

**Homework 4**  
**Ordinary Differential Equations**  
**Math 537**  
**Stephen Giang RedID: 823184070**

**Problem 1:** Consider the Lorenz model:

$$\begin{aligned}\frac{dX}{dt} &= -\sigma X + \sigma Y \\ \frac{dY}{dt} &= -XZ + rX - Y \\ \frac{dZ}{dt} &= XY - \beta Z\end{aligned}$$

- (a) Find the Jacobian matrix at the trivial critical point  $(X, Y, Z) = (0, 0, 0)$ .

Let  $f_1 = \frac{dX}{dt}$ ,  $f_2 = \frac{dY}{dt}$ ,  $f_3 = \frac{dZ}{dt}$ . Notice the following Jacobian:

$$J(X, Y, Z) = \begin{bmatrix} \frac{\partial f_1}{\partial X} & \frac{\partial f_1}{\partial Y} & \frac{\partial f_1}{\partial Z} \\ \frac{\partial f_2}{\partial X} & \frac{\partial f_2}{\partial Y} & \frac{\partial f_2}{\partial Z} \\ \frac{\partial f_3}{\partial X} & \frac{\partial f_3}{\partial Y} & \frac{\partial f_3}{\partial Z} \end{bmatrix} = \begin{bmatrix} -\sigma & \sigma & 0 \\ -Z + r & -1 & -X \\ Y & X & -\beta \end{bmatrix}$$

Now we get the following Jacobian at the trivial critical point:

$$J(0, 0, 0) = \begin{bmatrix} -\sigma & \sigma & 0 \\ r & -1 & 0 \\ 0 & 0 & -\beta \end{bmatrix}$$

- (b) Choose  $\sigma = 10$ . Perform a (linear) stability analysis in  $r, \beta$ -space using the matrix in (a).  
[Hint: Describe the regions where the Jacobian matrix has real and/or complex eigenvalues.]

Notice the following Jacobian at the trivial critical point with  $\sigma = 10$ :

$$J(0, 0, 0) = \begin{bmatrix} -10 & 10 & 0 \\ r & -1 & 0 \\ 0 & 0 & -\beta \end{bmatrix}$$

Notice we can find the eigenvalues by solving  $\det(J - \lambda I) = 0$ :

$$\begin{aligned}(-10 - \lambda)(-1 - \lambda)(-\beta - \lambda) - 10r(-\beta - \lambda) &= 0 \\ -(\beta + \lambda)\left((10 + \lambda)(1 + \lambda) - 10r\right) &= 0 \\ -(\beta + \lambda)(\lambda^2 + 11\lambda + 10(1 - r)) &= 0\end{aligned}$$

Thus we get the following eigenvalues:

$$\lambda_1 = -\beta, \quad \lambda_{2,3} = \frac{-11 \pm \sqrt{121 - 4(10)(1 - r)}}{2}$$

Notice we can the following:

$$\begin{array}{ll}
121 - 4(10)(1 - r) = 0 & 121 - 4(10)(1 - r) = 121 \\
121 - 40 + 40r = 0 & (1 - r) = 0 \\
r = \frac{-81}{40} & r = 1
\end{array}$$

Notice the linear stability analysis at the specified  $r, \beta$  spaces.

(a) Let  $r < \frac{-81}{40}$

We get the following:

$$\lambda_{2,3} = \frac{-11 \pm i\sqrt{|121 - 4(10)(1 - r)|}}{2}$$

If we let  $\beta > 0$ , we get  $\lambda_1 < 0$ , thus giving us 1 negative real eigenvalue and 2 complex eigenvalues with negative real parts. This results in a **Spiral Sink**.

If we let  $\beta < 0$ , we get  $\lambda_1 > 0$ , thus giving us 1 positive real eigenvalue and 2 complex eigenvalues with negative real parts. This results in a **Saddle Focus**.

(b) Let  $r = \frac{-81}{40}$

We get the following:

$$\lambda_{2,3} = \frac{-11}{2}$$

If we let  $\beta > 0$ , we get  $\lambda_1 < 0$ , thus giving us 3 negative eigenvalues. This results in a **Sink**.

If we let  $\beta < 0$ , we get  $\lambda_1 > 0$ , thus giving us 1 positive eigenvalue and 2 negative eigenvalues. This results in a **Saddle**.

(c) Let  $\frac{-81}{40} < r < 1$

We get the following:

$$\lambda_2 = \frac{-11 + \sqrt{121 - 4(10)(1 - r)}}{2} < 0, \quad \lambda_3 = \frac{-11 - \sqrt{121 - 4(10)(1 - r)}}{2} < 0$$

If we let  $\beta > 0$ , we get  $\lambda_1 < 0$ , thus giving us 3 negative eigenvalues. This results in a **Sink**.

If we let  $\beta < 0$ , we get  $\lambda_1 > 0$ , thus giving us 1 positive eigenvalue and 2 negative eigenvalues. This results in a **Saddle**.

(d) Let  $r = 1$

We get the following:

$$\lambda_2 = \frac{-11 + 11}{2} = 0, \quad \lambda_3 = \frac{-11 - 11}{2} = -11$$

If we let  $\beta > 0$ , we get  $\lambda_1 < 0$ , thus giving us a zero eigenvalue, and 2 negative eigenvalues. This results in a **Attractive Line of Equilibrium**

If we let  $\beta < 0$ , we get  $\lambda_1 > 0$ , thus giving us a zero eigenvalue, 1 positive eigenvalue, and 1 negative eigenvalue. This results in a **Saddle Around a Line of Equilibrium**.

(e) Let  $r > 1$

We get the following:

$$\lambda_2 = \frac{-11 + \sqrt{121 - 4(10)(1 - r)}}{2} > 0, \quad \lambda_3 = \frac{-11 - \sqrt{121 - 4(10)(1 - r)}}{2} < 0$$

If we let  $\beta > 0$ , we get  $\lambda_1 < 0$ , thus giving us 1 positive eigenvalues and 2 negative eigenvalue. This results in a **Saddle**

If we let  $\beta < 0$ , we get  $\lambda_1 > 0$ , thus giving us 2 positive eigenvalues and 1 negative eigenvalue. This results in a **Saddle**

**Problem 2:** Consider the non-dissipative Lorenz model:

$$\begin{aligned}\frac{dX}{dt} &= \sigma Y \\ \frac{dY}{dt} &= -XZ + rX \\ \frac{dZ}{dt} &= XY\end{aligned}$$

(a) Find critical points.

Notice we can find the critical points by solving:

$$\begin{bmatrix} \frac{dX}{dt} \\ \frac{dY}{dt} \\ \frac{dZ}{dt} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 & \sigma & 0 \\ r & 0 & -X \\ 0 & X & 0 \end{bmatrix} \begin{bmatrix} X \\ Y \\ Z \end{bmatrix}$$

This results in the critical points  $(\mathbf{0}, \mathbf{0}, B), (C, \mathbf{0}, r) \forall B, C \in \mathbb{R}$ .

(b) Find the Jacobian matrix at critical points(s).

Let  $f_1 = \frac{dX}{dt}$ ,  $f_2 = \frac{dY}{dt}$ ,  $f_3 = \frac{dZ}{dt}$ . Notice the following Jacobian:

$$J(X, Y, Z) = \begin{bmatrix} \frac{\partial f_1}{\partial X} & \frac{\partial f_1}{\partial Y} & \frac{\partial f_1}{\partial Z} \\ \frac{\partial f_2}{\partial X} & \frac{\partial f_2}{\partial Y} & \frac{\partial f_2}{\partial Z} \\ \frac{\partial f_3}{\partial X} & \frac{\partial f_3}{\partial Y} & \frac{\partial f_3}{\partial Z} \end{bmatrix} = \begin{bmatrix} 0 & \sigma & 0 \\ -Z + r & 0 & -X \\ Y & X & 0 \end{bmatrix}$$

Now we get the following Jacobian at the critical points:

$$J(0, 0, B) = \begin{bmatrix} 0 & \sigma & 0 \\ -B + r & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \quad J(C, 0, r) = \begin{bmatrix} 0 & \sigma & 0 \\ 0 & 0 & -C \\ 0 & C & 0 \end{bmatrix}$$

(c) Perform a linear stability analysis at each of the critical points.

For  $J(0, 0, B)$ , we get the following eigenvalues:

$$\begin{aligned} -\lambda^3 - \sigma(-B + r)(-\lambda) &= 0 \\ -\lambda(\lambda^2 - \sigma(-B + r)) &= 0 \\ \lambda_1 &= 0, \quad \lambda_{2,3} = \pm\sqrt{\sigma(-B + r)} \end{aligned}$$

If  $\sigma(-B + r) > 0$ , then we get 1 zero eigenvalue, 1 negative eigenvalue, and 1 positive eigenvalue. This would lead to a **Saddle Around a Line of Equilibrium**.

If  $\sigma(-B + r) < 0$ , then we get 1 zero eigenvalue, and two complex eigenvalues with zero real parts. This would lead to a **Center**

For  $J(C, 0, r)$ , we get the following eigenvalues

$$\begin{aligned} -\lambda(\lambda^2 + C^2) &= 0 \\ \lambda_1 &= 0, \quad \lambda_{2,3} = \pm i|C| \end{aligned}$$

If  $C \neq 0$ , we get 1 zero eigenvalue, and 2 complex eigenvalues with zero real parts. This would lead to a **Center**

If  $C = 0$ , we get 3 zero eigenvalues with **No Phase Portrait**.

**Problem 3:** Consider the following harmonic oscillators:

$$\begin{aligned}\frac{d^2x_1}{dt^2} &= -k_1x_1 \\ \frac{d^2x_2}{dt^2} &= -k_2x_2\end{aligned}$$

Let  $k_1 = 4\omega_1^2$  and  $k_2 = \omega_2^2$ .

- (a) Convert the above equations into a linear system with four first-order differential equations. Find the matrix  $A$  that represents the 4D system.

Let  $\frac{dx_1}{dt} = y_1$  and  $\frac{dx_2}{dt} = y_2$  such that:

$$y_1 = \frac{dx_1}{dt}, \quad y_1' = \frac{d^2x_1}{dt^2}, \quad y_2 = \frac{dx_2}{dt}, \quad y_2' = \frac{d^2x_2}{dt^2}$$

Using this and letting  $k_1 = 4\omega_1^2$   $k_2 = \omega_2^2$ , we get the following:

$$X' = \begin{bmatrix} \frac{dx_1}{dt} \\ \frac{d^2x_1}{dt^2} \\ \frac{dx_2}{dt} \\ \frac{d^2x_2}{dt^2} \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -4\omega_1^2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -\omega_2^2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \\ x_2 \\ y_2 \end{bmatrix} = Ax$$

- (b) Find the eigenvalues and eigenvectors of  $A$  in the 4-D phase space.

Notice we can find the eigenvalues by solving  $\det(J - \lambda I) = 0$ :

$$\begin{aligned}-\lambda \left( -\lambda(\lambda^2 + \omega_2^2) \right) + 4\omega_1^2(\lambda^2 + \omega_2^2) &= 0 \\ (\lambda^2 + 4\omega_1^2)(\lambda^2 + \omega_2^2) &= 0\end{aligned}$$

Thus we get  $\lambda_{1,2} = \pm 2i\omega_1$  and  $\lambda_{3,4} = \pm i\omega_2$ .

Notice we can find  $V_1$  by solving  $(A - \lambda I)V_1 = 0$  with  $\lambda = 2i\omega_1$

$$\begin{pmatrix} -2i\omega_1 & 1 & 0 & 0 \\ -4\omega_1^2 & -2i\omega_1 & 0 & 0 \\ 0 & 0 & -2i\omega_1 & 1 \\ 0 & 0 & -\omega_2^2 & -2i\omega_1 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \\ x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Notice we get that  $\mathbf{V}_1 = (\mathbf{1}, 2i\omega_1, \mathbf{0}, \mathbf{0})^T$ . Because  $\lambda_2 = -2i\omega_1$  is the conjugate of  $\lambda_1$ , then  $V_2$  is the conjugate of  $V_1$ , such that  $\mathbf{V}_2 = (\mathbf{1}, -2i\omega_1, \mathbf{0}, \mathbf{0})^T$ .

Notice we can find  $V_3$  by solving  $(A - \lambda I)V_3 = 0$  with  $\lambda = i\omega_2$

$$\begin{pmatrix} -i\omega_2 & 1 & 0 & 0 \\ -4\omega_1^2 & -i\omega_2 & 0 & 0 \\ 0 & 0 & -i\omega_2 & 1 \\ 0 & 0 & -\omega_2^2 & -i\omega_2 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \\ x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Notice we get that  $\mathbf{V}_3 = (\mathbf{0}, \mathbf{0}, \mathbf{1}, i\omega_2)^T$ . Because  $\lambda_4 = -i\omega_2$  is the conjugate of  $\lambda_3$ , then  $V_4$  is the conjugate of  $V_3$ , such that  $\mathbf{V}_4 = (\mathbf{0}, \mathbf{0}, \mathbf{1}, -i\omega_2)^T$ .

(c) Find the linear map  $T$  using (b) and compute  $T^{-1}AT$ .

Notice the following:

$$\begin{aligned}
 T = (V_1, V_2, V_3, V_4) &= \begin{pmatrix} 1 & 1 & 0 & 0 \\ 2i\omega_1 & -2i\omega_1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & i\omega_2 & -i\omega_2 \end{pmatrix} \\
 T^{-1}AT &= \begin{pmatrix} 1/2 & 1/4i\omega_1 & 0 & 0 \\ 1/2 & -1/4i\omega_1 & 0 & 0 \\ 0 & 0 & 1/2 & 1/2i\omega_2 \\ 0 & 0 & 1/2 & -1/2i\omega_2 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 & 0 \\ -4\omega_1^2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -\omega_2^2 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 & 0 \\ 2i\omega_1 & -2i\omega_1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & i\omega_2 & -i\omega_2 \end{pmatrix} \\
 &= \begin{pmatrix} i\omega_1 & 1/2 & 0 & 0 \\ -i\omega_1 & 1/2 & 0 & 0 \\ 0 & 0 & i\omega_2/2 & 1/2 \\ 0 & 0 & -i\omega_2/2 & 1/2 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 & 0 \\ 2i\omega_1 & -2i\omega_1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & i\omega_2 & -i\omega_2 \end{pmatrix} \\
 &= \begin{pmatrix} 2i\omega_1 & 0 & 0 & 0 \\ 0 & -2i\omega_1 & 0 & 0 \\ 0 & 0 & i\omega_2 & 0 \\ 0 & 0 & 0 & -i\omega_2 \end{pmatrix}
 \end{aligned}$$

Notice this is in the form of  $T^{-1}AT$  being a matrix with its diagonal consisting of its eigenvalues and the other entries being zero.

**Problem 4:** Consider the following matrix:

$$A = \begin{pmatrix} 2 & 3 & 0 \\ 0 & 2 & -1 \\ 0 & 0 & 2 \end{pmatrix}$$

- (a) Find the eigenvector(s) and generalized eigenvector(s) associated with the matrix  $A$ .

Notice that  $A$  is an upper triangular matrix. This means that we get a repeated eigenvalue of  $\lambda = 2$ .

Notice, we can find  $V_1$  by solving  $(A - \lambda I)V_1 = 0$ :

$$\begin{pmatrix} 0 & 3 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Because of the second and third row, we get that  $y = z = 0$ , so we let  $x = 1$ , such that  $V_1 = (1, 0, 0)^T$ .

Notice, we can find  $V_2$  by solving  $(A - \lambda I)V_2 = V_1$ :

$$\begin{pmatrix} 0 & 3 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

Because we need  $3y = 1$ , we get  $y = 1/3$ . Because of the second row, we get that  $z = 0$ . Lastly, we can let  $x = 1$ , such that  $V_2 = (1, 1/3, 0)^T$ .

Notice, we can find  $V_3$  by solving  $(A - \lambda I)V_3 = V_2$ :

$$\begin{pmatrix} 0 & 3 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 1/3 \\ 0 \end{pmatrix}$$

Because we need  $3y = 1$ , we get  $y = 1/3$ . Because we need  $-z = 1/3$ , we get  $z = -1/3$ . Lastly, we can let  $x = 1$ , such that  $V_3 = (1, 1/3, -1/3)^T$ .

- (b) Construct a linear map  $T$  using the eigenvector(s) and generalized eigenvector(s) in (a) and compute  $T^{-1}AT$ .

Notice the linear map  $T$  and  $T^{-1}AT$ :

$$T = (V_1 \ V_2 \ V_3) = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1/3 & 1/3 \\ 0 & 0 & -1/3 \end{pmatrix}$$

$$T^{-1}AT = \begin{pmatrix} 1 & -3 & 0 \\ 0 & 3 & 3 \\ 0 & 0 & -3 \end{pmatrix} \begin{pmatrix} 2 & 3 & 0 \\ 0 & 2 & -1 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1/3 & 1/3 \\ 0 & 0 & -1/3 \end{pmatrix} = \begin{pmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{pmatrix}$$

Notice that  $T^{-1}AT$  is in the form of case (iii) with its diagonal consisting of the repeated eigenvalue,  $\lambda = 2$  and its superdiagonal consisting of ones.