Statistical Theory and Modeling (ST2601) Lecture 9 - Statistical Information. Numerical Maximum Likelihood.

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Overview

- The information in a likelihood function
- Maximum likelihood estimator in large samples
- Numerical maximum likelihood

The Big Picture

- Four stages of learning modern statistical learning.
- 1 Understand probability and statistical models.
- 2 Mathematical derivation of the MLE
 - ▶ Write up the log-likelihood $\ell(\theta)$
 - Calculate derivative $\ell'(\theta)$
 - Solve for the MLE from $\ell'(\theta) = 0$
- 3 Numerical optimization for the MLE
 - ▶ Code up the log-likelihood $\ell(\theta)$
 - ▶ Use automatic differentiation to find $\ell'(\theta)$
 - ► Solve for the MLE using a numerical optimizer.
- 4 Probabilistic programming languages (PPL) (Stan etc)
 - Express the statistical model, almost like in textbooks.
 - Let the framework to all the work for you.
- Learning $1 \rightarrow 2 \rightarrow 3 \rightarrow 4$ makes Stage 4 understandable and explainable to clients, helps in debugging, allows you to go beyond models in manual.
- Stage 3 gives freedom when PPL doesn't do what you need.

iid Poisson model in Stan

IID Poisson model

$$Y_1, \ldots, Y_N | \lambda \stackrel{\text{iid}}{\sim} \operatorname{Pois}(\lambda)$$

```
data {
  int<lower = 0> N;
  int < lower = 0 > y[N];
parameters {
  real<lower = 0> lambda;
model {
  lambda ~ gamma(1, 1);
  y ~ poisson(lambda);
generated quantities {
  int<lower = 0> y_tilde = poisson_rng(lambda);
```

Negative Binomial regression in Turing.jl

```
# Negative binomial regression
@model function negbinomialReg(y, X, \tau, \mu_0, \sigma_0)
     p = size(X,2)
     \beta \sim filldist(Normal(0, \tau), p)
     \lambda = \exp((X * \beta))
     \psi \sim \text{LogNormal}(\mu_0, \sigma_0)
     n = length(y)
     for i in 1:n
          y[i] \sim NegativeBinomial(\psi, \psi/(\psi + \lambda[i]))
     end
end
```

How informative is my data about the parameters?

- **Probabilistic model** $p(Y_1, ..., Y_n | \theta)$ with parameter θ .
- Example: iid Poisson model:

$$Y_1, \ldots, Y_N | \lambda \stackrel{\text{iid}}{\sim} \operatorname{Pois}(\lambda)$$

■ Likelihood function (assuming independent data)

$$L(\theta) = p(y_1, \dots, y_n | \theta) = \prod_{i=1}^n p(y_i | \theta)$$

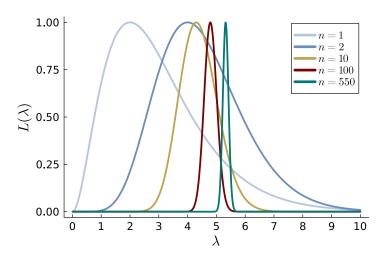
Log-likelihood function

$$\ell(\theta) = \log L(\theta)$$

- **Observed information: Given a dataset** y_1, \ldots, y_n , how much information is there about θ ?
- **Expected information**: Before collecting data, how information can I expected to get about θ ?

Observed information

- **Given a dataset**, how much information is there about θ ?
- **How peaked** is the likelihood function?



Observed information

The second derivative measures the curvature of a function

$$f''(x) = \frac{\mathrm{d}^2}{\mathrm{d}x^2} f(x) = \frac{\mathrm{d}}{\mathrm{d}x} f'(x)$$

Observed information from *n* observations

$$J_n(\hat{\theta}) = -\ell''(\hat{\theta})$$

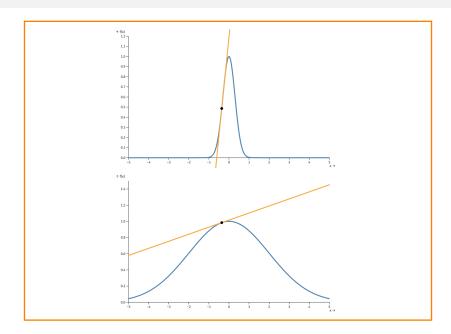
where $\hat{\theta}$ is the maximum likelihood estimate (MLE).

Often written as

$$\frac{\mathrm{d}^2}{\mathrm{d}\theta^2}\ell(\theta)\bigg|_{\theta=\hat{\theta}}$$

- Why a negative sign? The second derivative is negative at the maximum. We like information to be a positive number.
- Why the **log**-likelihood function? Suggested by likelihood theory. Log-likelihood is approx quadratic in large samples.

Second derivative measures curvature



Observed information in the iid Poisson model

■ IID Poisson model

$$Y_1, \ldots, Y_N | \lambda \stackrel{\text{iid}}{\sim} \operatorname{Pois}(\lambda)$$

Log-likelihood

$$\ell(\lambda) = \sum_{i=1}^{n} \log p(y_i|\lambda)$$

Log density for *i*th observation

$$\log p(y_i|\lambda) = \log \left(\frac{\lambda^{y_i} e^{-\lambda}}{y_i!}\right) = y_i \log(\lambda) - \lambda - \log(y_i!)$$

Log-likelihood

$$\ell(\lambda) = \sum_{i=1}^{n} (y_i \log(\lambda) - \lambda - \log(y_i!))$$
$$= \log(\lambda) \sum_{i=1}^{n} y_i - n\lambda - \sum_{i=1}^{n} \log(y_i!)$$

Observed information in the iid Poisson model

Log-likelihood (constants in orange)

$$\ell(\lambda) = \log(\lambda) \sum_{i=1}^{n} y_i - n\lambda - \sum_{i=1}^{n} \log(y_i!)$$

First derivative

$$\ell'(\lambda) = \frac{\sum_{i=1}^{n} y_i}{\lambda} - n$$

- Solving $\ell'(\lambda) = 0$ gives the MLE $\hat{\lambda} = \frac{\sum_{i=1}^{n} y_i}{n} = \bar{y}$.
- Second derivative

$$\ell''(\lambda) = -\frac{\sum_{i=1}^{n} y_i}{\lambda^2} = -\frac{n\bar{y}}{\lambda^2}$$

Observed information

$$J_n(\hat{\lambda}) = -\ell''(\hat{\lambda}) = \frac{n\bar{y}}{\hat{\lambda}^2} = \frac{n\bar{y}}{\bar{v}^2} = \frac{n}{\bar{v}}$$

Information grows linearly in sample size n. Always true for iid

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Expected information

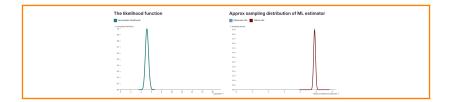
- The observed information varies from dataset to dataset.
- **Expected information**: Before collecting data, how information can I expected to get about θ ?
- The expected information over all possible datasets

$$I_n(\theta) = \mathbb{E}\left(J_{Y_{1:n}}(\theta)\right)$$

 $J_{Y_{1:n}}(\theta)$ is the observed information from $Y_{1:n}=(Y_1,\ldots,Y_n)$.

- Also called the Fisher information.
- Designing experiments and data collection (active learning).
- Also in sampling distribution of the MLE in large samples.

Likelihood and Information - widget



Maximum likelihood estimator in large samples

■ Sampling distribution of the MLE in large datasets

$$\hat{\theta}_n \overset{\mathrm{approx}}{\sim} \mathcal{N}\left(\theta, \frac{1}{I_n(\theta)}\right)$$
 for large n

- MLE is asymptotically unbiased (as $n \to \infty$).
- Asymptotically efficient (lowest possible variance among unbiased estimators. Cramér-Rao lower bound).
- In large samples $I_n(\theta) \approx J_n(\hat{\theta})$, so we can use $J_n(\hat{\theta})$.
- lacksquare The beauty: a computer can compute $\hat{ heta}_n$ and $J_n(\hat{ heta}_n)$. lacksquare

Maximum likelihood in large samples - example

■ MLE sampling distribution for large *n*

$$\hat{\theta}_n \overset{\text{approx}}{\sim} N\left(\theta, \frac{1}{J_n(\hat{\theta}_n)}\right)$$
 for large n

■ IID Poisson model

$$\hat{\lambda}_n(Y_1,\ldots,Y_n) \overset{\text{approx}}{\sim} N\left(\lambda,\frac{1}{J_n(\hat{\lambda}_n)}\right) = N\left(\lambda,\frac{1}{n/\bar{y}}\right) = N\left(\lambda,\frac{\bar{y}}{n}\right)$$

In this case we can compute the true sampling variance

$$\mathbb{V}(\hat{\lambda}) = \mathbb{V}(\bar{Y}) = \frac{\mathbb{V}(Y_i)}{n} = \frac{\lambda}{n}$$

since variance = mean for Poisson.

Multi-parameter case

- Multi-parameter models: $p(y_1, ..., y_n | \theta)$ where $\theta = (\theta_1, ..., \theta_p)^{\top}$ is a vector with parameters.
- **E**xample: Negative binomial with $\theta = (r, \mu)^{\top}$

$$Y_1, \ldots, Y_N | r, \mu \stackrel{\text{iid}}{\sim} \text{NegBin}(r, \mu)$$

Example: Two-dimensional observed information matrix)

$$\frac{\partial^2 \ell(\boldsymbol{\theta})}{\partial \boldsymbol{\theta} \partial \boldsymbol{\theta}^{\top}} = \begin{pmatrix} \frac{\partial^2}{\partial \theta_1^2} \ell(\theta_1, \theta_2) & \frac{\partial^2}{\partial \theta_1 \partial \theta_2} \ell(\theta_1, \theta_2) \\ \frac{\partial^2}{\partial \theta_2 \partial \theta_1} \ell(\theta_1, \theta_2) & \frac{\partial^2}{\partial \theta_2^2} \ell(\theta_1, \theta_2) \end{pmatrix}$$

■ Sampling distribution of the MLE in large samples

$$\hat{m{ heta}}_n \overset{\mathrm{approx}}{\sim} N\left(m{ heta}, J_n^{-1}(\hat{m{ heta}}_n)
ight)$$
 for large n

where N is the multivariate normal distribution and $J_n^{-1}(\hat{\theta}_n)$ is the matrix inverse of $J_n(\hat{\theta}_n)$.

Numerical optimization

Find the maximum of a function f(x)

$$x_{\max} = \underset{x \in \mathcal{X}}{\operatorname{arg} \max} f(x)$$

involves solving for x in f'(x) = 0.

Gradient ascent: find x_{max} by iterating until convergence:

$$x_{k+1} = x_k + \underbrace{\gamma}_{\text{learning rate}} \cdot \underbrace{f'(x_k)}_{\text{gradient}}$$

Newton-Raphson: find x_{max} by iterating until convergence:

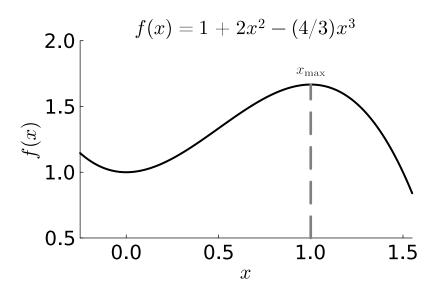
$$x_{k+1} = x_k - \frac{f'(x_k)}{f''(x_k)}$$

■ Multi-dimensional MLE solves $\ell'(\boldsymbol{\theta}) = 0$. Newton-Raphson:

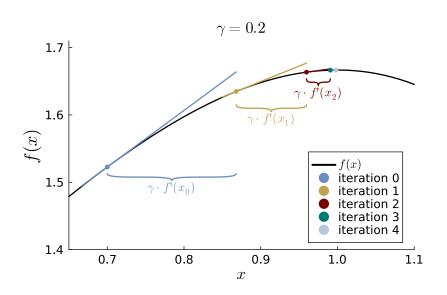
$$\theta_{k+1} = \theta_k + \underbrace{J^{-1}(\theta_k)}_{\text{inverse hessian}} \cdot \underbrace{f'(\theta_k)}_{\text{gradient}}$$

Inverse Hessian cheaply computed from gradients (BFGS).

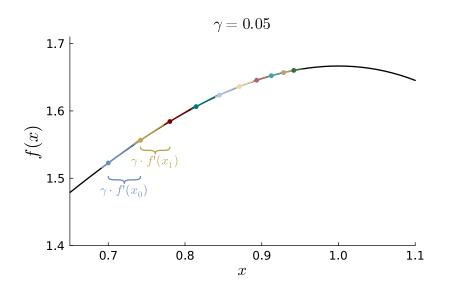
Finding the maximum



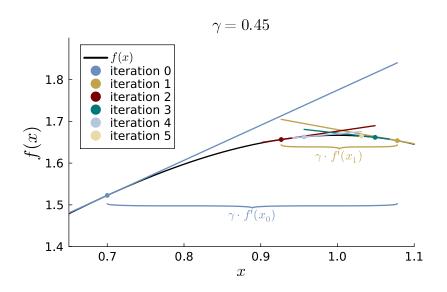
Gradient ascent - good learning rate



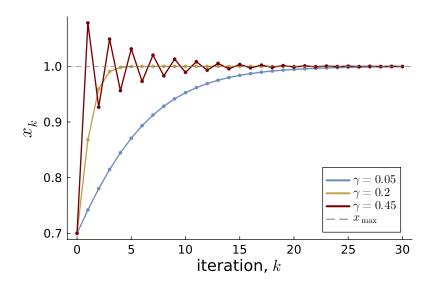
Gradient ascent - too small learning rate



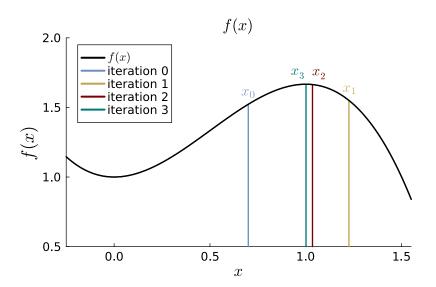
Gradient ascent - too large learning rate



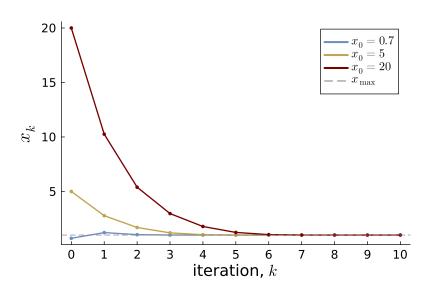
Gradient ascent convergence



Newton-Raphson



Newton-Raphson convergence



Optim in R

```
# Function to maximized. Depends on parameter a
myFunc <- function(x, a){</pre>
  funcVal = 1 - (x/a-2)^2
 return (funcVal)
# Run optim
a = 1
initVal <- c(3) # initial guess</pre>
OptimResults <- optim(initVal, myFunc, gr=NULL, a,
                      method=c("BFGS").
                      control=list(fnscale=-1),
                      hessian=TRUE)
OptimResults$par # maximizer
OptimResults$value # maximum function value
OptimResults$hessian # second derivative
```