

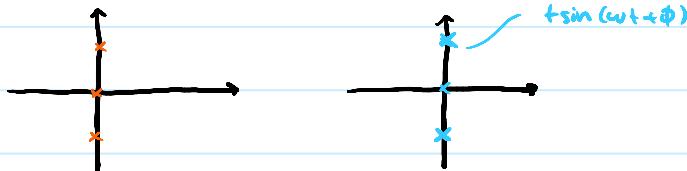
# Lecture 17

October 15, 2021 3:09 PM

**Observation:** A signal  $f(t)$  is bounded iff

$F(s)$  has poles with real part  $\leq 0$  and non-repeated poles with real part  $= 0$ .

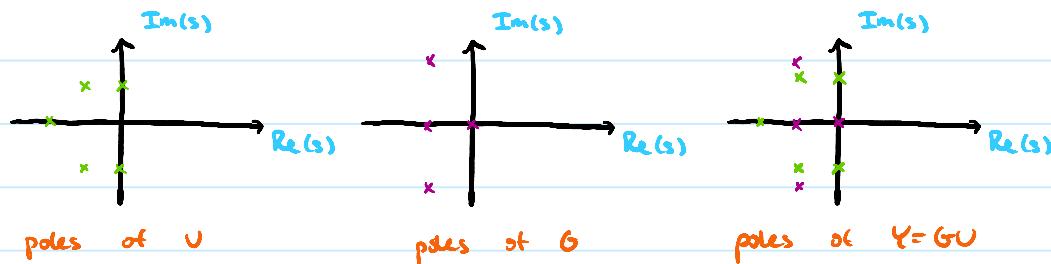
Property B



**Goal:** Find conditions for  $G$  under which the following implication holds:

$\forall u(t) \quad (u(t) \text{ bounded} \Rightarrow y(t) \text{ bounded})$

$\forall U(s)$  with property B,  $Y(s) = G(s)U(s)$  also has property B



If  $G$  has a pole anywhere on the imag. axis,

$\exists U(s)$  s.t.  $Y = GU$  is unbounded

(e.g.,  $\exists U(s)$  s.t.  $U, G$  share a pole on the imag. axis)

leads to yielding a repeated pole on imag. axis

WLOG, pick  $u(t)$  s.t.  $U(s)$  has no zeroes

↳ Then  $\{ \text{poles of } Y(s) \} = \{ \text{poles of } G(s) \cup \text{poles of } U(s) \}$

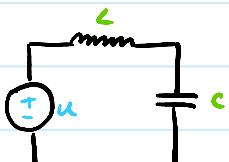
Want poles of  $Y$  to satisfy B for any  $U(s)$  satisfying B

↳  $G(s)$  cannot have poles with real part  $\geq 0$

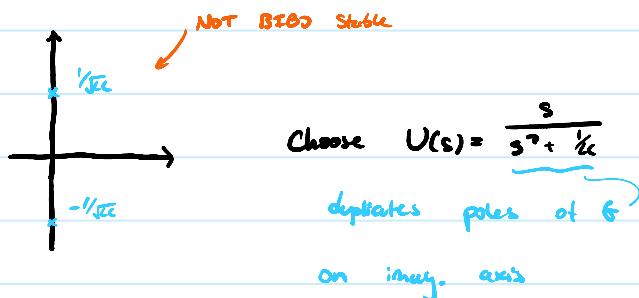
### Theorem 2:

↳  $Y(s) = G(s)U(s)$  is **BIBO Stable** iff all poles of  $G$  are in OLMR

e.g. Ideal LC circuit



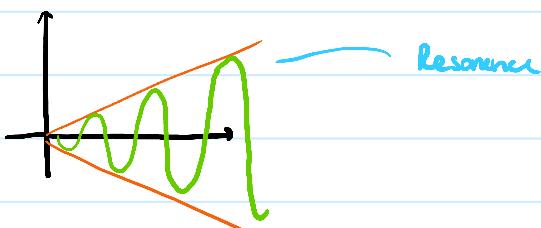
$$Y(s) = \frac{1/C}{s^2 + 1/LC} U(s)$$



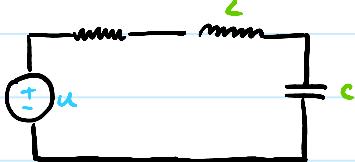
$$u(t) = \cos(\frac{1}{\sqrt{LC}} t + \phi)$$

$$Y(s) = \frac{s/\sqrt{LC}}{(s^2 + 1/\sqrt{LC})^2}$$

$$y(t) = \frac{1}{2\sqrt{LC}} t \sin(\frac{1}{\sqrt{LC}} t) + \frac{1}{2\sqrt{LC}} \cos(\frac{1}{\sqrt{LC}} t)$$

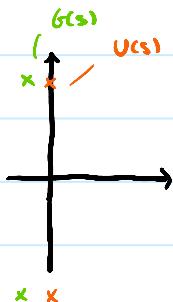


Now consider - RLC circuit



$$\frac{Y(s)}{U(s)} = \frac{\frac{1}{sC}}{s^2 + \frac{R_L}{L}s + \frac{1}{LC}}$$

poles in OHP  $\Rightarrow$  BIBO stable, no resonance



$$\text{Try again: } U(s) = \frac{s}{s^2 + \frac{1}{LC}}$$

$$y(t) = Ce^{-bt} \cos(\omega_0 t + \phi) + D \sin\left(\frac{1}{\sqrt{LC}} t + \varphi\right)$$

Theorem 1 - Asymptotic Stability

↳ eigenvalues of  $A$  in OHP

Theorem 2 - BIBO Stability

↳ poles of  $G(s)$  in OHP

Q: Is there a relationship between the eigenvalues of  $A$  and the poles of  $G$ ?

$$\dot{x} = Ax + Bu$$

$$\Rightarrow G(s) = C(sI - A)^{-1}B + D$$

$$y = Cx + Du$$

$$\left\{ \begin{array}{l} \text{eigenvalues of } A \\ n \end{array} \right\} \leftrightarrow \left\{ \begin{array}{l} \text{Poles of } G \\ \leq n \end{array} \right\}$$

$$G(s) = \frac{1}{\det(sI-A)} [C \text{Ad}_s(sI-A)B + D]$$

poly of degree  $\leq n$

The poles of  $G$  are necessarily the roots of  $\det(sI-A)$

↳ these are the eigenvalues of  $A$

↳ if  $p$  is a pole in  $G$ , then  $p$  is an eigenvalue of  $A$

↳  $\{\text{Poles of } G\} \subset \{\text{eigenvalues of } A\} = \text{spectrum of } A$

↳ some singularities may be cancelled by zeros

↳ singularities — eigenvalues of  $A$

e.g.

$$\dot{x}_1 = -x_1 + u$$

$$\dot{x}_2 = x_2$$

$$y = x_1$$

$$A = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\text{eigenvalues} = \{-1, 1\}$$

Sys unstable

↳ singularity at 1

$$x_2(u) = e^t x_2(0)$$

$$G(s) = [1 \ 0] \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \frac{1}{s+1}$$

$\therefore$  System is actually BIBO stable