

Relative to an origin O , the position vectors of three points A , B and C are given by

$$\overrightarrow{OA} = 3\mathbf{i} + p\mathbf{j} - 2p\mathbf{k}, \quad \overrightarrow{OB} = 6\mathbf{i} + (p+4)\mathbf{j} + 3\mathbf{k} \quad \text{and} \quad \overrightarrow{OC} = (p-1)\mathbf{i} + 2\mathbf{j} + q\mathbf{k},$$

where p and q are constants.

(i) In the case where $p = 2$, use a scalar product to find angle AOB .

[4]

[illegible]

[4]

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