

src\main.c

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1 // Practice assignment 9, exercise 1
2
3 #include <stdio.h>
4 #include <avr/io.h>
5 #include <util/delay.h>
6
7 //library init
8
9 int main(void) {
10
11
12     DDRC = 0xF0; // set data direction for port C pins, 0-3 as input (i.e. the buttons)
13     PORTC = 0x3F; // set pull-up resistor for port C
14     DDRD = 0xFF; // set data direction for port D, all output
15     PORTD= 0x00; // set output for port D (none)
16
17     while(1) { // start program loop
18         if(!(PINC & 1)) //read pin A0/PC0 by AND'ing it to mask 0x01. (as the Arduino is set to use
pull-up resistors on the buttons, the default state of the buttons is high, and therefore we
need to flip its result in the if statement)
19         {
20             PORTD ^= (1 << PIND4); //set pin with XOR and a mask to turn LED on
21             _delay_ms(250); // dealy
22             PORTD ^= (1 << PIND4); //set LED off
23             PORTD ^= (1 << PIND5); // do that again
24             _delay_ms(250);
25             PORTD ^= (1 << PIND5);
26             PORTD ^= (1 << PIND6);
27             _delay_ms(250);
28             PORTD ^= (1 << PIND6);
29             PORTD ^= (1 << PIND7);
30             _delay_ms(250);
31             PORTD ^= (1 << PIND7);
32         }
33         else if(!((PINC >> 1) & 1)) //same thing, but for a different button and with a different
delay
34         {
35             PORTD ^= (1 << PIND4);
36             _delay_ms(500);
37             PORTD ^= (1 << PIND4);
38             PORTD ^= (1 << PIND5);
39             _delay_ms(500);
40             PORTD ^= (1 << PIND5);
41             PORTD ^= (1 << PIND6);
42             _delay_ms(500);
43             PORTD ^= (1 << PIND6);
44             PORTD ^= (1 << PIND7);
45             _delay_ms(500);
```

```
46     PORTD ^= (1 << PIND7);
47 }
48 else if(!((PINC >> 2) & 1)) //same thing, again
49 {
50     PORTD ^= (1 << PIND4);
51     _delay_ms(1000);
52     PORTD ^= (1 << PIND4);
53     PORTD ^= (1 << PIND5);
54     _delay_ms(1000);
55     PORTD ^= (1 << PIND5);
56     PORTD ^= (1 << PIND6);
57     _delay_ms(1000);
58     PORTD ^= (1 << PIND6);
59     PORTD ^= (1 << PIND7);
60     _delay_ms(1000);
61     PORTD ^= (1 << PIND7);
62 }
63 else if(!((PINC >> 3) & 1)) //same thing, different delay
64 {
65     PORTD ^= (1 << PIND4);
66     _delay_ms(1500);
67     PORTD ^= (1 << PIND4);
68     PORTD ^= (1 << PIND5);
69     _delay_ms(1500);
70     PORTD ^= (1 << PIND5);
71     PORTD ^= (1 << PIND6);
72     _delay_ms(1500);
73     PORTD ^= (1 << PIND6);
74     PORTD ^= (1 << PIND7);
75     _delay_ms(1500);
76     PORTD ^= (1 << PIND7);
77 }
78 else // default state (no buttons)
79 {
80     PORTD ^= (1 << PIND4);
81     _delay_ms(500);
82     PORTD ^= (1 << PIND4);
83     PORTD ^= (1 << PIND5);
84     _delay_ms(500);
85     PORTD ^= (1 << PIND5);
86     PORTD ^= (1 << PIND6);
87     _delay_ms(500);
88     PORTD ^= (1 << PIND6);
89     PORTD ^= (1 << PIND7);
90     _delay_ms(500);
91     PORTD ^= (1 << PIND7);
92 }
93 }
94 return 0;
95 }
```

