

LABORATORY WORK REPORT №2
«Operational amplifiers circuits design»
Principles of Circuits

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1. Work purpose: to study parameters of Operational Amplifier and basis of Operational amplifiers circuits design

Goals:

- 1) Design amplifier model on the basis of operational amplifier «Inverting amplifier»
- 2) Simulate amplifier scheme and analyze dependencies of output voltage from load and resistor values variation
- 3) Analyze time domain and frequency domain of amplifier
- 4) Simulate underpower state/power supply check

2. Starting data

- Required gain of amplifier $K_{NI} = -2.000$
- Required tolerance: $\Delta K_{NIOPAMP} = 3\%$
- Operational Amplifier : Inverting amplifier
- Voltage source power supply $V_{PP+} = 9$ (V) / $V_{PP-} = 9$ (V)
- Frequency for time domain simulation

$$f_{test_1} = 100 \text{ (Hz)}$$

$$f_{test_2} = 2000 \text{ (Hz)}$$

$$f_{test_3} = 200000 \text{ (Hz)}$$

- Test signal voltage magnitude

$$V_{test_AC} = V_{test} = 0.5 \text{ (V)}$$

- Resistor parameters

$$R_1 = 11000 \text{ (}\Omega\text{)}$$

$$R_{fb} = 6000 \text{ (}\Omega\text{)}$$

$$R_3 = 19500 \text{ (}\Omega\text{)}$$

$$R_4 = 20001 \text{ (}\Omega\text{)}$$

$$R_{Load} = 1000000 \text{ (}\Omega\text{)}$$

- Amplifier scheme: Inverting amplifier

3. Simulation

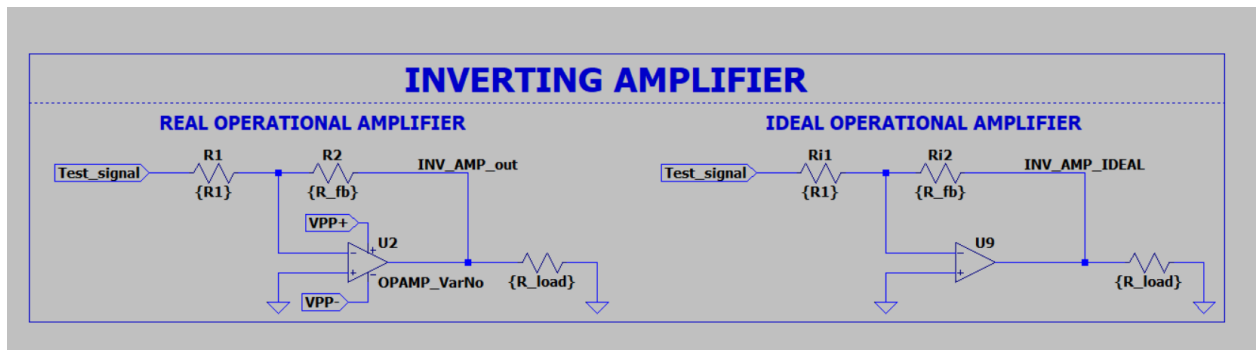


Figure 3.1 – Inverting amplifier scheme

3.1. Gain evaluation:

Gain evaluation with new resistors

$$K_{NI} = -\frac{R_{fb}}{R_1} = -0.5455$$

$$K_{NI_{max}} = -\frac{R_{fb_{max}}}{R_{1_{min}}} = -\frac{R_{fb}(1+M)}{R_{1_{min}}(1-M)} = -0.5565$$

$$K_{NI_{min}} = -\frac{R_{fb_{min}}}{R_{1_{max}}} = -\frac{R_{fb}(1-M)}{R_{1_{min}}(1+M)} = -0.5347$$

Define maximum deviation from K_{NI} defined by resistance tolerance

$$E_{NI_{R+}} = \left| \frac{K_{NI_{max}} - K_{NI}}{K_{NI}} \right| = 0.0202$$

$$E_{NI_{R-}} = \left| \frac{K_{NI_{min}} - K_{NI}}{K_{NI}} \right| = 0.0198$$

$$\Delta K_{NI_{OPAMP}} = \max \text{ of } E_{NI_{R+}} \text{ and } E_{NI_{R-}} = 0.0202$$

Table 1. Parameters of the amplifier

Обозначение	Simulation	
	Nominal	With tolerance variation
R_1 , k Ω	11	1%
R_2 , k Ω	6	1%
R_{Load} , k Ω	1 000 k (ideal)	100, 1000, 10000, 100000
K_{NI}	-0.5455	0.0202
$K_{NI_{max}}$	-0.5565	0.0202
$K_{NI_{min}}$	-0.5347	0.0198
$\Delta K_{NI_{OPAMP}}$	0.0202	0

3.2. Time domain simulation results

3.2.1. $f_{test_1} = 100$ (Hz)

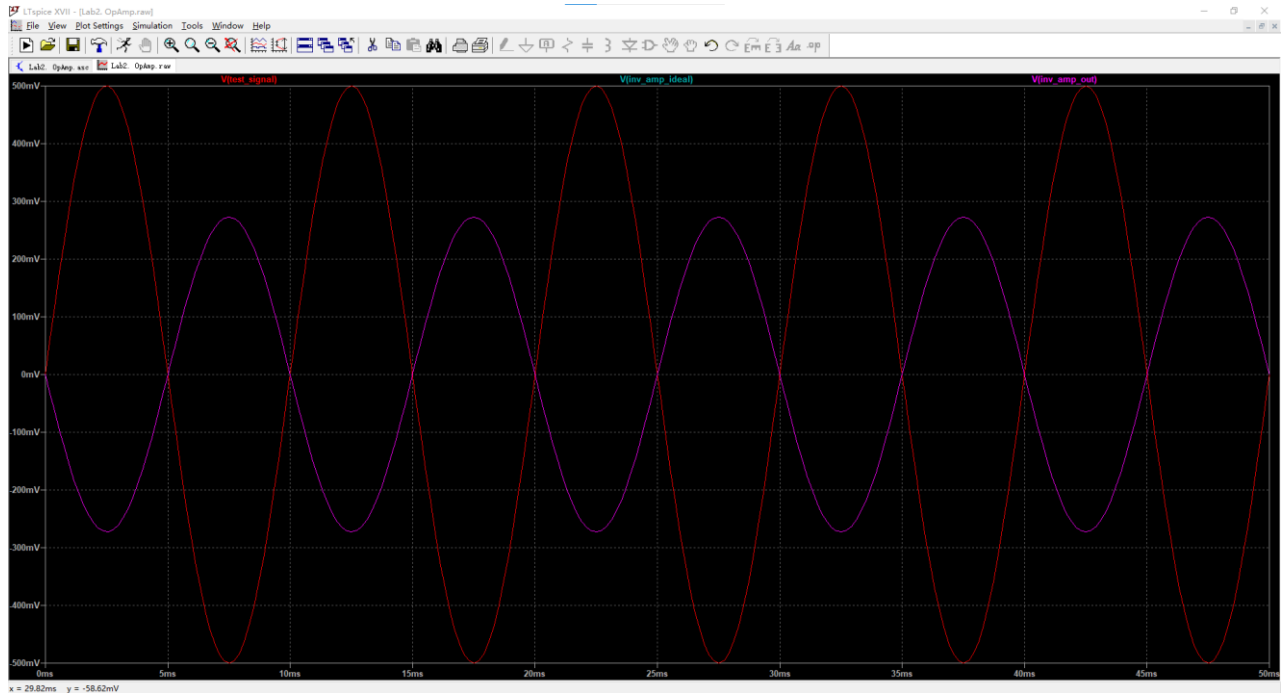


Figure 3.2 – Input and output voltages of ideal and real operational amplifiers

$f_{test_1} = 100, K_{NI} = 4, R_1$ variation 1%, R_{fb} variation 1%

3.2.2. $f_{test_2} = 2000$ (Hz)

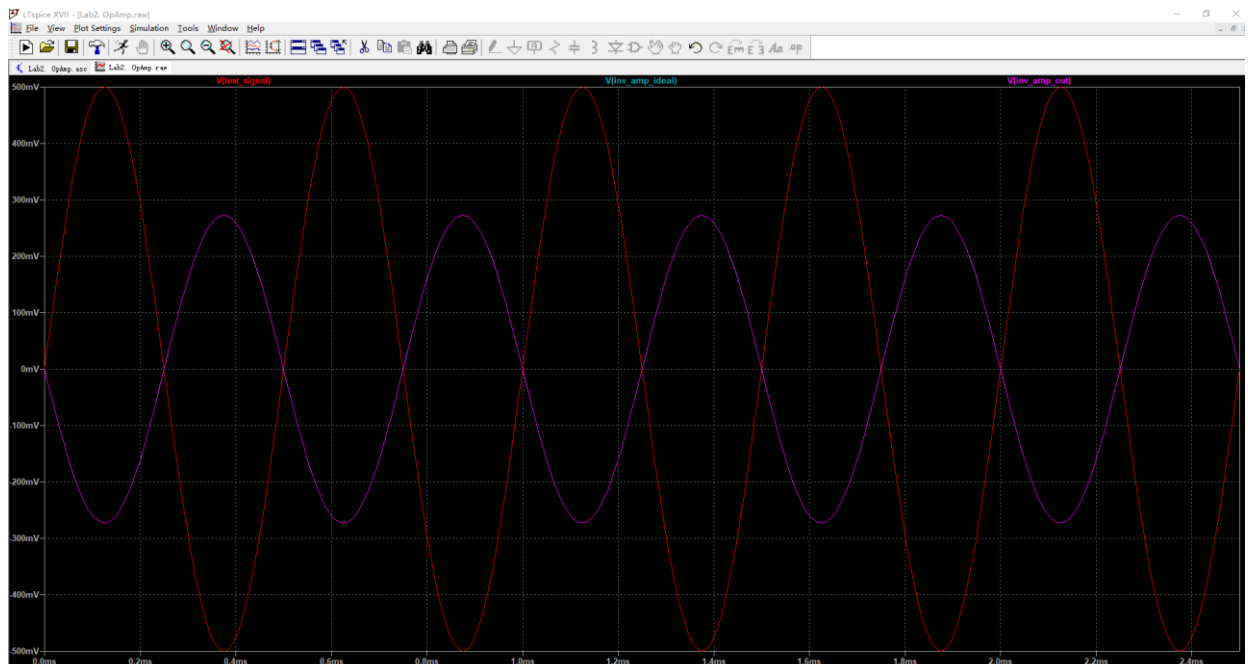


Figure 3.3 – Input and output voltages of ideal and real operational amplifiers

$f_{test_2} = 2000, K_{NI} = 4, R_1$ variation 1%, R_{fb} variation 1%

3.2.3. $f_{test_3} = 200000$ (Hz)

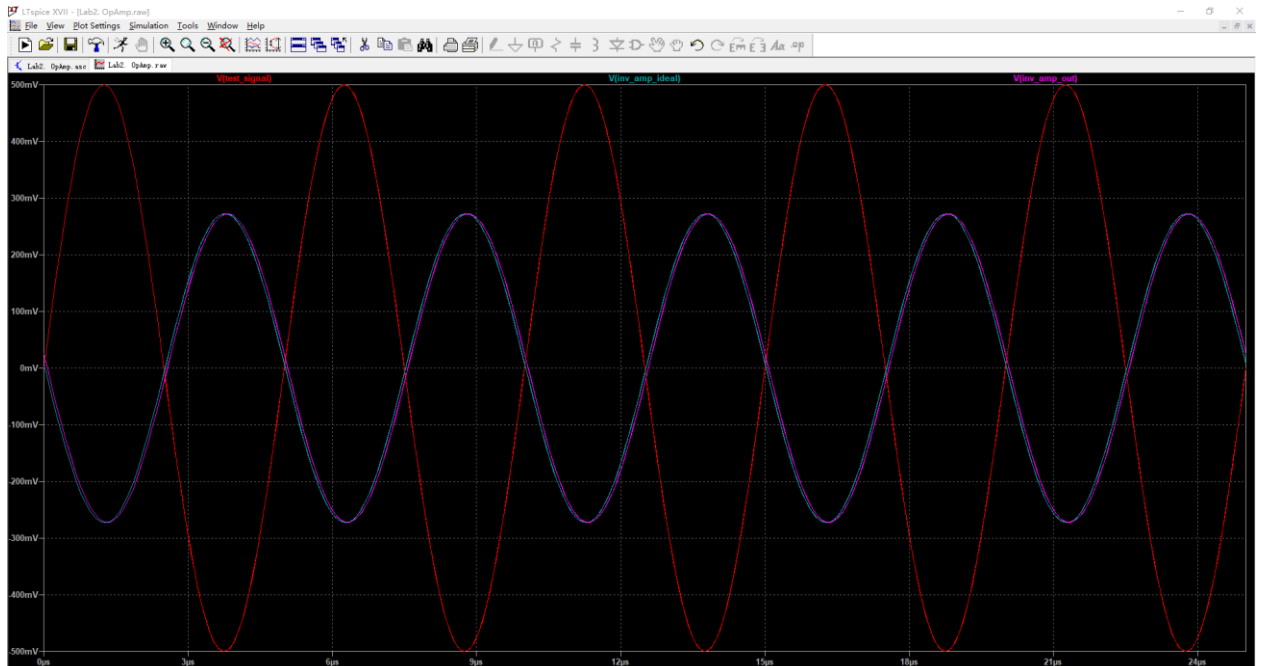


Figure 3.4 – Input and output voltages of ideal and real operational amplifiers

$$f_{test_3} = 200000, K_{NI} = 4, R_1 \text{ variation } 1\%, R_{fb} \text{ variation } 1\%$$

3.3. Frequency domain simulation results

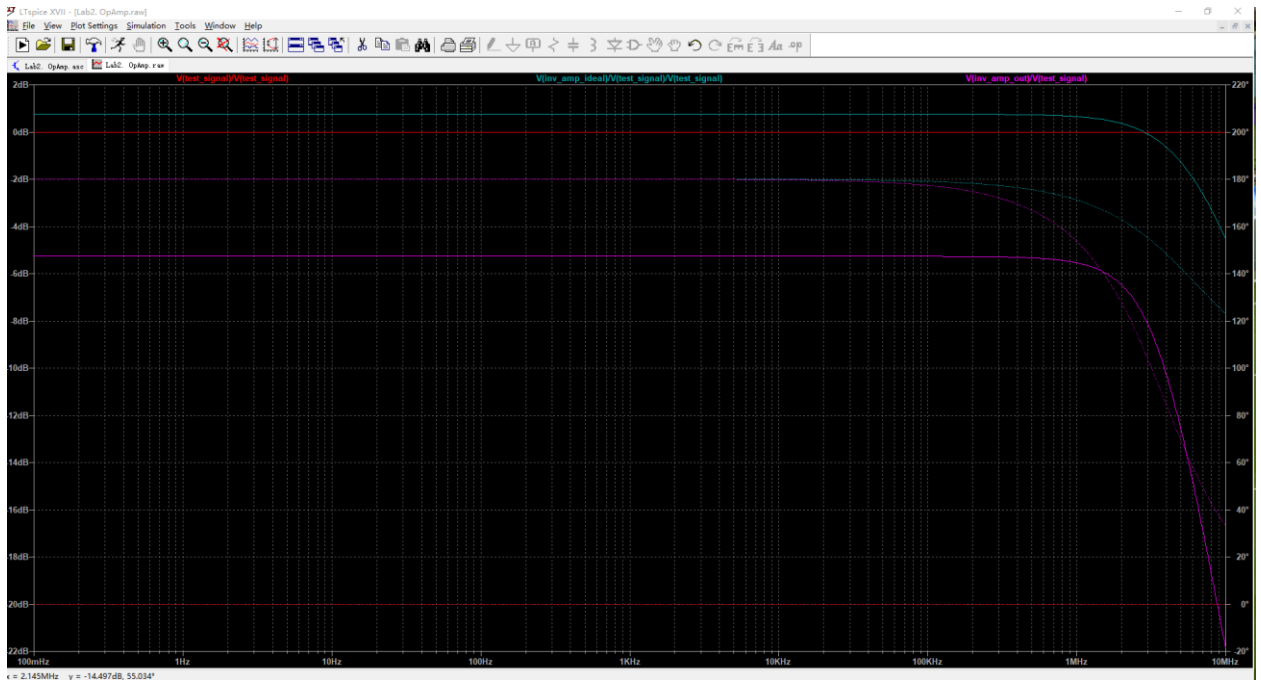


Figure 3.5 – Input and output voltages of ideal and real operational amplifiers

$$K_{NI} = -0.5455, R_1 \text{ variation } 1\%, R_{fb} \text{ variation } 1\%$$

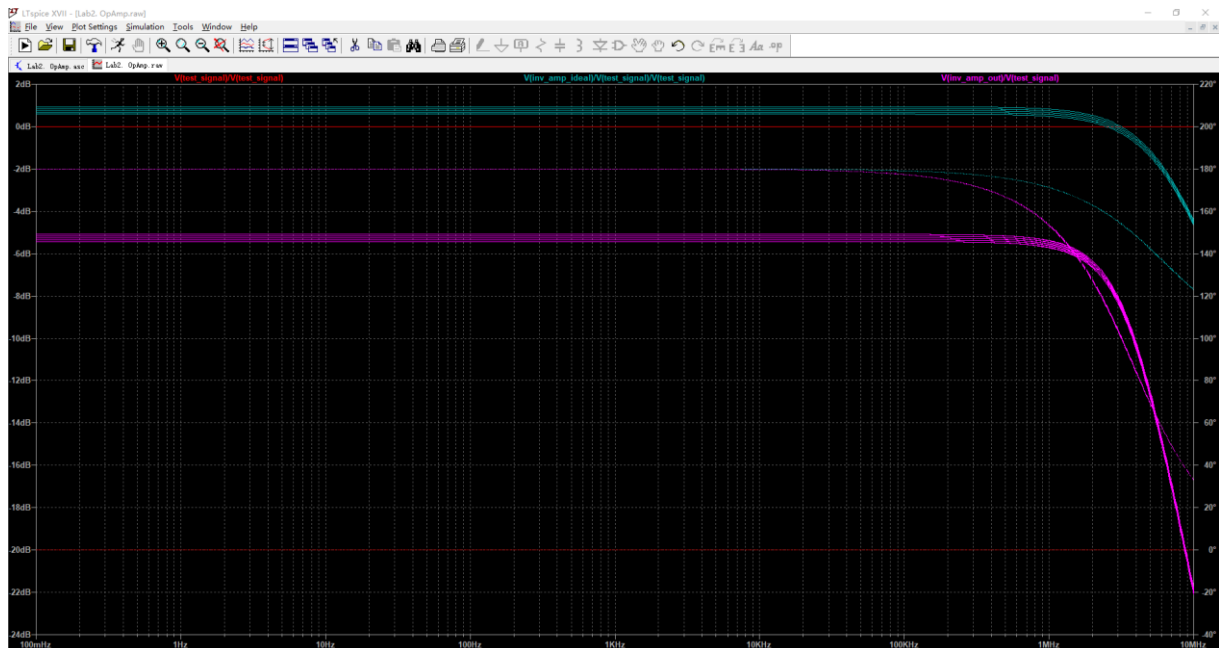


Figure 3.6 – Input and output voltages of ideal and real operational amplifiers

$K_{NI} = -0.5455$, R_1 variation 1%, R_{fb} variation 1% and R_{Load} variation

3.3.1. Simulation results

	Ideal	VarNo	Ideal	VarNo	Ideal	VarNo
frequency, kHz	100		2000		200000	
V_{test}, V	0.5	0.499	0.5	0.501	0.5	0.5
V_{out}, V	-0.27	0.269	-0.27	0.271	-0.27	0.27
K_{NI_exp}	-0.55	-0.54	-0.55	-0.54	-0.55	-0.55
ΔK_{NI}	0.0202	0.0182	0.0202	0.0182	0.0202	0.0202
$E_{NI_{max}}$	0.0202	0.0182	0.0202	0.0182	0.0202	0.0202
K_{OL}	-27.23	-15.13	-27.23	-15.13	-27.23	-27.72

4. Conclusions

Conclusions should contain:

1) Is it possible to realize amplifier with defined gain and gain tolerance?

Yes.

2) In which range can be load resistance R_{Load} varied?

10k ~ 100k

3) How was operational amplifier power supply modified?

By using vpp.