

## sec. 2.3 linear maps

$$\begin{aligned} \vec{u}_{n+1} &= f(\vec{u}_n) = M \cdot \vec{u}_n \\ \vec{u}_n &= \begin{pmatrix} x_n \\ y_n \end{pmatrix}, \quad M = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \end{aligned}$$

Def: A map  $A(\vec{v})$  from  $\mathbb{R}^m$  to  $\mathbb{R}^m$  is linear if  $\forall \alpha, \beta \in \mathbb{R}$  &  $\forall \vec{v}, \vec{w} \in \mathbb{R}^m$  we have:

$$A(\alpha \vec{v} + \beta \vec{w}) = \alpha A(\vec{v}) + \beta A(\vec{w})$$

- The origin  $\vec{0}$  will ALWAYS be a fixed pt of the map  $A(\vec{0}) = \vec{0}$

$$1D: f(x) = a \cdot x, \quad f'(x) = a$$

$\therefore$  Stab. given  $f'(0) = a$   
 $|a| < 1 \Rightarrow S$  &  $|a| > 1 \Rightarrow U$

$$2D: f(x) = A(x) = A \cdot \vec{x}$$

$\rightarrow$  Stab: check eigenvalues.

- Find eigenpairs:

$$\begin{aligned} A\vec{v} &= \lambda \vec{v} \quad \text{find } \begin{pmatrix} x \\ y \end{pmatrix} = \vec{v} \text{ & } \lambda \\ A\vec{v} &= \lambda I \vec{v} \Rightarrow [A - \lambda I] \vec{v} = \vec{0} \\ &\Rightarrow M \vec{v} = \vec{0} \end{aligned}$$

Non-trivial sols  $\Rightarrow \det(M) = |M| = 0$

$$\begin{aligned} M &= A - \lambda I = \begin{bmatrix} a & b \\ c & d \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \\ &= \begin{bmatrix} a-\lambda & b \\ c & d-\lambda \end{bmatrix} \end{aligned}$$

$$M = \begin{bmatrix} a-\lambda & b \\ c & d-\lambda \end{bmatrix}$$

$$\det(M) = (a-\lambda)(d-\lambda) - bc = 0$$

quadratic in  $\lambda$   $\begin{matrix} \swarrow \lambda_1 \\ \searrow \lambda_2 \end{matrix}$

- Evals: Solve  $|M| = 0 \Rightarrow \{\lambda_1, \lambda_2\}$

- Evecs: subs. in  $A\vec{v} = \lambda \vec{v} \Rightarrow$  compute  $\begin{pmatrix} x \\ y \end{pmatrix}$   
 $\nabla$  just need 1 eq. (since both are lin. dep.)

$$\begin{aligned} \text{Eigenpairs: } \langle \lambda_1, \vec{v}_1 \rangle &= \langle a, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rangle \\ \langle \lambda_2, \vec{v}_2 \rangle &= \langle b, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \rangle \end{aligned}$$

IC: aligned with evec.

$$\begin{aligned} \vec{v}_1: \vec{v}_1 &\xrightarrow{A} \lambda_1 \vec{v}_1 \xrightarrow{A} \lambda_1^2 \vec{v}_1 \xrightarrow{A} \dots \\ \vec{v}_2: \vec{v}_2 &\xrightarrow{A} \lambda_2 \vec{v}_2 \xrightarrow{A} \lambda_2^2 \vec{v}_2 \xrightarrow{A} \dots \end{aligned}$$

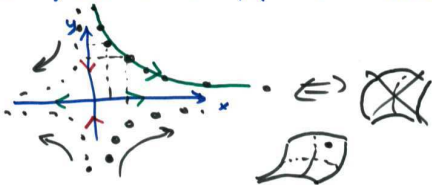
$$\begin{aligned} \text{In fact: } A^n(\vec{v}_1) &= \lambda_1^n \vec{v}_1 = a^n \vec{v}_1 \\ A^n(\vec{v}_2) &= b^n \vec{v}_2 \end{aligned}$$

Stability:  $|a| < 1$  &  $|b| < 1 \Rightarrow$  contraction  $\Rightarrow S$   
 $|a| > 1$  or  $|b| > 1 \Rightarrow$  expansion  $\Rightarrow U$

$\alpha$ : what happens if  $\vec{v}_0$  is not on  $\vec{v}_1$  or  $\vec{v}_2$ ?

$$\begin{aligned} A: \text{simple: just } \vec{v}_0 &= \alpha \vec{v}_1 + \beta \vec{v}_2 \\ \Rightarrow A(\vec{v}_0) &= A(\alpha \vec{v}_1 + \beta \vec{v}_2) = \alpha A(\vec{v}_1) + \beta A(\vec{v}_2) \\ &= \alpha \lambda_1 \vec{v}_1 + \beta \lambda_2 \vec{v}_2 \end{aligned}$$

$\nabla$   $|a| > 1, |b| < 1 \Rightarrow$  f. pt. is a SADDLE.



Ex 2.6: repeated evals

$$A = \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} \Rightarrow \begin{cases} \lambda_1 = a \\ \lambda_2 = a \end{cases}$$

$$A \begin{pmatrix} x_n \\ y_n \end{pmatrix} = \begin{pmatrix} x_{n+1} \\ y_{n+1} \end{pmatrix} : \begin{pmatrix} x_{n+1} \\ y_{n+1} \end{pmatrix} = A^n \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$$

So after  $p$  states I use  $A^p = \underbrace{A \dots A}_p$

$$p=1: A = \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix}$$

Eigen system: given matrix  $A$ ,  $\{\lambda, \vec{v}\}$  an eigenpair  $\lambda$ : eigenvalue &  $\vec{v}$ : eigenvector  
 if:  $A\vec{v} = \lambda \vec{v}$

$\alpha$ : what happens if IC is aligned with an eigenvector?

$A$ : IC:  $\vec{v}_0 = \vec{v}$  = eigenvector:

$$n=0: \vec{v}_0 \Rightarrow n=1 \quad \vec{v}_1 = A \vec{v}_0$$

$$\vec{v}_1 = A \vec{v}_0 = A \vec{v} = \lambda \vec{v} = \lambda \vec{v}_0$$

$$\vec{v}_1 = \lambda \vec{v}_0$$

$$\begin{aligned} n=2: \vec{v}_2 &= A \vec{v}_1 \\ &= A(\lambda \vec{v}_0) \\ &= \lambda A \vec{v}_0 \\ &= \lambda \lambda \vec{v}_0 \\ &= \lambda^2 \vec{v}_0 \end{aligned}$$

$$\begin{aligned} |\lambda| < 1 &\Rightarrow S \\ |\lambda| > 1 &\Rightarrow U \end{aligned}$$

- From charact. poly. in  $\lambda$  ( $|M|=0$ ) we see 3 cases:

1) Distinct REAL evals

2) repeated evals

3) complex evals (comp. conj.)

Ex 2.5: Distinct real evals.

$$\text{Ex: } A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\det(M) = \begin{vmatrix} a-\lambda & 0 \\ 0 & b-\lambda \end{vmatrix} = (a-\lambda)(b-\lambda) = 0$$

$$\lambda_1 = a, \lambda_2 = b$$

$$\text{evecs: } \lambda_1 = a: A \vec{v}_1 = \lambda_1 \vec{v}_1$$

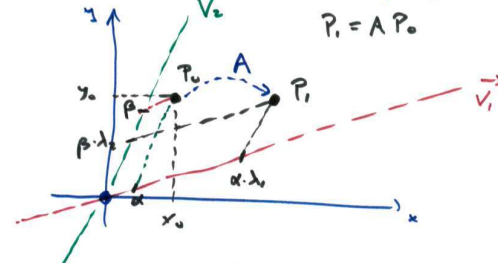
$$\Rightarrow \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = a \begin{pmatrix} x_1 \\ y_1 \end{pmatrix}$$

$$\Rightarrow \begin{cases} ax_1 = ax_1 \\ by_1 = ay_1 \end{cases} \Rightarrow \begin{cases} x_1 \in \mathbb{R} \\ y_1 = 0 \end{cases}$$

$$\Rightarrow \vec{v}_1 = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\lambda_2 = b \Rightarrow \vec{v}_2 = \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\begin{aligned} \vec{v}_0 &= \alpha \vec{v}_1 + \beta \vec{v}_2 \\ A(\vec{v}_0) &= \alpha \vec{v}_1 + \beta \vec{v}_2 \quad \text{where } \begin{cases} \alpha' = \alpha \lambda_1 \\ \beta' = \beta \lambda_2 \end{cases} \\ P_1 &= AP_0 \end{aligned}$$



Summary:  $A = \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix}$

$$\begin{pmatrix} x \\ y \end{pmatrix} \xrightarrow{A} \begin{pmatrix} ax \\ by \end{pmatrix}$$

$$A(N_{\vec{0}}(t)) \in \begin{matrix} b^t \\ a^t \end{matrix}$$

$$p=2: A^2 = \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} = \begin{pmatrix} a^2 & 0 \\ 0 & a^2 \end{pmatrix}$$

$$\begin{aligned} p=3: A^3 &= A^2 A = \begin{pmatrix} a^2 & 0 \\ 0 & a^2 \end{pmatrix} \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} = \begin{pmatrix} a^3 & 0 \\ 0 & a^3 \end{pmatrix} \\ &= \begin{pmatrix} a^3 & 0 \\ 0 & a^3 \end{pmatrix} = a^2 \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} \end{aligned}$$

$$A^2 = a^2 \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix}$$

$$A^3 = a^2 \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} \dots A^p = a^{p-1} \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix}$$

$$A^p = \begin{pmatrix} a^p & 0 \\ 0 & a^p \end{pmatrix} = \begin{pmatrix} a^p & 0 \\ 0 & a^p \end{pmatrix} + \begin{pmatrix} 0 & pa^{p-1} \\ 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \end{pmatrix} \xrightarrow{A^p} \begin{pmatrix} a^p x \\ a^p y \end{pmatrix} + \underline{pa^{p-1} y}$$