1 Problem

$$\min_{x} f(x)$$

$$g(x) \le 0$$

$$h(x) = 0$$

2 Algorithm

Algorithm 1 Filter Line Search

```
1:
2:
3:
4:
         procedure FILTER LINE SEARCH
          loop:
                while True do ineq \leftarrow m_g(x^k)
  5:
                      active \leftarrow [i]: m_g(x^k)_i \geq -\tau
                      c \leftarrow [m_h(x^k); m_g(x^k)_{active}]A \leftarrow [\nabla m_h(x^k); \nabla m_g(x^k)_{active}]
  6:
  7:
                       G \leftarrow \nabla m_f(x^k)
  8:
  9:
                       H \leftarrow \nabla^2 f(x^k)
10:
                       \theta \leftarrow \theta(x^{\vec{k}})
11:
                      if check stopping criteria with model functions at \boldsymbol{x}^k then
12:
13:
                            \begin{array}{ccc} \text{if} & r > \tau \text{ then} \\ & r \leftarrow \gamma_{dec} r \end{array}
14:
                                   improve model
                       continue.
return success
KKT \leftarrow [H, A^T; A, 0]
18:
19:
20:
                       rhs \leftarrow [G; c]
                       if cond(KKT) > maxconidition then
                             restore feasibility
                      continue  [d; \_] = -KKT^{-1}rhs   \alpha_{min} = \text{compute minimum alpha} 
21: 22: 23: 24: 25: 26: 27: 28: 30: 31: 32: 33: 34: 42: 44: 44:
                       \alpha = 1
                       \alpha = 1
accept = False
while notaccept do
                             m \leftarrow \alpha G^T d
Variant: clip to trust region
                             if \alpha < \alpha_{min} then
                                   restore feasibility
                             \begin{aligned} & \textbf{goto} \ loop \\ & x_{new} = x + \alpha * d \\ & \theta_{new} = \theta(x_{new}) \end{aligned}
                             f_{new} = m_f(x_{new})
                             if new inequality constraint becomes active then
                             plot model
                             if [f_n ew, \theta_{new}] is dominated then
                                   \alpha = \tau \alpha continue
                              ftype \leftarrow m < 0 \wedge (-m)^s f \alpha^{1-s} f > \delta \theta^s \theta
                              \  \, \textbf{if} \,\, ftype \,\, \textbf{then} \,\,
                                   if f_{new} \leq f + \eta_f m then
45:
46:
47:
48:
49:
50:
51:
52:
53:
55:
56:
                                         accept \leftarrow True
                                   else
                                         \alpha = \tau \alpha
continue
                             else
                                   check equation 8
                      \alpha = \tau \alpha
if accept then
                             rho \leftarrow compute rho
                             if rho is small then
if ||x_new - center|| < \frac{1}{2}r then
57:
58:
59:
60:
61:
62:
63:
                                         r \leftarrow \gamma_{dec} r
                                   \mathbf{else} \\ r \leftarrow \gamma_{inc} r
                                   improve the model
                             else if rho is medium then if lambda poised then
                                         r \leftarrow \gamma_{dec} r
64:
                                   improve the model
65:
66:
                            \begin{aligned} &\textbf{elsecontinue} \\ &\textbf{if } (1-\gamma_{\theta})*\theta_{new} > tol \textbf{ then } \textbf{add to filter: } [f_{new}-\gamma_{f}\theta_{new}, (1-constants.gamma_{t}heta)\theta_{new}] \end{aligned}
                            x^{k+1} \leftarrow x_{new} construct model functions m_f, m_h, m_g
67:
69:
                 i \leftarrow i + \max(\mathit{delta}_1(\mathit{string}(i)), \mathit{delta}_2(j)).
70:
                goto top.
```