



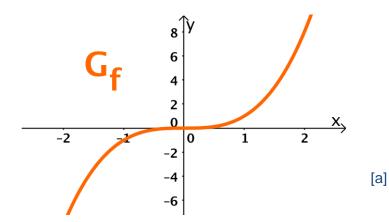
A. Maier, V. Christlein, K. Breininger, S. Vesal, F. Meister, C. Liu, S. Gündel, S. Jaganathan, N. Maul, M. Vornehm, L. Reeb, F. Thamm, C. Bergler, F. Denzinger, B. Geissler, Z. Yang, A. Popp, M. Nau

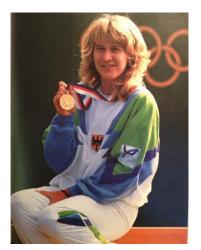
Pattern Recognition Lab, Friedrich-Alexander-Universität Erlangen-Nürnberg



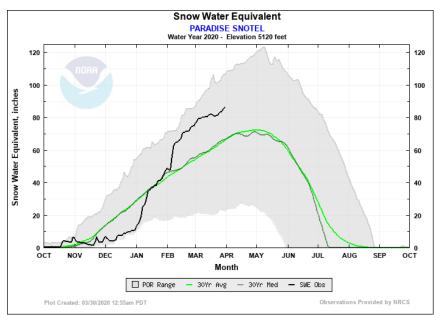








Steffi Graf (1999)





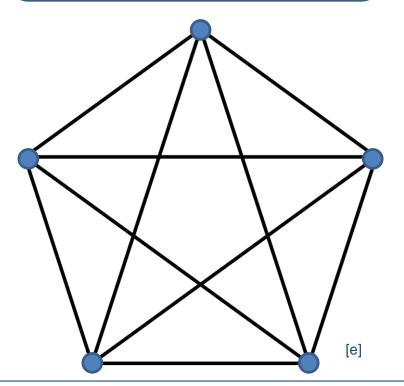
[b]





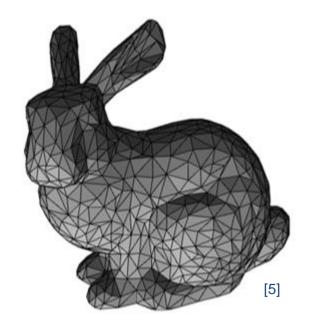
Computer Scientist:

A **Graph** is a set of nodes connected through edges



Mathematician:

A **Graph** is a manifold but a discrete one







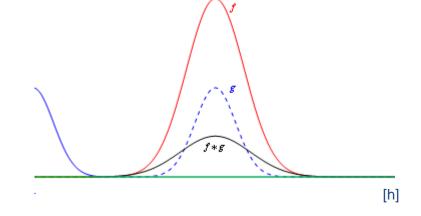
How would you define a convolution on Euclidean space?

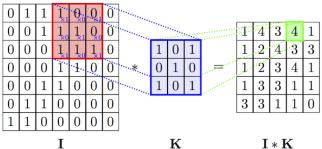
Computer Scientist + Mathematician:

$$(f \star g)(n) = \sum_{k \in D} f(k)g(n-k)$$

$$(f \star g)(n) = \int_{\mathbb{R}^n} f(\tau)g(x - \tau)d\tau$$







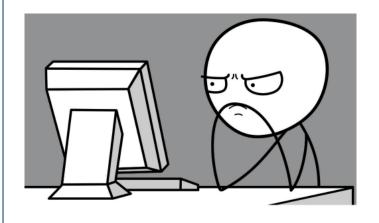
[g]





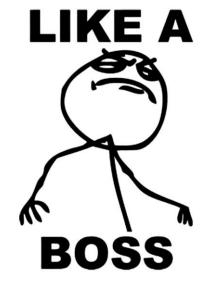
How would you define a convolution on graphs?

Computer Scientist:



Mathematician:

$$\Delta f = -\mathrm{div}(\nabla f)$$







How would you define a convolution on graphs?

Manifold Idea:

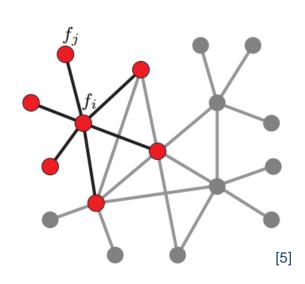
- We know to convolve manifolds
- 2. We can discretize convolutions
- 3. Thus, we know how to convolve graphs

Convolution on manifolds

max o min

discretize

Convolution on graphs





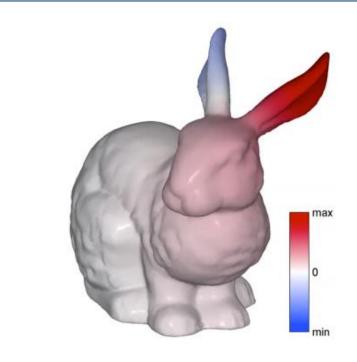


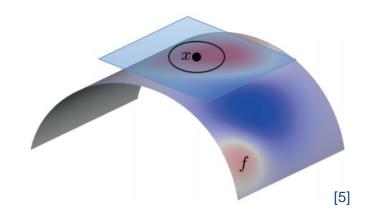
Lets diffuse some heat with Newton's Law of Cooling [6]:

$$f_t(x,t) = -\Delta f(x,t)$$

$$f(x,0) = f_0(x)$$

- f(x,t) amount of heat at point x at time t
- $f_0(x)$ initial heat distribution
- $\Delta f(x) = -\operatorname{div}(\nabla f)$ (Laplacian) difference between f(x) and the average of f on an infinitesimal sphere around x







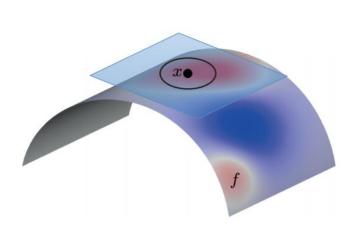


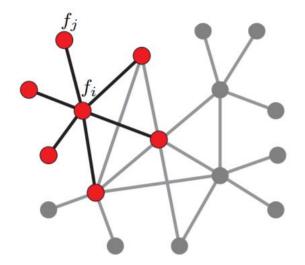
How do we express the Laplacian in a discrete form?

•
$$\Delta f(x) = -\operatorname{div}(\nabla f)$$

"difference between f(x) and the average of f on an infinitesimal sphere around x"

$$(\Delta f)_i = \frac{1}{d_i} \sum_{j:(i,j)\in E} a_{ij} (f_i - f_j)$$





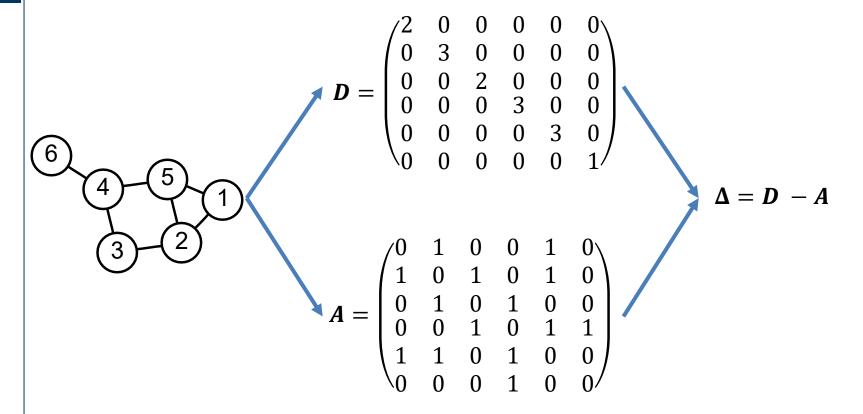




Is there another way of expressing this? (Below without the normalization d_i)

$$(\Delta f)_i = \sum_{i:(i,j)\in E} a_{ij} (f_i - f_j)$$

Yes.







- $\Delta \in \mathbb{R}^{N \times N}$ is known as the **Laplacian Matrix** of a (sub-)graph consisting of N nodes
- $D \in \mathbb{R}^{N \times N}$ is the **Degree Matrix** and describes the number of edges connected to each node
- $A \in \mathbb{R}^{N \times N}$ is the **Adjacency Matrix** and describes the connectivity of the graph
- For a directed graph Δ is not s.p.d. thus we normalize Δ and get Δ_{sym} s.t.

$$\Delta = D - A$$

$$\Delta_{sym} = D^{-\frac{1}{2}} \Delta D^{-\frac{1}{2}}$$

$$\Delta_{sym} = D^{-\frac{1}{2}} (D - A) D^{-\frac{1}{2}}$$

$$\Delta_{sym} = D^{-\frac{1}{2}} D D^{-\frac{1}{2}} - D^{-\frac{1}{2}} A D^{-\frac{1}{2}}$$

$$\Delta_{sym} = I - D^{-\frac{1}{2}} A D^{-\frac{1}{2}}$$





Let's do some magic!

• Δ_{sym} is now s.p.d.

$$\mathbf{\Delta}_{sym} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^T$$

$$\mathbf{U} = [\mathbf{u}_0, ..., \mathbf{u}_{N-1}] \in \mathbb{R}^{N \times N}$$

$$\mathbf{\Lambda} = \operatorname{diag}([\lambda_0, ..., \lambda_{N-1}]) \in \mathbb{R}^{N \times N}$$

- $u_0, ..., u_{N-1} \in \mathbb{R}^N$: Eigenvectors are known as the graph Fourier modes
- $\lambda_0, ..., \lambda_{N-1} \in \mathbb{R}$: Eigenvalues are known as the spectral frequencies
- That means: We can use U and U^T in order to Fourier transform a graph whereas Λ are the spectral filter coefficients!





Let's do some magic!

- Let $x \in \mathbb{R}^{N}$ be some signal (a scalar for every node)
- and using the Laplacians eigenvectors we can define its Fourier transform using ${\pmb U}^T$

$$\widehat{\mathbf{x}} = \mathbf{U}^T \mathbf{x}$$

and inverse

$$x = U\hat{x}$$

• We can therefore describe as convolution with a filter *g* in spectral domain

$$\mathbf{g} \star \mathbf{x} = \mathbf{U}((\mathbf{U}^T \mathbf{g}) \cdot (\mathbf{U}^T \mathbf{x}))$$

• Lets construct a filter $\widehat{\mathbf{G}}$ composed by a k-th order polynomial of Laplacians with $\theta_i \in \mathbb{R}$

$$\widehat{\boldsymbol{G}} = \sum_{i}^{k} \theta_{i} \, \boldsymbol{\Lambda}^{i} = \theta_{k} \boldsymbol{\Lambda}^{k} + \dots + \theta_{1} \boldsymbol{\Lambda}^{1} + \theta_{o}$$





Let's do some magic!

• Lets construct a filter $\hat{\mathbf{G}}$ composed by a k-th order polynomial of Laplacians

$$\widehat{\boldsymbol{G}} = \sum_{i}^{k} \theta_{i} \, \boldsymbol{\Lambda}^{i}$$

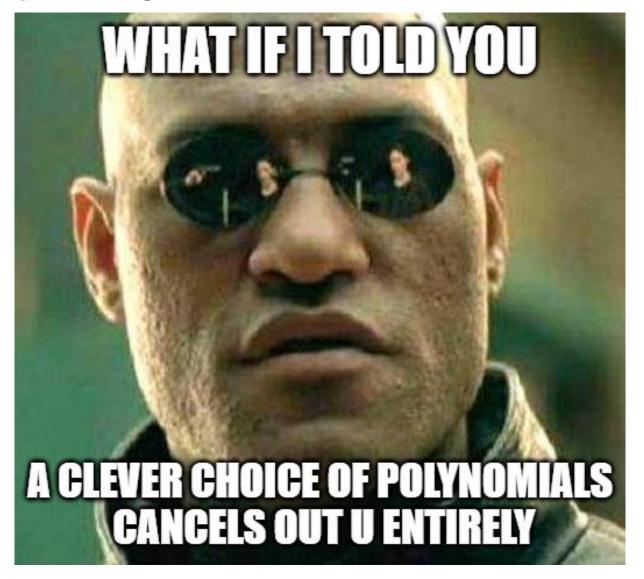
and filter some signal

$$\boldsymbol{U}\widehat{\boldsymbol{G}}\boldsymbol{U}^{T}\boldsymbol{x} = \boldsymbol{U}\left(\sum_{i}^{k}\theta_{i}\,\boldsymbol{\Lambda}^{i}\right)\boldsymbol{U}^{T}\boldsymbol{x}$$

- And now what?!
 - We can convolve now **x** using Laplacian as we adapt θ_i
 - ... but *U* is heavy to compute for every (sub-)graph we want to convolve!











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$$\boldsymbol{U}\widehat{\boldsymbol{G}}\boldsymbol{U}^{T}\boldsymbol{x} = \boldsymbol{U}\left(\sum_{i}^{k}\theta_{i}\,\boldsymbol{\Lambda}^{i}\right)\boldsymbol{U}^{T}\boldsymbol{x}$$

- Remedy: We choose k and θ such that we get rid of U
- Let k=1, $\theta_0=2\theta$ and $\theta_1=-\theta$ we get the following polynomial

$$\mathbf{U}\mathbf{G}\mathbf{U}^{T}\mathbf{x} = \mathbf{U}(2\theta\mathbf{\Lambda}^{0} - \theta\mathbf{\Lambda}^{1})\mathbf{U}^{T}\mathbf{x}
= (\mathbf{U}2\theta\mathbf{\Lambda}^{0}\mathbf{U}^{T} - \mathbf{U}\theta\mathbf{\Lambda}\mathbf{U}^{T})\mathbf{x}
= (2\theta\mathbf{U}\mathbf{U}^{T} - \theta\mathbf{U}\mathbf{\Lambda}\mathbf{U}^{T})\mathbf{x} \qquad \mathbf{\Delta}_{sym} = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^{T}
= (2\theta\mathbf{I} - \theta\mathbf{\Delta}_{sym})\mathbf{x}
= \theta(2\mathbf{I} - \mathbf{\Delta}_{sym})\mathbf{x} \qquad \mathbf{\Delta}_{sym} = \mathbf{I} - \mathbf{D}^{-\frac{1}{2}}\mathbf{A}\mathbf{D}^{-\frac{1}{2}}
= \theta(2\mathbf{I} - \mathbf{I} + \mathbf{D}^{-1/2}\mathbf{A}\mathbf{D}^{-1/2})\mathbf{x}
= \theta(\mathbf{I} + \mathbf{D}^{-1/2}\mathbf{A}\mathbf{D}^{-1/2})\mathbf{x}$$



We can convolve *x* in spectral domain

Polynomial is k=1 , $\theta_0=2\theta$ and $\theta_1=-\theta$ now only depends on θ

$$U\widehat{G}U^{T}x = \theta(I + D^{-1/2}AD^{-1/2})x$$

We construct \hat{G} as a polynomial of Laplacian filters

$$\widehat{\boldsymbol{G}} = \sum_{i}^{k} \theta_{i} \Lambda^{i}$$

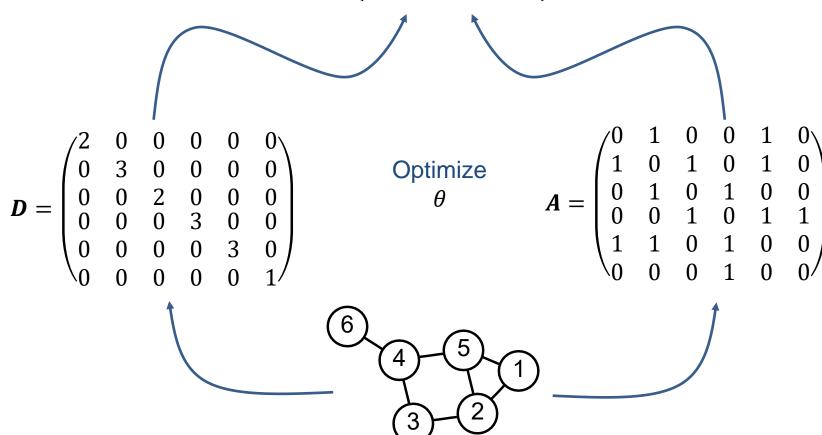
With all restrictions we got rid of the Fourier transform \boldsymbol{U}^T





Basic GCN Operation [1]:

$$U\widehat{\boldsymbol{G}}\boldsymbol{U}^{T}\boldsymbol{x} = \theta(\boldsymbol{I} + \boldsymbol{D}^{-1/2}\boldsymbol{A}\boldsymbol{D}^{-1/2})\boldsymbol{x}$$



[1]: Kipf, Thomas N., and Max Welling. "Semi-supervised classification with graph convolutional networks." arXiv preprint arXiv:1609.02907 (2016).





Question:

Is it *really* necessary to motivate the Graph Convolution from Spectral Domain?



No.

We can motivate spatially as well





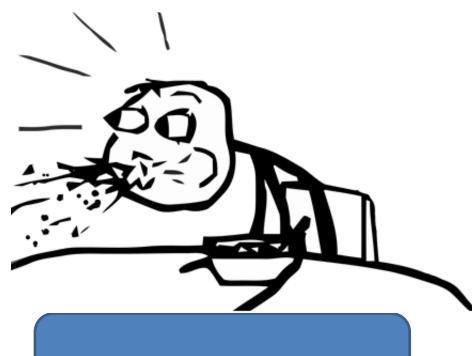
Computer Scientist:

A **Graph** is a set of nodes (vertices) connected through edges

We define how to **aggregate** the information of one Vertex through its **Neighbors**

Spatial Graph Convolution

Mathematician:



Spectral Graph Convolution

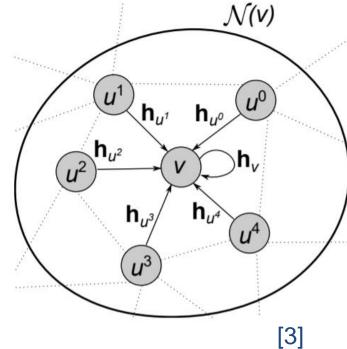




GraphSAGE [2]

Practically:

- We define a vertex of interest
- We define how neighbors contribute to vertex of interest



Technically:

- Feature vector at node v in k-th layer: \mathbf{h}_{v}^{k} e.g. the 0-th layer may contains the input: $\mathbf{h}_{v}^{0} = x_{v}$
- We aggregate h_v^k over h_v^{k-1} with its neighbors $h_u^{k-1} \, \forall \, u \in N(v)$

[2]: Hamilton, Will, Zhitao Ying, and Jure Leskovec. "Inductive representation learning on large graphs." Advances in neural information processing systems. 2017.

[3]: Wolterink, Jelmer M., Tim Leiner, and Ivana Išgum. "Graph convolutional networks for coronary artery segmentation in cardiac CT angiography." *International Workshop on Graph Learning in Medical Imaging*. Springer, Cham, 2019.





GraphSAGE [2] - The Algorithm

Algorithm 1: GraphSAGE embedding generation (i.e., forward propagation) algorithm

```
Input: Graph \mathcal{G}(\mathcal{V}, \mathcal{E}); input features \{\mathbf{x}_v, \forall v \in \mathcal{V}\}; depth K; weight matrices
                      \mathbf{W}^k, \forall k \in \{1, ..., K\}; non-linearity \sigma; differentiable aggregator functions
                      AGGREGATE_k, \forall k \in \{1, ..., K\}; neighborhood function \mathcal{N}: v \to 2^{\mathcal{V}}
    Output: Vector representations \mathbf{z}_v for all v \in \mathcal{V}
\mathbf{h}_{v}^{0} \leftarrow \mathbf{x}_{v}, \forall v \in \mathcal{V};
2 for k = 1...K do
           for v \in \mathcal{V} do
3
                  \mathbf{h}_{\mathcal{N}(v)}^k \leftarrow \text{AGGREGATE}_k(\{\mathbf{h}_u^{k-1}, \forall u \in \mathcal{N}(v)\});
                 \mathbf{h}_v^k \leftarrow \sigma\left(\mathbf{W}^k \cdot \text{CONCAT}(\mathbf{h}_v^{k-1}, \mathbf{h}_{\mathcal{N}(v)}^k)\right)
          \mathbf{h}_{v}^{k} \leftarrow \mathbf{h}_{v}^{k}/\|\mathbf{h}_{v}^{k}\|_{2}, \forall v \in \mathcal{V}
8 end
9 \mathbf{z}_v \leftarrow \mathbf{h}_v^K, \forall v \in \mathcal{V}
```

[2]: Hamilton, Will, Zhitao Ying, and Jure Leskovec. "Inductive representation learning on large graphs." Advances in neural information processing systems. 2017.





GraphSAGE [2] - Aggregators

Mean Aggregator:

$$\mathbf{h}_v^k \leftarrow \sigma(\mathbf{W} \cdot \text{MEAN}(\{\mathbf{h}_v^{k-1}\} \cup \{\mathbf{h}_u^{k-1}, \forall u \in \mathcal{N}(v)\})$$

- GCN Aggregator
- Pooling Aggregator

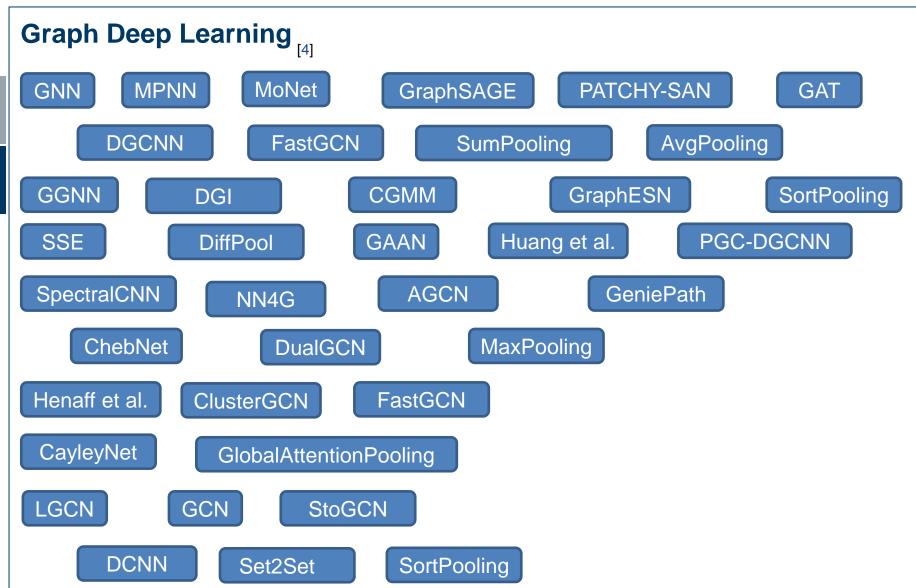
$$AGGREGATE_k^{pool} = \max(\{\sigma\left(\mathbf{W}_{pool}\mathbf{h}_{u_i}^k + \mathbf{b}\right), \forall u_i \in \mathcal{N}(v)\}).$$

LSTM Aggregator

[2]: Hamilton, Will, Zhitao Ying, and Jure Leskovec. "Inductive representation learning on large graphs." Advances in neural information processing systems. 2017.







[4]: Wu, Zonghan, et al. "A comprehensive survey on graph neural networks." arXiv preprint arXiv:1901.00596 (2019).





References

[1]: Kipf, Thomas N., and Max Welling. "Semi-supervised classification with graph convolutional networks." *arXiv preprint arXiv:1609.02907* (2016).

[2]: Hamilton, Will, Zhitao Ying, and Jure Leskovec. "Inductive representation learning on large graphs." *Advances in neural information processing systems*. 2017.

[3]: Wolterink, Jelmer M., Tim Leiner, and Ivana Išgum. "Graph convolutional networks for coronary artery segmentation in cardiac CT angiography." *International Workshop on Graph Learning in Medical Imaging*. Springer, Cham, 2019.

[4]: Wu, Zonghan, et al. "A comprehensive survey on graph neural networks." *arXiv preprint arXiv:1901.00596* (2019).

[5]: Bronstein, Michael et al. Lecture "Geometric deep learning on graphs and manifolds" held at SIAM Tutorial Portlan (2018)





Image References

- [a] https://de.serlo.org/mathe/funktionen/funktionsbegriff/funktionen-graphen/graph-funktion
- [b] https://www.nwrfc.noaa.gov/snow/plot_SWE.php?id=AFSW1
- [c] https://tennisbeiolympia.wordpress.com/meilensteine/steffi-graf/
- [d] https://www.pinterest.de/pin/624381935818627852/
- [e] https://www.uihere.com/free-cliparts/the-pentagon-pentagram-symbol-regular-polygon-golden-five-pointed-star-2282605
- [f] http://geometricdeeplearning.com/ (Geometric Deep Learning on Graphs and Manifolds)
- [g] https://i.stack.imgur.com/NU7y2.png
- [h] https://de.wikipedia.org/wiki/Datei:Convolution_Animation_(Gaussian).gif
- [i]https://www.researchgate.net/publication/306293638/figure/fig1/AS:396934507450372@147164796938 1/Example-of-centerline- extracted-left-and-coronary-artery-tree-mesh-reconstruction.png
- [j] https://www.eurorad.org/sites/default/files/styles/figure_image_teaser_large/public/figure_image/2018-08/0000015888/000006.jpg?itok=hwX1sbCO