Jess Backward Chaining

The Jess Language Part 5
CS3025, Knowledge-Based Systems
Lecture 16

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Outline

- Variable Binding in Condition Elements
- Refraction
- Jess Backward Chaining

Variable Binding in Condition Elements

Problem with OR

Condition Element Operators

- Remember:
 - Patterns appear on the LHS of a rule
 - Operators "and", "or", "not" are operators over complete patterns

```
(defrule rule-1a
    (myfirst (a ?x)(b ?x)(c yellow))
                                                    Is the same !!!
    (mysecond (d?x))
    =>
    (printout t "matched first "
                "and second with x=" ?x crlf)
                                    (defrule rule-1b
                                         (and
                                                        (a ?x) (b ?x) (c somevalue))
                                             (myfirst
 This LHS specifies:
                                             (mysecond
                                                        (d ?x)))
 if both patterns match, then the
                                        =>
                                        (printout t "matched first "
 rule is activated
                                                     "and second with x=" ?x crlf)
```

The Problem with "or"

- Operator "or":
 - The rule fires, if
 - Either: The first pattern matches
 - Or: The second pattern matches
 - Or: Both pattern match
- Problem!!
 - ?x will have binding only if first pattern matches !!!
 - Therefore: a rule cannot be defined like that !!!

The Problem with "or"

- Careful in case of "or":
 - If we use variable ?x at the RHS, it has to occur in all the patterns !!!

Refraction

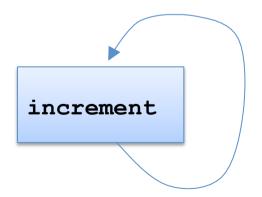
Avoiding Infinite Loops via unwanted re-activation of rules

Observation

Investigate the behaviour of the following

rule:

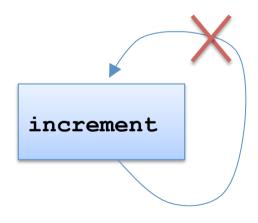
In Jess, loops are not only caused by "while", but also by a simple rule



fact: (person (name Tom) (salary 100))

Refraction Avoid Re-activation of a Rule

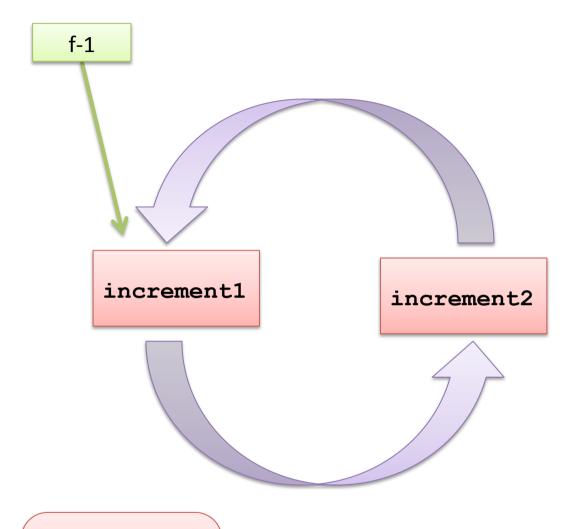
- Refraction is the act of preventing a rule from re-activating itself
- Declaration in rule:



```
(deftemplate person (slot name) (slot age) (slot salary))
(deffacts persons
  (person (name Tom) (age 10) (salary 100))
(defrule increment1
  (declare (no-loop TRUE))
  ?f <- (person (name ?name) (age 10) (salary ?salary))
  =>
  (modify ?f (salary (+ ?salary 10)))
  (modify ?f (age 9))
  (printout t?name "age 10 has salary "?salary crlf)
(defrule increment2
  (declare (no-loop TRUE))
  ?f <- (person (name ?name) (age 9) (salary ?salary))
  =>
  (modify ?f (salary (+ ?salary 10)))
  (modify ?f (age 10))
  (printout t?name "age 9 has salary "?salary crlf)
```

Another example

Ping-pang loop



Jess> (reset) Jess> (run) Tom age 10 has salary 100 Tom age 9 has salary 110 Tom age 10 has salary 120 Tom age 9 has salary 130 Tom age 10 has salary 140 Tom age 9 has salary 150 Tom age 10 has salary 160 Tom age 9 has salary 170 Tom age 10 has salary 180 Tom age 9 has salary 190 Tom age 10 has salary 200 Tom age 9 has salary 210 Tom age 10 has salary 220

Terminate batch job (Y/N)? y

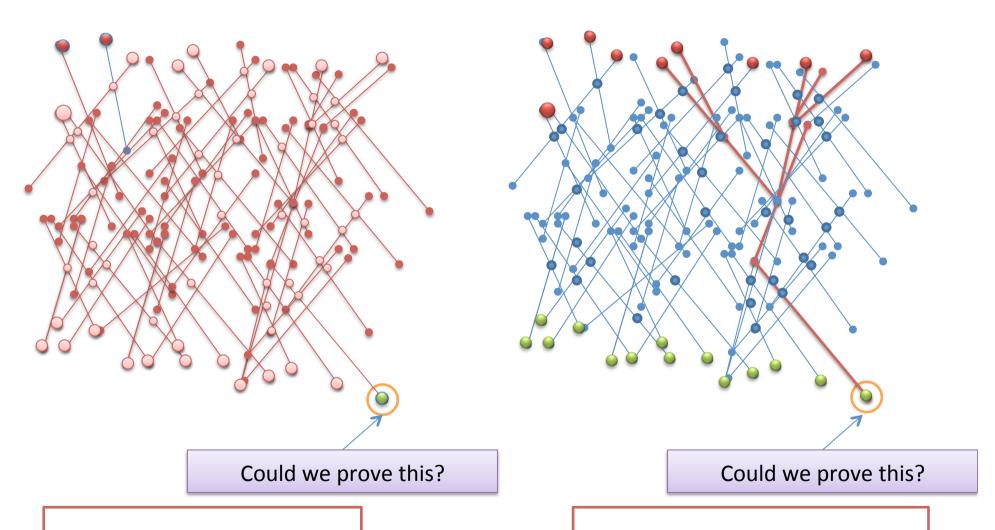
Challenge:

could you design a triangle loop?

Ctrl + c

Jess – Backward Chaining

Backward Chaining (motivation)



Forward chaining checks all facts and rules to prove it

Backward chaining checks only related facts and rules to prove it

Backward Chaining

- Given a particular hypothesis (a fact we regard as true), which we also call a "goal"
 - We want to prove that the hypothesis is true
- For each rule whose consequent matches the current hypothesis:
 - Find support (matching facts) for the rule's antecedents
 - Match them to known facts (in WM)
 - Chain backwards through other rules that create hypotheses that, if proven, will support antecedents of your current rule
 - If all the of the current rule's antecedents are supported (match facts or supported hypotheses), then we can conclude that its consequent (and our original hypothesis) is true
- Classical language based on backward chaining: Prolog

• R1: If A then B

• R2: If B and C then D

• R3: If B and E then F

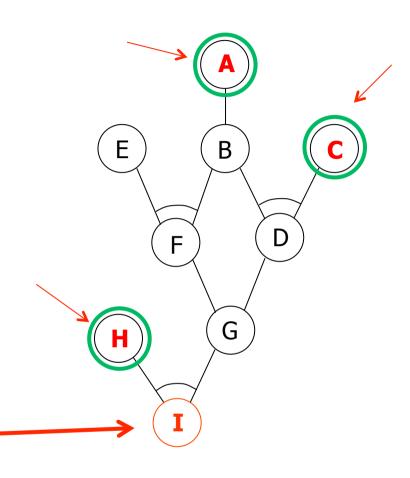
• R4: If F then G

• R5: If D then G

• R6: If G and H then I

In WM: A,C and H

Our Goal: I



R1: If A then B

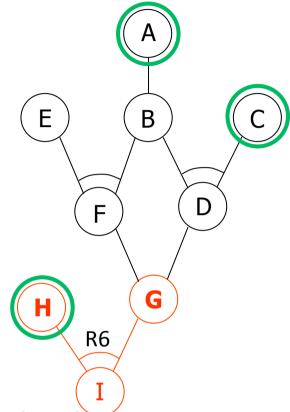
R2: If B and C then D

R3: If B and E then F

• R4: If F then G

R5: If D then G

R6: If G and H then I



- I is not known to be true, then check it
- Rule R6 supports I, but only if H and G are true
- We regard H and G as new "sub-goals" to be achieved

R1: If A then B

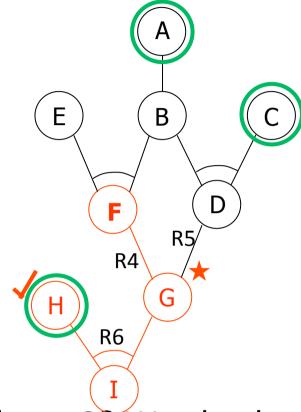
R2: If B and C then D

R3: If B and E then F

R4: If F then G

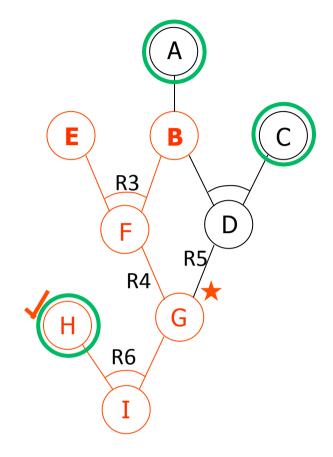
R5: If D then G

R6: If G and H then I



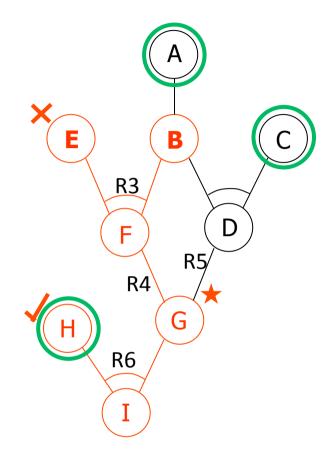
- H is known to be true, what about G? We check.
- Rules R4 and R5 support G choose R4 and mark R5 for *backtracking* (if backtracking – then back to here)

- R1: If A then B
- R2: If B and C then D
- R3: If B and E then F
- R4: If F then G
- R5: If D then G
- R6: If G and H then I



- F is not known to be true. We check if it is supported.
- Rule R3 supports F post E and B as goals

- R1: If A then B
- R2: If B and C then D
- R3: If B and E then F
- R4: If F then G
- R5: If D then G
- R6: If G and H then I



- E is not known to be true. We check if it is supported.
- No rule supports E
- Backtrack!!

• R1: If A then B

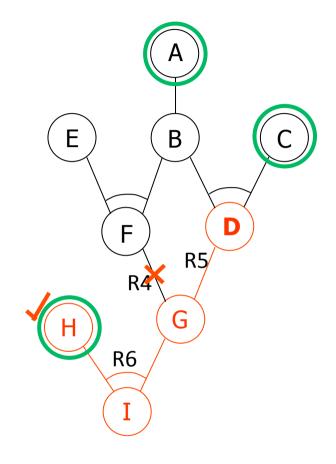
R2: If B and C then D

R3: If B and E then F

R4: If F then G

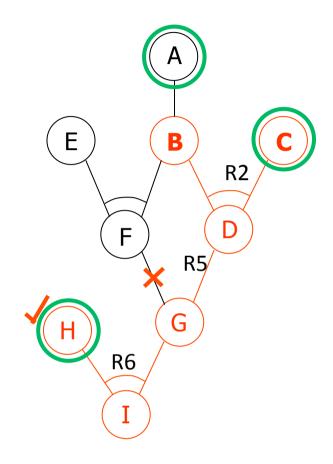
• R5: If D then G

R6: If G and H then I



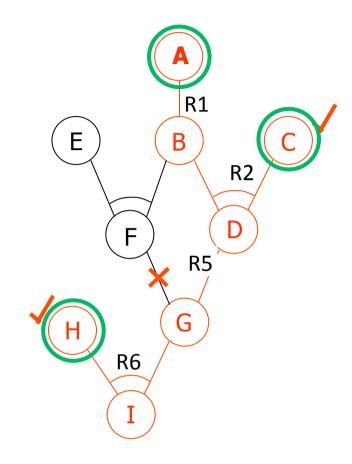
- Backtrack to G. It is unknown. We check if it is supported.
- Rule R5 supports G post D as a goal

- R1: If A then B
- R2: If B and C then D
- R3: If B and E then F
- R4: If F then G
- R5: If D then G
- R6: If G and H then I



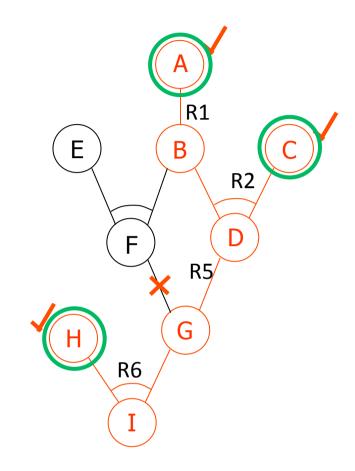
- D is not known to be true. We check it.
- Rule R2 supports D post B and C as a goals

- R1: If A then B
- R2: If B and C then D
- R3: If B and E then F
- R4: If F then G
- R5: If D then G
- R6: If G and H then I



- B is not known to be true, but C is. We check B.
- Rule R1 supports B post A as a goals

- R1: If A then B
- R2: If B and C then D
- R3: If B and E then F
- R4: If F then G
- R5: If D then G
- R6: If G and H then I



- A is known to be true.
- All supports for I found (R1, R2, R5, R6, A, C, H)
- I is proven

Backward Chaining in Jess

- Jess is a forward-chaining inference engine
- It provides mechanisms that "simulates" backward chaining – requires Jess programs to be programmed in a particular form

 Or we can program our own inference engine in Jess that does backward-chaining inference

Backward Chaining

- When do we need backward chaining?
 - Rules need to match particular supporting facts with LHS patterns
 - Other rules are fired **on-demand** to produce these supporting facts
 - E.g.: load additional facts from a database into
 WM

Dynamic situations, new facts keep on coming

Backward Chaining in Jess

- Rules may wait for a particular fact to be asserted
- Jess can help us in such a situation to actively fire other rules that would assert such a fact
 - Declare the corresponding pattern as "backward chaining reactive"
 - Jess will automatically assert a special patternspecific fact
 - We can write rules that react to this special fact and assert the fact our rules waits for

Backward Chaining in Jess

- Declare deftemplates and ordered facts representing your goals for backward chaining
 - (do-backward-chaining <fact/template name>)
- Define rules with patterns ("goal patterns") on the LHS that react to these "reactive" facts or "goals"
- Jess treats these goal patterns in a particular way:
 - For each of these patterns, Jess automatically asserts so-called "goal-seeking" or "trigger" facts. These facts are derived from the goal patterns, but get the prefix "need-" added to their name.

Price check

```
Jess needs a price fact to activate this rule
```

```
(defrule price-check
    (do-price-check ?name)
    (price ?name ?price)
    =>
        (printout t "Price of " ?name " is " ?price crlf)

(reset)
    (assert (do-price-check waffles))
    (do-price-check waffles))
```

- Solution 1:
 - All prices are asserted into WM
- Solution 2:
 - We have to fetch the price from an external database and create price facts only on-demand – how to trigger the database access?

```
| Declare your fact for backward chaining,
| We say: the fact "price" is now
| "backward-chaining reactive"

| (defrule price-check
| (do-price-check ?name)
| Oprice ?name ?price)
| =>
| (printout t "Price of " ?name " is " ?price crlf))
```

```
Declare your fact for backward chaining
(do-backward-chaining price)
(defrule price-check
                                        Jess asserts a fact with prefix "need-"
   (do-price-check ?name)
  (price ?name ?price)
   =>
   (printout t "Price of " ?name " is " ?price crlf))
                                               (need-price ?name ?price)
                                                              "Trigger fact"
WM:
f-0
        (MAIN::initial-fact)
f-1
        (MAIN::do-price-check Fred)
f-2
        (MAIN::need-price Fred nil)
f-3
        (MAIN::do-price-check Ann)
                                              Price set to nil, because we
                                              don't know it yet
f-4
        (MAIN::need-price Ann nil)
f-5
        (MAIN::do-price-check Mary)
f-6
        (MAIN::need-price Mary nil)
```

```
Declare your fact for backward chaining
(do-backward-chaining price)
(defrule price-check
                                             Jess asserts a fact with prefix "need-"
    (do-price-check ?name)
    (price ?name ?price)
    =>
    (printout t "Price of " ?name " is " ?price crlf))
                                                     (need-price ?name ?price)
                                                                      "Trigger fact"
(defrule query-database
                                          We can write rules that react to these facts
    (need-price ?name ?
    =>
    (assert
        (price ?name (queryDB ?name)))
                                 We assume to have implemented a function "queryDB".
```

(printout t "Achieved goal " ?x crlf)

```
(do-backward-chaining goal)
(set-strategy breadth)
(defrule r1 (qoal A) => (assert (goal B)))
(defrule r2 (goal B) (goal C) => (assert (goal D)))
(defrule r3 (goal B) (goal E) => (assert (goal F)))
(defrule r4 (goal F) => (assert (goal G)))
(defrule r5 (goal D) => (assert (goal G)))
(defrule r6 (goal G) (goal H) => (assert (goal I)))
(defrule r6-back (need-goal I) => (assert (proof G) (proof H)))
(defrule r5-back (need-goal G) => (assert (proof D) (proof F)))
(defrule r4-back (need-goal D) => (assert (proof B) (proof C)))
(defrule r3-back (need-goal F) => (assert (proof B) (proof E)))
(defrule r2-back (need-goal F) => (assert (proof B) (proof E)))
(defrule r1-back (need-goal B) => (assert (proof A)))
                                                    (deffacts initialdata
(defrule r7-proof
                                                      (qoal A) (qoal C) (qoal H)
    (proof ?x)
    (qoal ?x)
                                                    (reset)
                                                    (assert (proof I))
   =>
```

(facts)

(run) (facts)

```
f-0
                                                        (MAIN::initial-fact)
f-0
      (MAIN::initial-fact)
                                                 f-1
                                                        (MAIN::need-goal A)
f-1
      (MAIN::need-goal A)
                                                 f-2
                                                        (MAIN::need-goal B)
f-2
      (MAIN::need-goal B)
                                                 f-3
                                                        (MAIN::need-goal F)
f-3
      (MAIN::need-goal F)
                                                 f - 4
                                                        (MAIN::need-goal D)
f-4
      (MAIN::need-goal D)
                                                 f-5
                                                        (MAIN::need-goal G)
f-5
      (MAIN::need-goal G)
                                                 f-6
                                                        (MAIN::goal A)
f-6
      (MAIN::goal A)
                                                 f-7
                                                        (MAIN::goal C)
f-7
      (MAIN::qoal C)
                                                 f-8
                                                        (MAIN::goal H)
f-8
      (MAIN::qoal H)
                                                 f-9
                                                        (MAIN::proof I)
f-9
      (MAIN::proof I)
                                                 f-10
                                                         (MAIN::need-goal I)
f-10
       (MAIN::need-goal I)
                                                 f-11
                                                         (MAIN::proof A)
For a total of 11 facts in module MAIN.
                                                 f-12
                                                         (MAIN::proof B)
Achieved goal A
                                                 f-13
                                                         (MAIN::proof E)
Achieved goal C
                                                 f-14
                                                         (MAIN::need-goal E)
Achieved goal B
                                                 f-15
                                                         (MAIN::proof C)
Achieved goal H
                                                 f-16
                                                         (MAIN::proof D)
Achieved goal D
                                                 f-17
                                                         (MAIN::proof F)
Achieved goal G
                                                 f-18
                                                         (MAIN::goal B)
Achieved goal I
                                                 f-19
                                                         (MAIN::proof G)
                                                 f-20
                                                         (MAIN::proof H)
                                                 f-21
                                                         (MAIN::goal D)
                                                 f-22
```

(MAIN::goal G)

(MAIN::qoal I)

f-23

Summary

Jess Backward chaining

• • •

• Question?

Refraction Avoid Re-activation of a Rule

- Refraction is the act of preventing a rule from re-activating itself
- Declaration in deftemplate

```
(deftemplate person
      (declare (slot-specific TRUE))
      (slot name)
      (slot salary))
```

Declaration in rule: