x)$ then 3 | return true; 4 | end 5 end 6 return false;

 A_4 solves $L_1 \cap L_2$ in $O(n^{\max(k_1,k_2)})$, so $L_1 \cap L_2 \in P$.

5.3 L_1L_2

Algorithm 4: $A_5(x)$ 1 for i=1 to (n-1) do 2 | if $A_1(x_1 \dots x_i)$ then 3 | if $A_2(x_{i+1} \dots x_n)$ then 4 | return true; 5 | end 6 | end 7 end 8 return false;

 A_5 solves L_1L_2 in $O(n^{\max(k_1,k_2)+1})$, so $L_1L_2 \in P$.

5.4 \overline{L}_1

 A_6 solves \overline{L}_1 in $O(n^{k_1})$, so $\overline{L}_1 \in P$.

Algorithm 5: $A_6(x)$

```
1 if A_1(x) then
2 | return false;
3 end
4 return true;
```

5.5 L_1^*

Let f[i][j] indicate whether $x_i \dots x_j$ is belong to L_1^* .

```
\forall x \in L_1^*, x \in L_1 \text{ or } \exists k, x_1 \dots x_k \in L_1^* \land x_{k+1} \dots x_n \in L_1^*.
```

Therefore, we can construct a dynamic programming algorithm A_7 . A_7 solves L_1^* in $O(n^{k_1+2})$, so $L_1^* \in P$.

```
Algorithm 6: A_7(x)
 1 for i = 1 to n do
        \quad \mathbf{for} \ j = i+1 \ to \ n \ \mathbf{do}
             f[i][j] = \text{false};
 3
 4
        end
 5 end
 \mathbf{6} \ \mathbf{for} \ i = 1 \ to \ n \ \mathbf{do}
        for j = i to n do
             if A_1(x_i \dots x_j) then
 8
               f[i][j] = true;
             end
10
        end
11
12 end
13 for i = 1 to n do
        for j = i + 1 to n do
14
             for k = i \text{ to } (j - 1) \text{ do}
15
                  if f[i][k] and f[k+1][j] then
16
                     f[i][j] = \text{true};
17
                  end
18
19
             end
20
        end
21 end
22 return f[1][n];
```

6 Problem 6

(a)

Consider (deterministic polynomial time) Turing Machine M defined as follows: Let $G_1=(V_1,E_1)$, $G_2=(V_2,E_2)$, Turing Machine M accept input (G_1,G_2,π) if and only if π is a bijection between G_1 and G_2 , and $\pi(u)\pi(v)\in E_2$ if and only if $uv\in E_1$.

(b)

Note that $\overline{TAUTOLOGY}$ is the language of boolean formulas which can be false for some input.

(a)

for any language $L \in P$, there exists a (deterministic polynomial time) Turing Machine M defined as follows: M(x) = 1 if and only if $x \in L$. Therefore, we may define a (deterministic polynomial time) Turing Machine M' in the following way.

• for any x and proof w, M'(x, w) = 1 - M(x).

It can be seen that $\bar{L} \in NP$. Hence, $L \in coNP$.

(b)

If not, $L \in NP \Rightarrow L \in P \Rightarrow \bar{L} \in P \Rightarrow \bar{L} \in NP \Rightarrow L \in coNP$. Similarly, we have $L \in coNP \Rightarrow L \in NP$, leading to contradiction.