

Using Inside AirBnb Data for price Prediction with Deep Learning Methods

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Repeated, Absent, Irrelevant

Repeated and Absent

- "host listings count == "host total listings count"
- "bathrooms"
- "license"
- "calendar updated"

Irrelevant

- Latitude
- Longitude
- Scrape Id

NA Rate > 0.5 & Trustfulness variables

NA Rate > 0.5

- "neighborhood"
- "neighborhood overview",
- "host neighborhood"

Trustfulness variables correlate possible with reviews

- "host about",
- "host response rate",
- "host acceptance rate",
- "host response time"

Initial Dataset

17290 observations

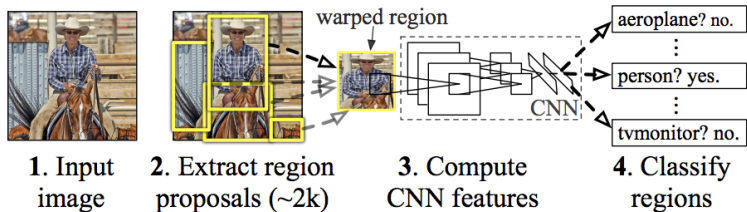
Cleaned Dataset

12175 i.e. 0.2958357% information loss.

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R-CNN: *Regions with CNN features*



[Girshick et al.,]

Multi object detection: Example



Correlated color temperature Example 1

Dominant colors

CCT mean: 4312.0



CCT Example 2

Dominant colors

CCT mean: 9251.0



Brightness

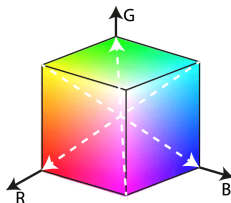


Figure: [Aguirre-Pablo et al., 2017]

3D colour space

$$\text{brightness} = \sqrt{R^2 + G^2 + B^2} \quad (1)$$

Perceived brightness formula

$$\text{brightness} = \sqrt{0.241 * R^2 + 0.691 G^2 + 0.068 B^2} \quad (2)$$

[Dobovizki, 2022]

Perceived brightness results



Figure: Brightness: 122.8



Figure: Brightness: 107.2

Resulting data

- Data set holding data for each picture per host.
 - huge number of columns/variables
- Data set summarizing the results:
 - sums per detected object per host
 - means of brightness and cct per host

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- Way to proceed was dynamic

Given this resources constrain and aiming to fulfill interpretability requirement

- Plan: Use DNN for image scrapping and then employ a regularization model (Lasso) for variable selection.
- Expanded to include further "competitive" models (GBM, Random Forests)

- We initially worked for Berlin working with a partition of 80:10:10 for train validation and test
- Then, Munich came → Berlin 90 : 10 and Munich fully used as test set
- Munich demanded an analysis of the data by the same criteria as Berlin i.e Absence > Na Rates > Irrelevance

Munich data set before 4995

After cleaning: 3222

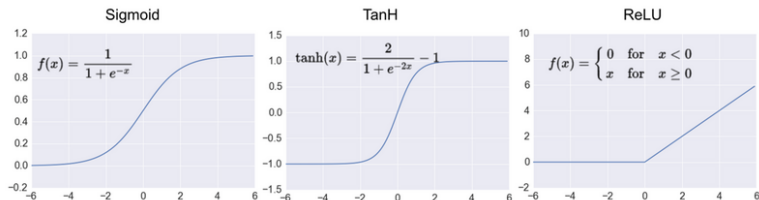
Lost rate: 0.354955%

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Hyperparameter Tuning

- k fold cross-validation
- Method: adaptive cv
- Results:
 - activation function: TanH
 - dropout: 0.17



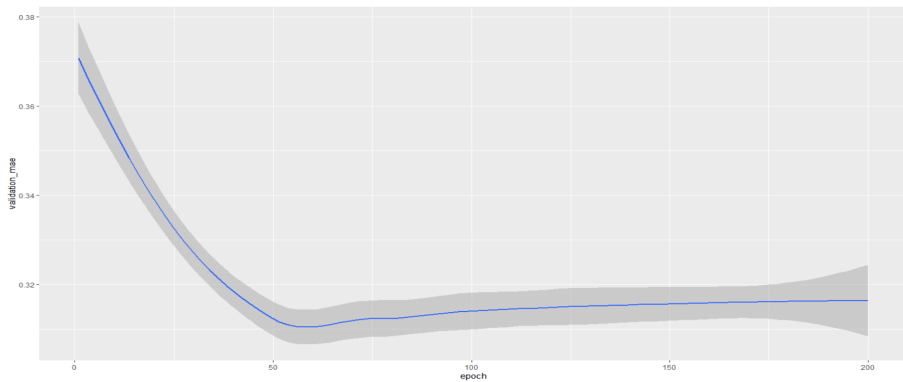
[Develop Paper, 2020]

- adaptive learning rate: rmsprop (Root Mean Square Propagation)

DNN Summary

Layer (type)	Output Shape	Param #
dense_184 (Dense)	(None, 189)	12096
dropout_138 (Dropout)	(None, 189)	0
dense_183 (Dense)	(None, 126)	23940
dropout_137 (Dropout)	(None, 126)	0
dense_182 (Dense)	(None, 63)	8001
dropout_136 (Dropout)	(None, 63)	0
dense_181 (Dense)	(None, 1)	64
Total params: 44,101		
Trainable params: 44,101		
Non-trainable params: 0		

Training Curves



Models to be trained:

- 1 OLS for reference
- 2 No data preprocessing
- 3 Normalized i.e location and scale
- 4 Normalized i.e location and scale with $\log(\text{price})$

Parameters to tune

- Parameter to tune: λ i.e shrinkage parameter.
- Grid: from 10^{10} to 0.01
- best λ : 1.14

[James et al., 2021]

Training times on Berlin data set: circa 3 Minutes

Models to be trained:

- 1 No data preprocessing
- 2 Normalized i.e location and scale
- 3 Normalized i.e location and scale with $\log(\text{price})$

Tuning was attempted for every parameter.

Computationally prohibitive i.e. failed after 24 hours CPU time

Parameters to tune

- `interaction.depth = 1`
- `shrinkage seq(0.001, 0.202, 0.04)`. Best: 0.001
- `n.trees = 5000`
- `n.minobsinnode 10`

[James et al., 2021]

Training times on Berlin Data Set: circa 16 hours.

- 1 No data preprocessing
- 2 Normalized i.e location and scale
- 3 Normalized i.e location and scale with $\log(\text{price})$

Parameters to tune

- $mtry = -7 + p/3, p/3, 7 + p/3$ with $p/3 = 21$. Best: 21
- $min.node.size = 5$

[Hastie et al., 2009]

Training times on Berlin Data Set: circa 3 hours.

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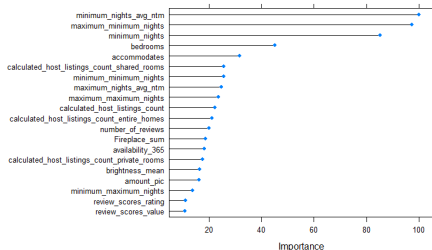
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Results Berlin

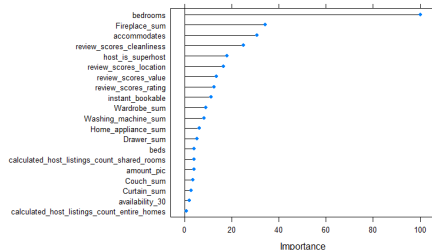
	RMSE <dbl>	Rsquared <dbl>	MAE <dbl>
OLS	0.5547540	0.3818374	0.4107917
Lasso	0.4935600	0.4465568	0.3757873
Lasso Standard	0.4935600	0.4465568	0.3757873
Boost	0.5088589	0.4297071	0.3963260
RF	0.4085395	0.6140226	0.3083759
RF Centered	0.4087117	0.6139556	0.3084462
Lasso S + log(price)	0.4436540	0.5181270	0.3442663
DNN	0.3807523	0.6436791	0.2860852

Variable Importance Berlin

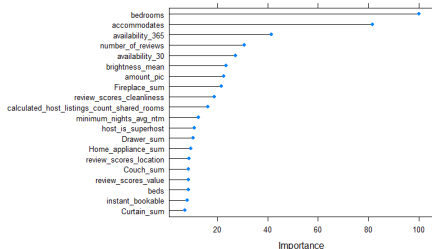
OLS



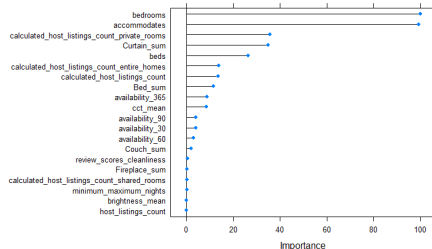
Lasso



Lasso Centered



Boost

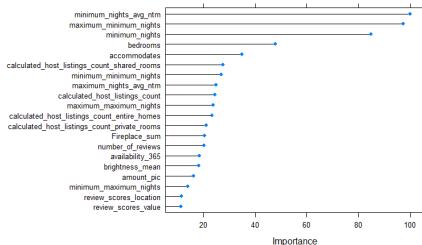


Results Munich

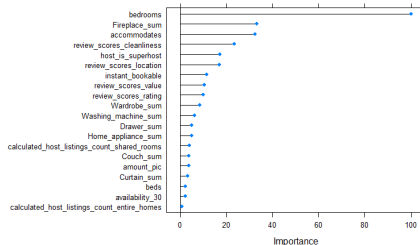
	RMSE <dbl>	Rsquared <dbl>	MAE <dbl>
OLS	0.6330120	0.2460199	0.4687229
Lasso	0.5868852	0.2998020	0.4312133
Lasso N	0.5868852	0.2998020	0.4312133
Boost	0.6560061	0.2191735	0.4775103
Boost N	0.6575854	0.2427723	0.4705026
RF	0.5270313	0.3860209	0.3767017
RF N	0.5304562	0.3782364	0.3798950
Lasso N-log(price)	0.6404690	0.2869786	0.4614091
Boost N-log(price)	0.5896727	0.3410397	0.4201564
RF N-log(price)	0.5456279	0.4245355	0.3867661
DNN	0.8698481	-0.7196968	0.4800993

Variable Importance Munich Lasso

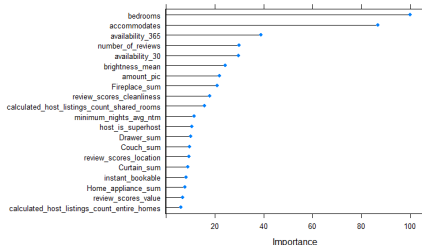
OLS



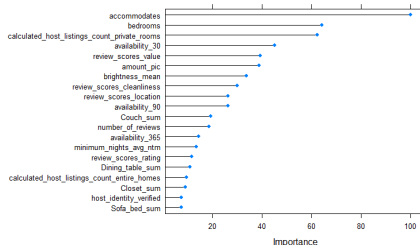
Lasso



Lasso N

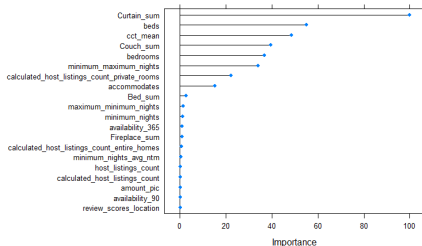


Lasso N-log(price)

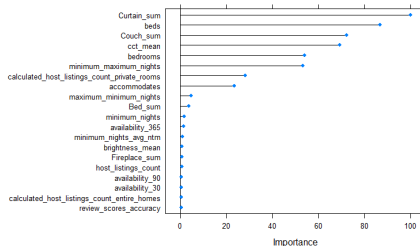


Variable Importance Munich Boost

Boost



Boost N



Boost N-log(price)

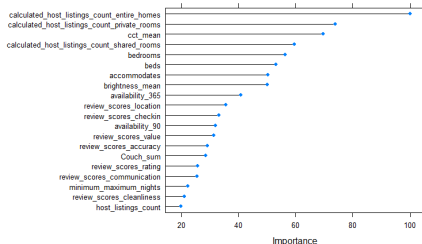


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Takeaways

- Lacking computational power
- further theoretical analysis: Outliers, Variable Exclusion pre-training
- vary threshold for multi detection model
- increase cluster amount for CCT analysis
- scene identification to exclude pictures not showing the flat

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Literature and further References I



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