#### **Announcements**

- Program 6 is due December 11 at 11:59 PM (in two days...)
- Wednesdays lecture will have no quiz, it is strictly a review session
- A reminder that the Final exam is: 12/14 (This Saturday) at 2:30 4:30 PM in Room: Storm Hall West (SHW) 11
- The make up exam (for those who signed up), will be: 12/14 at 5:00 7:00 PM in Room: GMCS 301

# Program 6 Questions?

# Final Quiz Time;)

#### Hash Table

A *hash table* is a data structure that stores <u>unordered items</u> by <u>mapping</u> (or hashing) <u>each item to a location in an array</u>.

In a hash table, an item's key is the value used to map to an index.

For all items that might possibly be stored in the hash table, <u>every key is ideally unique</u>, so that the hash table's algorithms can <u>search for a specific item by that key</u>.

The **key** <u>does not</u> necessarily need to be a <u>number</u>, it can also (and very commonly) be a <u>string</u>.

Elements are <u>inserted into a hash table</u> as part of a pairing called a: **Key / Value pair**.

Let's look at an example on the board...

Each <u>hash table array element</u> is called a **bucket**.

A *hash function* computes a <u>bucket index from the item's key</u>.

A common easy <u>hash function</u> uses the *modulo operator* %, which computes the <u>integer remainder when dividing two numbers</u>.

Ex: For a 20 element hash table, a hash function of key % 20 will map keys to bucket indices 0 to 19. This is because the remainder will never exceed 20.

Let's look at an example...

The issue with using modulo as a hashing function is that it does not really produce unique values.

For example:

5 % 20 ---> This results in 5

25 % 20 ---> This also results in 5

When two keys map to the same location, we call this a collision.

Various techniques are used to handle collisions during insertions, such as chaining or open addressing.

**Chaining** is a collision resolution technique where each bucket has a list of items (so bucket 5's list would become 55, 75). In other words an array of lists.

*Open addressing* (also called probing) is a collision resolution technique where collisions are resolved by looking for an empty bucket elsewhere in the table (so 75 might be stored in bucket 6).

Chaining

**Chaining** handles hash table collisions by using a list for each bucket, where each list may store multiple items that map to the same bucket.

The <u>insert operation</u> first uses the item's <u>key to determine the bucket</u>, and then inserts the item in that bucket's list.

Searching also first determines the bucket, and then searches the bucket's list.

Let's look at an example...

**Linear Probing** 

A hash table with *linear probing* handles a collision by <u>starting</u> at the key's <u>mapped bucket</u>, and then <u>linearly searches subsequent buckets</u> until an <u>empty bucket</u> is found.

Let's look at an example...

Linear probing distinguishes two types of empty buckets.

An empty-since-start bucket has been empty since the hash table was created.

An *empty-after-removal* bucket had an item removed that caused the bucket to now be empty.

The distinction will be <u>important during searches</u>, since searching only <u>stops for empty-since-start</u>, not for empty-after-removal.