"Control of Mobile Robot" Project

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Abstract

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2.1.1 Original MIT Racecar Packages

ackermann_cmd_mux	...
ackermann_msgs	...
racecar	...
racecar_control	Contains launch files to load controllers used to manage the motors of the racecar. Also load nodes which dispatch messages to controllers.
racecar_description	Contains a description of the racecar, in terms of models, meshes ecc... It will be used by Gazebo to represent it.
racecar_gazebo	Mainly contains launch scripts used to load all necessary nodes, worlds and other components to open a Gazebo instance with a controllable car.

2.1.2 Added Packages

car_control	Contains nodes used to send commands to the racecar, receive odometry data and control the car autonomously.

Chapter 3

Original System Introduction

Chapter 4

(Our) System Description

Chapter 5

Detailed Package Description