

src\main.c

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1
2 // task 3
3
4 #include <stdio.h>
5 #include <avr/io.h> //init libraries
6 #include <util/delay.h>
7
8 #include "usart.h"
9
10 unsigned long power(int n) // same function as task 2
11 {
12     unsigned long p=1;
13     for(int i=1;i<=n;i++)
14     {
15         p*=2;
16     }
17     return p;
18 }
19
20 unsigned int b2d(unsigned long n) // binary to decimal func prototype
21 {
22     unsigned int d=0; // make somewhat big variable for the result
23     for(int i=0;n!=0;i++) // make for loop, set condition to be when n is zero (when all binary
digits have been used)
24     {
25         d=d+(n%10)*power(i); // go by the algorithm for B2D, result is the sum of 2^i * the last
digit in the binary number
26         n=n/10; // slice last digit off binary number
27     }
28     return d; // return variable
29 }
30
31 int main(void) {
32
33     unsigned long input;
34
35     uart_init(); // open the communication to the microcontroller
36     io_redirect(); // redirect input and output to the communication
37
38     while(1) {
39
40         printf("The binary number is...\n");
41         scanf("%lu", &input);
42         printf("The result: %u\n", b2d(input)); //call function while printing number
43
44     }
45
46     return 0;
```

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47 | }  
48 |
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