# An Attempt to Find an Optimal Wavelet for an **Arbitrary Input Signal**

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#### Section Outline

Problem Statement Setup

Supervised Learning in ML

ML Wavelet Building

Results

Conclusion/Discussion

References

### Project Goal

I wanted to see if, given an arbitrary input signal, I could use an ML algorithm to 'learn' the best parameters for a predefined wavelet shape.

Problem Statement Setup

$$\hat{\psi}(t) = \exp\left(\frac{-t^2}{2}\right) (\varepsilon t + A\sin\left(Bt\right))$$

By using only odd functions being damped by a Gaussian, we satisfy (odd function times even is odd) the first condition. Dividing by the  $L^2$  Norm we satisfy the second.

$$\underbrace{\int_{\mathbb{R}} \varphi \ dt = 0, \qquad ||\varphi||_{L^2} = 1}_{\text{Conditions}} \qquad \Rightarrow \qquad \psi(t) = \frac{\psi(t)}{||\hat{\psi}(t)||_{L^2}}$$

### General Equation Form

Problem Statement Setup

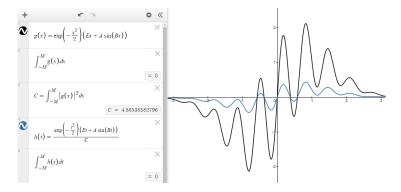
Therefore, our overall analytical expression for a daughter wavelet indexed by  $j \in (J \subset \mathbb{Z}^+)$  becomes

$$\varphi_{j}(t) = \frac{1}{\sqrt{a^{j}}} \psi\left(\frac{t}{a^{j}}\right)$$

$$= \frac{1}{\sqrt{a^{j}}} \frac{\exp\left(-\frac{1}{2}\frac{t^{2}}{a^{2j}}\right) \left(\frac{\varepsilon t}{a^{j}} + A\sin\left(\frac{Bt}{a^{j}}\right)\right)}{\left(\int_{\mathbb{R}} \exp\left(-\frac{t^{2}}{a^{2j}}\right) \left(\frac{\varepsilon t}{a^{j}} + A\sin\left(\frac{Bt}{a^{j}}\right)\right)^{2} dt\right)^{1/2}}$$

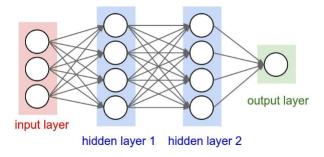
#### **Example Mother Wavelet**

For values of  $\varepsilon=1.8$ , A=1.5 and B=9.5. The blue curve is the normalization of the black curve.



## How ML Works (1)

Think of each node (circle) as containing some value and the (lines) mathematical operations performed on them produce new nodes.



## How ML Works (2)

The input to the NN,  $\mathbf{x}$ , is fed through some function or set of functions which we'll generically call  $\mathcal{N}$ , produces some output  $\mathbf{y}$ . So,

$$\mathcal{N}(\mathbf{x}) = \mathbf{y}$$

We want to know, how well did y match up to our expectations?

This is determined by a **cost function**. In *supervised learning*, we already know ahead of time what we wish the answer to be. Using least squares ( $D \equiv \text{Desired}$ )

$$C = (\mathcal{N}(\mathbf{x}) - \mathcal{N}_D(\mathbf{x}))^2$$

# How ML Works (3)

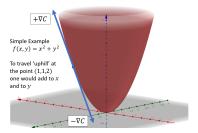
We need a way for the NN to learn. Using gradient descent, we determine the partial derivative per each parameter,  $p_n \in \{p_1, ..., p_N\}$  to get  $-\nabla C$  where

$$\nabla C = \begin{bmatrix} \frac{\partial C}{\partial p_1} \\ \vdots \\ \frac{\partial C}{\partial p_N} \end{bmatrix}$$

The big take-away here is that we are trying to minimize our cost function.

# How ML Works (4)

Gradients give steepest ascent for a given parameter<sup>1</sup>. Then, simply add or subtract a small value known as the **learning rate** from the parameter to move it 'downhill'.



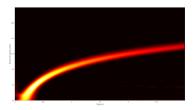
This whole process is known as **back propagation**.

<sup>&</sup>lt;sup>1</sup>This is what's given to us from finding  $\nabla C$ .

### Challenge with Supervised Learning

What is a 'good' wavelet?

I noticed this classic example seemed to be zero almost everywhere except in a tight band.



I told the algorithm to learn to minimize the field, i.e.,  $\forall i \in (J \subset \mathbb{Z}^+), \forall t \in \Omega, \ \mathcal{N}_D(\mathbf{x}) = 0.$ 

# Choice of $\hat{\psi}$

Recall:

$$\hat{\psi}(t) = \exp\left(\frac{-t^2}{2}\right) (\varepsilon t + A\sin\left(Bt\right))$$

This brings us back to the  $\varepsilon t$  term. This will ensure that our wavelet simply doesn't learn to become zero. Cheeky little devil!

Also, we note that we'll possibly need a more robust way to ensure that our algorithm doesn't simply learn to minimize our parameters to be zero to simply be negligibly small.

#### **Enhanced Cost Function**

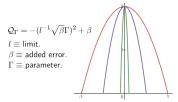
We'll keep the zero field idea

$$C = (\mathcal{N}(\mathbf{x}) - \mathcal{N}_D(\mathbf{x}))^2$$

but now we'll add in two biasing terms that heavily penalize the algorithm if it tries to make our parameters too small.

$$C = (\mathcal{N}(\mathbf{x}) - \mathcal{N}_D(\mathbf{x}))^2 + \mathcal{Q}_A + \mathcal{Q}_B$$

Again we note that from our form of  $\hat{\psi}(t)$  our only two parameters for this example are A and B ( $\Gamma \in \{A, B\}$ ).



# Forward Propagation (1)

We know that in the forward direction we'll generate a **scalogram** by computing

$$\forall j \in J, \qquad \varphi_j(t) * f(t) = \int_{\mathbb{R}} \varphi_j(t-\tau) * f(\tau) \ d\tau$$

Therefore, on this heinous equation, I needed to perform back propagation. Many details later...

## Forward Propagation (2)

Note here we still need to do  $\int_{\mathbb{R}} W \ d au$  as this is the convolution<sup>2</sup>

$$W := \frac{e^{-\frac{(t-\tau)^2}{2a^{2j}}} \left(\frac{\varepsilon(t-\tau)}{a^j} + A\sin\left(\frac{B(t-\tau)}{a^j}\right)\right) f(\tau)}{\sqrt{a^j}}$$

$$\int_{-\infty}^{\infty} e^{-\frac{(t-\tau)^2}{a^{2j}}} \left(\frac{\varepsilon(t-\tau)}{a^j} + A\sin\left(\frac{B(t-\tau)}{a^j}\right)\right)^2 d\tau$$

<sup>&</sup>lt;sup>2</sup>The outside integral is irrelevant to the calculations but was too computationally excessive for Maple so I left it out.

## Forward Propagation (3)

Each discrete point in the field/scalogram is a convolution

Each point was calculated because nicely we know

$$\hat{h}[k] = \hat{f}[k]\hat{g}[k] = \widehat{f \otimes g}[k]$$

# Analytical Back Propagation - Finding $\nabla C$ (1)

Again here we still need to do  $\int_{\mathbb{D}} EQA \ d\tau$ 

$$\begin{split} & = \operatorname{EQA} \coloneqq \operatorname{diff}(W, A) \\ & = \operatorname{e}^{-\frac{(t-\tau)^2}{2 \, a^{2J}}} \sin\left(\frac{B\left(t-\tau\right)}{a^J}\right) f(\tau) \\ & = \operatorname{EQA} \coloneqq \frac{\left(t-\tau\right)^2}{\sqrt{a^J}} \int_{-\infty}^{\infty} \operatorname{e}^{-\frac{(t-\tau)^2}{a^{2J}}} \left(\frac{\varepsilon\left(t-\tau\right)}{a^J} + A \sin\left(\frac{B\left(t-\tau\right)}{a^J}\right)\right)^2 \mathrm{d}\tau \\ & + A \sin\left(\frac{B\left(t-\tau\right)}{a^J}\right)\right) f(\tau) \left(\int_{-\infty}^{\infty} 2 \operatorname{e}^{-\frac{(t-\tau)^2}{a^{2J}}} \left(\frac{\varepsilon\left(t-\tau\right)}{a^J} + A \sin\left(\frac{B\left(t-\tau\right)}{a^J}\right)\right) \sin\left(\frac{B\left(t-\tau\right)}{a^J}\right) \mathrm{d}\tau \right) \right) \\ & \left(2\sqrt{a^J} \left(\int_{-\infty}^{\infty} \operatorname{e}^{-\frac{(t-\tau)^2}{a^{2J}}} \left(\frac{\varepsilon\left(t-\tau\right)}{a^J} + A \sin\left(\frac{B\left(t-\tau\right)}{a^J}\right)\right)^2 \mathrm{d}\tau \right)^{3/2} \right) \end{split}$$

# Analytical Back Propagation - Finding $\nabla C$ (2)

Again we still need to do  $\int_{\mathbb{D}} EQB \ d\tau$ 

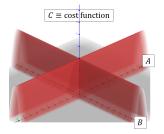
$$\begin{split} & > EQB \coloneqq diff(W,B) \\ & = \underbrace{\frac{(t-\tau)^2}{2 \, a^{JJ}} \, A \, (t-\tau) \cos \left( \frac{B \, (t-\tau)}{a^J} \right) f(\tau)}_{= \, CB} = \underbrace{-\frac{(t-\tau)^2}{2 \, a^{JJ}} \, A \, \left( \frac{\varepsilon \, (t-\tau)}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right)^2 d\tau}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{2 \, a^{JJ}} \, \left( \frac{\varepsilon \, (t-\tau)}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right)^2 d\tau}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{2 \, a^{JJ}} \, \left( \frac{\varepsilon \, (t-\tau)}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right) A \, (t-\tau) \cos \left( \frac{B \, (t-\tau)}{a^J} \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} \, \left( \frac{\varepsilon \, (t-\tau)}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right) A \, (t-\tau) \cos \left( \frac{B \, (t-\tau)}{a^J} \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} \, \left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right) A \, (t-\tau) \cos \left( \frac{B \, (t-\tau)}{a^J} \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} \, \left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right)^2 d\tau}_{= \, CB} \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right) A \, (t-\tau) \cos \left( \frac{B \, (t-\tau)}{a^J} \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right)^2 d\tau}_{= \, CB} \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right) A \, (t-\tau) \cos \left( \frac{B \, (t-\tau)}{a^J} \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right) A \, (t-\tau) \cos \left( \frac{B \, (t-\tau)}{a^J} \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right) A \, (t-\tau) \cos \left( \frac{B \, (t-\tau)}{a^J} \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)}{a^J} \right) \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)^2}{a^J} \right) \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)^2}{a^J} \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)^2}{a^J} \right) \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)^2}{a^J} \right)}_{= \, CB} - \underbrace{\left( \frac{\varepsilon \, (t-\tau)^2}{a^J} + A \sin \left( \frac{B \, (t-\tau)^2}{a^J} \right)}_{= \, CB} - \underbrace{\left( \frac$$

# Analytical Back Propagation - Finding $\nabla C$ (3)

```
def EQA(neg_oh,t,tau,two,thd2,a_to_j,A,B,f_t,delta_t,eps):
  01 = (t-tau)/a to i
  a to i2 = a to i**two
  SI = A*np.sin(B*01)
  numl = np.exp(neq oh*(t-tau)**two/(a to i2))*np.sin(B*01)*f t
  deml into = np.exp(-(t-tau)**two/a to i2)*(eps*01+S1)**two
  deml integral = integrate.simpson(deml intg,dx=delta t)
  deml = np.sqrt(a_to_j)*np.sqrt(deml integral)
  T1 = num1/dem1
 LT = np.exp(neg oh*(t-tau)**two/(two*a to i2))*(eps*01+S1)*f t
 RT into = two*np.exp(-(t-tau)**two/a to i2)*(eps*01+S1)*np.sin(B*01)
 RT = integrate.simpson(RT intg.dx=delta t)
  dem2 intg = np.exp(-(t-tau)**two/a to i\bar{2})*(eps*01+S1)**two
  dem2 = two*np.sqrt(a_to_j)*(integrate.simpson(dem2_intg,dx=delta_t))**(thd2)
  A curve = T1-LT*RT/dem2
  return integrate.simpson(A_curve,dx=delta_t)
def EOB(neg oh.t.tau.two.thd2.a to i.A.B.f t.delta t.eps):
  01 = B*(t-tau)/a to i
  02 = eps*(t-tau)/a to i
  Trias = A*np.sin(01)
  Trigc = A*(t-tau)*np.cos(01)
  # now to use em
  numl = np.exp(neg oh*(t-tau)**two)*Trigc*f t
  deml into = np.exp(-(t-tau)**two/a to i**two)*(02+Trigs)**two
  dem1 = a to i**thd2*np.sgrt(integrate.simpson(dem1 intg.dx=delta t))
  LT = np.exp(neg oh*(t-tau)**two/a to i**two)*(02+Trigs)*f t
  RT intg = two*np.exp(-(t-tau)/a to i)*(02+Trigs*Trigc)
 RT = integrate.simpson(RT intg.dx=delta t)
  dem2_intg = np.exp(-(t-tau)**two/a_to_j**two)*(Q2+Trigs)**two
  dem2 = two*np.sgrt(a to i)*(integrate.simpson(dem2 intg.dx=delta t))**thd2
  B curve = num1/dem1-LT*RT/dem2
  return integrate.simpson(B_curve,dx=delta_t)
```

#### Quick Note on Parameter Space

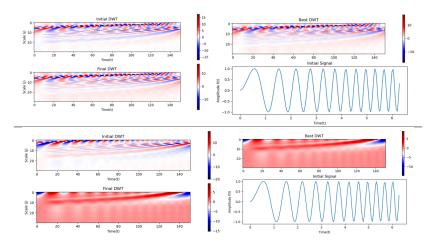
Because we did a lot of work to make sure we wouldn't simply learn A=B=0, we effectively took our parameter space and did the following.



Therefore, while testing, I had to be cognizant of which of the 4 sections I was starting in  $(A^+B^+, A^-B^+, A^+B^-, A^-B^-)$ 

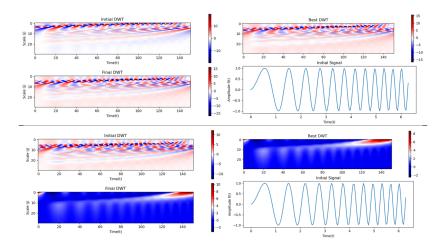
# Mixed Results for Chirp (1): $f(t) = \sin(4t^{1.6})$

Top:  $A^+, B^+$ , Bottom:  $A^+, B^-$ 



# Mixed Results for Chirp (2): $f(t) = \sin(4t^{1.6})$

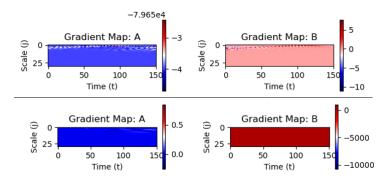
Top:  $A^-, B^+$ , Bottom:  $A^-, B^-$ 



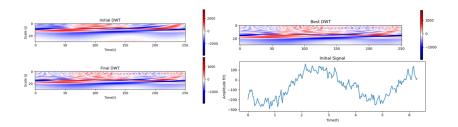
#### Verification of Minimization

Did the algorithm actually do what I wanted it to?

Top:  $A^+, B^+$ , Bottom:  $A^+, B^-$ 



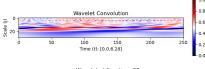
I took this signal from Dr. Gilles' seismic data (available in MatLab). From an eyeball perspective, this did seem to work decently well, and gave the DWT a more structured appearance while also minimizing the field.

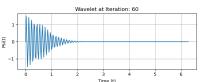


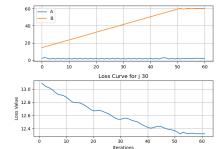
### Optimized to a Non-Trivial Curve

Here we see all of this nicely come together.

- 1. The loss curve goes down.
- 2. Clear difference in wavelet shape from  $A_0, B_0 \rightarrow A_{63}, B_{63}$
- 3. The scalogram looks more organized







### Concluding Thoughts

- o This method was finicky and required several iterations. Manual verification was often required. However, some results did seem promising/interesting.
- o I would be curious to know what an expert in this space would have to say about my final results.
- o More complex potential wavelet forms both real and complex possible (where  $\mathcal{O} \equiv$  odd functions)

$$\hat{\psi}(t) = \exp\left(\frac{-t^2}{2}\right) \left(\sum_{n=1}^{N} A_n \sin(B_n t) + \sum_{n=1}^{N} E_n t^{2n-1} + \sum_{n=1}^{N} C_n t^{2n-1}\right)$$

Questions?

#### References

- 1. Jerome Gilles (2023). Empirical Wavelet Transforms (https://www.mathworks.com/matlabcentral/fileexchange/42141empirical-wavelet-transforms), MATLAB Central File Exchange. Retrieved April 25, 2023.
- 2. Jerome Gilles (2023). Course Reader for Math 668 Fourier Analysis. San Diego State University.

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