

26 mai 2022

Leminar 16

Perpendiculară comună a două drepte necoplanare:

$$\mathbb{R}^3 \quad d_k: \frac{x-x_k}{\alpha_k} = \frac{y-y_k}{\beta_k} = \frac{z-z_k}{\gamma_k} = (t_k), k=1,2$$

$$P_k(x_k, y_k, z_k) \begin{cases} P_1 \in d_1 \\ P_2 \in d_2 \end{cases} \quad \overrightarrow{P_1 P_2} = (x_2 - x_1, y_2 - y_1, z_2 - z_1)$$

$$\vec{v}_{d_k} = (\alpha_k, \beta_k, \gamma_k), k=1,2$$

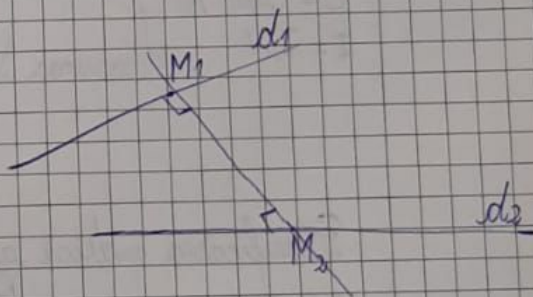
$$d_1, d_2 - \text{dr. necoplanare} \Leftrightarrow \begin{vmatrix} \alpha_1 & \alpha_2 & x_2 - x_1 \\ \beta_1 & \beta_2 & y_2 - y_1 \\ \gamma_1 & \gamma_2 & z_2 - z_1 \end{vmatrix} \neq 0$$

Perp. com. a 2 dr. necoplanare (II)

Algoritm $\begin{cases} \langle \overrightarrow{P_1 P_2}, \vec{v}_{d_1} \rangle = 0 \\ \langle \overrightarrow{P_1 P_2}, \vec{v}_{d_2} \rangle = 0 \end{cases} \Rightarrow P_1' P_2' \quad \text{Ec. l. com.: } \overrightarrow{P_1' P_2'} \perp d_1, d_2$

Appl $d_1: \frac{x-2}{1} = \frac{y}{2} = \frac{z-3}{1} (=t_1)$

$d_2: \frac{x-1}{2} = \frac{y-3}{1} = \frac{z}{1} (=t_2)$



a) d_1, d_2 necopl.

b) ec. l. com.

c) dist(d_1, d_2)

a) $P_1(2, 0, 3)$

$P_2(1, 3, 0)$

$\overrightarrow{P_1 P_2} = (-1, 3, -3)$

$$\Delta = \begin{vmatrix} 1 & 2 & -1 \\ 2 & 1 & 3 \\ 1 & 1 & -3 \end{vmatrix} = -3 - 2 + 6 + 1 - 3 + 12 = 11 \neq 0 \Rightarrow d_1, d_2 \text{ necopl.}$$

b) Luăm $M_1 \in d_1$ cu $M_1(t_1+2, 2t_1, t_1+3)$ $M_2 \in d_2$ cu $M_2(2t_2+1, t_2+3, t_2)$

$\overrightarrow{M_1 M_2} = (2t_2 - t_1 - 1, t_2 - 2t_1 + 3, t_2 - t_1 - 3)$

$\langle \overrightarrow{M_1 M_2}, \vec{v}_{d_1} \rangle = 0 \Rightarrow \begin{cases} 2t_2 - t_1 - 1 + 2t_2 - 4t_1 + 6 + t_2 - t_1 - 3 = 0 \\ 4t_2 - 2t_1 - 2 + t_2 - 2t_1 + 3 + t_2 - 2t_1 - 3 = 0 \end{cases}$

$\langle \overrightarrow{M_1 M_2}, \vec{v}_{d_2} \rangle = 0 \Rightarrow \begin{cases} 3t_2 - t_1 - 3 = 0 \\ -5t_1 + 6t_2 = 2 \end{cases}$

$\Rightarrow \begin{cases} -5t_1 + 6t_2 = 2 \\ -25t_1 + 30t_2 = 10 \end{cases} \Rightarrow \begin{cases} -5t_1 + 6t_2 = 2 \\ -5t_1 + 6t_2 = 2 \end{cases} \Rightarrow t_1 = 2, t_2 = 2$

$$M_1(4, 5), M_2(5, 2)$$

$$M_1 M_2: \frac{x-4}{1} = \frac{y-5}{1} = \frac{z-5}{-3}$$

$$c) d(d_1, d_2) = |M_1 M_2| = \sqrt{(5-4)^2 + (5-4)^2 + (2-5)^2} = \sqrt{1+1+9} = \sqrt{11}$$

Conice

$$\mathbb{R}^2 \quad E_2 = (\mathbb{R}^2 |_{\mathbb{R}}, \langle \cdot, \cdot \rangle_{p.c.})$$

$$\Gamma = f(x, y) = 0, \quad f(x, y) = a_{11}x^2 + a_{22}y^2 + 2a_{12}xy + 2a_{10}x + 2a_{20}y + a_{00}$$

$$a_{ij} \in \mathbb{R}, \quad \forall i, j = 0, 2$$

ec. gen. a unei conice (hipercuadr. în dim. 2)

$$f. \text{ matr. } f(X) = {}^t X a X + 2 b X + c, \quad a = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}, \quad b = \begin{pmatrix} a_{10} \\ a_{20} \end{pmatrix}, \quad c = (a_{00})$$

$$A = \begin{pmatrix} a & b \\ b & c \end{pmatrix}$$

$$m. \text{ sim. } (a = {}^t a)$$

$$\left. \begin{array}{l} \delta = \det a \\ \Delta = \det A \\ I = \text{tr } A \end{array} \right\} \text{ - invariante metrice (rămân nemodificate la act. unei izometrie)}$$

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$d(A, B) = d(f(A), f(B)) \quad \forall A, B$$

Clasificarea metrică a conicelor

$$\Delta \neq 0 \Leftrightarrow \text{conica este nedeg.}$$

$$\delta \neq 0 \Leftrightarrow \text{conica are centru unic}$$

$$\Delta \neq 0 \begin{cases} \delta > 0 \rightarrow \text{elipsă: } \frac{x^2}{a^2} + \frac{y^2}{b^2} - 1 = 0 \\ \delta = 0 \rightarrow \text{parabolă: } y^2 = 2px \\ \delta < 0 \rightarrow \text{hiperbolă: } \frac{x^2}{a^2} - \frac{y^2}{b^2} - 1 = 0 \end{cases}$$

$$\Delta = 0 \begin{cases} \delta > 0 \rightarrow \text{pct. sau } \emptyset \\ \delta = 0 \rightarrow 2 \text{ dr. ||} \\ \delta < 0 \rightarrow 2 \text{ dr. concurente} \end{cases}$$

Ex. 1. Fie Γ de ec. $x_1^2 - 3x_1x_2 + x_2^2 - 4x_1 + 2x_2 - 1 = 0$

Se clasifică izom conica Γ

Se aducă la o formă can. Γ , prin izom.

Rez: $a = \begin{pmatrix} 1 & -\frac{3}{2} \\ -\frac{3}{2} & 1 \end{pmatrix} \quad \delta = |a| \quad \delta = \det a = 1 - \frac{9}{4} = -\frac{5}{4} < 0$

$A = \begin{pmatrix} 1 & -\frac{3}{2} & -2 \\ -\frac{3}{2} & 1 & 1 \\ -2 & 1 & -1 \end{pmatrix} \rightarrow \Delta = -1 + 3 + 3 - 4 + \frac{9}{4} - 1 = \frac{9}{4} \neq 0$

$\Delta \neq 0, \delta < 0 \Rightarrow \Gamma$ hiperbolă

$\delta \neq 0 \Rightarrow$ conica Γ are centru unic

Coord. centrului unic (x_1^0, x_2^0) se det ca sol unică $\begin{cases} \frac{\partial f}{\partial x_1} = 0 \\ \frac{\partial f}{\partial x_2} = 0 \end{cases}$

Ex. 2. $\Gamma: x_1^2 - 2x_1x_2 + x_2^2 - 2x_1 + 4x_2 + 1 = 0$

Clasif. izometrică (prin izometrii) pt. conica Γ

$a = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \rightarrow \delta = \det a = 0$

$A = \begin{pmatrix} 1 & -1 & -1 \\ -1 & 1 & 2 \\ -1 & 2 & 1 \end{pmatrix} \rightarrow \Delta = \det A = -1 \neq 0$

$\Delta \neq 0, \delta = 0 \Rightarrow \Gamma$ parabolă

Det. val. proprii coresp. lui a :

Rezolvac. caract. $\det(a - \lambda I_2) = 0$, în \mathbb{R}

$\begin{vmatrix} 1-\lambda & -1 \\ -1 & 1-\lambda \end{vmatrix} = 0 \Leftrightarrow (1-\lambda)^2 - 1 = 0 \Leftrightarrow -\lambda(2-\lambda) = 0 \begin{cases} \lambda_1 = 0 \\ \lambda_2 = 2 \end{cases}$

Det. subsp. pr. coresp.

$V_{\lambda_1} = \{ v \in \mathbb{R}^2 \mid a v = \lambda_1 v \}$

$$\begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \rightarrow x - y = 0$$

$$\begin{cases} x = \lambda \\ y = \lambda \end{cases}, \lambda \in \mathbb{R}$$

$$V_{\lambda_1} = \{ \lambda (1, 1) \mid \lambda \in \mathbb{R} \}$$

$$V_{\lambda_2} = \{ v \in \mathbb{R}^2 \mid av = \lambda_2 v \}$$

$$\begin{pmatrix} -1 & -1 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow x + y = 0$$

$$\begin{cases} x = -\lambda \\ y = \lambda \end{cases}, \lambda \in \mathbb{R}$$

$$V_{\lambda_1} = \{ \lambda (1, 1) \mid \lambda \in \mathbb{R} \}$$

$$V_{\lambda_2} = \{ \lambda (-1, 1) \mid \lambda \in \mathbb{R} \}$$

Cons.: $\begin{cases} f_1 = (1, 1) \\ f_2 = (-1, 1) \end{cases} \xrightarrow{f_1 + f_2} \begin{cases} e_1 = \frac{f_1}{\|f_1\|} = \frac{1}{\sqrt{2}} (1, 1) \\ e_2 = \frac{f_2}{\|f_2\|} = \frac{1}{\sqrt{2}} (-1, 1) \end{cases}$

$$R: \begin{cases} x_1' = \frac{1}{\sqrt{2}} (x_1 + x_2) \\ x_2' = \frac{1}{\sqrt{2}} (-x_1 + x_2) \end{cases} \Rightarrow \begin{cases} x_1 = \frac{1}{\sqrt{2}} (x_1' + x_2') \\ x_2 = \frac{1}{\sqrt{2}} (x_1' - x_2') \end{cases}$$

$$R^{-1} = R^T$$