## **State-Space Model of Modified IEEE-Second Benchmark (M-IEEE-SBM):**

For a power system with N synchronous machines equipped with PSS and excitation systems, along with the mechanical section of the shaft-turbine model, the state variables of  $i^{th}$  synchronous machine can be defined as follows:

$$x_{i}(t) = \begin{bmatrix} \Delta E'_{qi} & \Delta E_{fdi} & \Delta y_{pss_{-}i} & \Delta \delta_{i} & \Delta \omega_{Gi} & \Delta \delta_{LPi} & \Delta \omega_{LPi} & \Delta \delta_{HPi} & \Delta \omega_{HPi} \end{bmatrix}^{T}$$

$$B = \begin{bmatrix} 0 & \frac{K_{ai}}{T_{ai}} & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}^{T}$$

$$C = [0 \quad 0 \quad 0 \quad 0 \quad 1 \quad 0 \quad 0 \quad 0]$$

$$R_a = [0 \quad 0 \quad \frac{-K_{p_i}T_{1i}}{2H_iT_{2i}} \quad 0 \quad -\frac{1}{2H_i} \quad 0 \quad 0 \quad 0 \quad 0]^T$$

If the developed power grid consists of more synchronous machines, all the mentioned state variables in  $x_i(t)$  must be rewritten for new machines and combined together to generate a consolidated state matric A. Moreover, the interconnection between  $i^{th}$  and  $j^{th}$  synchronous machines <u>must be also considered</u> to obtain the comprehensive state variable vector of the system and complete the state matrix A.