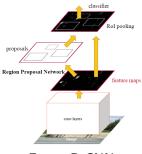
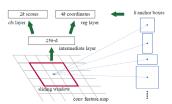
Object Detectors



Object Detectors



Faster R-CNN



Region Proposal Network

Object Detectors



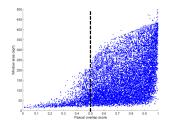
Προτάσεις περιοχών

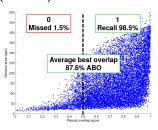


Αποτελέσματα

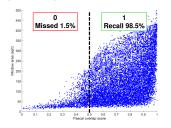
Losses

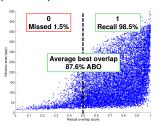
Mean Average Best Overlap (MABO)



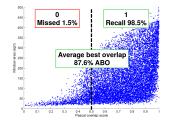


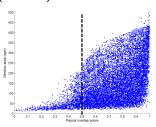
Mean Average Best Overlap (MABO)



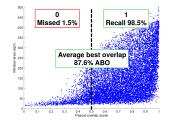


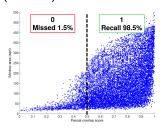
Mean Average Best Overlap (MABO)



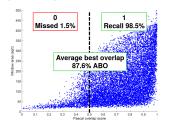


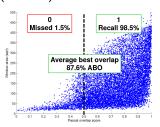
Mean Average Best Overlap (MABO)



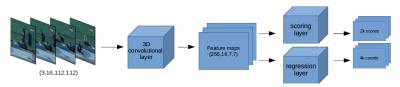


Mean Average Best Overlap (MABO)



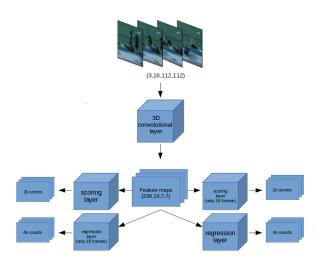


Αρχική προσέγγιση



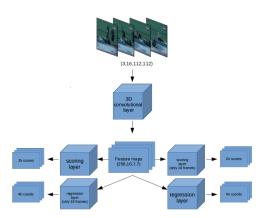
- 1 3D Convolutional Layer $\mu\epsilon$ kernel size = 3, stride = 3 $\kappa\alpha\iota$ padding = 1
- 1 Classification Layer
- 1 Regression Layer

Βελτίωση της μεθόδου

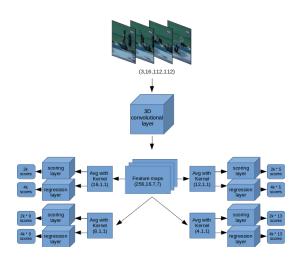


Βελτίωση της μεθόδου

- 1 3D Convolutional
 Layer με kernel size = 3,
 stride = 3 και padding
 = 1
- 2 Classification Layer
- 2 Regression Layer



2η προσέγγιση



2η προσέγγιση

- 1 3D Convolutional Layer με kernel size = 3, stride = 3 και padding = 1
- 4 Max Pooling Layers
- 4 Classification Layer
- 4 Regression Layer

