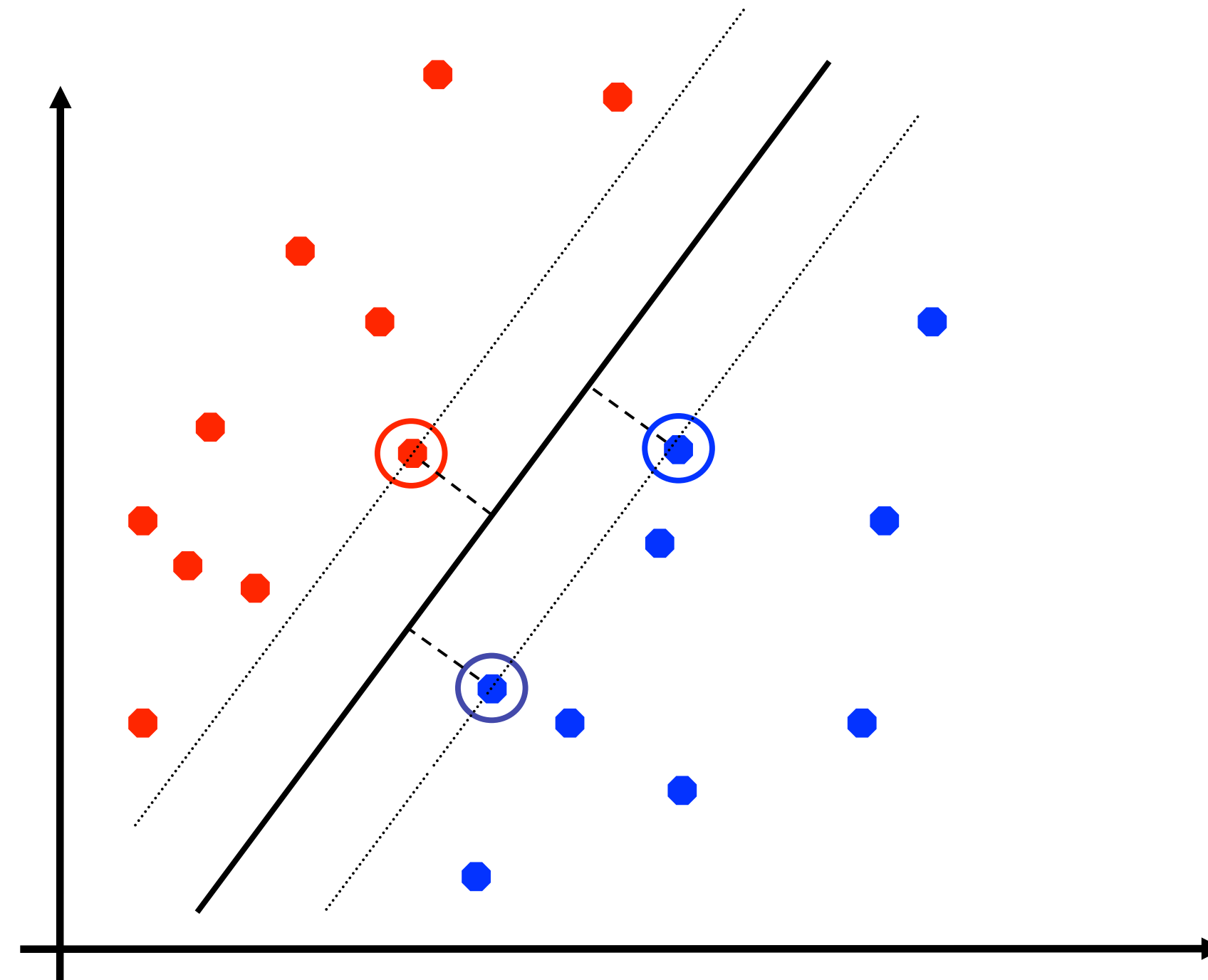


Today

- Last time
 - Towards support vector machines
 - Perceptron algorithm
 - Optimal margin classifiers
- Today
 - Dual formulation of SVMs
 - Bishop Chapter 7
 - Hastie Chapter 12
 - <http://cs229.stanford.edu/notes/cs229-notes3.pdf>
- Announcements
 - Blended lab session on Wed (make sure you know your seat number)
 - Homework 1 due on Wed *before class*

Support vector machines

- SVMs (Vapnik, 1990's) choose the linear separator with the **largest margin**



- Good according to intuition, theory, practice

Notation

- Class labels $y \in \{-1, 1\}$
- Parametrize with w, b rather than θ (intercept treated separately)

$$h_{\theta}(x) = g(w^T x + b)$$

with

$$g(z) = \begin{cases} 1, & z \geq 0 \\ 0, & z < 0 \end{cases}$$

Functional margin

- Define functional margin of training sample $(x^{(i)}, y^{(i)})$ w.r.t. (w, b) as

$$\hat{\gamma}^{(i)} = y^{(i)}(w^T x + b)$$

- If $y^{(i)} = 1$, then need $w^T x + b \gg 0$ for $\hat{\gamma}^{(i)}$ large
- If $y^{(i)} = -1$, then need $w^T x + b \ll 0$ for $\hat{\gamma}^{(i)}$ large
- Holds $y^{(i)}(w^T x + b) > 0$, then prediction correct
- Large functional margin = confident + correct prediction
- Scaling

- For our choice $g(z) = 1 \text{ if } z \geq 0 : 0$ have

$$g(2w^T x + 2b) = g(w^T x + b)$$

which means that h_θ is invariant under scaling even though $\hat{\gamma}^{(i)}$ is not

—> normalize by enforcing $\|w\| = 1$

Geometric margin

- Geometric margin of (w, b)

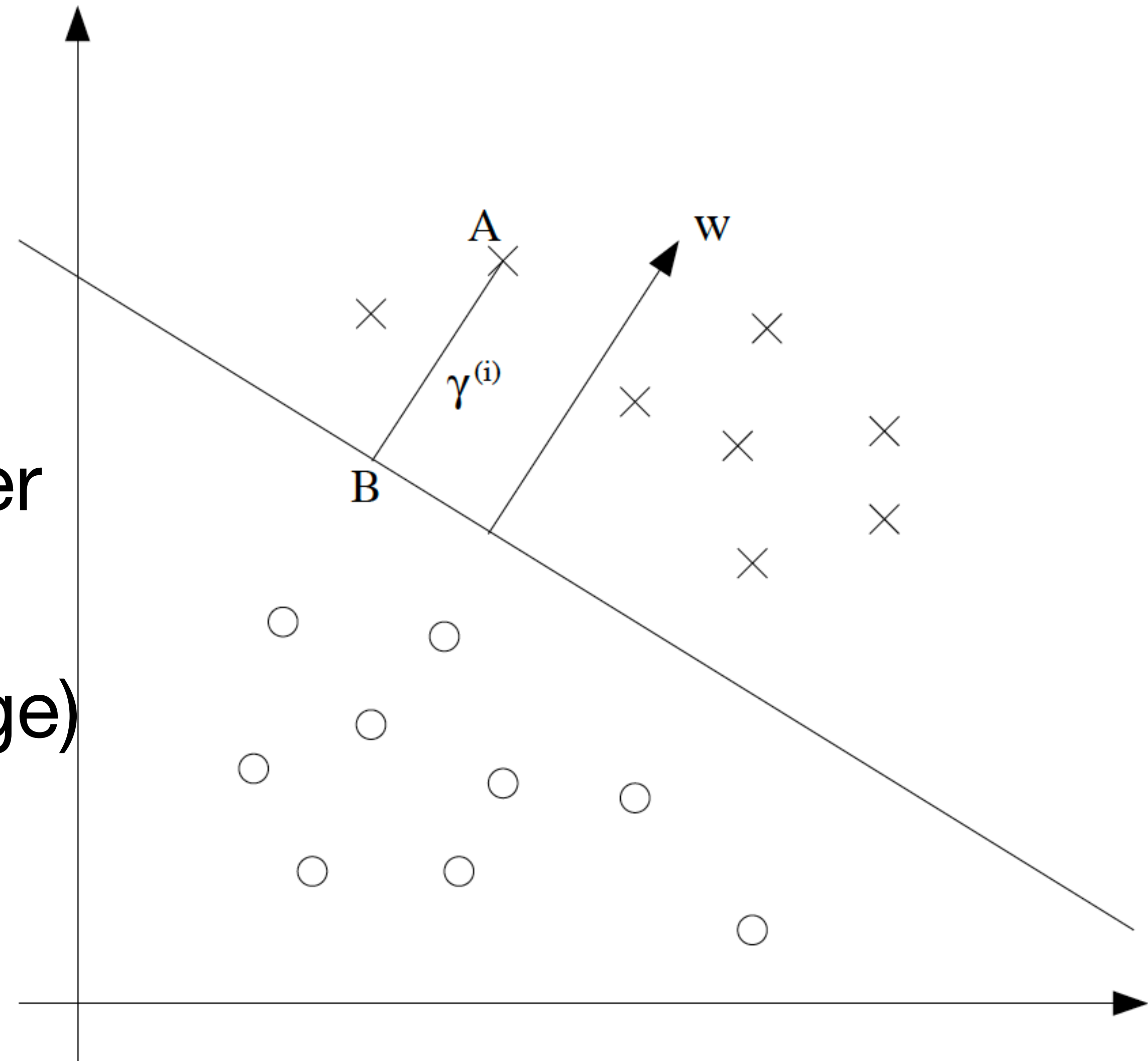
w.r.t. $(x^{(i)}, y^{(i)})$

$$\gamma^{(i)} = y^{(i)} \left(\frac{w^T x^{(i)}}{\|w\|} + \frac{b}{\|w\|} \right)$$

- Geometric margin is invariant under scaling of w, b (e.g., replace w, b with $2w, 2b$ then $\gamma^{(i)}$ doesn't change)

- Geometric margin w.r.t. set \mathcal{D}

$$\gamma = \min_{i=1, \dots, N} \gamma^{(i)}$$



Optimal margin classifier

- Find decision boundary that maximizes geometric margin
- **Assumption: Training set \mathcal{D} is linearly separable**
- Pose optimization problem

$$\begin{aligned} \max_{\gamma, w, b} \quad & \gamma \\ \text{s.t.} \quad & y^{(i)}(w^T x^{(i)} + b) \geq \gamma, \quad i = 1, \dots, N \\ & \|w\| = 1 \end{aligned}$$

- Constraint $\|w\| = 1$ ensures that functional margin $(\hat{\gamma}^{(i)} =)y^{(i)}(w^T x^{(i)} + b))$ is equal to geometric margin
- Constraint $\|w\| = 1$ is non-convex (nasty to optimize)

Optimal margin classifier (cont'd)

- Note that functional margin $\hat{\gamma}$ and geometric margin γ are related as

$$\gamma = \hat{\gamma} / \|w\|$$

- Optimize normalized functional margin

$$\begin{array}{ll} \max_{\hat{\gamma}, w, b} & \frac{\hat{\gamma}}{\|w\|} \\ \text{s.t.} & y^{(i)}(w^T x^{(i)} + b) \geq \hat{\gamma}, \quad i = 1, \dots, N \end{array}$$

- Got rid of constraint $\|w\| = 1$ but introduced objective $\hat{\gamma} / \|w\|$

Optimal margin classifier (cont'd)

- Invoke that functional margin $\hat{\gamma}$ depends on scaling
 - Multiplying w, b by constant, multiplies $\hat{\gamma}$ by that constant
- Introducing constraint $\hat{\gamma} = 1$, which indeed is a scaling constraint on w, b and obtain

$$\min_{w,b} \quad \frac{1}{2} \|w\|^2$$

$$\textbf{s.t.} \quad y^{(i)}(w^T x^{(i)} + b) \geq 1, \quad i = 1, \dots, N$$

- Note: maximizing $\hat{\gamma}/\|w\|$ (with $\hat{\gamma} = 1$) is same as minimizing $\|w\|^2$
- Convex quadratic objective, linear constraints
- The solution is the optimal margin classifier

Why is this called “support vector machines”? - Dual formulation of SVMs

board

Support vector

- Write constraints of problem

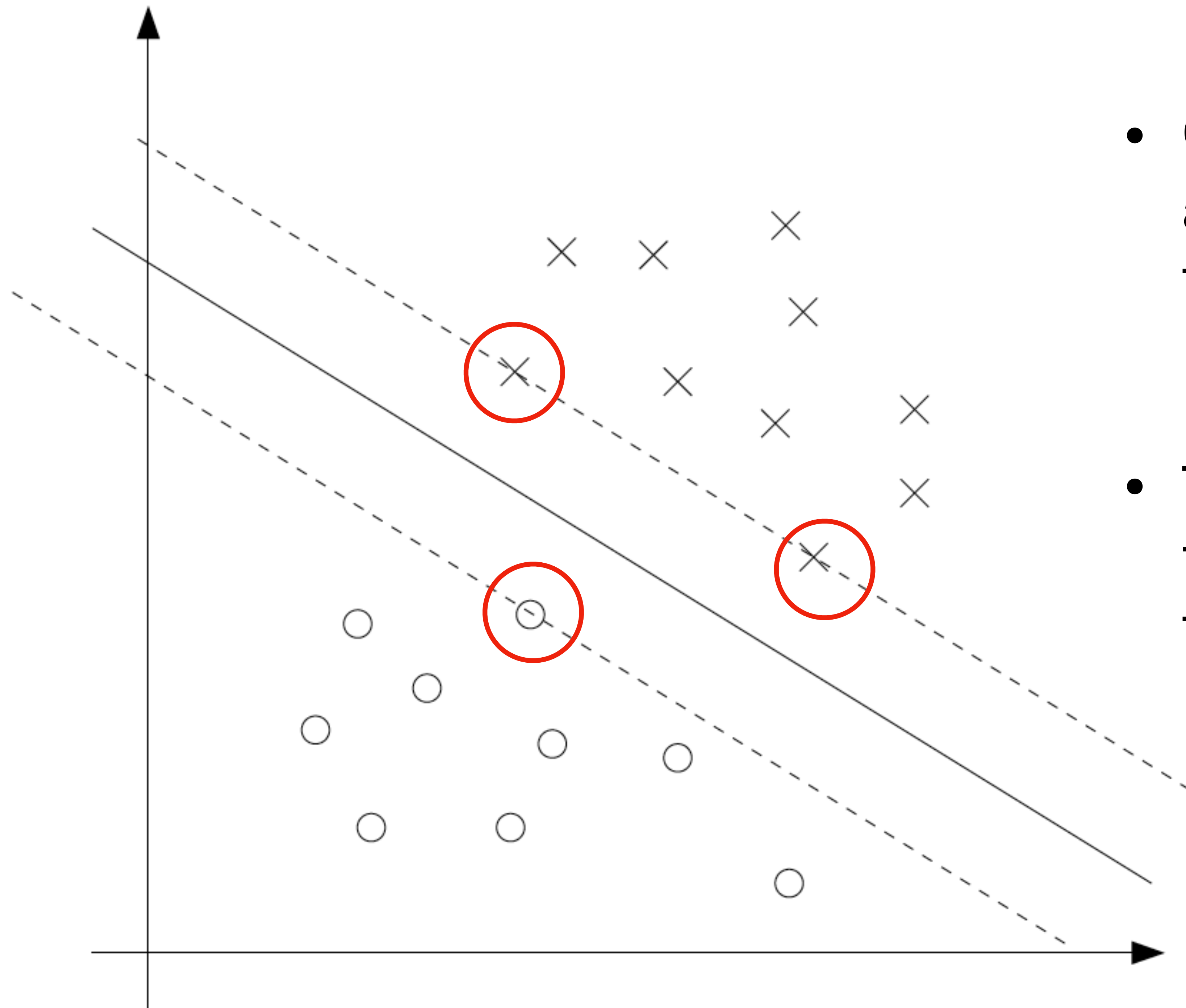
$$\min_{w,b} \quad \frac{1}{2} \|w\|^2$$

$$\text{s.t.} \quad y^{(i)}(w^T x^{(i)} + b) \geq 1, \quad i = 1, \dots, N$$

as

$$g_i(w) = -y^{(i)}(w^T x^{(i)} + b) + 1 \leq 0$$

- Know from KKT conditions that g_i active for $\alpha_i^* > 0$
- Corresponds to training points with functional margin $\hat{\gamma}^{(i)} = 1$
- These training points are called the **support vectors**



- Constraint g_i active for few training points only
—> support vectors
- Typically have much fewer support vectors than training points

Dual formulation

- Lagrangian of our optimization problem is

$$\mathcal{L}(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^N \alpha_i (y^{(i)}(w^T x + b) - 1)$$

- Dual problem is

$$\max_{\alpha} \quad \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i,j=1}^N y^{(i)} y^{(j)} \alpha_i \alpha_j < x^{(i)}, x^{(j)} >$$

$$\text{s.t.} \quad \alpha_i \geq 0, i = 1, \dots, N$$

$$\sum_{i=1}^N \alpha_i y^{(i)} = 0$$

- Can solve dual instead of primal problem

Dual solution \iff primal solution

- In the derivation of the dual problem, we obtained

$$w = \sum_{i=1}^N \alpha_i y^{(i)} x^{(i)}$$

- If we solved the dual to obtain $\alpha_1^*, \dots, \alpha_N^*$, we can find w^* with the equation above

- The optimal value b^* of the intercept term is

$$b^* = - \frac{\max_{i, y^{(i)} = -1} (w^*)^T x^{(i)} + \min_{i, y^{(i)} = 1} (w^*)^T x^{(i)}}{2}$$

Prediction with SVMs

- Suppose found w^* via α^*
- Naive: Compute $(w^*)^T x + b$ and assign $y = 1$ if positive and $y = -1$ otherwise
- Write $(w^*)^T x + b$ in terms of α^*

$$\begin{aligned}(w^*)^T x + b &= \left(\sum_{i=1}^N \alpha_i^* y^{(i)} x^{(i)} \right)^T x + b \\ &= \sum_{i=1}^N \alpha_i^* y^{(i)} \langle x^{(i)T}, x \rangle + b\end{aligned}$$

- What structure does this formulation reveal?

Prediction with SVMs (cont'd)

$$\begin{aligned}(w^*)^T x + b &= \left(\sum_{i=1}^N \alpha_i^* y^{(i)} x^{(i)} \right)^T x + b \\ &= \sum_{i=1}^N \alpha_i^* y^{(i)} < (x^{(i)})^T, x > + b\end{aligned}$$

- Only the inner product with training data $x^{(i)}$ required
- Additionally
 - The α_i^* are all 0 except for the (typically, few) support vectors
 - Thus, need only the support vector to make prediction (storage)

Inner product and SVMs

Solve:

$$\max_{\alpha} \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i,j=1}^N y^{(i)} y^{(j)} \alpha_i \alpha_j \langle x^{(i)}, x^{(j)} \rangle$$

$$\text{s.t. } \alpha_i \geq 0, i = 1, \dots, N$$

$$\sum_{i=1}^N \alpha_i y^{(i)} = 0$$

Predict:

$$\sum_{i=1}^N \alpha_i^* y^{(i)} \langle x^{(i)}, x \rangle + b$$

- Solve and predict “touch” training data only via inner products
- This is key for using SVMs with kernels