

CS21BTECH11061

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1 Linear Systems and Signal Processing Assignment

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```
[ ]: import numpy as np
import scipy as sp
import matplotlib.pyplot as plt
from scipy.io import wavfile
```

2 Question 2

2.1 Question (A)

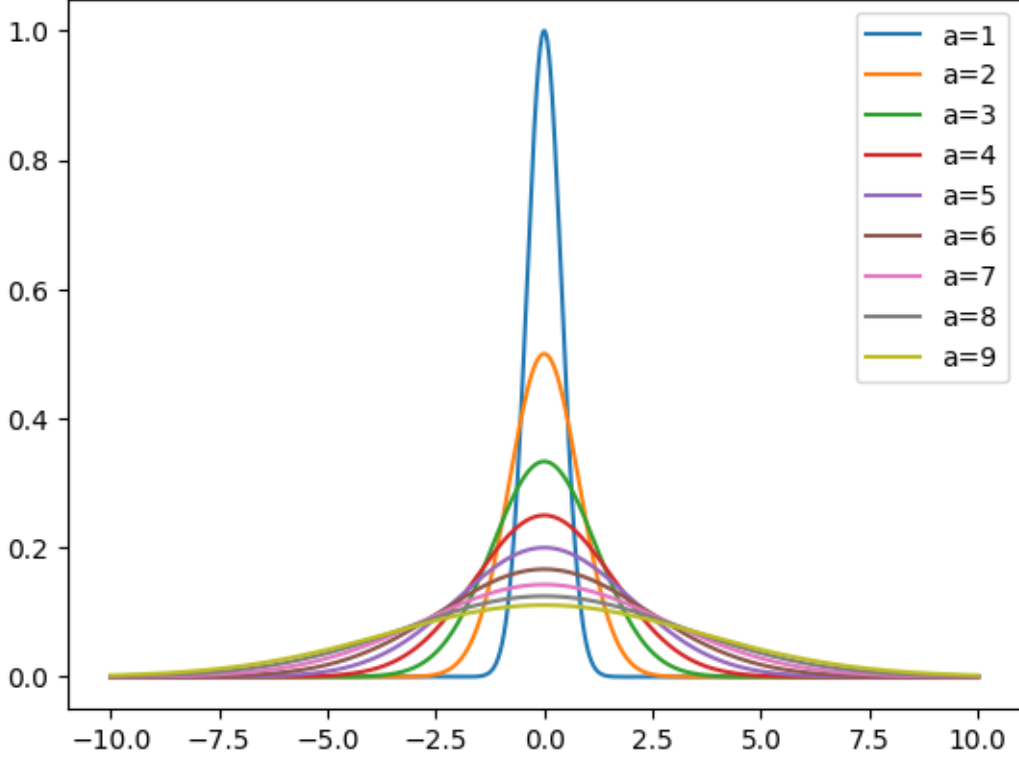
By the below graphs, it can be seen as a :

- Increases, then the width of the distribution decreases and the height increases.
- Decreases, then the width of the distribution increases and the height decreases.

```
[ ]: def func(x,a):
    return (1/a)*np.exp(-(np.pi*x*x)/(a*a))

x = np.linspace(-10,10,1000)
arr = np.arange(1,10)
for a in arr:
    plt.plot(x,func(x,a),label='a='+str(a))

plt.legend()
plt.show()
```



2.2 Question (B)

If $a = 1$, and we take 20 samples per second then $R_{time} = \frac{1}{20}$

$$f(t) = e^{-\pi t^2}$$

$$\mathcal{F}f(s) = e^{-\pi s^2}$$

Approximate the integral using the sequence $f(nR_{time})$ for $-\infty < n < \infty$

$$\mathcal{F}f(s) \approx \sum_{n=-\infty}^{\infty} f\left(\frac{n}{R_{time}}\right) e^{-2\pi i s n R_{time}}$$

$$\mathcal{F}f(s) \approx \sum_{n=-\infty}^{\infty} f\left(\frac{n}{20}\right) e^{-\frac{\pi i s n}{10}}$$

2.3 Question (C)

$w_1(t)$ will limit the signal from $-\frac{L}{2}$ to $\frac{L}{2}$. Thus, summation will go from $-10L$ to $10L$

$$\mathcal{F}f(s) = \sum_{n=-10L}^{10L} f\left(\frac{n}{20}\right) e^{-\frac{\pi i s n}{10}}$$

2.4 Question (D)

For $s = mR_{freq}$,

$$\mathcal{F}f(s) = \sum_{n=-10L}^{10L} f\left(\frac{n}{20}\right) e^{-\frac{\pi i m R_{freq} n}{10}}$$

2.5 Question (E)

If:

$$LR_{freq} = 1 = BR_{time}$$

Then,

$$R_{time} = \frac{1}{B}$$

$$R_{freq} = \frac{1}{L}$$

The range of nR_{time} is $[-\frac{L}{2}, \frac{L}{2}]$. Thus,

$$-\frac{BL}{2} \leq n \leq \frac{BL}{2}$$

The range of mR_{freq} is $[-\frac{L}{2}, \frac{L}{2}]$. Thus,

$$-\frac{BL}{2} \leq n \leq \frac{BL}{2}$$

Number of values in both the domains are BL .

Sampling at twice the highest frequency according to **Nyquist Sampling** theorem, we have,

$$freq_{max} = \frac{B}{2}$$

Only at these sampling rates, the continuous fourier transform and the DFT are can related by discretizing time and frequency.

$$e^{2\pi i s t} \text{ becomes } e^{2\pi i m n R_{freq} R_{time}}$$

Substituting $R_{time} = \frac{1}{B}$ and $R_{freq} = \frac{1}{L}$ and $BL = N$:

$$= e^{\frac{2\pi i m n}{N}}$$

which is the exponent used in DFT.

2.6 Question (F)

Using $a = 1$, 20 samples per second

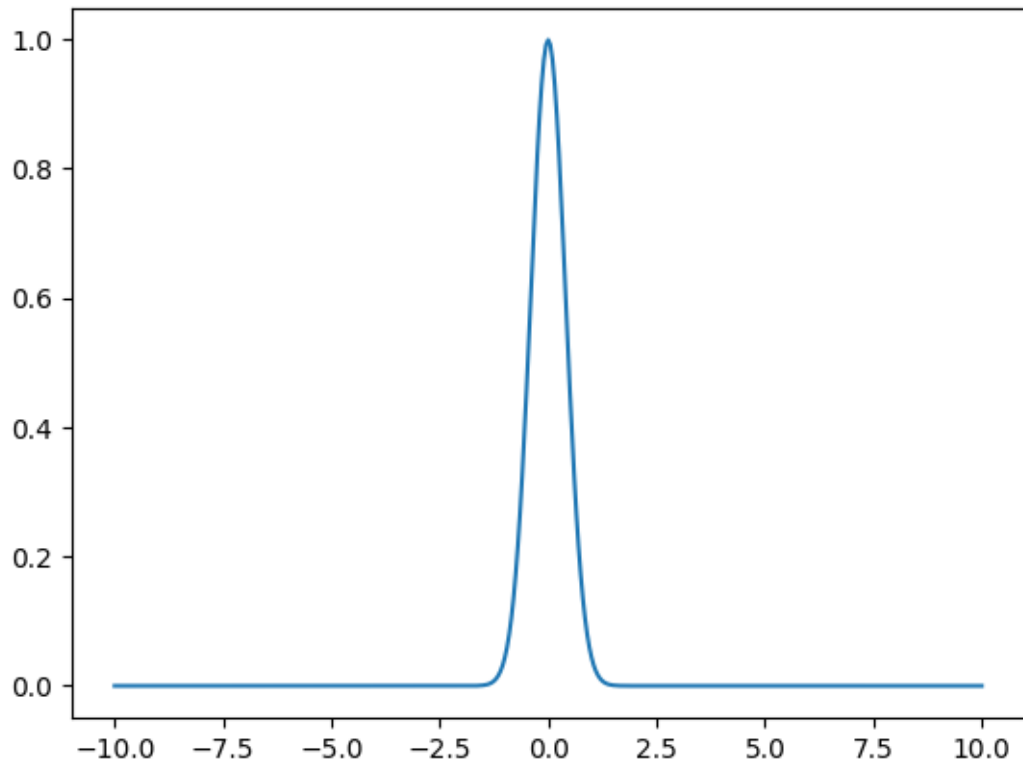
```
[ ]: L = 20
      B = 20
      Rt = 1 / B
      Rf = 1 / L

      def func(n):
          return np.exp(-np.pi*n*n)

      def pl(B,L, f):
          ran = np.arange(-L/2,(L/2)+(1/B),(1/B))
          s=np.arange(-B/2,B/2+(1/L),(1/L))
          y=np.fft.fftshift(np.absolute(np.fft.fft(f(ran)))/np.sqrt(len(f(ran))))
          return s,y

      s,y = pl(B,L, func)
      plt.plot(s,y)
```

```
[ ]: [ <matplotlib.lines.Line2D at 0x7fe5ad0f5510>]
```



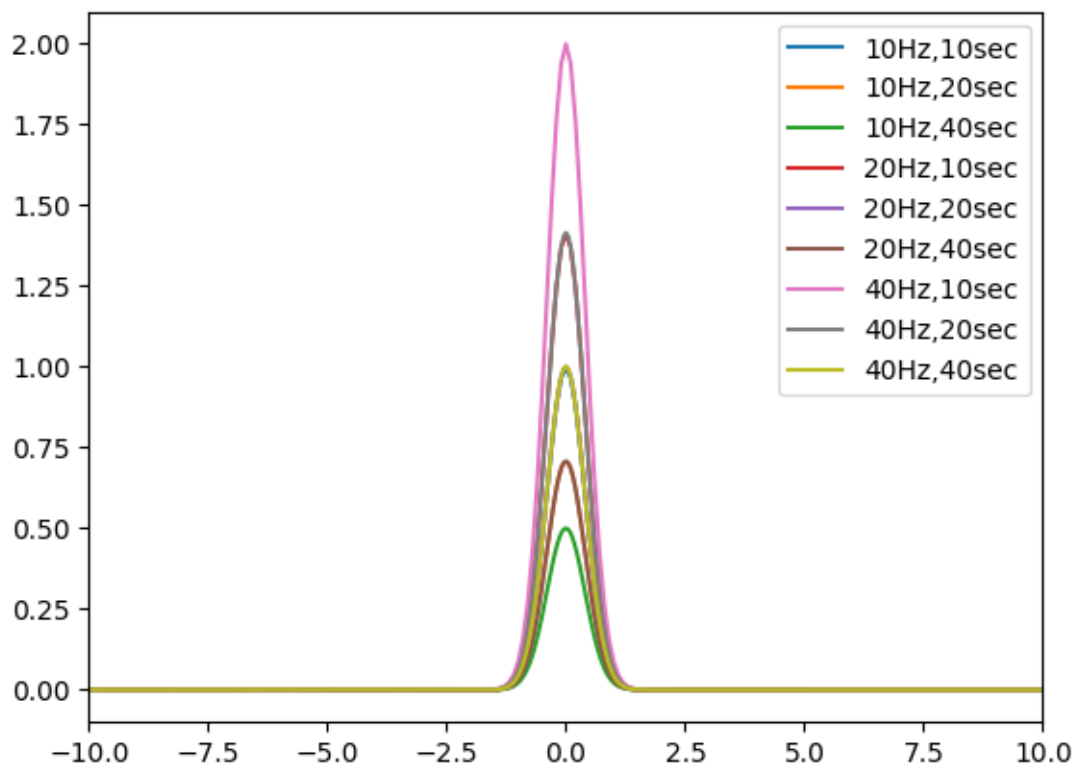
2.7 Question (G)

Since, the ideal condition is:

$$LR_{freq} = BR_{time} = 1$$

```
[ ]: for B in [10,20,40]:
      for L in [10,20,40]:
          s,y = pl(B,L, func)
          plt.plot(s,y,label=str(B)+'Hz,'+str(L)+'sec')

plt.legend()
plt.xlim(-10,10)
plt.show()
```



The function is smoother with more samples per unit bandwidth, which is why in the above graph 10Hz, 40sec graph is the smoothest.

Also,

$$Amplitude \propto \frac{B}{L}$$

2.8 Question (H)

For:

$$w_2(t) = \begin{cases} 1 - \frac{2|t|}{L} & \text{for } |t| < \frac{L}{2} \\ 0 & \text{elsewhere} \end{cases}$$

and

$$w_3(t) = \begin{cases} \sin^2 \frac{2\pi t}{L} & \text{for } |t| < \frac{L}{2} \\ 0 & \text{elsewhere} \end{cases}$$

```
[ ]: B = 20
     L = 20
```

```

def w2(x):
    if np.abs(x) <= L/2:
        return 1 - 2*np.abs(x)/L
    else:
        return 0

def w3(x):
    if np.abs(x)<=L/2:
        return np.sin(2*np.pi*x/L)**2
    else:
        return 0

ran = np.arange(-L/2,L/2+(1/B),1/B)
s = np.arange(-B/2,B/2+(1/L),(1/L))

filt=np.zeros((len(s)))
ffilt=np.zeros((len(s)))

for i in range(0, B*L + 1):
    filt[i]=w2(-L/2+(i/B))

ffilt=np.multiply(filt,func(ran))

y=np.fft.fftshift(np.absolute(np.fft.fft(ffilt))/np.sqrt(len(ffilt)))

plt.plot(s,y, label='For W2(x)')

for i in range(0, B*L + 1):
    filt[i]=w3(-L/2+(i/B))

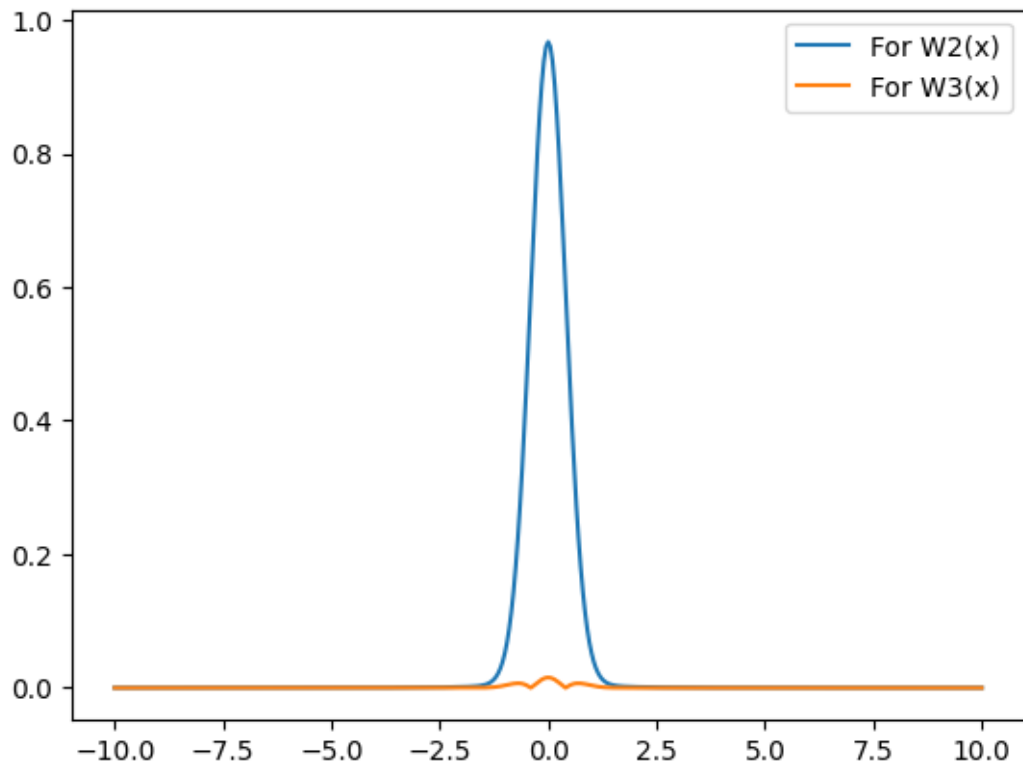
ffilt=np.multiply(filt,func(ran))

y=np.fft.fftshift(np.absolute(np.fft.fft(ffilt))/np.sqrt(len(ffilt)))

plt.plot(s,y, label='For W3(x)')
plt.legend()

```

```
[ ]: <matplotlib.legend.Legend at 0x7fe5bca4f650>
```



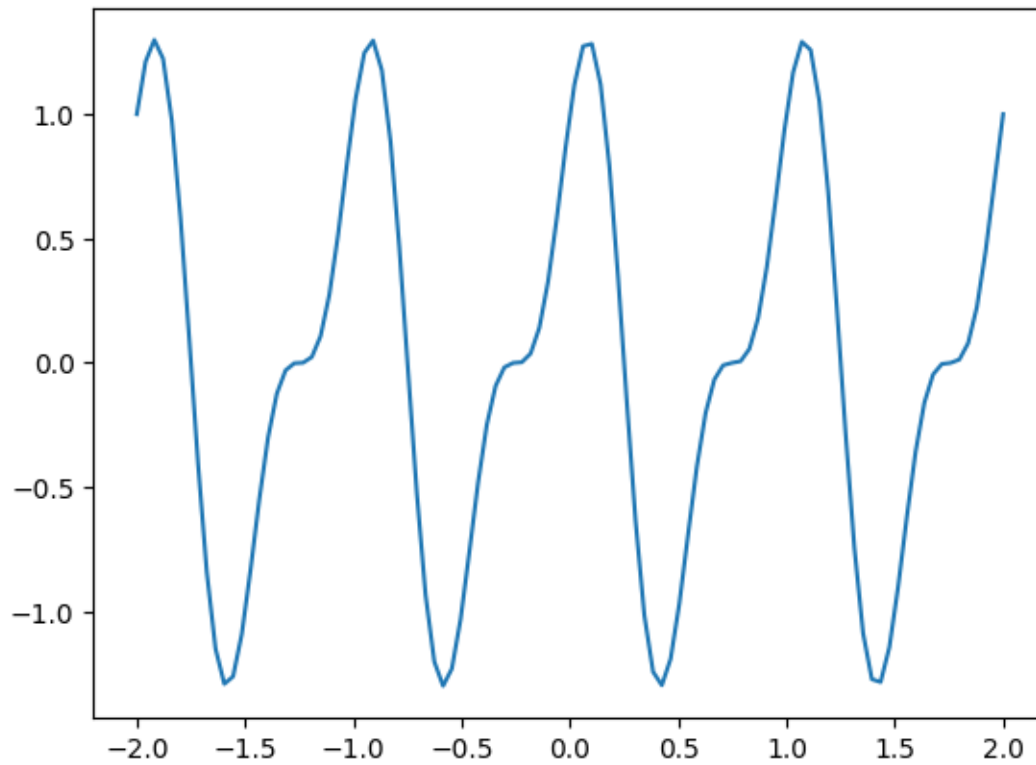
2.9 Question (I)

For:

$$g(t) = \cos(2\pi t) + 0.5\sin(4\pi t)$$

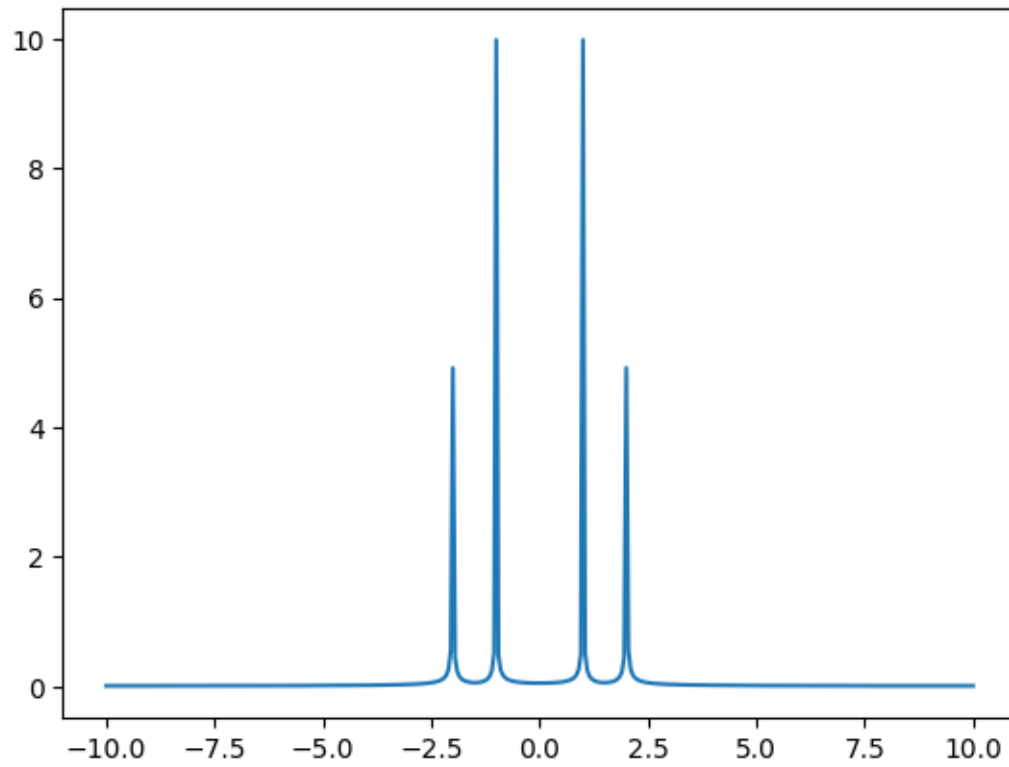
```
[ ]: def func2(x):  
      return np.cos(2*np.pi*x) + 0.5*np.sin(4*np.pi*x)  
  
      x = np.linspace(-2,2,100)  
  
      plt.plot(x,func2(x))
```

```
[ ]: [<matplotlib.lines.Line2D at 0x7fe5acfe8510>]
```

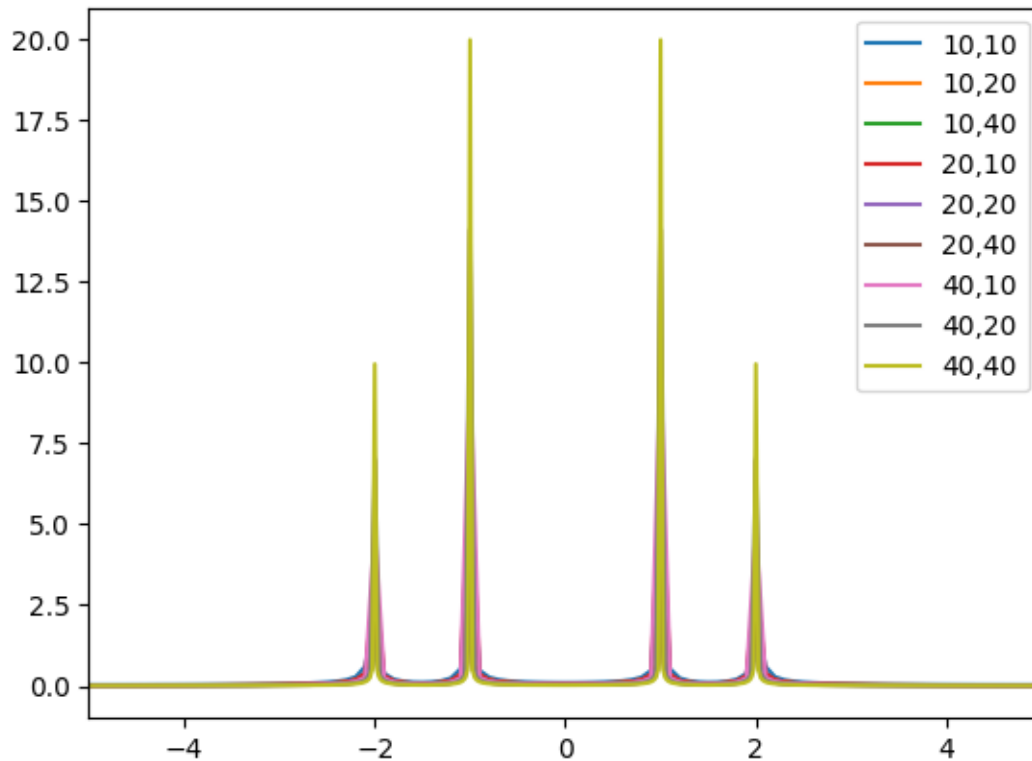



```
[ ]: # DFT  
  
L = 20  
B = 20  
Rtime=1/B  
Rfreq=1/L  
  
s,y = pl(B,L, func2)  
plt.plot(s,y)
```

```
[ ]: [<matplotlib.lines.Line2D at 0x7fe5ad13e990>]
```



```
[ ]: for B in [10,20,40]:  
      for L in [10,20,40]:  
          s,y = pl(B,L, func2)  
          plt.plot(s,y,label=str(B)+' '+str(L))  
  
plt.legend()  
plt.xlim(-5,5)  
plt.show()
```



```
[ ]: ran = np.arange(-L/2,L/2+(1/B),1/B)
s = np.arange(-B/2,B/2+(1/L),(1/L))

filt=np.zeros((len(s)))
ffilt=np.zeros((len(s)))

for i in range(0,B*L+1):
    filt[i]=w2(-L/2+(i/B))

ffilt=np.multiply(filt,func2(ran))

y=np.fft.fftshift(np.absolute(np.fft.fft(ffilt))/np.sqrt(len(ffilt)))

plt.plot(s,y, label='For W2(x)')
plt.legend()

for i in range(0,B*L+1):
    filt[i]=w3(-L/2+(i/B))

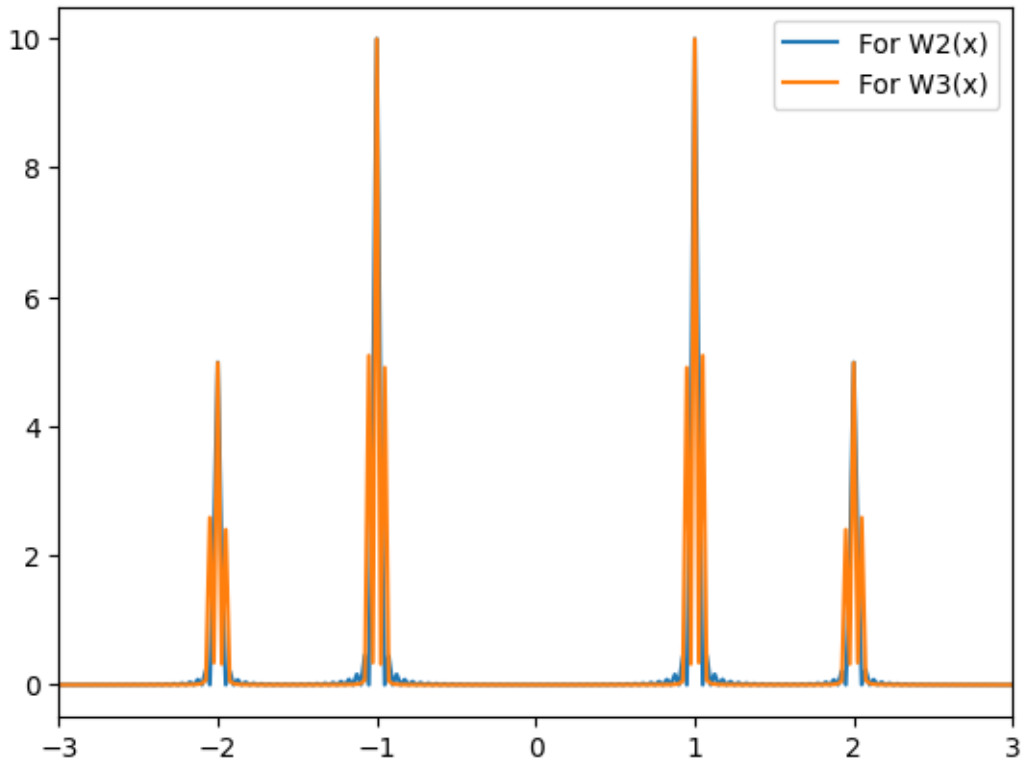
ffilt=np.multiply(filt,func2(ran))

y=np.fft.fftshift(np.absolute(np.fft.fft(ffilt))/np.sqrt(len(ffilt)))
```

```
plt.plot(s,y, label='For W3(x)')
plt.legend()

plt.xlim(-3,3)
```

```
[ ]: (-3.0, 3.0)
```



3 Question 3

Let frame rate of camera be R_1 and frame rate of rotor be R_2 .

3.1 Question (A)

The helicopter is flying, yet the rotor is not turning. This is because the number of rotations of rotor per second per blade is an integral multiple of the frame rate of the camera. So, the rotor appears to be stationary.

$$nR_1 = \frac{R_2}{N}$$

where n is a integer and N is the number of blades in the rotor.

3.2 Question (B)

For $nR_1 = \frac{R_2}{5}$ where n is an integer if the rotor has 5 blades.

Thus,

$$R_2 = 5nR_1$$

3.3 Question (C)

The assumption that the rotor has 5 blades is valid, because it is a frame shot.

Suppose, we had seen 6 blades then, the rotor would have 6 blades. due to the same reason.

$$nR_1 = \frac{R_2}{6}$$

4 Question 4

4.1 Question (A):

```
[ ]: # Generate a sinusoidal waveform with two frequency components, say 5 Hz and 10 Hz.
      ↪ Hz.
# The sampling rate must be chosen to properly produce the waveform without
      ↪ aliasing.
# Any rate above 20 Hz will suffice.
# Produce a one second plot of the waveform.

# Parameters
dur = 1 # 1 second
samp_rate = 1000 # 1000 samples per second

# Time axis
t = np.linspace(0, dur, int(samp_rate * dur), endpoint=False)

# Generate the sinusoidal waveform components
freq_1 = 5 # 5 Hz
freq_2 = 10 # 10 Hz

wave_1 = np.sin(2 * np.pi * freq_1 * t)
wave_2 = np.sin(2 * np.pi * freq_2 * t)
# wave_2 = 0

# Combine the two components to get the final waveform
wave_f = wave_1 + wave_2

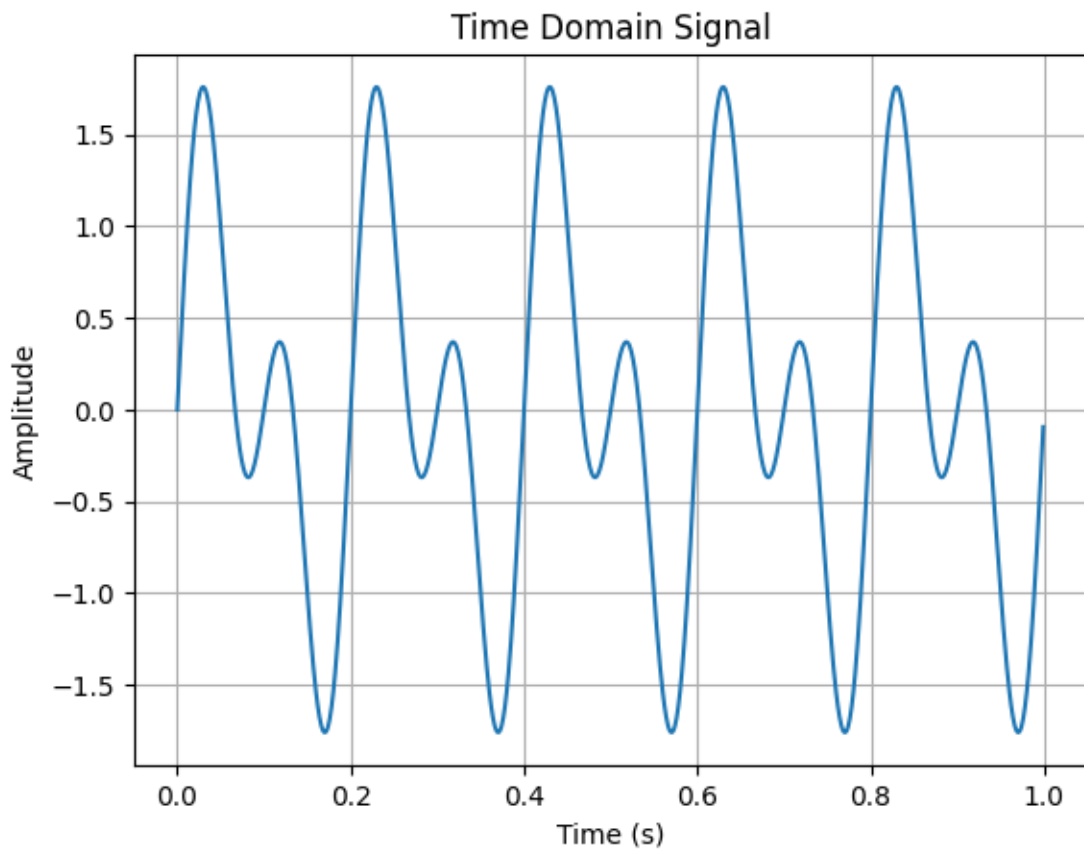
# Perform FFT
res_fft = np.fft.fft(wave_f)
```

```

# Plot the FFT result
plt.plot(t, wave_f)
plt.title('Time Domain Signal')
plt.xlabel('Time (s)')
plt.ylabel('Amplitude')
plt.grid(True)

plt.savefig('4.1.png')

```



4.2 Question (B):

```

[ ]: # We next will find the frequency spectrum of the signal from part a.
      # To do so, first use the Fast Fourier Transform function (numpy.fft) to
      ↪ compute the DFT and bring the signal into the frequency domain.
      # Use the fftshift function (numpy.fft.fftshift) to produce a plot that will
      ↪ zero centre the signal.

```

```

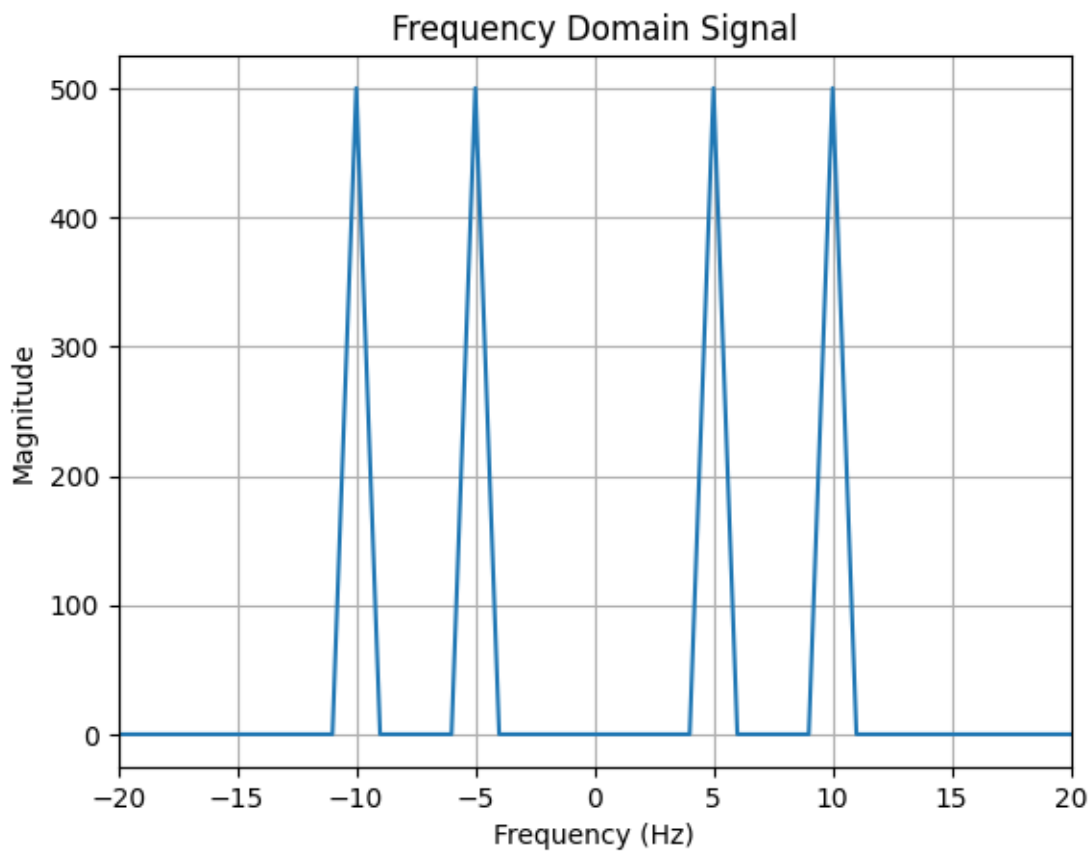
res_fftfreqs = np.fft.fftfreq(len(wave_f), 1/samp_rate)

# Shift the FFT result to center the frequencies
res_fft_shifted = np.fft.fftshift(res_fft)
res_fftfreqs_shifted = np.fft.fftshift(res_fftfreqs)

# Plot the FFT result (Frequency Domain)
plt.plot(res_fftfreqs_shifted, np.abs(res_fft_shifted))
plt.title('Frequency Domain Signal')
plt.xlabel('Frequency (Hz)')
plt.ylabel('Magnitude')
plt.grid(True)
plt.xlim(-20, 20)

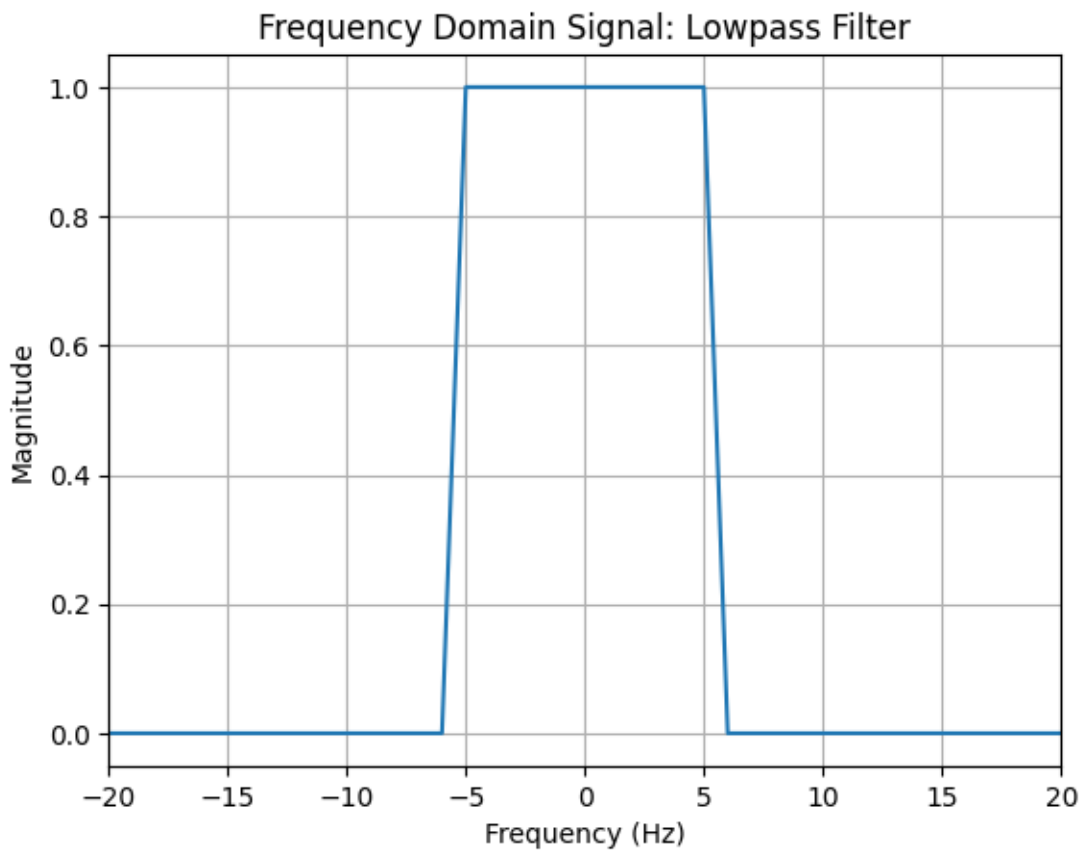
plt.savefig('4.2.png')

```



4.3 Question (C):

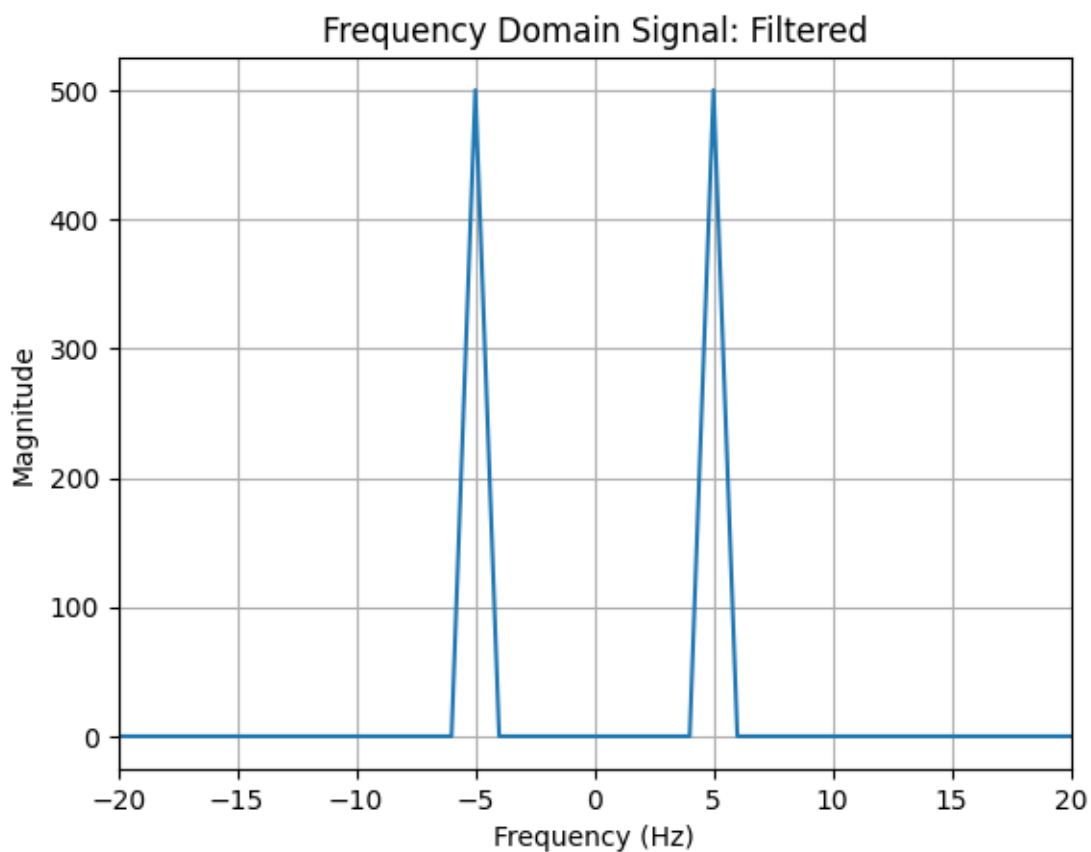
```
[ ]: # Now, create a lowpass filter to recover the 5 Hz component of the signal.  
# Produce a plot of the filter and the filtered signal in the frequency domain.  
  
# Create a lowpass filter  
cutoff_freq = 5  
filter_res = np.zeros_like(res_fftfreqs)  
filter_res[np.abs(res_fftfreqs) <= cutoff_freq] = 1  
filter_res_shifted = np.fft.fftshift(filter_res)  
  
# Plot the FFT result (Frequency Domain)  
plt.plot(res_fftfreqs_shifted, np.abs(filter_res_shifted))  
plt.title('Frequency Domain Signal: Lowpass Filter')  
plt.xlabel('Frequency (Hz)')  
plt.ylabel('Magnitude')  
plt.grid(True)  
plt.xlim(-20, 20)  
  
plt.savefig('4.3-1.png')
```




```
[ ]: # Apply the filter to the FFT result
sig_fft_filtered = np.fft.fftshift(res_fft * filter_res)

# Plot the FFT result (Frequency Domain)
plt.plot(res_fftfreqs_shifted, np.abs(sig_fft_filtered))
plt.title('Frequency Domain Signal: Filtered')
plt.xlabel('Frequency (Hz)')
plt.ylabel('Magnitude')
plt.grid(True)
plt.xlim(-20, 20)

plt.savefig('4.3-2.png')
```



4.4 Question (D):

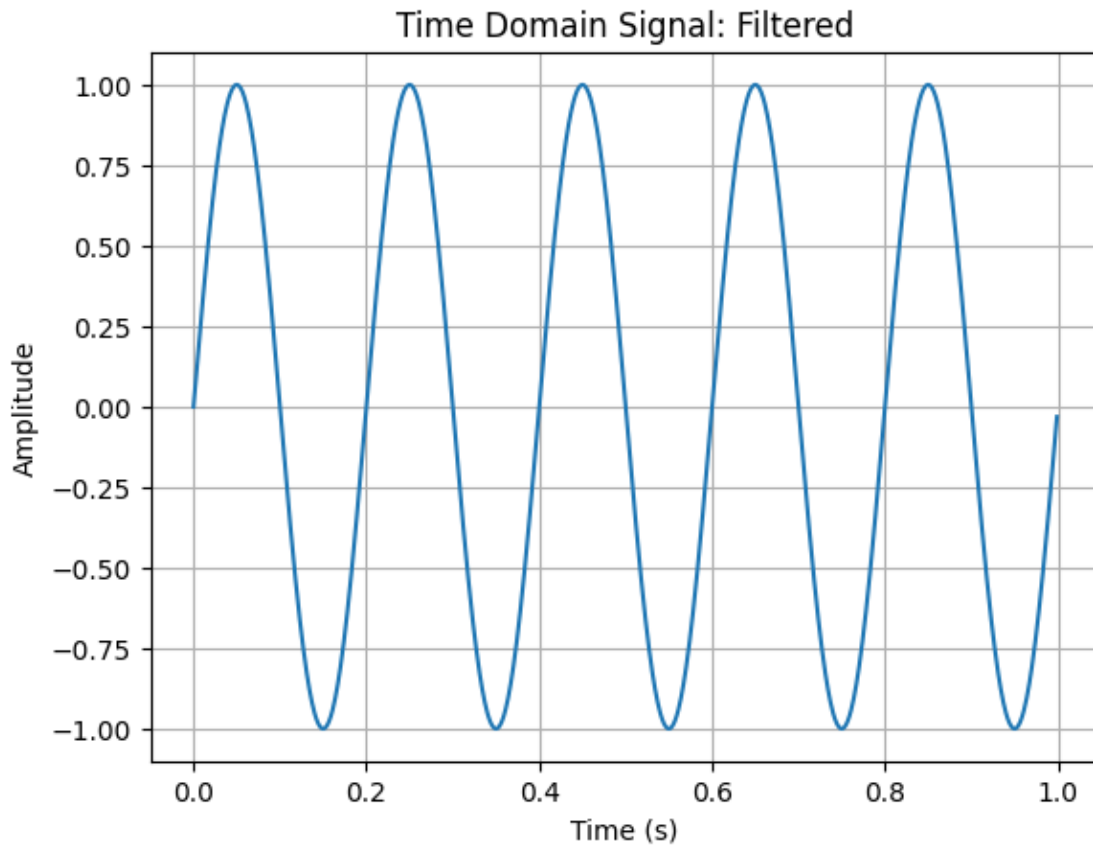
```
[ ]: # With the filtered signal, take the Inverse Discrete Fourier Transform (via
↳ numpy.ifft) to bring the signal back into the time domain.
# Produce a plot with one second of the signal to show that the 5 Hz signal was
↳ recovered.
```

```
# Perform Inverse FFT
sig_filtered = np.fft.ifft(np.fft.ifftshift(sig_fft_filtered))

# Plot the IFFT result
plt.plot(t, sig_filtered)
plt.title('Time Domain Signal: Filtered')
plt.xlabel('Time (s)')
plt.ylabel('Amplitude')
plt.grid(True)

plt.savefig('4.4.png')
```

```
/home/sterben/.local/lib/python3.11/site-packages/matplotlib/cbook.py:1699:
ComplexWarning: Casting complex values to real discards the imaginary part
    return math.isfinite(val)
/home/sterben/.local/lib/python3.11/site-packages/matplotlib/cbook.py:1345:
ComplexWarning: Casting complex values to real discards the imaginary part
    return np.asarray(x, float)
```



5 Question 5

Note for running code: > For the wav file, keep it in a folder named `audio`, or change the variable `filepath` in the code. > For the generated files, it gets generated in a folder called `output` inside the `audio` folder. If needed change the variable called `genfilepath`

Here is the code for the question:

```
[ ]: # filepath = './audio/CantinaBand3.wav'
      filepath = './audio/StarWars3.wav'
      # Read a wav file and obtain the original sampling rate
      ori_rate, ori_data = wavfile.read(filepath)
```

5.1 Changing Sampling Rate

```
[ ]: def change_sampling_rate(ori_data, ori_rate, new_rate):
      resample_ratio = new_rate / ori_rate

      points = int(len(ori_data) * resample_ratio)
      resampled_data = np.zeros(points)
      for i in range(points):
          pos = i / resample_ratio
          lsi = int(pos)
          rsi = lsi+1
          fp = pos - lsi

          if rsi < len(ori_data):
              ls = ori_data[lsi]
              rs = ori_data[rsi]
              inters = int((1-fp)*ls + fp*rs)
              resampled_data[i] = inters

      return resampled_data
```

5.2 Quantization

```
[ ]: def quantize(data, bits):
      quant_step = 2 / (2**bits - 1)
      quantized_data = np.round(data/ quant_step)*quant_step
      return quantized_data
```

5.3 Writing the audio files and graphing them

Here, all the audio files are written to the `audio` folder, and `output` subfolder.

```
[ ]: sampling_rates = [8000, 16000, 22050, 44100] # Different sampling rates to
      ↪test, for example
      quantization_bits = [8, 16, 32] # Different quantization levels to test
```

```

x = len(sampling_rates)
y = len(quantization_bits)

# Make 13 subplots
fig, axes = plt.subplots(1+x*y, figsize=(10, 30))

# Plot the quantized audio
res_fft = np.fft.fft(ori_data)
res_fft_freq = np.fft.fftfreq(len(ori_data), 1.0/ori_rate)

axes[0].plot(res_fft_freq, res_fft)
axes[0].set_title('Original audio' + ' (' + str(ori_rate) + ' Hz) : Freq vs_
↳Amplitude')
axes[0].set_xlabel("Frequency")
axes[0].set_ylabel("Amplitude")
axes[0].grid(True)

for i in range(x):
    for j in range(y):
        rate = sampling_rates[i]
        bits = quantization_bits[j]

        # Change sampling rate
        new_data = change_sampling_rate(ori_data, ori_rate, rate)
        # Quantize the audio data
        quantized_data = quantize(new_data, bits)

        # Save the quantized audio
        output_file = 'audio_' + str(rate) + '_' + str(bits) + '.wav'
        output_filename = 'audio/output/' + output_file

        wavfile.write(output_filename, rate, quantized_data)

        res_fft = np.fft.fft(quantized_data)
        # res_fft_shifted = np.fft.fftshift(res_fft)

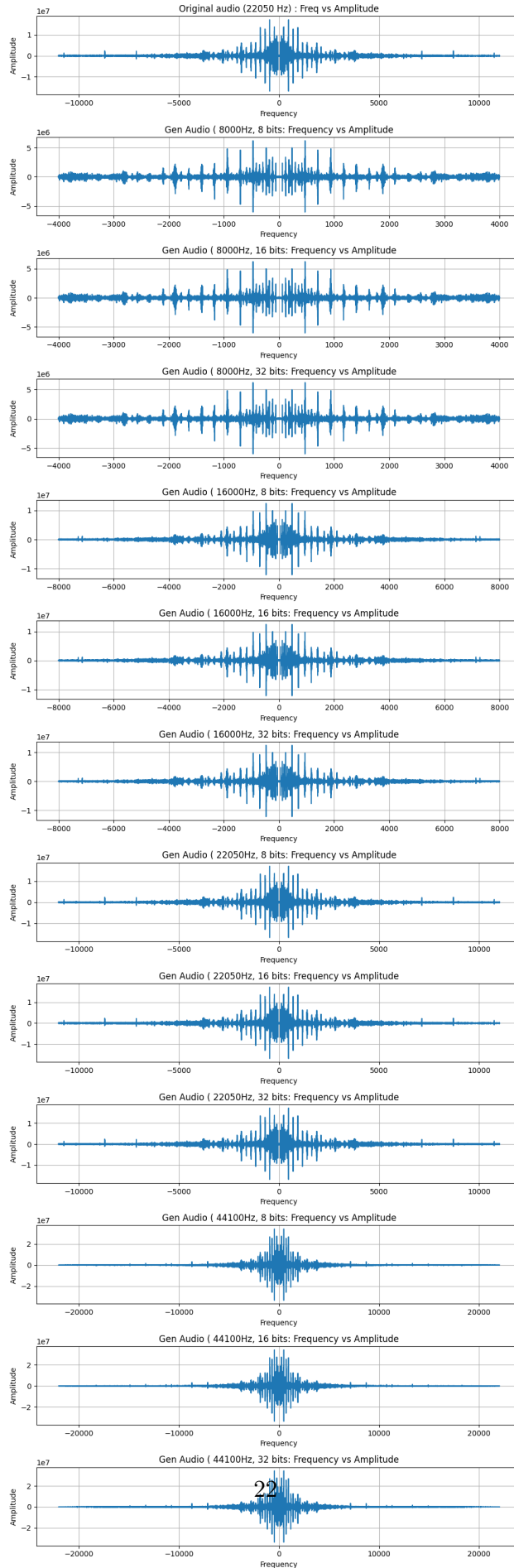
        res_fft_freq = np.fft.fftfreq(len(quantized_data), 1.0/rate)

        # Plot the quantized audio
        axes[1+i*y+j].plot(res_fft_freq, res_fft)
        title = 'Gen Audio ( ' + str(rate)+'Hz, ' + str(bits) +' bits: Frequency_
↳vs Amplitude'
        axes[1+i*y+j].set_title(title)
        axes[1+i*y+j].set_xlabel("Frequency")
        axes[1+i*y+j].set_ylabel("Amplitude")

```

```
axes[1+i*y+j].grid(True)

plt.tight_layout()
plt.savefig('audio/graph.png')
```



As we see above, the original audio signals differs a bit from the generated signals.

This is because of:

- **Quantization Error:** The quantization error is the difference between the original signal and the quantized signal. The quantization error is due to the fact that the quantizer is not able to represent the signal exactly. More the number of bits, lesser the quantization error. It is occurring in all signals, but is more prominent in the 8 bit signal
- **Sampling Error:** Changing the sampling rate of a signal can cause distortion of the signal, known as aliasing, as seen in the sampling theory. It is occurring in the 8000 Hz signal and 16000Hz signal in my case. Also, lower the sampling rate, the more muffled the audio sounds.