

# ML Homework 06: Kernel K-Means and Spectral Clustering

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## ML Homework 06: Kernel K-Means and Spectral Clustering

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## Code with Detailed Explanations

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### Prerequisites

I use Python 3.6 for this implementation based on platform Ubuntu 18.04, with the following packages

- NumPy,
- SciPy `scipy.spatial.distance`, and
- imageio.

### Input Data

Input format is an image of size 100×100. We use `imageio` to read an image file.

```
1 import imageio
2
3
4 # filename = 'image1.png' or 'image2.png'
5 def load_image(filename):
6     img = imageio.imread(filename)
7     return img[..., :3]
```

Since we concern the spatial position of each pixel, we add x-axis value and y-axis as two addition channels to original data.

```
1 import numpy as np
2
```

```

3
4 def add_spatial_channels(img):
5     super_image = np.zeros(img.shape[:2] + (5, ))
6     super_image[..., :3] = img[..., :3]
7
8     indices = np.indices(img.shape[:2])
9     super_image[..., 3] = indices[0]
10    super_image[..., 4] = indices[1]
11    return super_image
12
13
14 # main procedure for loading data
15 # filename = 'image1.png' or 'image2.png'
16 def load_data(filename):
17     img = load_image(filename)
18     data = add_spatial_channels(img)
19     return data

```

Hence for any input data, the first three channels are related to RGB, and the later two channels are related to spatial position.

## Gram Matrix (Kernel Matrix)

According to the equation

$$k(x_i, x_j) = \exp(-\gamma_s \|S(x_i) - S(x_j)\|) \times \exp(-\gamma_c \|C(x_i) - C(x_j)\|),$$

where  $S(x)$  is the spatial information (the last 2 channels) and  $C(x)$  is the color information (the first 3 channels), we build the gram matrix

$$K = \begin{pmatrix} k(x_1, x_1) & \cdots & k(x_1, x_n) \\ \vdots & & \vdots \\ k(x_n, x_1) & \cdots & k(x_n, x_n) \end{pmatrix},$$

where  $n$  is the number of pixels. In our cases  $n = 10000$ .

My default configuration of  $(\gamma_c, \gamma_s)$  is  $(10^{-4}, 10^{-3})$ .

```

1 from scipy.spatial.distance import cdist
2
3
4 def gram_matrix(data, gamma_c=1e-4, gamma_s=1e-3):
5     size = data.shape[0]
6     matrix = np.zeros((size, size))
7
8     color_distance = cdist(data[:, :3], data[:, :3], metric='sqeuclidean')
9     spatial_distance = cdist(data[:, 3:], data[:, 3:], metric='sqeuclidean')
10
11    color_kernel = np.exp(-gamma_c * color_distance)
12    spatial_distance = np.exp(-gamma_s * spatial_distance)
13
14    matrix = color_kernel * spatial_distance
15    return matrix

```

# [Part 1] Clustering Procedure

## Kernel K-Means

Suppose we obtain an initial label for each data point (will be discussed in the third part).

```
1 class KernelKMeans(object):
2     def __init__(self, data, k, gram=None, init='random', tol=1e-3):
3         self.data = data
4         self.size = data.shape[0]
5         self.k = k
6         self.gram = gram_matrix(data) if gram is None else gram
7         self.label = self._get_init_label(init)
8         self.label_history = [self.label]
9         self.tol = tol
```

Then for each iteration <sup>1</sup>,

1. We calculate the distance of each data points  $x_i$  and each cluster mean in feature space using the equation

$$k(x_i, x_i) - \frac{2}{|C_k|} \sum_{j \in C_k} k(x_i, x_j) + \frac{1}{|C_k|^2} \sum_{p \in C_k} \sum_{q \in C_k} k(x_p, x_q),$$

where  $C_k = \{i | x_i \text{ belongs to cluster } k\}$ .

```
1 class KernelKMeans(object):
2     def _calc_feature_space_distance(self, label_matrix=None):
3         if label_matrix is None:
4             k = self.k
5             label_matrix = self.label_matrix
6             label_count = self.label_count
7         else:
8             k = label_matrix.shape[1]
9             label_count = label_matrix.sum(axis=0)
10        assert np.all(label_count > 0)
11
12        # calculate distance in feature space using equation (2) in
13        # https://www.cs.utexas.edu/users/inderjit/public\_papers/kdd\_spectral\_kernelmeans.pdf
14        distance = np.zeros((self.size, k))
15        distance += np.diag(self.gram)[:, np.newaxis]
16
17        distance -= 2 * (self.gram @ label_matrix) / label_count
18
19        scale = 1 / label_count**2
20        distance += np.diag(label_matrix.T @ self.gram @ label_matrix) *
21        scale
22        return distance
```

2. For each data point, we choose the minimum distance of them and assign such cluster to the data point **line 8**.
3. Check if the procedure converge, else we back to step 1 and perform the next iteration **line 11-16**.

We measure the convergence by the value

$$\frac{|\{i : x_i \text{ change another cluster though this iteration}\}|}{n},$$

and the convergence rate in my implementation is  $10^{-3}$ .

```
1 class KernelKMeans(object):
2     def train(self, max_iter=100):
3         n_iter = 0
4         while n_iter < max_iter:
5             n_iter += 1
6             logger.debug('train iter [%d/%d]' % (n_iter, max_iter))
7             distance = self._calc_feature_space_distance()
8             label = np.argmin(distance, axis=1)
9             self.label_history.append(label)
10
11             err = len(np.where(self.label != label)[0]) / self.size
12             logger.debug('err: %f' % err)
13             if err < self.tol:
14                 logger.debug('training terminated due to convergence')
15                 self.label = label
16                 break
17
18             self.label = label
```

Note that we do not maintain mean of each cluster in feature space (especially for RBF kernel, the dimension of its feature space is infinity).

After the clustering algorithm, we calculate mean of each cluster and pick the color part for visualization.

```
1 class KernelKMeans(object):
2     def visualize_as_gif(self, image_shape, filename):
3         label_color = (self.label_matrix.T @ self.data)[: , :3]
4         label_color /= self.label_count[: , np.newaxis]
5         label_color = label_color.astype(np.uint8)
6         with imageio.get_writer(filename, mode='I') as writer:
7             for label in self.label_history:
8                 image = label_color[label.reshape(image_shape)]
9                 writer.append_data(image)
10
11     def visualize_as_image(self, image_shape, filename):
12         label_color = (self.label_matrix.T @ self.data)[: , :3]
13         label_color /= self.label_count[: , np.newaxis]
14         label_color = label_color.astype(np.uint8)
15
16         image = label_color[self.label.reshape(image_shape)]
17         imageio.imwrite(filename, image)
```

Finally the main function is shown below:

```
1 if __name__ == '__main__':
2     # fixed random seed for debugging
3     np.random.seed(0)
4
```

```

5     parser = argparse.ArgumentParser()
6     parser.add_argument('filename', type=str, help='path to image file')
7     parser.add_argument('k', type=int, help='number of clusters')
8     parser.add_argument('init', type=str, help='methods of initialization')
9     parser.add_argument('--debug',
10                          action='store_true',
11                          help='show debug message')
12
13     args = parser.parse_args()
14     if args.debug:
15         logger.setLevel(logging.DEBUG)
16     filename = args.filename
17     k = args.k
18     init = args.init
19
20     raw_filename = osp.splitext(filename)[0]
21     gif_filename = 'images/%s_%d_%s_kkm_result.gif' % (raw_filename, k,
22 init)
23     png_filename = 'images/%s_%d_%s_kkm_result.png' % (raw_filename, k,
24 init)
25
26     data = load_data(filename)
27     logger.debug('calculating gram matrix')
28     gram = gram_matrix(data.reshape(-1, 5))
29
30     logger.debug('initializing kernel k-means')
31     kkm = kernelKMeans(data.reshape(-1, 5), k, gram, init)
32
33     kkm.train()
34
35     logger.debug('visualizing result')
36     kkm.visualize_as_gif(data.shape[:2], gif_filename)
37     kkm.visualize_as_image(data.shape[:2], png_filename)

```

## Spectral Clustering

According to <sup>2</sup>, first we calculate Graph Laplacian  $L$  with the equation

$$L = D - K,$$

where

$$D = \begin{pmatrix} \sum_j k(x_j, x_1) & & & \\ & \sum_j k(x_j, x_2) & & \\ & & \ddots & \\ & & & \sum_j k(x_j, x_n) \end{pmatrix}.$$

Then we solve the eigenvalue problem on different matrices:

- $L_{\text{ratio}} = L$  for unnormalized (ratio-cut) case,
- $L_{\text{normalized}} = D^{-1/2} L D^{-1/2}$  for normalized case.

```

1 class SpectralClustering(object):
2     def _calc_graph_laplacian(self, mode='unnormalized'):
3         graph_laplacian = self.degree_matrix - self.gram
4         if mode == 'unnormalized':
5             pass
6         elif mode == 'normalized':
7             d = np.diag(1 / np.sqrt(np.diag(self.degree_matrix)))
8             graph_laplacian = d @ graph_laplacian @ d
9         else:
10            raise NotImplementedError("Unknown clustering mode")
11
12        return graph_laplacian

```

We will obtain a set of ordered nonzero eigenvalues  $\Lambda = \{\lambda_1, \dots, \lambda_m\}$  and corresponding eigenvectors  $V = \{v_1, \dots, v_m\}$  with  $m \leq n$ . Later we define the feature matrix

$$U = (v_1 \ v_2 \ \dots \ v_k) \in \mathbb{R}^{n \times k},$$

and the feature mapping  $\phi(x_i) = Ue_i$ .

$e_i$  is the  $i$ -th vector of the standard basis of  $\mathbb{R}^n$ .

Afterward we perform the standard K-Means algorithm to figure out the clustering result.

```

1 class SpectralClustering(object):
2     def __init__(self,
3                 gram,
4                 k,
5                 kmeans_init='random',
6                 mode='unnormalized',
7                 tol=1e-3):
8         self.gram = gram
9         self.size = gram.shape[0]
10        self.k = k
11        self.kmeans_init = kmeans_init
12        self.tol = tol
13        self.degree_matrix = np.diag(gram.sum(axis=1))
14        self.graph_laplacian = self._calc_graph_laplacian(mode)
15        self.features = np.zeros((self.size, self.k))
16
17        self.eigvals = None
18        self.eigvecs = None
19
20        self.km = None
21
22        @property
23        def label(self):
24            return self.km.label
25
26        @property
27        def label_history(self):
28            return self.km.label_history
29
30        def train(self):
31            # solve the eigenvalue problem
32            if self.eigvals is None or self.eigvecs is None:
33                eigvals, eigvecs = np.linalg.eig(self.graph_laplacian)

```

```

34         self.eigvals = eigvals
35         self.eigvecs = eigvecs
36
37         # pick up the first k nonzero eigenvalues with ones corresponding
38         # eigenvectors, and generate the feature mapping
39         indices = np.argsort(self.eigvals)
40         self.eigvals = self.eigvals[indices]
41         self.eigvecs = self.eigvecs[:, indices].real
42         base_idx = np.where(self.eigvals > 1e-8)[0][0]
43         self.features = self.eigvecs[:, base_idx:base_idx + self.k]
44
45         # trigger the K-Means algorithm
46         self.km = KMeans(self.features, self.k, self.kmeans_init, self.tol)
47         self.km.train()

```

The K-Means algorithm is similar to the Kernel K-Means while the Euclidean distance is used and we have to maintain the mean of each cluster (hence we have the maximisation step).

```

1  class KMeans(object):
2      def __init__(self, data, k, init='random', tol=1e-3):
3          self.data = data
4          self.size = data.shape[0]
5          self.degree = data.shape[1]
6          self.k = k
7          self.cluster_means = self._get_init_cluster_means(init)
8          self.label = None
9          self.label_history = []
10         self.tol = tol
11
12         @property
13         def label_matrix(self):
14             matrix = np.zeros((self.size, self.k), dtype=int)
15             matrix[np.arange(self.size), self.label] = 1
16             return matrix
17
18         @property
19         def label_count(self):
20             return self.label_matrix.sum(axis=0)
21
22         def _expectation_step(self):
23             distance = np.zeros((self.size, self.k))
24             for i in range(self.k):
25                 diff = self.data - self.cluster_means[i]
26                 distance[:, i] = np.linalg.norm(diff, axis=1)
27             label = np.argmin(distance, axis=1)
28             return label
29
30         def _maximisation_step(self, label):
31             cluster_means = np.zeros((self.k, self.degree))
32             for i in range(self.k):
33                 indices = np.argwhere(label == i).flatten()
34                 cluster_means[i] = np.mean(self.data[indices], axis=0)
35             return cluster_means
36
37         def train(self, max_iter=100):
38             n_iter = 0
39             while n_iter < max_iter:

```

```

40         n_iter += 1
41         logger.debug('train iter [%d/%d]' % (n_iter, max_iter))
42         label = self._expectation_step()
43         cluster_means = self._maximiation_step(label)
44
45         # handling first iteration
46         if self.label is None:
47             self.label = label
48             self.cluster_means = cluster_means
49             self.label_history.append(label)
50             continue
51
52         # check if converge
53         err = len(np.where(self.label != label)[0]) / self.size
54         logger.debug('err: %f' % err)
55         if err < self.tol:
56             logger.debug('training terminated due to convergence')
57             self.label = label
58             self.cluster_means = cluster_means
59             self.label_history.append(label)
60             break
61
62         self.label = label
63         self.cluster_means = cluster_means
64         self.label_history.append(label)

```

The visualization method of Spectral Clustering is same as the method used in Kernel K-Means.

Finally the main function is shown below:

```

1  if __name__ == '__main__':
2      # fixed random seed for debugging
3      np.random.seed(0)
4
5      parser = argparse.ArgumentParser()
6      parser.add_argument('filename', type=str, help='path to image file')
7      parser.add_argument('k', type=int, help='number of clusters')
8      parser.add_argument('mode', type=str, help='clustering mode')
9      parser.add_argument('init', type=str, help='methods of initialization')
10     parser.add_argument('--debug',
11                          action='store_true',
12                          help='show debug message')
13     parser.add_argument('--cache',
14                          action='store_true',
15                          help='use cached eigenvalues and eigenvectors')
16     parser.add_argument('--save-cache',
17                          action='store_true',
18                          help='use cached eigenvalues and eigenvectors')
19
20     args = parser.parse_args()
21     if args.debug:
22         logger.setLevel(logging.DEBUG)
23     filename = args.filename
24     k = args.k
25     mode = args.mode
26     init = args.init
27

```



```

28     raw_filename = osp.splitext(filename)[0]
29     gif_filename = 'images/%s_%d_%s_%s_sc_result.gif' % (raw_filename, k,
init,
30                                     mode)
31     png_filename = 'images/%s_%d_%s_%s_sc_result.png' % (raw_filename, k,
init,
32                                     mode)
33     eig_filename = 'images/%s_%d_%s_%s_sc_eig_result.png' % (raw_filename,
k,
34                                     init, mode)
35     cache_eigvals_filename = '%s.%s.eigvals.npy' % (raw_filename, mode)
36     cache_eigvecs_filename = '%s.%s.eigvecs.npy' % (raw_filename, mode)
37
38     data = load_data(filename)
39     logger.debug('calculating gram matrix')
40     gram = gram_matrix(data.reshape(-1, 5))
41
42     logger.debug('initializing spectral clustering')
43     sc = SpectralClustering(gram, k, init, mode)
44
45     if args.cache:
46         sc.eigvals = np.load(cache_eigvals_filename)
47         sc.eigvecs = np.load(cache_eigvecs_filename)
48
49     logger.debug('trigger clustering')
50     sc.train()
51
52     sc.visualize_as_gif(data[... , :3], gif_filename)
53     sc.visualize_as_image(data[... , :3], png_filename)
54     sc.visualize_eigenspace_as_image(eig_filename)
55
56     if args.save_cache:
57         np.save(cache_eigvals_filename, sc.eigvals)
58         np.save(cache_eigvecs_filename, sc.eigvecs)

```

- Since the computation cost of eigenvalue problem is heavy, we compute eigenvalues and eigenvectors in the first run and save as `.npy` files for caching. You can add `--save-cache` for the first computation and add `--cache` for later computation.
- We will discuss the visualization of eigenspace (line 54) in part 4.

## [Part 2] Change of $k$

In part one, the number of clusters is generalized, so we are able to change  $k$  when initializing a new instance of `KernelKMeans` or `SpectralClustering`.

The task trying different  $k$  is written outside the file.

```

1  import subprocess
2
3
4  # Kernel K-Means
5  for img in ['image1.png', 'image2.png']:
6      for init in ['random', 'k-means++']:
7          for k in map(str, [2, 3, 4]):
8              cmd = ([
9                  'python3', 'HW06_KernelKMeans.py', img, k, init, '--debug'
10                 ])

```

```

11         subprocess.check_output(cmd)
12
13     # Spectral Clustering
14     for img in ['image1.png', 'image2.png']:
15         for init in ['random', 'k-means++']:
16             for gl in ['unnormalized', 'normalized']:
17                 for k in map(str, [2, 3, 4]):
18                     cmd = ([
19                         'python3', 'HW06_SpectralClustering.py', img, k, gl,
init,
20                         '--debug'
21                     ])
22                     subprocess.check_output(cmd)

```

## [Part 3] Initialization of K-Means

In addition to random initialization, I implement the K-Means++ algorithm<sup>3</sup> in the two clustering methods.

The classical procedure is shown as follow:

1. Choose an initial center  $c_1$  uniformly at random from data points.
2. Choose the next center  $c_i = x'$  from data points with probability

$$\frac{D(x')^2}{\sum_x D(x)^2},$$

where  $D(x)$  is the shortest distance from a data point  $x$  to the closest center we have already chosen.

3. Repeat step 2 until we have chosen a total of  $k$  centers.

```

1  class KMeans(object):
2      def _get_init_cluster_means(self, init='random'):
3          cluster_means = np.zeros((self.k, self.degree))
4          if init == 'random':
5              logger.debug('use random initialization for k-means')
6              indices = np.random.randint(0, self.size, self.k)
7              cluster_means[:] = self.data[indices]
8          elif init == 'k-means++':
9              logger.debug('use k-means++ initialization for k-means')
10             idx = np.random.randint(0, self.size, 1)[0]
11             cluster_means[0] = self.data[idx]
12             for i in range(1, self.k):
13                 distance = np.zeros((self.size, i))
14                 for j in range(i):
15                     diff = self.data - cluster_means[j]
16                     distance[:, j] = np.sum(diff**2, axis=1)
17                 distance = np.min(distance, axis=1)
18                 distance = distance / np.sum(distance)
19                 print(distance)
20                 idx = np.random.choice(np.arange(self.size), p=distance)
21                 # idx = np.argmax(distance)
22                 cluster_means[i] = self.data[idx]
23             else:
24                 raise NotImplementedError("Unknown init type")
25
26         return cluster_means

```

As for Kernel K-Means, we also choose  $k$  centers. Note that

- the definition of distance is same as the one defined in Kernel K-Means;
- I will perform one step iteration so as to assign labels to all data points.

```
1 class KernelKMeans(object):
2     def _get_init_label(self, init='random'):
3         if init == 'random':
4             return np.random.randint(0, self.k, self.size, dtype=int)
5         elif init == 'k-means++':
6             label = -1 * np.ones(self.size)
7             label = label.astype(int)
8             # randomly select a data point (as the center of the first
cluster)
9             label[np.random.randint(0, self.size, 1)] = 0
10
11             # choose k-1 centers
12             for i in range(1, self.k):
13                 label_matrix = np.zeros((self.size, i), dtype=int)
14                 label_matrix[np.arange(self.size), label] = 1
15                 label_matrix[np.argwhere(label == -1).flatten()] = 0
16
17                 distance = self._calc_feature_space_distance(label_matrix)
18                 distance = np.min(distance, axis=1)
19                 distance = distance / np.sum(distance)
20
21                 idx = np.random.choice(np.arange(self.size), p=distance)
22                 label[idx] = i
23
24             # filling labels
25             label_matrix = np.zeros((self.size, self.k), dtype=int)
26             label_matrix[np.arange(self.size), label] = 1
27             label_matrix[np.argwhere(label == -1).flatten()] = 0
28
29             distance = self._calc_feature_space_distance(label_matrix)
30             label = np.argmin(distance, axis=1)
31
32             return label
```

## [Part 4] Eigenspace of Graph Laplacian

We consider the relationship of eigenspace of graph Laplacian and clustering result. For my visualization, the coordinate in subspace of the eigenspace is computed by  $U^T e_i$ , where  $e_i$  is the  $i$ -th vector of the standard basis of  $\mathbb{R}^n$ .

```
1 class SpectralClustering(object):
2     def visualize_eigenspace_as_image(self, filename):
3         plt.figure()
4         plt.xlabel('first non-null eigenvector')
5         plt.ylabel('second non-null eigenvector')
6         coord = self.features[:, :2]
7         for i in range(self.k):
8             indices = np.argwhere(self.label == i).flatten()
9             plt.scatter(coord[indices, 0], coord[indices, 1])
10        plt.savefig(filename, dpi=500)
```

# Experiments Settings, Results, and Discussion



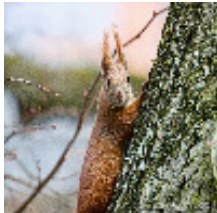
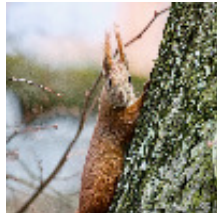
















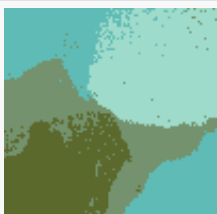

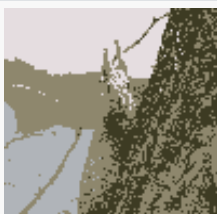
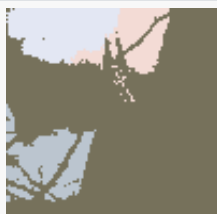


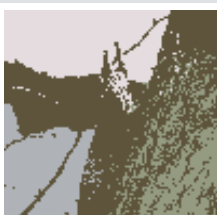
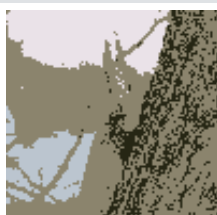
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I use two settings of  $(\gamma_c, \gamma_s)$  to see the differences between them. Overall the experiment results with different settings are shown below.

## Kernel K-Means

Here are some observations:

1. The higher value of  $\gamma_c$  means that we have more concern of color information. In experiment results (especially for `image1.png`) the clustering result is more sparse than the other one (there are some "salt and pepper" in the case  $\gamma_c = 10^{-3}$ ).
2. Different initialization methods cannot guarantee the convergence speed, but the results using K-Means++ are in general more reasonable than the results using random initialization.
3. For my visualization, colors are the means of clusters. You can see that especially for  $(\gamma_c, \gamma_s) = (10^{-3}, 10^{-3})$ , contrast of the results using K-Means++ are higher than the one of the results using random initialization.

	image1.png ( $\gamma_c, \gamma_s$ ) = ( $10^{-4}, 10^{-3}$ )	image1.png ( $\gamma_c, \gamma_s$ ) = ( $10^{-3}, 10^{-3}$ )	image2.png ( $\gamma_c, \gamma_s$ ) = ( $10^{-4}, 10^{-3}$ )	image2.png ( $\gamma_c, \gamma_s$ ) = ( $10^{-3}, 10^{-3}$ )
Original image				
2 Clusters (random)				
2 Clusters (K-Means++)				
3 Clusters (random)				
3 Clusters (K-Means++)				
4 Clusters (random)				
4 Clusters (K-Means++)				

Click the result image to see the GIF file (make sure that folder `images33` and `images43` are preserved).

## Spectral Clustering

Here are some observations:

1. Same as Kernel K-Means, the higher value of  $\gamma_c$  means that we have more concern of color information. In experiment results (especially for `image1.png`) the clustering result is more sparse than the other one (there are some "salt and pepper" in the case  $\gamma_c = 10^{-3}$ ).

2. Without normalization of Graph Laplacian, one may occasionally trap into an unbalanced result (see Ratio-Cut in 3 and 4 clusters with K-Means++ algorithm).
3. Due to K-Means algorithm, we can see data points having same label cluster in the eigenspace of Graph Laplacian. Note that for ratio-cut cases we can see unbalanced numerical difference of coordinates of the first and the second non-null eigenvectors.



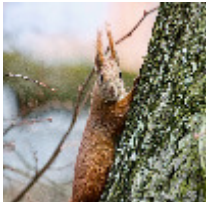
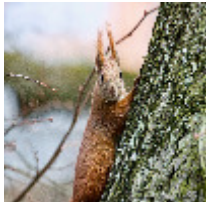



















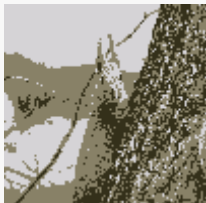



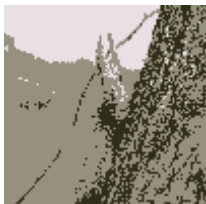



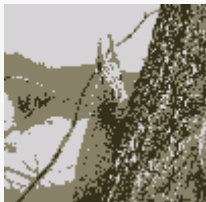






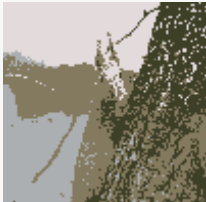


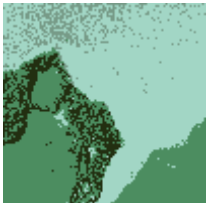





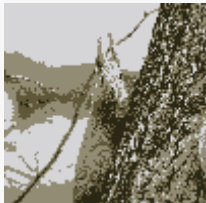




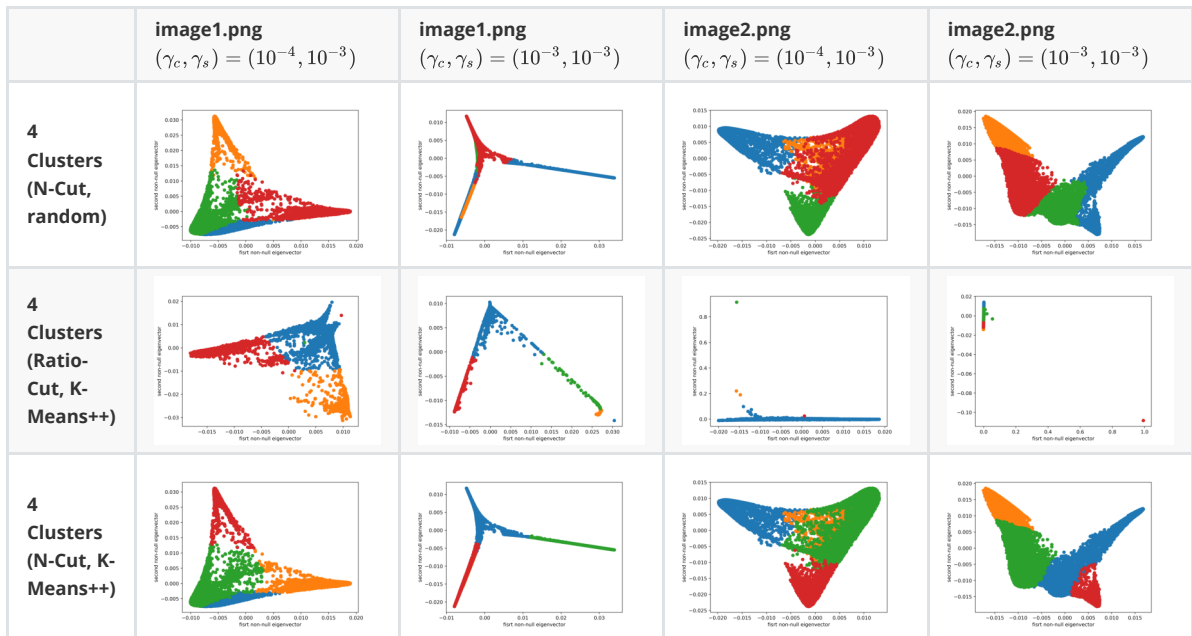
	image1.png $(\gamma_c, \gamma_s) = (10^{-4}, 10^{-3})$	image1.png $(\gamma_c, \gamma_s) = (10^{-3}, 10^{-3})$	image2.png $(\gamma_c, \gamma_s) = (10^{-4}, 10^{-3})$	image2.png $(\gamma_c, \gamma_s) = (10^{-3}, 10^{-3})$
Original image				
2 Clusters (Ratio-Cut, random)				
2 Clusters (N-Cut, random)				
2 Clusters (Ratio-Cut, K-Means++)				
2 Clusters (N-Cut, K-Means++)				
3 Clusters (Ratio-Cut, random)				
3 Clusters (N-Cut, random)				
3 Clusters (Ratio-Cut, K-Means++)				
3 Clusters (N-Cut, K-Means++)				

	image1.png $(\gamma_c, \gamma_s) = (10^{-4}, 10^{-3})$	image1.png $(\gamma_c, \gamma_s) = (10^{-3}, 10^{-3})$	image2.png $(\gamma_c, \gamma_s) = (10^{-4}, 10^{-3})$	image2.png $(\gamma_c, \gamma_s) = (10^{-3}, 10^{-3})$
4 Clusters (Ratio-Cut, random)				
4 Clusters (N-Cut, random)				
4 Clusters (Ratio-Cut, K-Means++)				
4 Clusters (N-Cut, K-Means++)				

Click the result image to see the GIF file (make sure that folder `images33` and `images43` are preserved).



	image1.png $(\gamma_c, \gamma_s) = (10^{-4}, 10^{-3})$	image1.png $(\gamma_c, \gamma_s) = (10^{-3}, 10^{-3})$	image2.png $(\gamma_c, \gamma_s) = (10^{-4}, 10^{-3})$	image2.png $(\gamma_c, \gamma_s) = (10^{-3}, 10^{-3})$
Original image				
2 Clusters (Ratio-Cut, random)				
2 Clusters (N-Cut, random)				
2 Clusters (Ratio-Cut, K-Means++)				
2 Clusters (N-Cut, K-Means++)				
3 Clusters (Ratio-Cut, random)				
3 Clusters (N-Cut, random)				
3 Clusters (Ratio-Cut, K-Means++)				
3 Clusters (N-Cut, K-Means++)				
4 Clusters (Ratio-Cut, random)				



## References

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3. Arthur, D., & Vassilvitskii, S. (2006). *k-means++: The advantages of careful seeding*. Stanford. [↗](#)