

CornerNet——基于关键点的 目标检测算法

汇报人：范越巧

什么是目标检测？

定位 (localization) :



图像识别 (classification) :



R-CNN → **OverFeat** → MultiBox → SPP-Net → MR-CNN → DeepBox → AttentionNet →
 2013.11 ICLR' 14 CVPR' 14 ECCV' 14 ICCV' 15 ICCV' 15 ICCV' 15

Fast R-CNN → DeepProposal → **Faster R-CNN** → **OHEM** → **YOLO v1** → G-CNN → AZNet →
 ICCV' 15 ICCV' 15 NIPS' 15 CVPR' 16 CVPR' 16 CVPR' 16 CVPR' 16

Inside-OutsideNet(ION) → HyperNet → CRAFT → MultiPathNet(MPN) → **SSD** → GBDNet →
 CVPR' 16 CVPR' 16 CVPR' 16 BMVC' 16 ECCV' 16 ECCV' 16

CPF → MS-CNN → **R-FCN** → PVANET → DeepID-Net → NoC → DSSD → TDM → **YOLO v2** →
 ECCV' 16 ECCV' 16 NIPS' 16 NIPSW' 16 PAMI' 16 TPAMI' 16 arXiv' 17 CVPR' 17 CVPR' 17

Feature Pyramid Net(**FPN**) → RON → DCN → DeNet → CoupleNet → **RetinaNet** → DSOD →
 CVPR' 17 CVPR' 17 ICCV' 17 ICCV' 17 ICCV' 17 ICCV' 17 ICCV' 17

Mask R-CNN → SMN → **YOLO v3** → SIN → STDN → **RefineDet** → MLKP → Relation-Net →
 ICCV' 17 ICCV' 17 arXiv' 18 CVPR' 18 CVPR' 18 CVPR' 18 CVPR' 18 CVPR' 18

Cascade R-CNN → RFBNet → CornerNet → PFPNet → Pelee → HKRM → R-DAD → **M2Det** ...
 CVPR' 18 ECCV' 18 ECCV' 18 ECCV' 18 NIPS' 18 NIPS' 18 AAAI' 19 AAAI' 19

CornerNet: Detecting Objects as Paired Keypoints

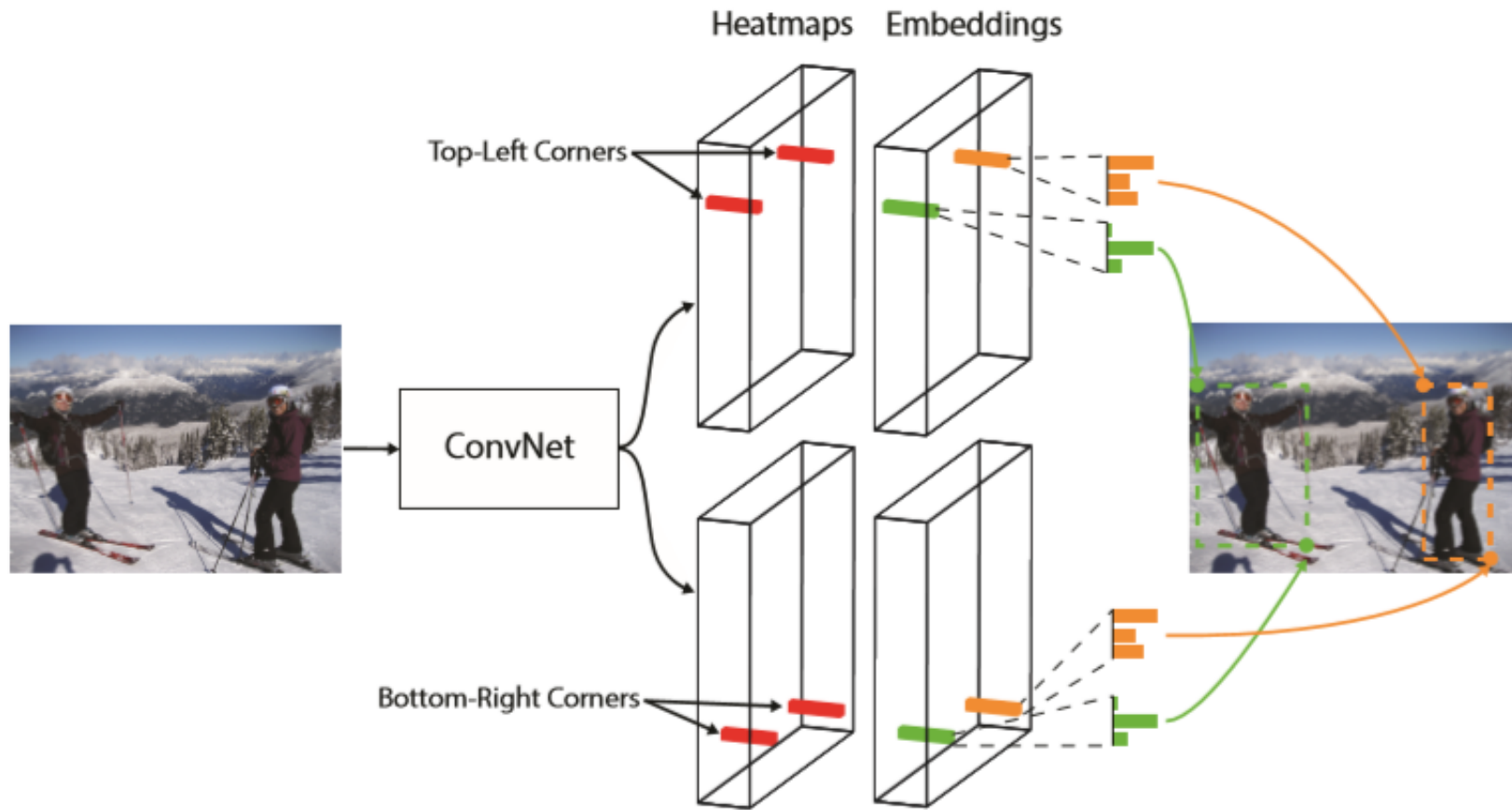
同学帮视觉系

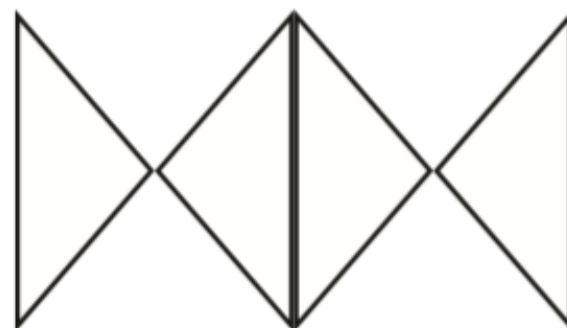
Abstract : We propose CornerNet, a new approach to object detection where we detect an object bounding box as **a pair of keypoints**, the top-left corner and the bottom-right corner, **using a single convolution neural network**. By detecting objects as paired keypoints, we eliminate the need for designing a set of **anchor boxes** commonly used in prior **single-stage** detectors. In addition to our novel formulation, we introduce **corner pooling**, a new type of pooling layer that helps the network **better localize** corners. Experiments show that CornerNet achieves a 42.2% AP on MS COCO, outperforming all existing one-stage detectors.

H. Law and J. Deng. Cornernet: Detecting objects as paired keypoints. In Proceedings of the European Conference on Computer Vision (ECCV), pages 734–750, 2018.

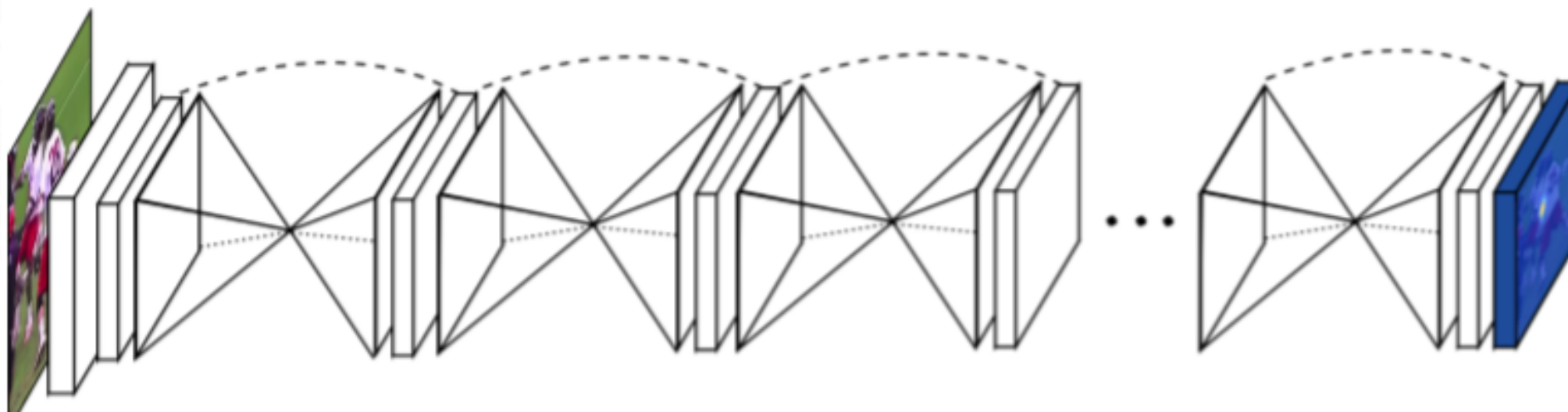
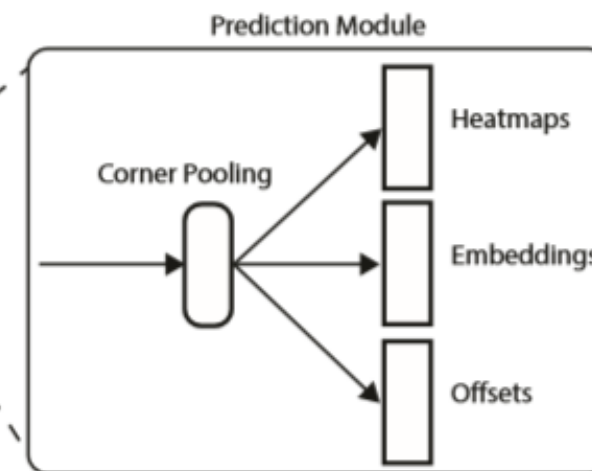
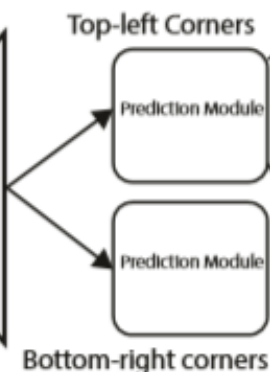
CornerNet: Detecting Objects as Paired Keypoints





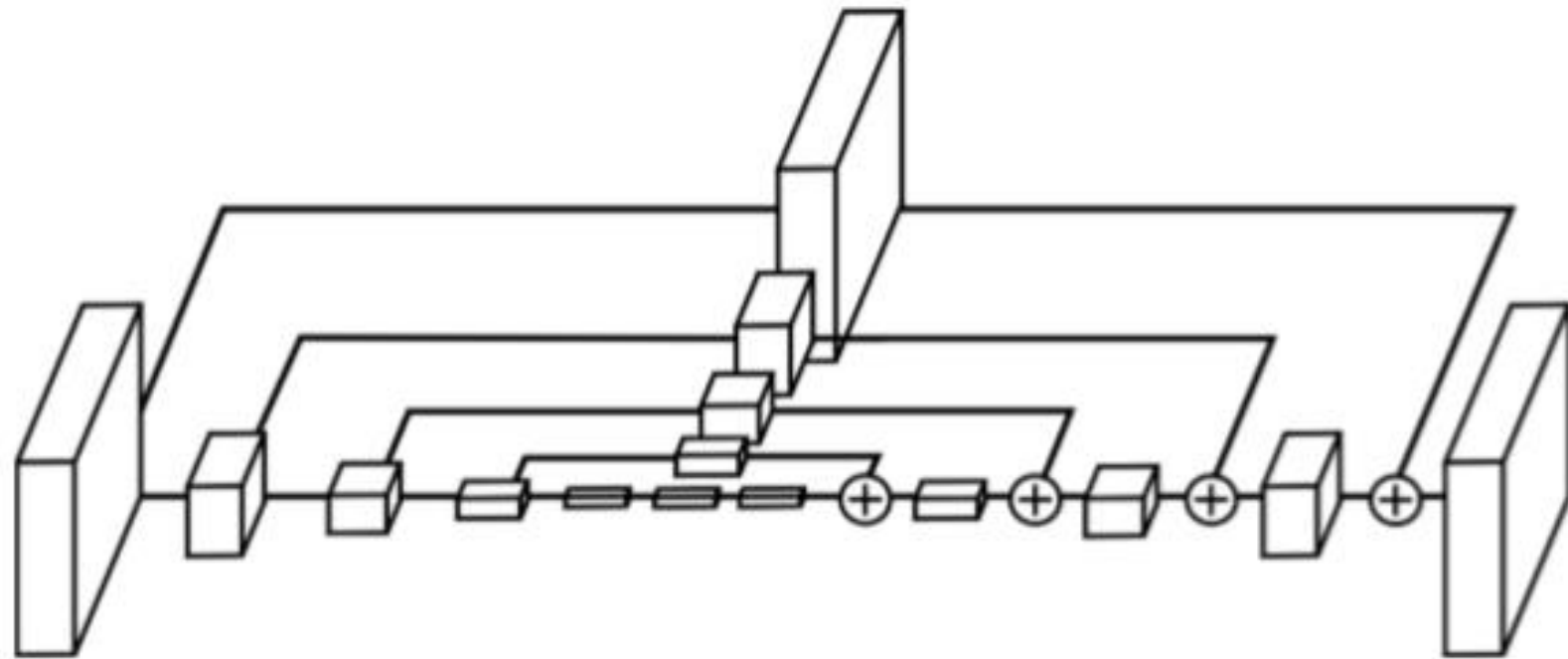


Hourglass Network

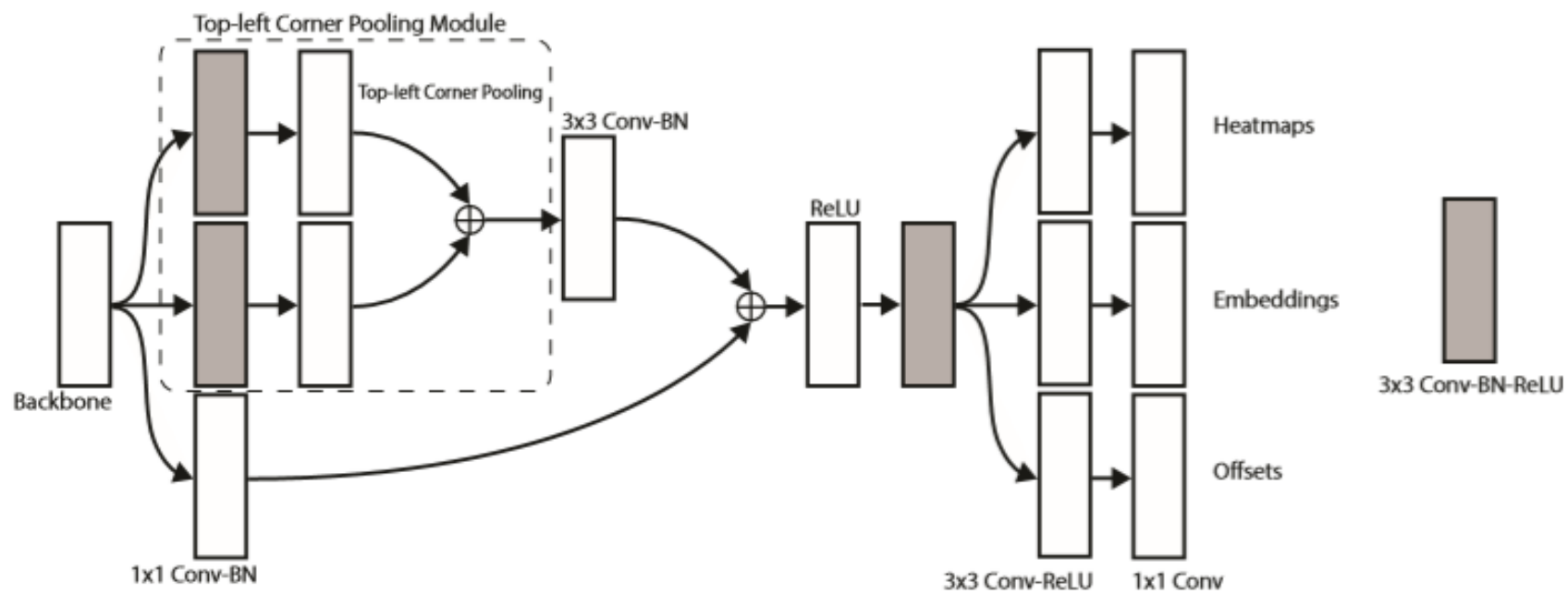


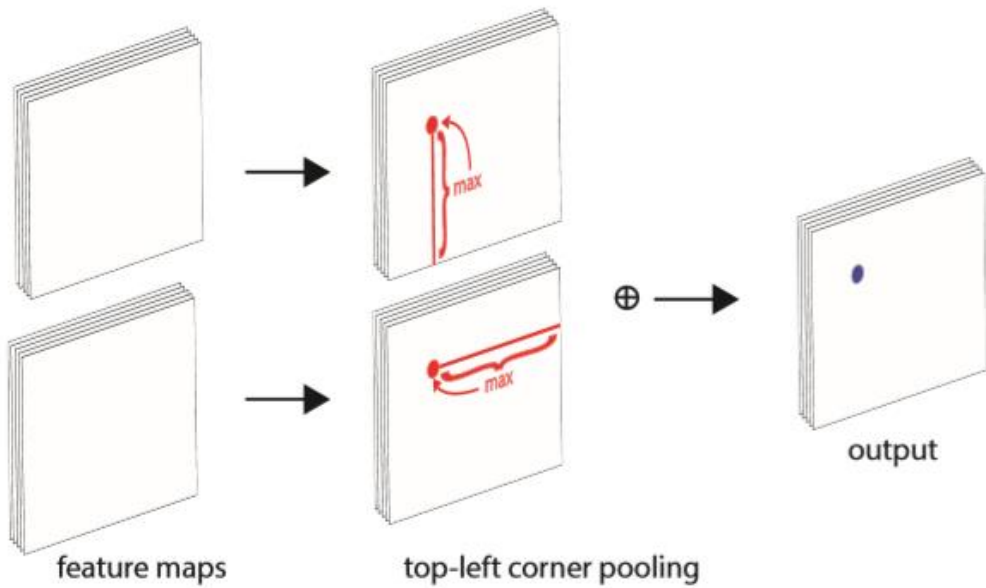
Newell, A., Yang, K., and Deng, J. (2016). Stacked hourglass networks for human pose estimation. In European Conference on Computer Vision, pages 483–499. Springer.

2/15



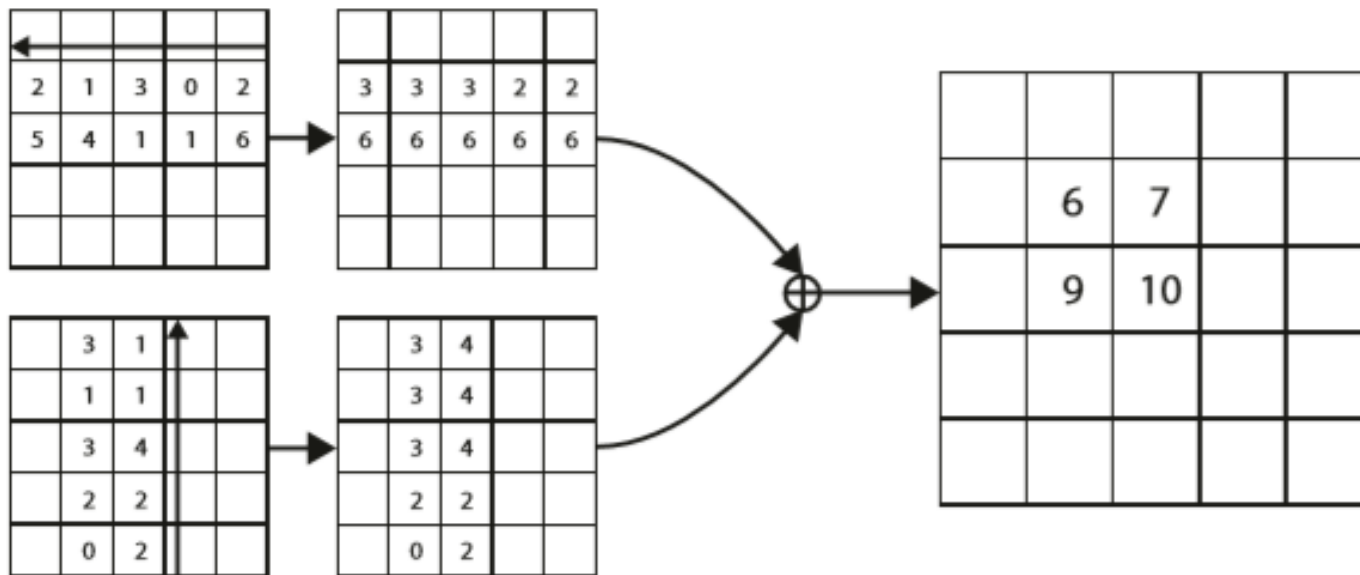
Prediction Module





$$t_{ij} = \begin{cases} \max(f_{t_{ij}}, t_{(i+1)j}) & \text{if } i < H \\ f_{t_{Hj}} & \text{otherwise} \end{cases}$$

$$l_{ij} = \begin{cases} \max(f_{l_{ij}}, l_{i(j+1)}) & \text{if } j < W \\ f_{l_{iW}} & \text{otherwise} \end{cases}$$

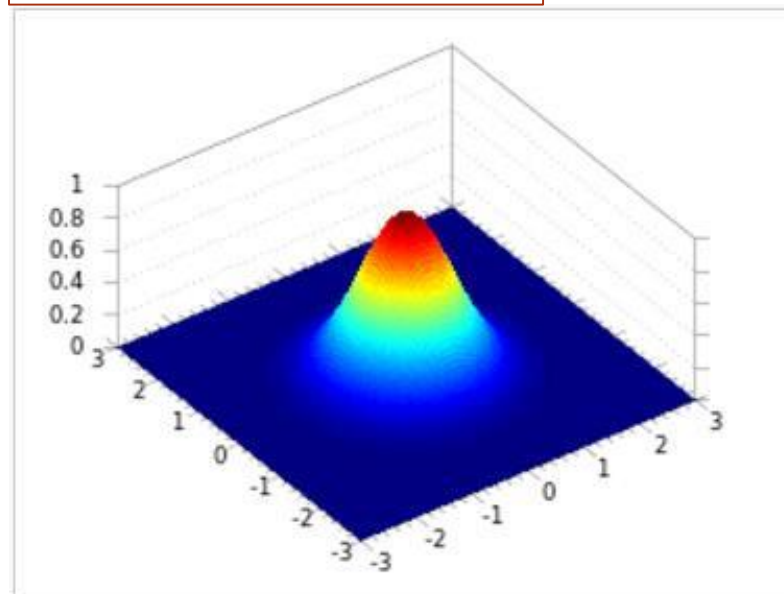


CornerNet——corners




$$e^{\frac{-(x^2+y^2)}{2\sigma^2}}$$

$$\sigma = \frac{1}{3}r$$



同学帮/视觉系


$$L_{det} = \frac{-1}{N} \sum_{c=1}^C \sum_{i=1}^H \sum_{j=1}^W \begin{cases} (1 - p_{cij})^\alpha \log(p_{cij}) & \text{if } y_{cij} = 1 \\ (1 - y_{cij})^\beta (p_{cij})^\alpha \log(1 - p_{cij}) & \text{otherwise} \end{cases}$$

平衡因子

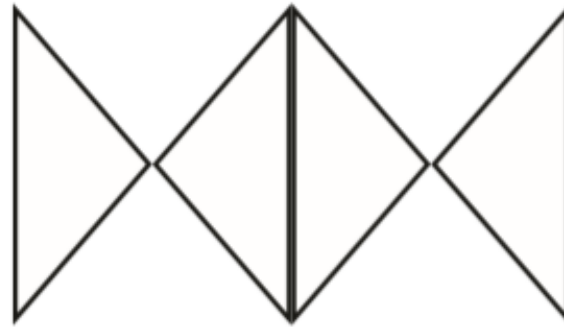
focal loss

- 样本类别分类不均衡
- 样本正负案例不均衡

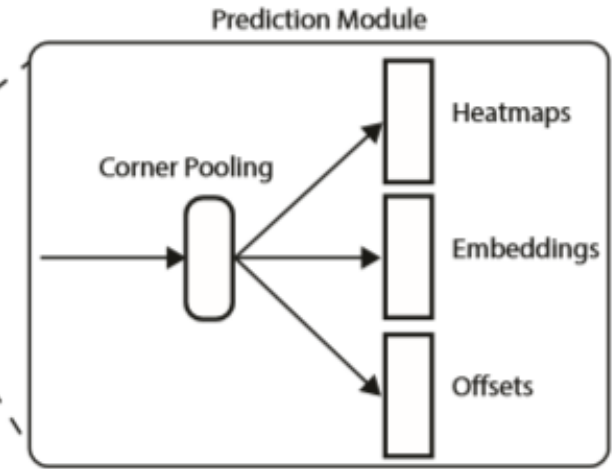
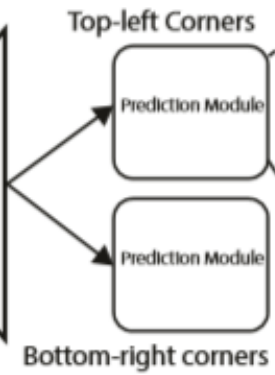
$$\alpha=2, \beta=4$$

y_{cij} 是用非标准化高斯增强的ground-truth热图

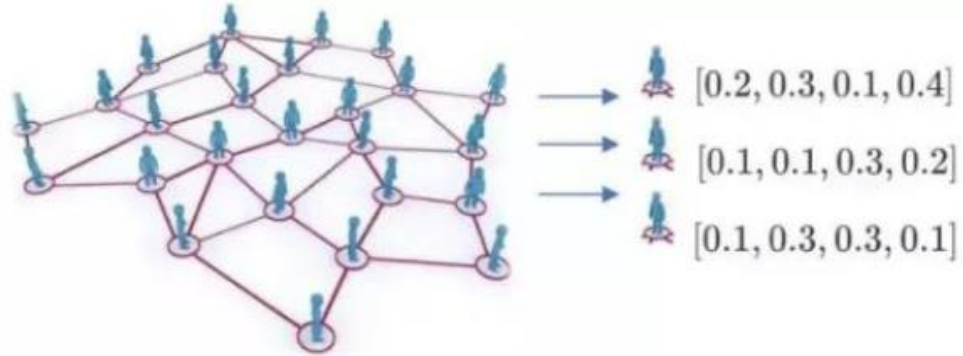
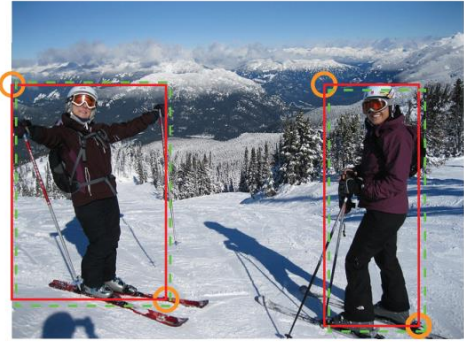
p_{cij} 是预测热图中C类位置(i, j)的得分



Hourglass Network



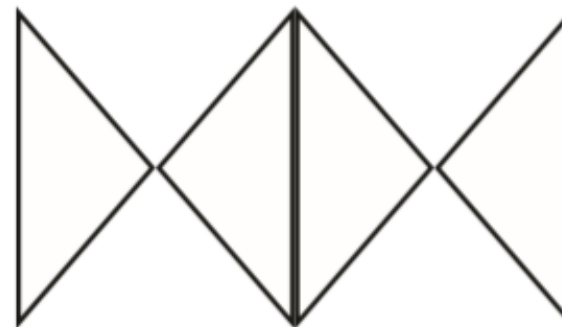
Embedding and vector embedding



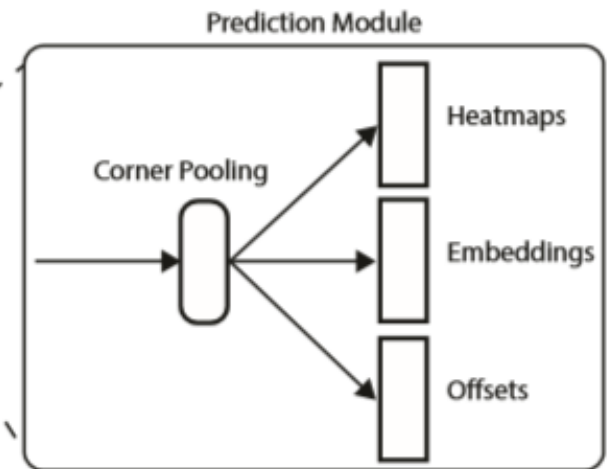
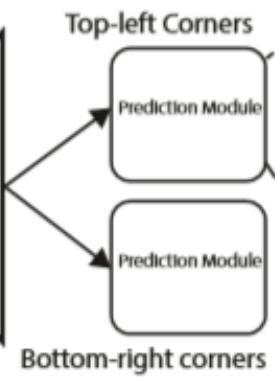
$$L_{pull} = \frac{1}{N} \sum_{k=1}^N \left[(e_{t_k} - e_k)^2 + (e_{b_k} - e_k)^2 \right]$$

$$L_{push} = \frac{1}{N(N-1)} \sum_{k=1}^N \sum_{\substack{j=1 \\ j \neq k}}^N \max(0, \Delta - |e_k - e_j|)$$

Newell, A., Huang, Z., and Deng, J. (2017). Associative embedding: End-to-end learning for joint detection and grouping. In Advances in Neural Information Processing Systems, pages 2274–2284.



Hourglass Network




$$(x, y) \longrightarrow \left(\left\lfloor \frac{x}{n} \right\rfloor, \left\lfloor \frac{y}{n} \right\rfloor \right)$$

$$\mathbf{o}_k = \left(\frac{x_k}{n} - \left\lfloor \frac{x_k}{n} \right\rfloor, \frac{y_k}{n} - \left\lfloor \frac{y_k}{n} \right\rfloor \right)$$

$$L_{off} = \frac{1}{N} \sum_{k=1}^N \text{SmoothL1Loss}(\mathbf{o}_k, \hat{\mathbf{o}}_k)$$

$$L = L_{det} + \alpha L_{pull} + \beta L_{push} + \gamma L_{off}$$

$$\alpha=0.1, \beta=0.1, \gamma=1$$

$$L_{det} = \frac{1}{N} \sum_{c=1}^C \sum_{i=1}^H \sum_{j=1}^W \begin{cases} (1 - p_{cij})^\alpha \log(p_{cij}) & \text{if } y_{cij} = 1 \\ (1 - y_{cij})^\beta (p_{cij})^\alpha \log(1 - p_{cij}) & \text{otherwise} \end{cases}$$

$$L_{pull} = \frac{1}{N} \sum_{k=1}^N \left[(e_{t_k} - e_k)^2 + (e_{b_k} - e_k)^2 \right]$$

$$L_{push} = \frac{1}{N(N-1)} \sum_{k=1}^N \sum_{\substack{j=1 \\ j \neq k}}^N \max(0, \Delta - |e_k - e_j|)$$

$$L_{off} = \frac{1}{N} \sum_{k=1}^N \text{SmoothL1Loss}(\mathbf{o}_k, \hat{\mathbf{o}}_k)$$

Method	Backbone	AP	AP ⁵⁰	AP ⁷⁵	AP ^s	AP ^m	AP ^l	AR ¹	AR ¹⁰	AR ¹⁰⁰	AR ^s	AR ^m	AR ^l
Two-stage detectors													
DeNet (Tychsen-Smith and Petersson, 2017a)	ResNet-101	33.8	53.4	36.1	12.3	36.1	50.8	29.6	42.6	43.5	19.2	46.9	64.3
CoupleNet (Zhu et al., 2017)	ResNet-101	34.4	54.8	37.2	13.4	38.1	50.8	30.0	45.0	46.4	20.7	53.1	68.5
Faster R-CNN by G-RMI (Huang et al., 2017)	Inception-ResNet-v2 (Szegedy et al., 2017)	34.7	55.5	36.7	13.5	38.1	52.0	-	-	-	-	-	-
Faster R-CNN+++ (He et al., 2016)	ResNet-101	34.9	55.7	37.4	15.6	38.7	50.9	-	-	-	-	-	-
Faster R-CNN w/ FPN (Lin et al., 2016)	ResNet-101	36.2	59.1	39.0	18.2	39.0	48.2	-	-	-	-	-	-
Faster R-CNN w/ TDM (Shrivastava et al., 2016)	Inception-ResNet-v2	36.8	57.7	39.2	16.2	39.8	52.1	31.6	49.3	51.9	28.1	56.6	71.1
D-FCN (Dai et al., 2017)	Aligned-Inception-ResNet	37.5	58.0	-	19.4	40.1	52.5	-	-	-	-	-	-
Regionlets (Xu et al., 2017)	ResNet-101	39.3	59.8	-	21.7	43.7	50.9	-	-	-	-	-	-
Mask R-CNN (He et al., 2017)	ResNeXt-101	39.8	62.3	43.4	22.1	43.2	51.2	-	-	-	-	-	-
Soft-NMS (Bodla et al., 2017)	Aligned-Inception-ResNet	40.9	62.8	-	23.3	43.6	53.3	-	-	-	-	-	-
LH R-CNN (Li et al., 2017)	ResNet-101	41.5	-	-	25.2	45.3	53.1	-	-	-	-	-	-
Fitness-NMS (Tychsen-Smith and Petersson, 2017b)	ResNet-101	41.8	60.9	44.9	21.5	45.0	57.5	-	-	-	-	-	-
Cascade R-CNN (Cai and Vasconcelos, 2017)	ResNet-101	42.8	62.1	46.3	23.7	45.5	55.2	-	-	-	-	-	-
D-RFCN + SNIP (Singh and Davis, 2017)	DPN-98 (Chen et al., 2017)	45.7	67.3	51.1	29.3	48.8	57.1	-	-	-	-	-	-
One-stage detectors													
YOLOv2 (Redmon and Farhadi, 2016)	DarkNet-19	21.6	44.0	19.2	5.0	22.4	35.5	20.7	31.6	33.3	9.8	36.5	54.4
DSOD300 (Shen et al., 2017a)	DS/64-192-48-1	29.3	47.3	30.6	9.4	31.5	47.0	27.3	40.7	43.0	16.7	47.1	65.0
GRP-DSOD320 (Shen et al., 2017b)	DS/64-192-48-1	30.0	47.9	31.8	10.9	33.6	46.3	28.0	42.1	44.5	18.8	49.1	65.0
SSD513 (Liu et al., 2016)	ResNet-101	31.2	50.4	33.3	10.2	34.5	49.8	28.3	42.1	44.4	17.6	49.2	65.8
DSSD513 (Fu et al., 2017)	ResNet-101	33.2	53.3	35.2	13.0	35.4	51.1	28.9	43.5	46.2	21.8	49.1	66.4
RefineDet512 (single scale) (Zhang et al., 2017)	ResNet-101	36.4	57.5	39.5	16.6	39.9	51.4	-	-	-	-	-	-
RetinaNet800 (Lin et al., 2017)	ResNet-101	39.1	59.1	42.3	21.8	42.7	50.2	-	-	-	-	-	-
RefineDet512 (multi scale) (Zhang et al., 2017)	ResNet-101	41.8	62.9	45.7	25.6	45.1	54.1	-	-	-	-	-	-
CornerNet511 (single scale)	Hourglass-104	40.6	56.4	43.2	19.1	42.8	54.3	35.3	54.7	59.4	37.4	62.4	77.2
CornerNet511 (multi scale)	Hourglass-104	42.2	57.8	45.2	20.7	44.8	56.6	36.6	55.9	60.3	39.5	63.2	77.3





CornerNet 实现

https://blog.csdn.net/qq_36492210/article/details/84993195

<https://github.com/princeton-vl/CornerNet-Lite>

<https://github.com/princeton-vl/CornerNet>

CornerNet 代码

链接：<https://pan.baidu.com/s/16QreUNVwGK7E95oDfAsvtg>

提取码：9es