

Oct 14, 2024

Logistic Delay Differential Equation:

$$\underbrace{\frac{dx(t)}{dt}} = r \underbrace{x(t)} \left[1 - \frac{x(t-\tau)}{K} \right].$$

• Scaling (Dimensional Analysis).

$$x(t) = [x] x^*(t) \quad \text{and}$$

$$t = [t] t^*$$

$$\begin{aligned} \frac{dx(t)}{dt} &= [x] \frac{dx^*(t)}{dt} = [x] \cdot \frac{dx^*([t]t^*)}{d([t]t^*)} \\ &= \frac{[x]}{[t]} \frac{dx^*([t]t^*)}{dt^*} \end{aligned}$$

Assuming $y^*(t^*) = x^*([t]t^*)$,

we get $\frac{dx(t)}{dt} = \frac{[x]}{[t]} \frac{dy^*(t^*)}{dt^*}$.

and

$$\begin{aligned} r x(t) \left[1 - \frac{x(t-\tau)}{K} \right] &= r x([t]t^*) \left[1 - \frac{x([t]t^* - \tau)}{K} \right] \\ &= r [x] y^*(t^*) \left[1 - \frac{[x]}{K} x^*([t]t^* - \tau) \right] \end{aligned}$$

$$\begin{aligned} \therefore \frac{[x]}{[t]} \frac{dy^*(t^*)}{dt^*} &= r [x] y^*(t^*) \left[1 - \frac{[x]}{K} x^*([t]t^* - \tau) \right] \\ \text{or, } \frac{dy^*(t^*)}{dt^*} &= [t] \cdot r y^*(t^*) \left[1 - \frac{[x]}{K} x^*([t]t^* - \tau) \right] \end{aligned}$$

$$[x] = K, \quad [t] = \frac{1}{r}$$

$$\begin{aligned} \Rightarrow \frac{dy^*(t^*)}{dt^*} &= y^*(t^*) \left[1 - x^*([t](t^* - \frac{\tau}{[t]})) \right] \\ &= y^*(t^*) \left[1 - y^*(t^* - \tau r) \right] \end{aligned}$$

$$\because y^*(t^*) = x^*([t]t^*)$$

$$\Rightarrow \frac{dy^*(t^*)}{dt^*} = y^*(t^*) \left[1 - y^*(t^* - \underline{\underline{\tau}}) \right]$$

$$\Rightarrow \frac{dy}{dt} = \underline{\underline{y(t) \left[1 - y(t - \tau) \right]}}$$

Here τ is the relative size of delay which is very important as it may cause oscillation or because of which carrying capacity is not constant.

\therefore the relative size of the delay is one of the sources for the system to lose its stability at carry capacity ($y=1$) and for the occurrence of non-linear oscillation.

Linear stability Analysis:

$$\underline{\underline{y(t) = 1 + \varepsilon z(t)}}, \quad \varepsilon \ll 1$$

[$\because K \sim 1$ and case to observe is near carrying capacity]

$$\Rightarrow \varepsilon \frac{dz(t)}{dt} = \left[\underline{\underline{1 + \varepsilon z(t)}} \right] \left[\underline{\underline{1 - 1 - \varepsilon z(t - \tau)}} \right]$$

$$\Rightarrow \frac{dz(t)}{dt} = -z(t - \tau) - \varepsilon \underline{\underline{z(t) z(t - \tau)}}$$

$$\underline{\underline{\varepsilon \ll 1}} \Rightarrow \frac{dz}{dt} = -z(t - \tau)$$

$$\text{Let } z(t) = z_0 e^{\lambda t} \quad (\text{solution})$$

$$\text{Then } \frac{d}{dt} z_0 e^{\lambda t} = -z_0 e^{\lambda(t - \tau)}$$

$$\Rightarrow \lambda z_0 e^{\lambda t} = -z_0 e^{\lambda t} \cdot e^{-\lambda \tau}$$

$$\Rightarrow \lambda = -e^{-\lambda \tau}$$

$$\Rightarrow \underline{\underline{\lambda + e^{-\lambda \tau} = 0}} \quad [\text{transcendental equation}]$$

This is the characteristic equation.

Note that $1 + e^{-\lambda\tau} = 0$ has no real solution as $g(\frac{\lambda}{\tau}) = \underline{\lambda + e^{-\lambda\tau}}$ has absolute minimum of 1 at $\lambda = 0$

$$\left[\begin{aligned} \because g'(\lambda) &= 1 - \tau e^{-\lambda\tau} = 0 \\ \Rightarrow \frac{1}{\tau} &= e^{-\lambda\tau} \Rightarrow \lambda = -\frac{1}{\tau} \ln \tau \\ \Rightarrow &\text{absolute min of } 1 \text{ at } \lambda = 0 \end{aligned} \right]$$

Let's seek for complex solution $\lambda = a + ib$

$$\begin{aligned} a + ib + e^{-\tau(a+ib)} &= 0 \\ \Rightarrow a + ib + e^{-a\tau} \cdot e^{-ib\tau} &= 0 \\ \Rightarrow a + ib + e^{-a\tau} (\cos b\tau - i \sin b\tau) &= 0 \\ \Rightarrow (a + e^{-a\tau} \cos b\tau) + i (b - e^{-a\tau} \sin b\tau) &= 0 \end{aligned}$$

Equating the real and imaginary parts, we get

$$\begin{cases} a + e^{-a\tau} \cos b\tau = 0 \\ b - e^{-a\tau} \sin b\tau = 0 \end{cases}$$

$$\Rightarrow \begin{cases} e^{-a\tau} \cos b\tau = -a \\ e^{-a\tau} \sin b\tau = b \end{cases}$$

• $\tau = 0$ (no delay)

$$a = -1, b = 0$$

$$Z(t) = Z_0 e^{-t} \rightarrow 0 \text{ as } t \rightarrow \infty$$

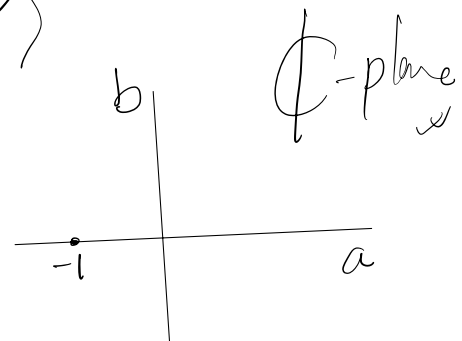
$$\Rightarrow y(t) \rightarrow 1 \text{ as } t \rightarrow \infty$$

$\therefore y^* = 1$ (carrying capacity) is asymptotically stable.

• $\tau < 1$ (small delay)

$$\Rightarrow \underline{a < 0}, \quad 0 < b < 1$$

$$\Rightarrow e^{\lambda t} = \underline{e^{at}} \cdot e^{ibt} \rightarrow 0 \text{ as } t \rightarrow \infty$$



$$Z(t) = Z_0 e^{\lambda t} = Z_0 e^{at} (\cos bt + i \sin bt)$$

$$\longrightarrow 0 \text{ as } t \rightarrow \infty$$

$$\text{i.e. } y(t) \longrightarrow 1 \text{ as } t \rightarrow \infty.$$

$\Rightarrow y^*(t) = 1$ (carrying capacity) is asymptotically stable.

\Rightarrow No oscillation can be observed in a not too large delay.

• large τ :

Q: (Is there a value of τ) what would be the critical value of τ when one obtains periodic solution?

Assume that $\hat{\tau}$ is the critical value, $a = 0$ for $\tau = \hat{\tau}$.

$$\Rightarrow \begin{cases} \cos b \hat{\tau} = 0 \\ \sin b \hat{\tau} = b \end{cases}$$

$$\Rightarrow \begin{cases} b \hat{\tau} = \frac{\pi}{2} + 2k\pi \\ \cos^2 b \hat{\tau} + \sin^2 b \hat{\tau} = b^2 \Rightarrow b = 1 \text{ (positive value)} \end{cases}$$

$$\Rightarrow \hat{\tau} = \frac{\pi}{2}$$

At critical value $\hat{\tau} = \frac{\pi}{2}$,

$$Z(t) = Z_0 e^{it} = Z_0 (\cos t + i \sin t).$$

In this case, $\frac{dZ(t)}{dt} = -Z(t-\tau)$ has a solution $Z(t) = \cos t + i \sin t$, periodic with period 2π . For the original logistic equation, the

oscillation takes place at $\tau = \frac{\hat{z}}{\gamma} = \frac{\pi}{2\gamma}$.

$$\frac{\text{Period}}{\text{delay}} = \frac{2\pi}{\pi/2\gamma} = 4\gamma$$

$$\therefore \text{Period} = 4\gamma \text{ delay.}$$