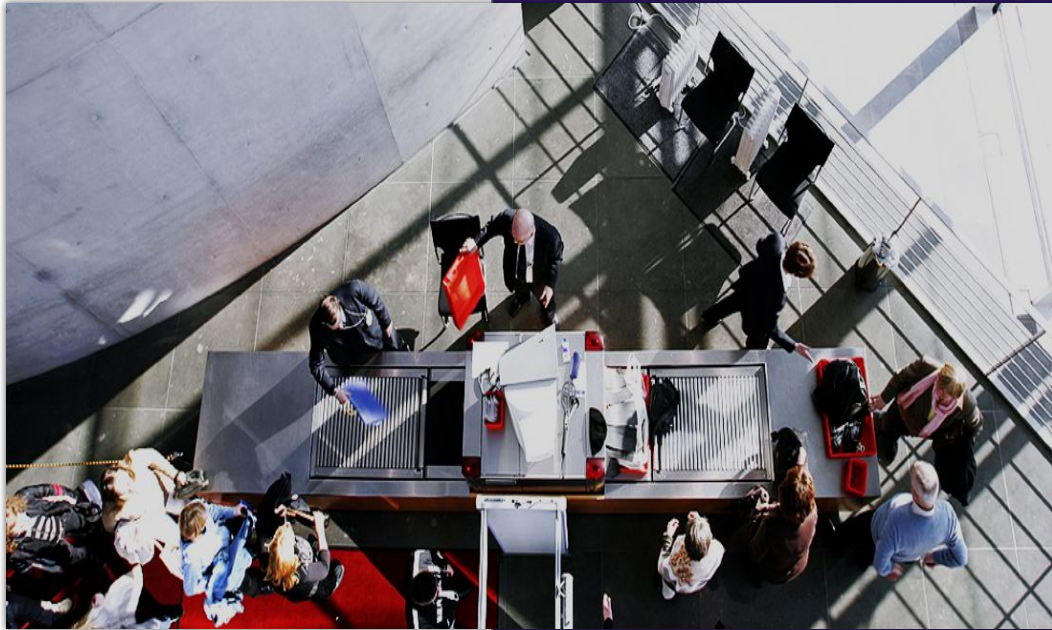


Potentially suspicious items Detection in X-ray Scans with Faster R-CNN

Project by:

- Nikolaos Prevolis
- Stefanos Tzaferis
- Eleftheria Galiatsatou
- Peter Kayiwa



About the Project

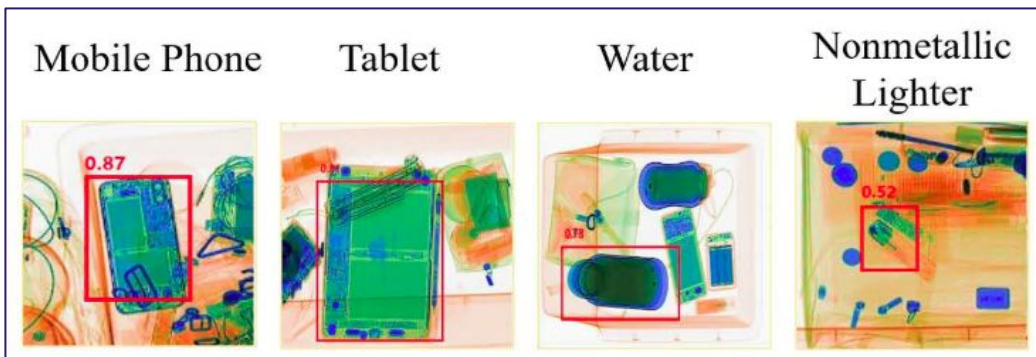
This project aims to help airport security by:

- ➡ **Detecting potentially suspicious items in luggage X-ray scans using a deep learning model.** We trained a Faster R-CNN model to recognize 8 kinds of suspicious items.
- ➡ **Highlighting the location of items clearly on the X-ray image.** The model draws a box around any detected object and labels it, so that a human operator can quickly spot it.
- ➡ **Making the inspection process faster and more consistent.** By helping detect items automatically, the system reduces the chances of human error and speeds up decision-making during security checks.



Dataset

- ➔ Dataset: Hi-Xray – 45,364 annotated X-ray images (36,295 train / 9,069 test).
- ➔ Classes: Portable Charger (1 & 2), Mobile Phone, Laptop, Tablet, Cosmetic, Water, Non-metallic Lighter



The Process

1

Data Preparation

Hi-Xray dataset with 45,000+ annotated X-ray images

2

Pre-Processing

- Resized images to a standard shape.
- Normalized pixel values and converted images to tensors.

3

Model architecture

Built a custom Faster R-CNN object detection model using VGG16,RPN,ROI pooling

4

Training

- Used Stochastic Gradient Descent (SGD) optimizer

5

Evaluation

- using Mean Average Precision (mAP)
- Calculated **AP scores** for each class

6

Interface

simple interface using **OpenCV** and **Gradio**

7

Final output

Complete system that:

- Processes new images
- Flags potentially suspicious items

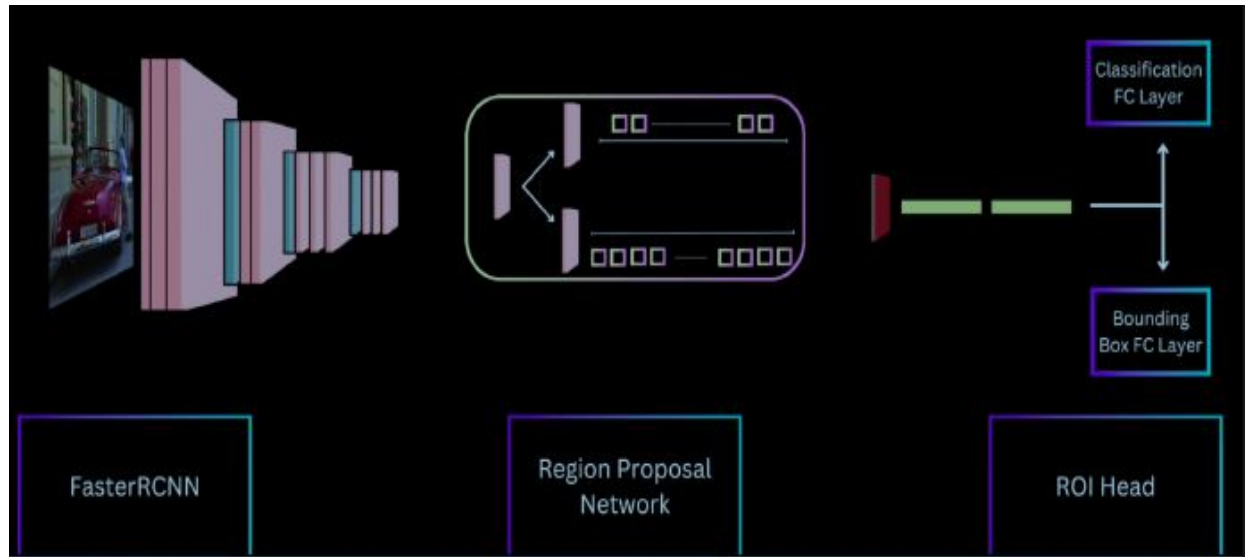
Model Architecture

Based on Faster R-CNN which uses:

- ➡ VGG16 Convolutional Backbone
- ➡ Region Proposal Network (RPN) for anchor-based object proposals
- ➡ RoI Pooling for fixed-size region features
- ➡ Classifier & Regressor heads for object class & bounding boxes

Non-Maximum Suppression (NMS) applied to refine overlapping detections





Model take in an image:

1. The image passes through a CNN (VGG16) that turns it into feature maps.

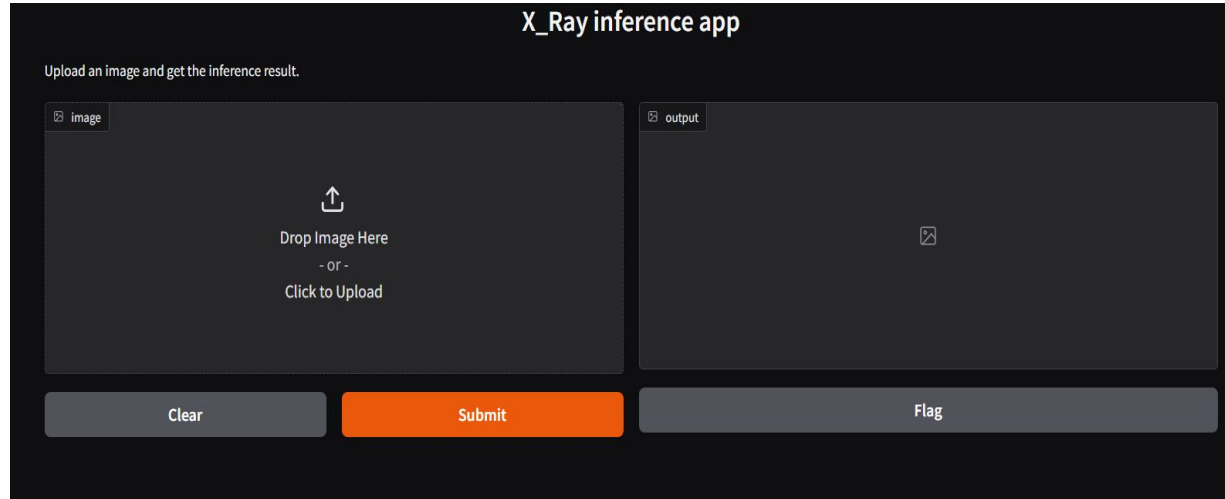
2. The **Region Proposal Network** (RPN) scans those features and suggests regions that might contain objects.

3. These regions are processed by the **RoI Head**, which decides *what* the object is and *where* it is.

4. The model then draws a box and a label on the image.



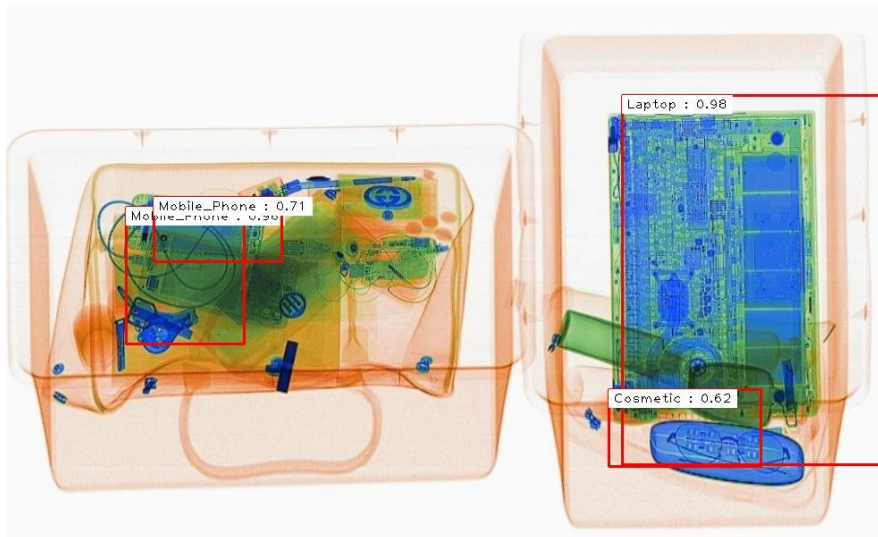
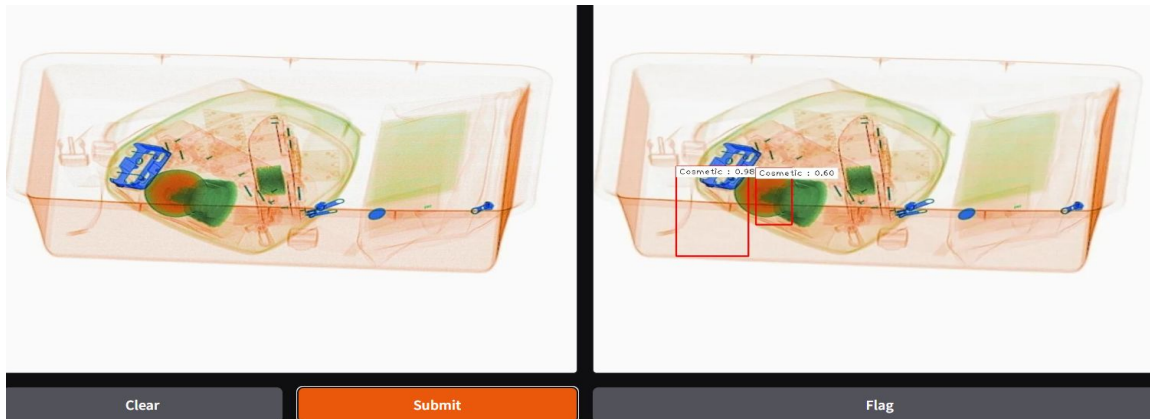
User Interface and Output



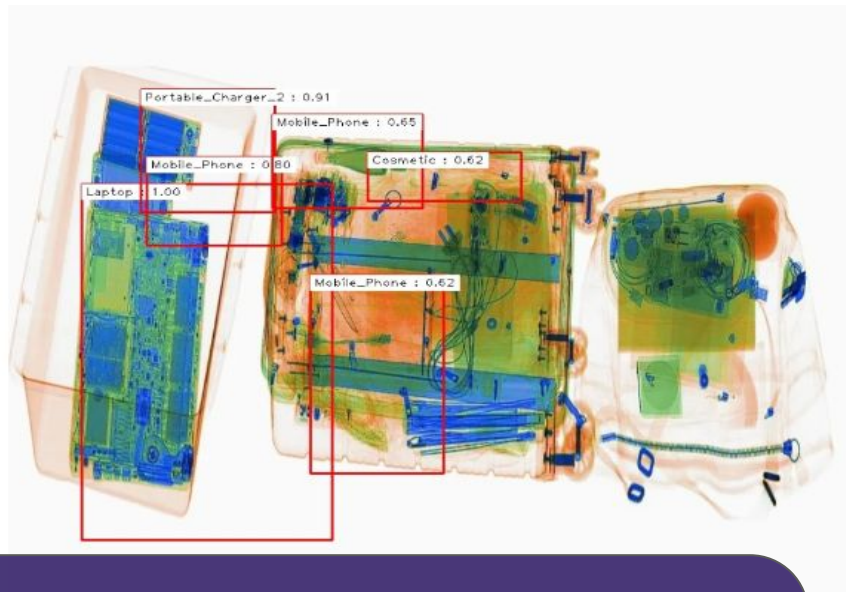
Built a simple interface using **OpenCV** and **Gradio**. User can upload an X-ray image, and the model:

- ➡ Predicts items
- ➡ Draws boxes with labels and confidence scores
- ➡ Saves or displays results in real time





Evaluation



Evaluated the model using **Mean Average Precision (mAP)**

Calculated **AP scores** for each class (Laptop, Phone, etc.)

Best performance on large, distinct objects like **Laptop (AP: 1.0)** and **Portable Charger (0.91)**.



THANK YOU

