

Robotics 311 : How to build robots and make them move

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Fall 2022

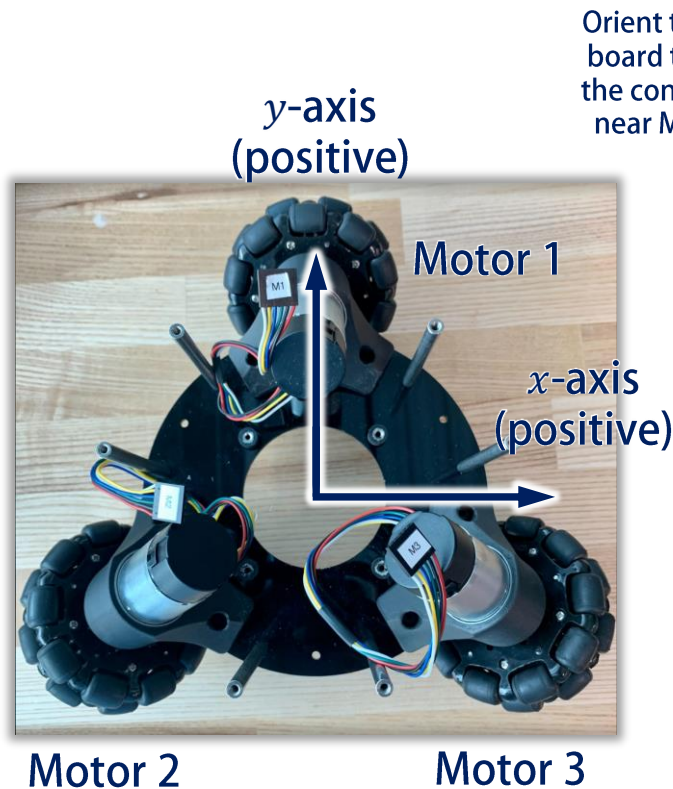


ROB 311 – Lab 6

- Today, we will assemble our ball-bots!
- SLS parts are in the makerspace—pick them up when ready
- Following assembly, we will connect the wiring for the motors / encoders
- The motors need to go in a specific order for the coordinate axes

Fasteners /
stand offs are
in these

Take what you
need



Orient the Pico
board to have
the connectors
near Motor 1

