

# Modeling Point Patterns using NHPPs

Statistical modeling depends on a sampling model for the data and the associated likelihood function.

Conditional on the number of points,  $Num(D) = n$ , the location density can be specified as:

Then considering the location and number of points simultaneously, we have

Alternatively, consider a fine partition for  $D$ , then using the Poisson assumption, the likelihood is the product of the counts across the partitions.

The likelihood is a function of the entire intensity surface  $\lambda(\mathbf{s})$ . Hence, a functional description of  $\lambda(\mathbf{s})$  is necessary.

There are two general approaches for modeling  $\lambda(\mathbf{s})$ : parametric and non-parametric.

A simple, but “silly” example of a parametric form would be

Suppose remote-sensed covariate information is available on a grid. How might this be used for constructing  $\lambda(\mathbf{s})$ ?

In general a parametric function  $\lambda(\mathbf{s}; \theta)$  could be specified, but it would require a richly specified class that would need to be non-negative. A common approach for this type of problem is to use a set of basis functions such that  $\lambda(\mathbf{s}; \theta) = \sum_k a_k g_k(\mathbf{s})$ .

- Sketch a set of basis functions to create a multimodal curve in 1D.

Sometimes

The most common approach is to specify  $\log(\lambda(\mathbf{s})) = X^t(\mathbf{s})\gamma$ .

Specifying covariates still requires integrating  $\int_D \exp(X^t(\mathbf{s})\gamma) d\mathbf{s}$ , which is challenging as  $X^t(\mathbf{s})$  is not often specified in a functional form.

Now, considering  $\lambda(\mathbf{s})$  through the non-parametric lens, *let*

Suppose  $\lambda(\mathbf{s}) = \exp(Z(\mathbf{s}))$  where  $Z(\mathbf{s})$  is a realization from a spatial Gaussian process with mean  $X^t(\mathbf{s})\gamma$  and covariance function  $\sigma^s \rho(\cdot)$ .

The LGCP provides a prior for  $\lambda(\mathbf{s})$ . This can be written as  $X^t(\mathbf{s})\gamma + w(\mathbf{s})$  where  $w(\mathbf{s}) = \log \lambda_0(\mathbf{s})$ .