

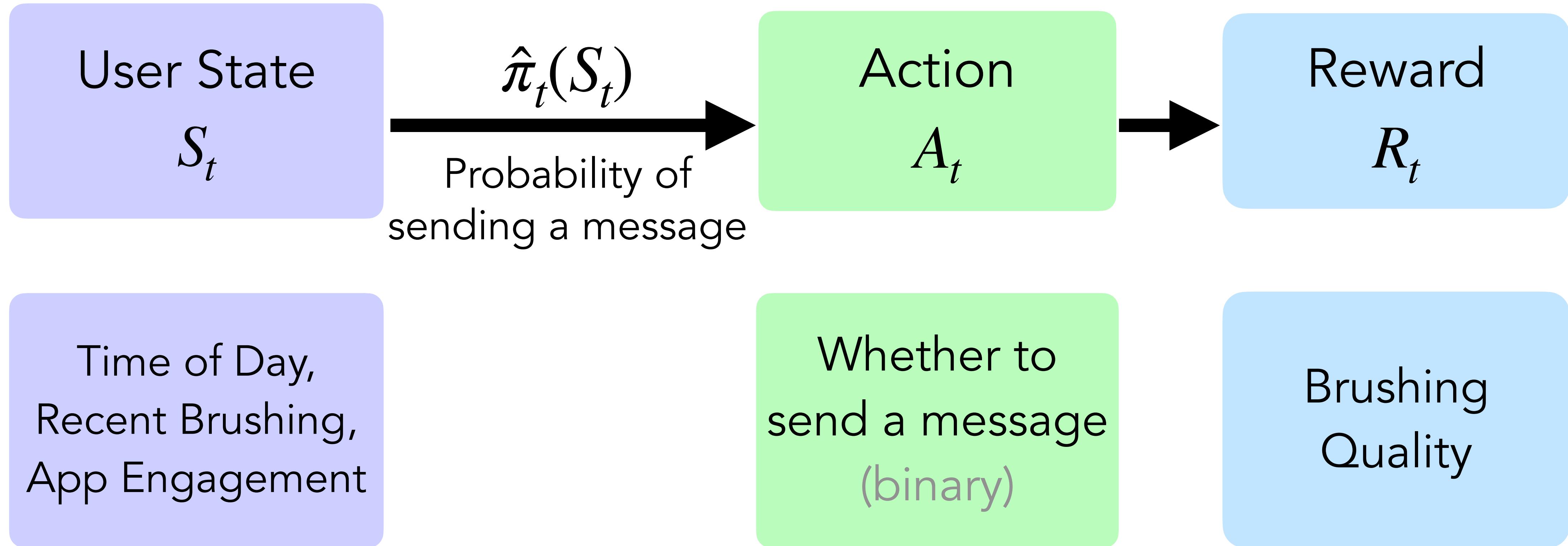
# **Software Package for Inference after Pooling**

**How to Interface with the RL Algorithm**

**Kelly Zhang and Nowell Closser**

# Motivation and Challenges Due to Using Pooling RL Algorithms

# Online Reinforcement Learning (RL)



Oralytics Setting

Use  $(S_t, A_t, R_t)$  to  
update and form  $\hat{\pi}_{t+1}$

# MRT Study Data

- **Total Decision Times:**  $T$
- **Number of users:**  $N$
- **Data Collected After Study:** For each user  $i \in [1 : N]$ ,

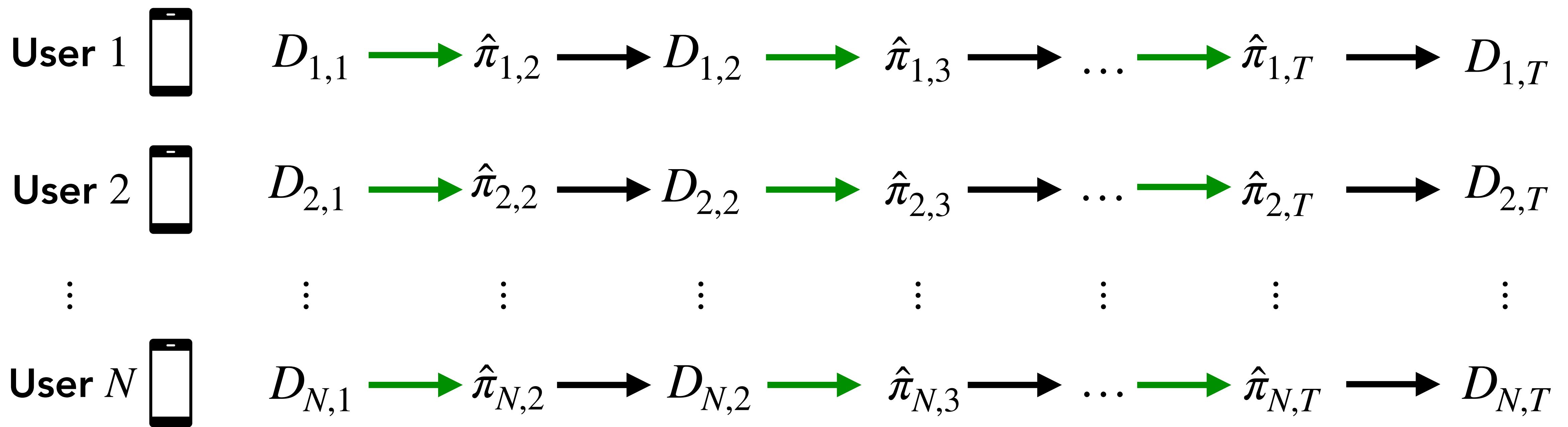
$$\underbrace{(S_{i,1}, A_{i,1}, R_{i,1})}_{D_{i,1}} \quad \underbrace{(S_{i,2}, A_{i,2}, R_{i,2})}_{D_{i,2}} \quad \cdots \quad \underbrace{(S_{i,T}, A_{i,T}, R_{i,T})}_{D_{i,T}}$$

- **User History:**  $H_{i,t} = \{D_{i,1}, D_{i,2}, D_{i,3}, \dots, D_{i,t}\}$

$$D_{i,t} \triangleq (S_{i,t}, A_{i,t}, R_{i,t})$$

## Individual RL Algorithms

→ Algorithm Update  
→ Data Collection



### Dependence Within a User

User states/rewards can be dependent over time

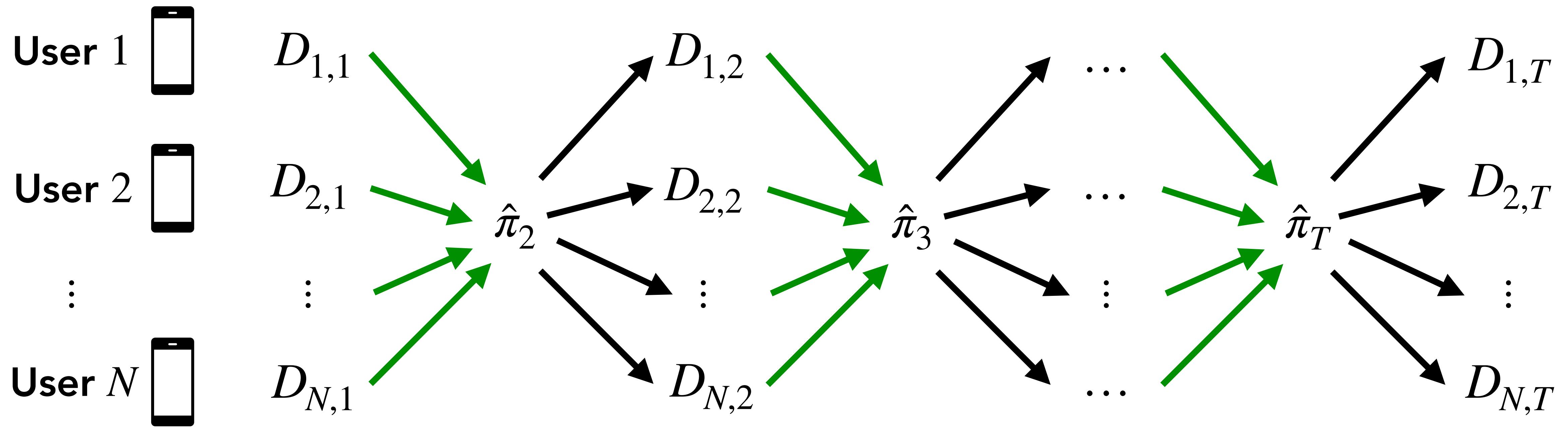
### Limitations

Rewards are noisy and few decision times per user → slow learning

$$D_{i,t} \triangleq (S_{i,t}, A_{i,t}, R_{i,t})$$

# Pooling RL Algorithm

→ Algorithm Update  
→ Data Collection



## Dependence Within a User

User states/rewards can be dependent over time

## Dependence Between Users

Due to use of pooling algorithm

# Inference After Pooling Approach Overview

# Pooling Algorithm

- At each decision time  $t$ , use **all past user data** to form a statistic  $\hat{\beta}_{t-1}^{(N)}$  (e.g. estimator for parameters in a reward model)
- $\hat{\pi}_t(s) = \pi_t(s; \hat{\beta}_{t-1}^{(N)})$  is pooled policy at time  $t$
- Select action  $A_{i,t} \mid S_{i,t}, H_{1:n,t-1} \sim \text{Bernoulli}(\hat{\pi}_t(S_{i,t}))$

# What is $\hat{\beta}_t$ in general?

$$\phi_t(H_t; \beta) = (R_t - \beta_a^\top f(S_t) - \beta_b^\top A_t g(S_t)) \begin{bmatrix} f(S_t) \\ A_t g(S_t) \end{bmatrix}$$

$\hat{\beta}_t \in \mathbb{R}^{p_\beta}$  is the solution to an estimating equation for

$$0 = \frac{1}{N} \sum_{i=1}^N \phi_t(H_{i,t}; \hat{\beta}_{1:t}) \in \mathbb{R}^{p_\beta}$$

e.g. minimizer of a loss function, least squares, MLEs, etc.

**Theory applies when:**  $\hat{\beta}_t^{(N)} \rightarrow \beta_t^*$  as  $N \rightarrow \infty$

where  $0 = \mathbb{E}_\star \left[ \phi_t(H_{i,t}; \beta_{1:t}^*) \right] \in \mathbb{R}^{p_\beta}$

# Inference Approach

- **Inferential Goal:**

$$0 = \mathbb{E}_\star \left[ \psi(H_{i,T}; \theta^\star, \beta_{1:T-1}^\star) \right] \in \mathbb{R}^{p_\theta}$$

- **Estimator:**

$$0 = \frac{1}{N} \sum_{i=1}^N \psi(H_{i,T}; \hat{\theta}, \hat{\beta}_{1:T-1}) \in \mathbb{R}^{p_\theta}$$

e.g. minimizer of a loss function, least squares, MLEs, etc.

# Asymptotic Normality Result ( $T = 3$ Case)

$$\sqrt{n} \begin{pmatrix} \hat{\beta}_1 - \beta_1^* \\ \hat{\beta}_2 - \beta_2^* \\ \hat{\theta} - \theta^* \end{pmatrix} \xrightarrow{D} \mathcal{N} \left( 0, B^{-1} \Sigma (B^{-1})^\top \right)$$

$$\Sigma = \mathbb{E}_\star \left[ \begin{pmatrix} \phi_1(H_{i,1}; \beta_1^*) \\ \phi_2(H_{i,2}; \beta_{1:2}^*) \\ \psi(H_{i,3}; \theta^*, \beta_{1:2}^*) \end{pmatrix}^{\otimes 2} \right] = \mathbb{E}_\star \left[ \begin{pmatrix} \phi_{i,1}(\beta_1^*) \\ \phi_{i,2}(\beta_{1:2}^*) \\ \psi_i(\theta^*, \beta_{1:2}^*) \end{pmatrix}^{\otimes 2} \right]$$

# Asymptotic Normality Result ( $T = 3$ Case)

$$\sqrt{n} \begin{pmatrix} \hat{\beta}_1 - \beta_1^* \\ \hat{\beta}_2 - \beta_2^* \\ \hat{\theta} - \theta^* \end{pmatrix} \xrightarrow{D} \mathcal{N} \left( B^{-1} \Sigma (B^{-1})^\top \right)$$

$$B = \frac{\partial}{\partial(\beta_1, \beta_2, \theta)} \mathbb{E}_\star \left[ \begin{array}{c} \phi_{i,1}(\beta_1) \\ W_{i,2}^*(\beta_1) \phi_{i,2}(\beta_{1:2}) \\ W_{i,2}^*(\beta_1) W_{i,3}^*(\beta_2) \psi_i(\theta, \beta_{1:2}) \end{array} \middle| \beta_1^*, \beta_2^*, \theta^* \right]$$

$$W_{i,t}^*(\beta_{t-1}) = \left( \frac{\pi_t(S_{i,t}; \beta_{t-1})}{\pi_t(S_t; \beta_{t-1}^*)} \right)^{A_{i,t}} \left( \frac{1 - \pi_t(S_{i,t}; \beta_{t-1})}{1 - \pi_t(S_t; \beta_{t-1}^*)} \right)^{1-A_{i,t}}$$

# Rewriting the “bread” part $B$

$$\mathbb{E}_\star \begin{bmatrix} \frac{\partial}{\partial \beta_1} \phi_1(\beta_1) & 0 & 0 \\ \left[ \frac{\partial}{\partial \beta_1} W_2^\star(\beta_1) \right] \phi_2 + \frac{\partial}{\partial \beta_1} \phi_2(\beta_{1:2}) & \frac{\partial}{\partial \beta_2} \phi_2(\beta_{1:2}) & 0 \\ \left[ \frac{\partial}{\partial \beta_1} W_2^\star(\beta_1) \right] \psi + \frac{\partial}{\partial \beta_1} \psi(\beta_{1:2}, \theta) & \left[ \frac{\partial}{\partial \beta_2} W_3^\star(\beta_2) \right] \psi + \frac{\partial}{\partial \beta_2} \psi(\beta_{1:2}, \theta) & \frac{\partial}{\partial \theta} \psi(\beta_{1:2}, \theta) \end{bmatrix} \Big|_{\beta_{1:2}^\star, \theta^\star}$$

$$W_t^\star(\beta_{t-1}) = \left( \frac{\pi_t(S_t; \beta_{t-1})}{\pi_t(S_t; \beta_{t-1}^\star)} \right)^{A_t} \left( \frac{1 - \pi_t(S_t; \beta_{t-1})}{1 - \pi_t(S_t; \beta_{t-1}^\star)} \right)^{1-A_t}$$

# **Software and Computational Challenges**

# Estimating the Matrix $B$

$$\frac{1}{N} \sum_{i=1}^N \begin{bmatrix} \frac{\partial}{\partial \beta_1} \phi_{i,1} & 0 & 0 \\ \left[ \frac{\partial}{\partial \beta_1} W_{i,2}(\beta_1) \right] \phi_{i,2} + \frac{\partial}{\partial \beta_1} \phi_{i,2} & \frac{\partial}{\partial \beta_2} \phi_{i,2} & 0 \\ \left[ \frac{\partial}{\partial \beta_1} W_{i,2}(\beta_1) \right] \psi_i + \frac{\partial}{\partial \beta_1} \psi_i & \left[ \frac{\partial}{\partial \beta_2} W_{i,3}(\beta_2) \right] \psi_i + \frac{\partial}{\partial \beta_2} \psi_i & \frac{\partial}{\partial \theta} \psi_i \end{bmatrix} \Bigg|_{\hat{\beta}_{1:2}, \hat{\theta}}$$

$$W_{i,t}(\beta_{t-1}) = \left( \frac{\pi_t(S_{i,t}; \beta_{t-1})}{\pi_t(S_{i,t}; \hat{\beta}_{t-1})} \right)^{A_{i,t}} \left( \frac{1 - \pi_t(S_{i,t}; \beta_{t-1})}{1 - \pi_t(S_{i,t}; \hat{\beta}_{t-1})} \right)^{1-A_{i,t}} \frac{\partial}{\partial \beta_{t-1}} \pi_t(S_{i,t}; \beta_{t-1})$$

# Considerations

## 1. Quality of Variance Estimator

- Accuracy and Numerical Stability

## 2. Computational Considerations

- How long to compute the standard errors from a run? (simulate thousands of runs)

## 3. RL Algorithm Designer Experience

- Want to allow for flexibility in algorithm design
- Want to make it easy and automatic for RL algorithm to provide necessary statistics

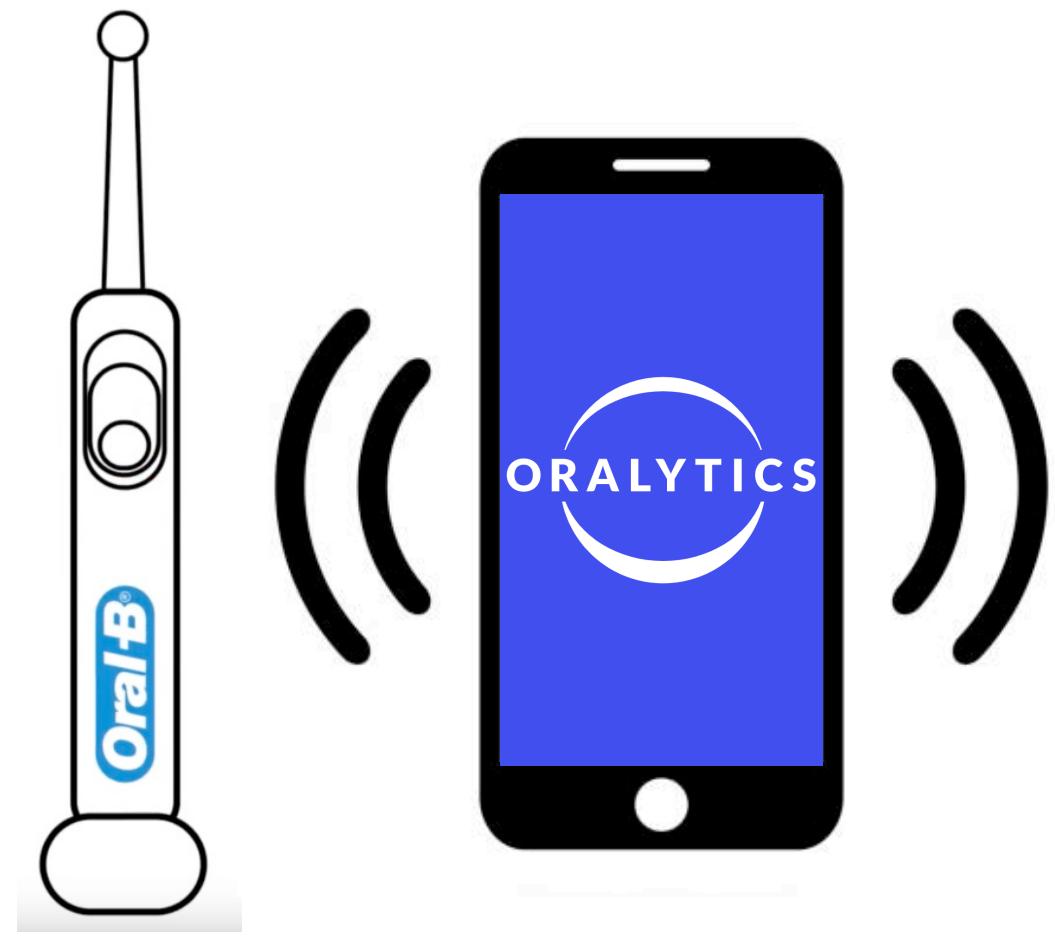
## 4. Data Analyzer Experience

- Want to allow for a variety of analyses
- Want to allow data analyzer to have little to no knowledge of RL algorithm to use

**Approaches (go to following google doc):**

[https://docs.google.com/document/d/  
1NVAiaqv5fNhPUtkUMv1pPY55jO4jUDx0  
hdlKrJPy84Q/edit?usp=sharing](https://docs.google.com/document/d/1NVAiaqv5fNhPUtkUMv1pPY55jO4jUDx0hdlKrJPy84Q/edit?usp=sharing)

# **Backup Slides**



## Digital Oral Health Coaching

# **Challenge:** Learning what interventions to deliver—and when

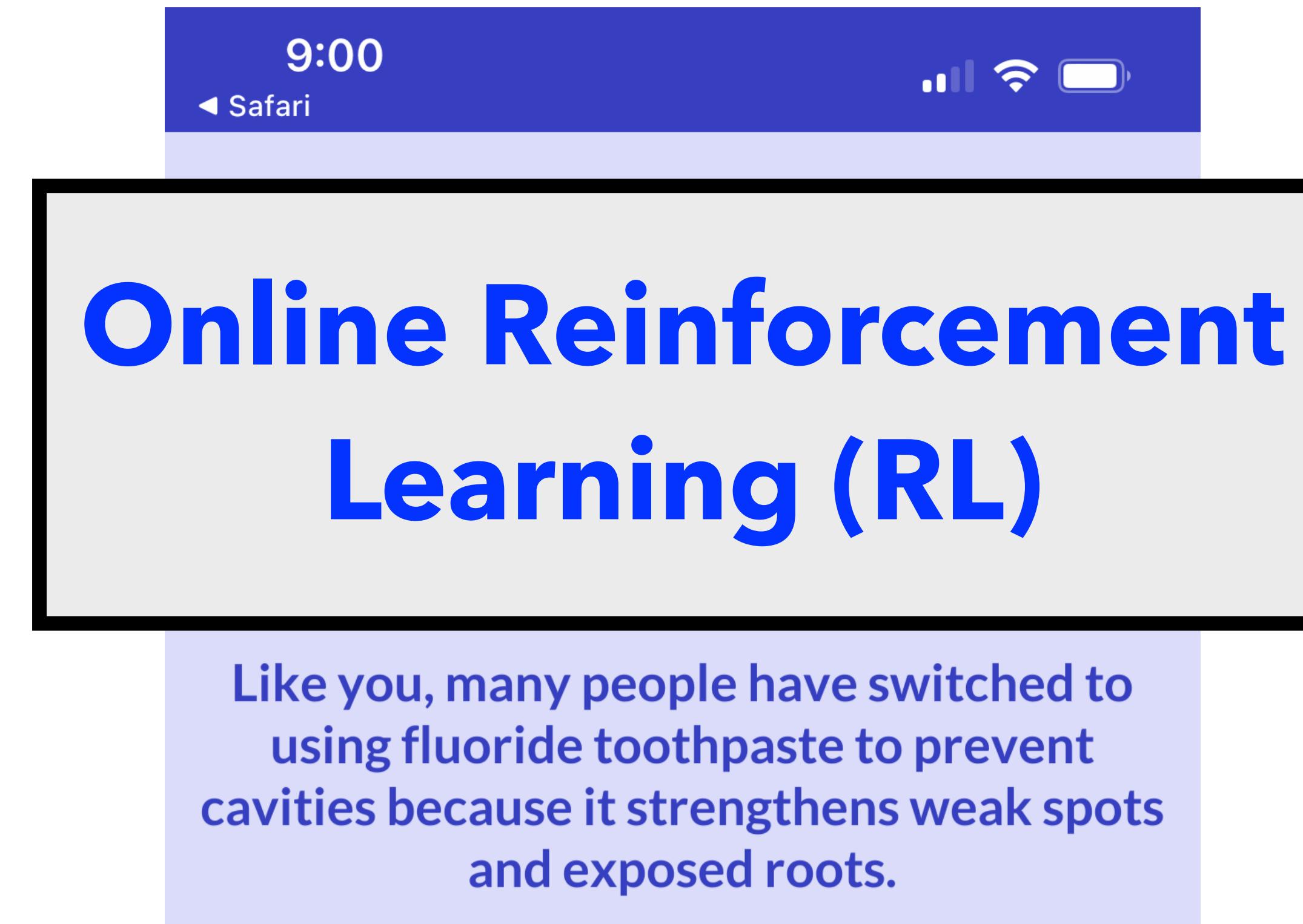
**Minimize:**  
User Burden



**Maximize:**  
User Benefit

# **Challenge:** Learning what interventions to deliver—and when

**Minimize:**  
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**Maximize:**  
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# Digital Intervention Study Design Objectives

## Within-Study Personalization

### Maximize User Benefit

- Send messages at opportune moments

### Use Online RL Algorithms

$$\mathbb{E} \left[ \sum_{t=1}^T R_t \right]$$

## After-Study Analyses

# Digital Intervention Study Design Objectives

## Within-Study Personalization

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## Use Online RL Algorithms

$$\mathbb{E} \left[ \sum_{t=1}^T R_t \right]$$

## After-Study Analyses

Evaluate the Intervention

- Understand heterogeneity across user types and user states

Infer Treatment Effects

$$\mathbb{E}[R_t | S_t, A_t = 1] - \mathbb{E}[R_t | S_t, A_t = 0]$$

# Digital Intervention Study Design Objectives

## Within-Study Personalization

### Maximize User Benefit

- Send messages at opportune moments

## Use Online RL Algorithms

$$\mathbb{E} \left[ \sum_{t=1}^T R_t \right]$$

## After-Study Analyses

### Confidence Intervals Critical for

- Replicable science
- Publishing and sharing results

### Infer Treatment Effects

$$\mathbb{E}[R_t | S_t, A_t = 1] - \mathbb{E}[R_t | S_t, A_t = 0]$$