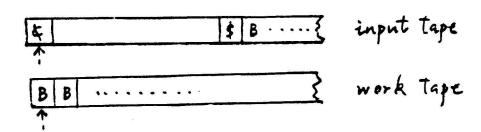
Resource Bounded TM's

 \triangle A TM has unlimited resources: <u>time</u> and <u>space</u>.

In practice, we need to restrict them.

- \triangle TMs with restricted resources are the topic of complexity theory. Here, we briefly introduce the basic concepts of P, NP, etc. .
- △ We use the off-line DTMs and NTMs which have been introduced before. An off-line TM (DTM or NTM) has
 - a read-only input tape;
 - a read-write work tape; (storage)



Note:

- 1. There are two end-markers at the two ends of the input word. The read-only head never moves out of the two ends.
- 2. Both heads can make three kinds of moves, i.e., L, R, λ .
- 3. The work tape is initially blank.
- \triangle Given an off-line <u>DTM</u> M, if each <u>accepted</u> <u>word</u> of length <u>n</u> causes M to visit at most $\underline{S(n)}$ distinct cells <u>on the work tape</u>, then M is said to be an $\underline{S(n)}$ space-bounded <u>DTM</u>.

 Note:
 - (1) We only consider accepted words.
 - (2) S(n) is a function from N to N.
 - (3) We only count the cells used on the work tape.

- \triangle Given an off-line <u>DTM</u> M, if each <u>accepted</u> word of <u>length</u> n causes M to compute <u>at most</u> T(n) steps before M accepts, then M is said to be a T(n) time-bounded DTM.
- \triangle Given an off-line NTM M, if each accepting configuration sequence visits at most S(n) distinct cells on the work tape, then M is said to be an S(n) space-bounded NTM.
- \triangle Similarly, we define T(n) time-bounded NTMs.

\triangle A language L is of

- (1) deterministic-space complexity S(n), if L = L(M) and M is S(n) space-bounded off-line DTM.
 - (2) deterministic-time complexity T(n).
 - (3) nondeterministic-space complexity S(n).
 - (4) nondeterministic-time complexity T(n).

Attention has focused on polynomial functions, since these appear to be the the most practical.

Example:

$$n$$
 | 1 10 20 ...

 $100n^2$ | 100 10000 40000 ...

 2^n | 2 1024 1048576 ...

We define the following four families of languages:

- (1) $\mathcal{L}_{DPSPACE} = \{L \mid L \text{ has det.-space complexity } S(n), \text{ for some polynomial } S(n)\}$
- (2) $\mathcal{L}_{DPTIME} = \{L \mid L \text{ has deterministic-time complexity } T(n), \text{ for some polynomial } T(n)\}$
- (3) $\mathcal{L}_{NPSPACE} = \{L \mid L \text{ has nondet.-space complexity } S(n), \text{ for some polynomial } S(n)\}$
- (4) $\mathcal{L}_{NPTIME} = \{L \mid L \text{ has nondet.-time complexity } T(n), \text{ for some polynomial } T(n)\}$

\triangle We know that

$$\mathcal{L}_{DPSPACE} \subseteq \mathcal{L}_{NPSPACE}$$

and

$$\mathcal{L}_{DPTIME} \subseteq \mathcal{L}_{NPTIME}$$

Why?

 \triangle We also know that

$$\mathcal{L}_{DPTIME} \subseteq \mathcal{L}_{DPSPACE}$$

and

$$\mathcal{L}_{NPTIME} \subseteq \mathcal{L}_{NPSPACE}$$

Why?

 \triangle It has been proven that

$$\mathcal{L}_{DPSPACE} = \mathcal{L}_{NPSPACE}$$

and that

$$\mathcal{L}_{NPSPACE} \subset \mathcal{L}_{REC}$$

 \triangle So, we have

$$\underbrace{\mathcal{L}_{DPTIME}}_{P} \subseteq \underbrace{\mathcal{L}_{NPTIME}}_{NP} \subseteq \underbrace{\mathcal{L}_{DPSPACE}}_{CDPSPACE} \subset \mathcal{L}_{REC}$$

Corresponding to these four families of languages, we have four <u>classes</u> of problems:

- (1) PSPACE: the class of all problems that can be solved in deterministic polynomial space.
- (2) P: the class of all problems that can be solved in deterministic polynomial time.
- (3) NPSPACE : . . . in nondeterministic polynomial space
- (4) NP: ... in nondeterministic polynomial time.

$$P \subseteq NP \subseteq PSPACE = NPSPACE$$

 $problems \Leftrightarrow decision problems \Leftrightarrow languages$

$$P? = ?NP$$

 \triangle We define a relation \prec on problems (languages).

For L_1, L_2 in \mathcal{L}_{REC} ,

$$L_1 \prec L_2$$

If L_1 requires no more time than L_2 to accept.

 $\triangle \alpha$ is <u>transitive</u> and <u>reflexive</u>. It is a pre-order.

 \triangle L is said to be <u>NP-hard</u> if L' α L for all L' in \mathcal{L}_{NPTIME} .

 \triangle L is said to be <u>NP-complete</u> if it is also in \mathcal{L}_{NPTIME} .

A clear concept of NP-completness was given by Steven Cook. He showed that satisfiability problem is NP-complete.

SATISFIABILITY PROBLEM (SAT)

INSTANCE: A set U of variables and a collection C of clauses over U.

QUESTION: Is there a satisfying truth assignment for C?

SAT is NP-complete.