

# LECTURE 19: AREAL DATA MODELING

# CLASS INTRO

# INTRO QUESTIONS

With Areal Data we have discussed:

1. Data Visualization
2. Proximity Matrices
3. Measures of Spatial Association
4. Spatial Smoothing
5. Technical Details for Autocorrelated Models

# AREAL DATA OVERVIEW

Today

- Disease Models
- CAR / SAR Models

Next

- Model fitting with `spdep` and JAGS

# AREAL DATA MODELS

# DISEASE MAPPING

- Areal data with counts is often associated with disease mapping, where there are two quantities for each areal unit:  
     $Y_i$  = observed number of cases of disease in county  $i$   
     $E_i$  = expected number of cases of disease in county  $i$

## EXPECTED COUNTS

- One way to think about the expected counts is

$$E_i = n_i \bar{r} = n_i \left( \frac{\sum_i y_i}{\sum_i n_i} \right),$$

where  $\bar{r}$  is the overall disease rate and  $n_i$  is the population for region  $i$ .

- However note that  $\bar{r}$ , and hence,  $E_i$  is not fixed, but is a function of the data. This is called *internal standardization*.
- An alternative is to use some standard rate for a given age group ( $r_j$ ), such that  $E_i = \sum_j n_{ij} r_j$ . This is *external standardization*.

# TRADITIONAL MODELS

- Often counts are assumed to follow the Poisson model where  $Y_i | \eta_i \sim \text{Poisson}(E_i \eta_i)$ ,  
where  $\eta_i$  is the relative risk of the disease in region  $i$ .
- **Discuss:** how does  $\eta_i$  impact our expectation about the number of diseases cases?
- **Discuss:** How can  $\eta_i$  be interpreted?



# TRADITIONAL MODELS

- Often counts are assumed to follow the Poisson model where  $Y_i | \eta_i \sim \text{Poisson}(E_i \eta_i)$ , where  $\eta_i$  is the relative risk of the disease in region  $i$ .
- Then the MLE of  $\eta_i$  is  $\frac{Y_i}{E_i}$ . This quantity is known as the *standardized morbidity ratio* (SMR).
- Note the SMR is multiplicative rather than additive.

# POISSON-GAMMA MODEL

- Consider the following framework

$$Y_i | \eta_i \sim Po(E_i \eta_i), \quad i = 1, \dots, I$$

The goal is estimate  $\eta_i$  and eventually include spatial effects.

- We start with a prior for  $\eta_i$  as

$$\eta_i \sim Gamma(a, b),$$

where the gamma distribution has mean  $\frac{a}{b}$  and variance is  $\frac{a}{b^2}$ .

- This can be reparameterized such that  $a = \frac{\mu^2}{\sigma^2}$  and  $b = \frac{\mu}{\sigma^2}$ .

# POISSON-GAMMA CONJUGACY

- For the Poisson sampling model, the gamma prior is conjugate. This means that the posterior distribution  $p(\eta_i|y_i)$  is also a gamma distribution.
- In particular the posterior distribution  $p(\eta_i|y_i)$  is  $\text{Gamma}(y_i + a, E_i + b)$ .

# BAYESIAN POINT ESTIMATE

- The mean of this distribution is

$$\begin{aligned}
 E(\eta_i|\mathbf{y}) &= E(\eta_i|y_i) = \frac{y_i + a}{E_i + b} = \frac{y_i + \frac{\mu^2}{\sigma^2}}{E_i + \frac{\mu}{\sigma^2}} \\
 &= \frac{E_i(\frac{y_i}{E_i})}{E_i + \frac{\mu}{\sigma^2}} + \frac{(\frac{\mu}{\sigma^2})\mu}{E_i + \frac{\mu}{\sigma^2}} \\
 &= w_i SMR_i + (1 - w_i)\mu,
 \end{aligned}$$

where  $w_i = \frac{E_i}{E_i + (\mu/\sigma^2)}$

- Discuss:** this result and suggestions for selecting  $\mu$  and  $\sigma^2$ .

# POISSON-LOGNORMAL MODELS

- Unfortunately the Poisson-gamma framework does not easily permit spatial structure with the  $\eta_i$  and a univariate gamma distribution.
- A relatively new option is to use the **multivariate-log gamma distribution** as the prior.
- A common alternative is to use the Poisson-lognormal model.

# POISSON-LOGNORMAL MODELS

The model can be written as

$$Y_i | \psi_i \sim \text{Poisson}(E_i \exp(\psi_i))$$

$$\psi_i = \mathbf{x}_i^T \boldsymbol{\beta} + \theta_i + \phi_i$$

where  $\mathbf{x}_i$  are spatial covariates,  $\theta_i$  corresponds to region wide heterogeneity, and  $\psi_i$  captures local clustering.

## DATA SIMULATION EXERCISE

1. Simulate and visualize data following the Poisson-gamma framework.
2. Now think about adding spatial structure using the log-normal structure. How would you generate  $\theta_i$  and  $\phi_i$ ?

# CONDITIONAL AUTOREGRESSIVE MODELS



## GAUSSIAN MODEL

- Suppose the full conditionals are specified as

$$Y_i | y_j, j \neq i \sim N \left( \sum_j b_{ij} y_j, \tau_i^2 \right)$$

- Then using Brooks' Lemma, the joint distribution is

$$p(y_1, \dots, y_n) \propto \exp \left( -\frac{1}{2} \mathbf{y}^T \mathbf{D}^{-1} (\mathbf{I} - \mathbf{B}) \mathbf{y} \right),$$

where  $\mathbf{B}$  is a matrix with entries  $b_{ij}$  and  $\mathbf{D}$  is a diagonal matrix with diagonal elements  $D_{ii} = \tau_i^2$ .

# GAUSSIAN MODEL

- The previous equation suggests a multivariate normal distribution, but  $D^{-1}(I - B)$  should be symmetric.
- Symmetry requires
$$\frac{b_{ij}}{\tau_i^2} = \frac{b_{ji}}{\tau_j^2}, \quad \forall i, j$$
- In general,  $B$  is not symmetric, but setting  $b_{ij} = w_{ij}/w_{i+}$  and  $\tau_i^2 = \tau^2/w_{i+}$  satisfies the symmetry assumptions (given that we assume  $W$  is symmetric)

# GAUSSIAN MODEL

- Now the full conditional distribution can be written as

$$Y_i | y_j, j \neq i \sim N \left( \sum_j w_{ij} y_j / w_{i+}, \tau^2 / w_{i+} \right)$$

- Similarly the joint distribution is now

$$p(y_1, \dots, y_n) \propto \exp \left( -\frac{1}{2\tau^2} \mathbf{y}^T (D_w - W) \mathbf{y} \right)$$

where  $D_w$  is a diagonal matrix with diagonal entries  $(D_w)_{ii} = w_{i+}$

# GAUSSIAN MODEL

- The joint distribution can also be re-written as

$$p(y_1, \dots, y_n) \propto \exp\left(-\frac{1}{2\tau^2} \sum_{i \neq j} w_{ij} (y_i - y_j)^2\right)$$

- However, both these formulations results in an improper distribution. This could be solved with a constraint, such as  $Y_i = 0$ .
- The result is the joint distribution is improper, despite proper full conditional distributions. This model specification is often referred to as an *intrinsically autoregressive* model (IAR).

# IAR

- The IAR cannot be used to model data directly, rather this is used as a prior specification and attached to random effects specified at the second stage of the hierarchical model.
- The impropriety can be remedied by defining a parameter  $\rho$  such that  $(D_w - W)$  becomes  $(D_w - \rho W)$  such that this matrix is nonsingular.
- The parameter  $\rho$  can be considered an extra parameter in the CAR model.

## POSTERIOR DISTRIBUTION

- With or without  $\rho$ ,  $p(\mathbf{y})$  (or the Bayesian posterior when the CAR specification is placed on the spatial random effects) is proper.

- When using  $\rho$ , the full conditional becomes

$$Y_i | y_j, j \neq i \sim N \left( \rho \sum_j w_{ij} y_j / w_{i+}, \tau^2 / w_{i+} \right)$$

- The authors state, “we do not take a position with regard to propriety or impropriety in employing CAR specifications”

# **SIMULTANEOUS AUTOREGRESSION MODEL**

# SIMULTANEOUS AUTOREGRESSION MODEL

- Rather than specifying the distribution on  $Y$ , as in the CAR specification, the distribution can be specified for  $\epsilon$  which induces a distribution for  $Y$ .
- Let  $\epsilon \sim N(\mathbf{0}, \tilde{D})$ , where  $\tilde{D}$  is a diagonal matrix with elements  $(\tilde{D})_{ii} = \sigma_i^2$ .
- Now  $Y_i = \sum_j b_{ij} Y_j + \epsilon_i$  or equivalently  $(I - B)Y = \epsilon$ .



## SAR MODEL

- If the matrix  $(I - B)$  is full rank, then
$$Y \sim N \left( \mathbf{0}, (I - B)^{-1} \tilde{D} (I - B)^{-1}{}^T \right)$$
- If  $\tilde{D} = \sigma^2 I$ , then  $Y \sim N \left( \mathbf{0}, \sigma^2 [(I - B)(I - B)^T]^{-1} \right)$

## CHOOSING B

There are two common approaches for choosing B

1.  $B = \rho W$ , where  $W$  is a contiguity matrix with entries 1 and 0. The parameter  $\rho$  is called the spatial autoregression parameter.
2.  $B = \alpha \tilde{W}$  where  $(\tilde{W})_{ij} = w_{ij}/w_{i+}$ . The  $\alpha$  parameter is called the spatial autocorrelation parameter.

## SAR MODEL FOR REGRESSION

- SAR Models are often introduced in a regression context, where the residuals ( $U$ ) follow a SAR model.
- Let  $U = Y - X\beta$  and then  $U = BU + \epsilon$  which results in  $Y = BY + (I - B)X\beta + \epsilon$
- Hence the model contains a spatial weighting of neighbors ( $BY$ ) and a regression component  $((I - B)X\beta)$ .
- What is the result of extreme cases for  $B = 0$  or  $B = I$ .

## OTHER NOTES

- The SAR specification is not typically used in a GLM setting.
- SAR models are well suited for maximum likelihood
- Without specifying a hierarchical form, Bayesian sampling of random effects is more difficult than the CAR specification.