

Lecture 7

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Residue Theorem

$$\mathcal{L}^{-1}\{F(s)\} = \sum_{i=1}^N \text{Res}(F(s)e^{st}, s=p_i) \quad \text{where } p_1, \dots, p_N \text{ are poles of } F$$

$$\text{Res}(G(s), s=p) := \frac{1}{(r-1)!} \left. \frac{d^{r-1}}{ds^{r-1}} [G(s)(s-p)^r] \right|_{s=p} \quad \text{where } r = \text{multiplicity of } p$$

eg. Find $\mathcal{L}^{-1}\{F(s)\} = \mathcal{L}^{-1}\left\{\frac{1}{(s+1)(s^2+2s+2)}\right\}$

$$F(s) = \frac{1}{(s+1)(s^2+2s+2)} \quad \mathcal{L}^{-1}\{F(s)\} = \text{Res}(F(s)e^{st}, s=-1) + \text{Res}(F(s)e^{st}, s=-1+i) + \text{Res}(F(s)e^{st}, s=-1-i)$$

$$f(t) = \mathcal{L}^{-1}\{F(s)\} = \frac{e^{-t}}{1-2+2} + \frac{e^{(-1+i)t}}{(-1+i+1)(-1+i+1+i)} + \frac{e^{(-1-i)t}}{(-1-i+1)(-1-i+1-i)}$$

$$= e^{-t} + e^{-t} \left(\frac{e^{it}}{(2-i)(i)} + \frac{e^{-it}}{(-i)(1-2i)} \right) = e^{-t} [1 - \cos(t)] 1(t)$$

Alternatively, using PF

$$F(s) = \frac{1}{(s+1)(s^2+2s+2)} = \frac{A}{s+1} + \frac{Bs+C}{s^2+2s+2} \quad \text{Find } \begin{matrix} A=1 \\ B=-1 \\ C=-1 \end{matrix}$$

$$= \frac{1}{s+1} - \frac{s+1}{s^2+2s+2}$$

$$= \frac{1}{s+1} - \frac{s+1}{(s+1)^2+1} \Rightarrow f(t) = (e^{-t} - e^{-t}\cos(t)) 1(t)$$

eg. RLC circuit

$$LC \frac{d^2y}{dt^2} + RC \frac{dy}{dt} + y = u(t) \quad y = V_C$$

Note: Use Laplace Transforms to solve constant coeff. ODEs (TD Model)

$$u(t) = 1(t) \quad y(0) = \dot{y}(0) = 0$$

$$\mathcal{L}\{\dot{y}(t)\} = sY(s) - y(0) = sY(s)$$

$$\mathcal{L}\{\ddot{y}(t)\} = s^2Y(s) - sy(0) - \dot{y}(0) = s^2Y(s)$$

$$\mathcal{L}\{1(t)\} = \frac{1}{s}$$

$$LCs^2Y(s) + RCsY(s) + Y(s) = \frac{1}{s}$$

$$Y(s) = \frac{1/s}{LCs^2 + RCs + 1} \quad \text{pick } LC=1/5, R_L=4$$

$$= \frac{1/LC}{s(s^2 + R_Ls + 1/LC)}$$

$$= \frac{3}{s(s^2 + 4s + 5)} = \frac{3}{s(s+1)(s+5)}$$

$$y(t) = \mathcal{L}^{-1}\{Y(s)\} = \left[1 - \frac{3}{2}e^{-t} + \frac{1}{2}e^{-5t} \right] 1(t)$$



Check: $y(0)=0$ $\dot{y}(0)=0$



What if $y(0)=2$ $\dot{y}(0)=1$

$$LC\ddot{y} + RC\dot{y} + y = u$$

$$LC[s^2 Y(s) - s(2) - 1] + RC[sY(s) - 2] + Y(s) = 1/s$$

Initial conditions Not zero!

$$Y(s) = \frac{1/s}{LCs^2 + RCs + 1} + \frac{LC(2s+1) + 2RC}{LCs^2 + RCs + 1}$$

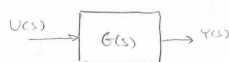
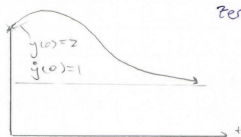
$$y(t) = y_1 + y_2$$

$$y_1 = \mathcal{L}^{-1} \left\{ \frac{1/s}{LCs^2 + RCs + 1} \right\}$$

Zero-state response

$$y_2 = \mathcal{L}^{-1} \left\{ \frac{LC(2s+1) + 2RC}{LCs^2 + RCs + 1} \right\}$$

Zero-input response



Transfer Function (TF)

$$\frac{d^m y}{dt^m} + a_{n-1} \frac{d^{n-1} y}{dt^{n-1}} + \dots + a_0 y = b_m \frac{d^m u}{dt^m} + \dots + b_0 u, \quad m \leq n \quad (\text{I/O Model})$$

Assume zero initial conditions: $y(0)=\dot{y}(0)=\ddot{y}(0)=\dots=\frac{d^{n-1}y}{dt^{n-1}}(0)=0$
 $u(0)=\dot{u}(0)=\ddot{u}(0)=\dots=\frac{d^{m-1}u}{dt^{m-1}}(0)=0$

TF does NOT take into account initial conditions

$$\mathcal{L} \left\{ \frac{d^m y}{dt^m} \right\} = s^m Y(s); \quad \mathcal{L} \left\{ \frac{d^k u}{dt^k} \right\} = s^k U(s)$$

$$Y(s) [s^n + a_{n-1}s^{n-1} + \dots + a_1s + a_0] = U(s) [b_ms^{m-1} + \dots + b_0]$$

$$Y(s) = \frac{b_ms^{m-1} + \dots + b_0}{s^n + a_{n-1}s^{n-1} + \dots + a_1s + a_0} U(s)$$

$G(s) = \frac{b_ms^{m-1} + \dots + b_0}{s^n + a_{n-1}s^{n-1} + \dots + a_1s + a_0}$ is the Transfer Function!!

(IO) \Leftrightarrow (TF)
Time Domain \quad s Domain

$$Y(s) = G(s) U(s)$$