

# Research Project

Master Artificial Intelligence & Robotics  
2023/2024

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Friday 29th March 2024

## Exploring Plasticity-Driven SNNs for Enhanced ML



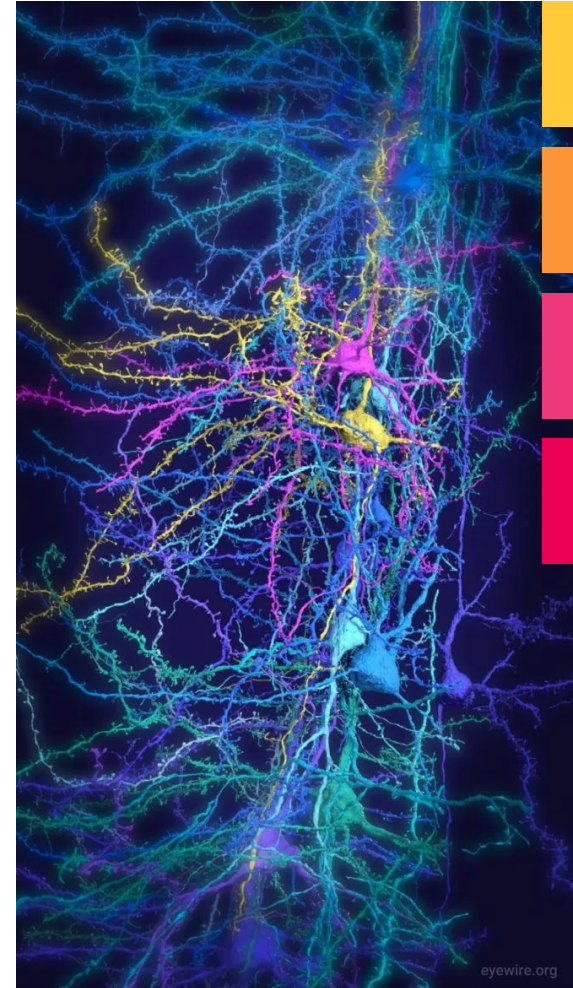
Équipes Traitement  
de l'Information  
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eyewire.org

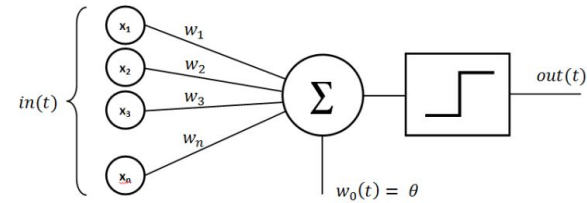
## Introduction

History & context  
Objectives & Challenges



**Generations****1<sup>st</sup>****Perceptron & ADALINE**

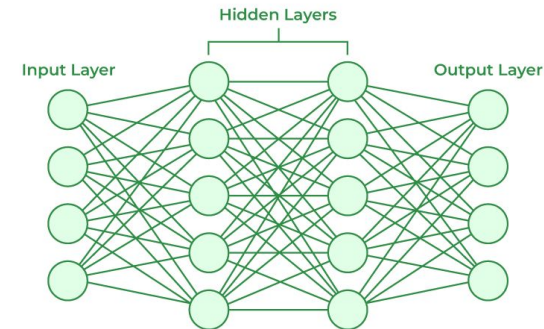
1940 - Adaptive Filters



source : datascientest.com

**2<sup>nd</sup>****Artificial Neural Networks (ANNs)**

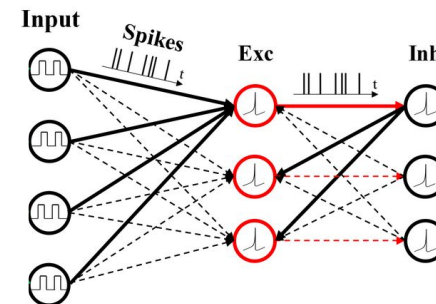
1980 - Non-linear problem



source : geeksforgeeks.org

**3<sup>rd</sup>****Spiking Neural Networks (SNNs)**

1990 - Biological Process



source : xialod.top



# Introduction

## Objectives & Challenges

### Objectives



#### Exploring SNNs:

Boost their application in machine learning.

#### Mechanisms of Adaptability:

Learning through local plasticity rules.

#### Practical Application:

Demonstrate the effectiveness of enhanced SNNs in machine learning.

### Challenges



#### Training SNNs:

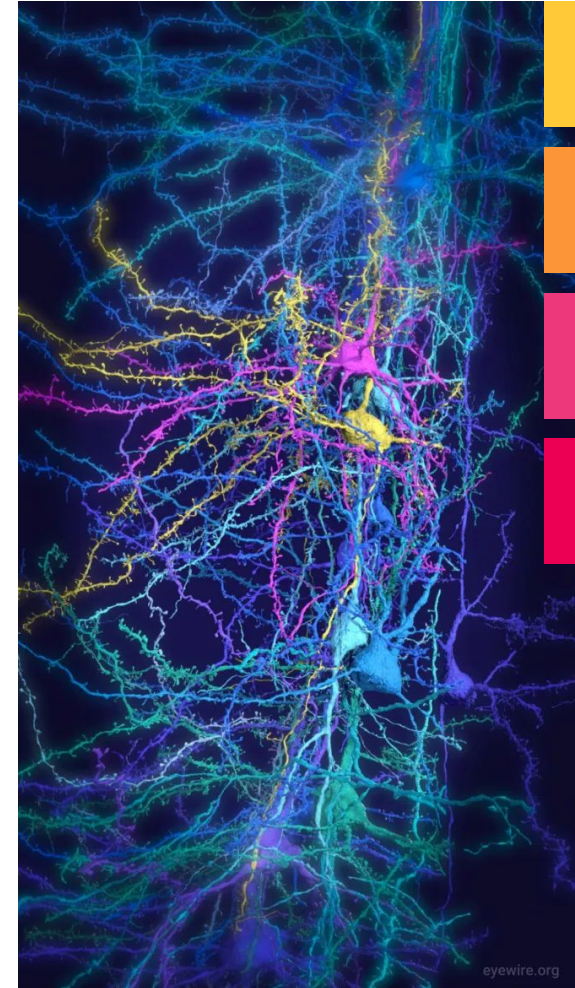
Machine learning tasks without gradient-based methods.

#### Nature of Spikes:

Spikes complicates the use of backpropagation.

#### Incorporating Plasticity:

Local plasticity rules adds complexity to network architecture and training.



## Literature Review

- Leaky Integrate-and-Fire (LIF)
- Spike-Timing- Dependent Plasticity (STDP)
- Neural Simulation Tool (NEST)
- Mountain Car (MC)
- Genetic Algorithms (GAs)
- Learning to learn (L2L)

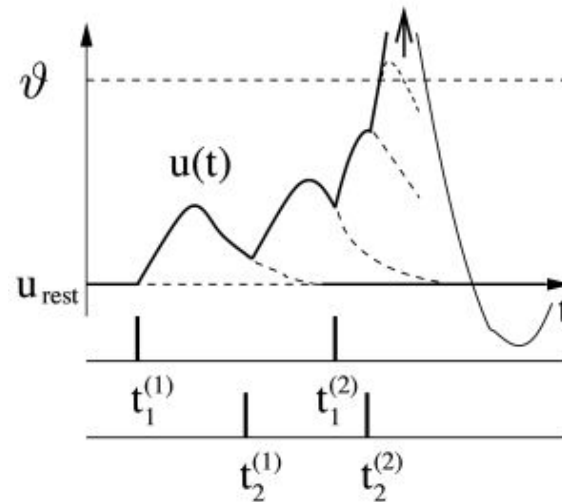
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## Neuron model : LIF

$$\frac{dV_m}{dt} = \frac{V_m - E_L}{\tau_m} + \frac{I_{syn} + I_e}{C_m}$$

Parameter	Unit	Description	Value
$V_{th}$	mV	Spike threshold	-55
$E_L$	mV	Resting membrane potential	-70
$C_m$	pF	Membrane capacitance	250
$\tau_m$	ms	Membrane time constant	10.0
$\tau_{ref}$	ms	Refractory period duration	1.0
$V_{reset}$	mV	Reset potential	-70
$\tau_{syn\_ex}$	ms	Excitatory synaptic time constant	2.0
$\tau_{syn\_in}$	ms	Inhibitory synaptic time constant	2.0
$I_e$	pA	Constant input current	—



source : [neurondynamics.epfl.ch/index.html](http://neurondynamics.epfl.ch/index.html)

**State of the art :** Hodgkin-Huxley Model, Exponential Integrate-and-Fire (EIF), Adaptive Exponential Integrate-and-Fire (AdEx)

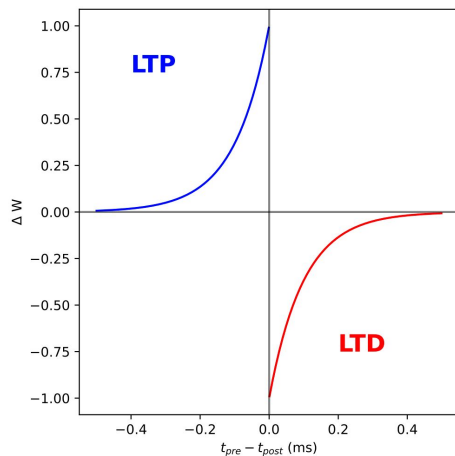
## Synapse model : STDP

Synaptic weight potentiation:

$$w_{pot} = W_{max} \left( \frac{w}{W_{max}} + \lambda \left( 1 - \frac{w}{W_{max}} \right)^{\mu_+} pre\_trace \right) \quad (8)$$

Synaptic weight depression:

$$w_{dep} = W_{max} \left( \frac{w}{W_{max}} - \alpha \lambda \left( \frac{w}{W_{max}} \right)^{\mu_-} post\_trace \right) \quad (9)$$



- **Weight ( $w$ ):** The strength of the synaptic connection, set by the plasticity mechanism.
- **Transmission delay ( $d$ ):** The time taken for the signal to traverse the synapse, set to 1.0 ms.
- **Learning rate ( $\lambda$ ):** Determines the rate at which the synapse can change, set to 0.01.
- **Pre-trace and post-trace time constants ( $\tau_{plus}, \tau_{minus}$ ):** Governs the decay of spike traces, both set to 20.0 ms.
- **Potentiation factor ( $\mu_{plus}$ ):** Modulates the weight change during potentiation, set to 1.0.
- **Depression factor ( $\mu_{minus}$ ):** Modulates the weight change during depression, set to 1.0.
- **Maximum synaptic weight ( $W_{max}$ ):** Defines the upper limit within which the synaptic weight can vary, set to 3000.0.

**State of the art :** Hebbian Learning, Rate-Based Plasticity, Short-Term Plasticity (STP), R-STDP



## Neural Simulation Tool (NEST)

- Simulation software for SNNs.
- Highly regarded simulator in computational neuroscience.
- Rich library of neuron & synapse models and dynamics.

**State of the art** : NEURON, Brian, Nengo, PyNN, CARLsim

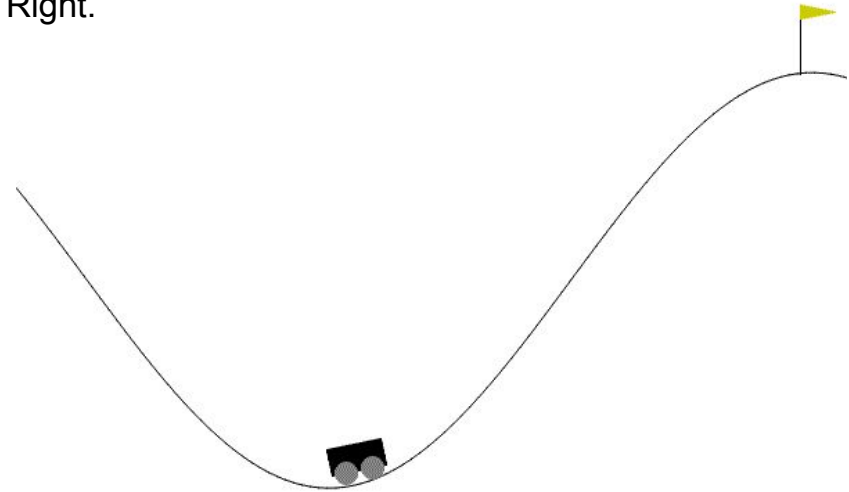


## Mountain Car (MC)

**The MC environment**, a benchmark in RL, involves a car in a valley, requiring strategic accelerations to reach a goal atop a hill. The agent must learn to navigate to the goal efficiently.

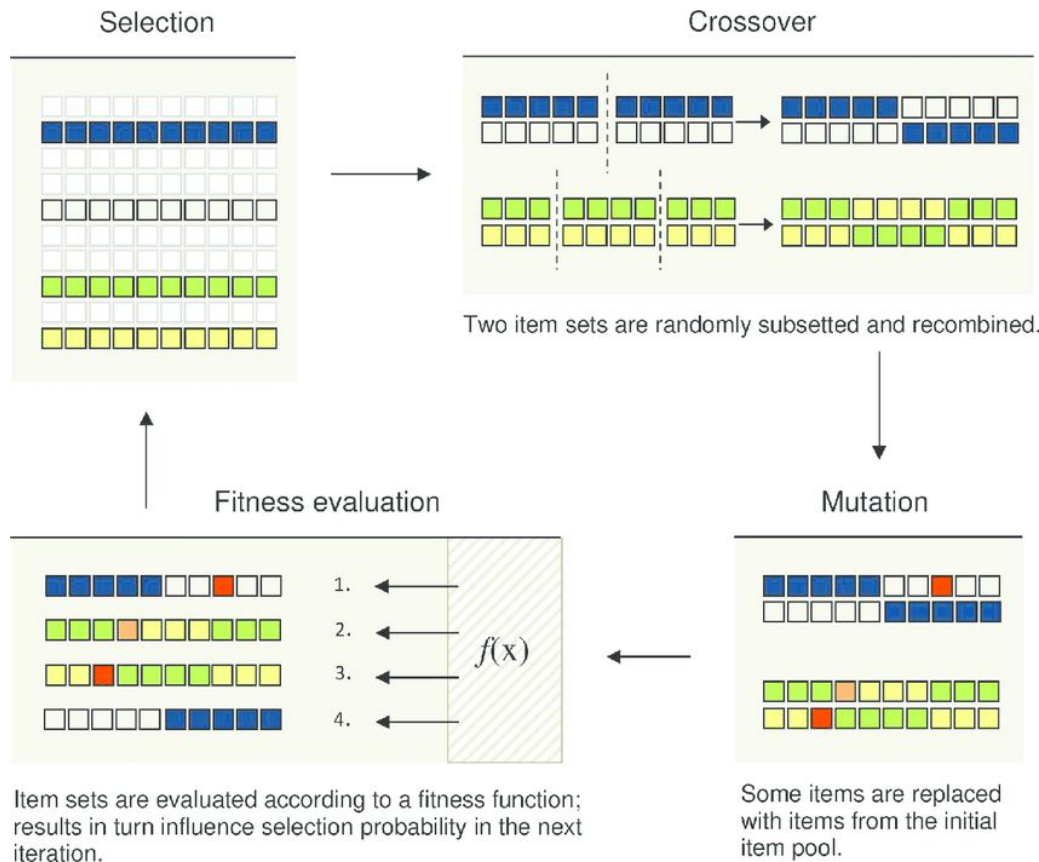
**Observations** : Position & Velocity

**Actions** : Accelerate Left, No Acceleration, Accelerate Right.



# Literature Review

## Genetic Algorithms (GAs)

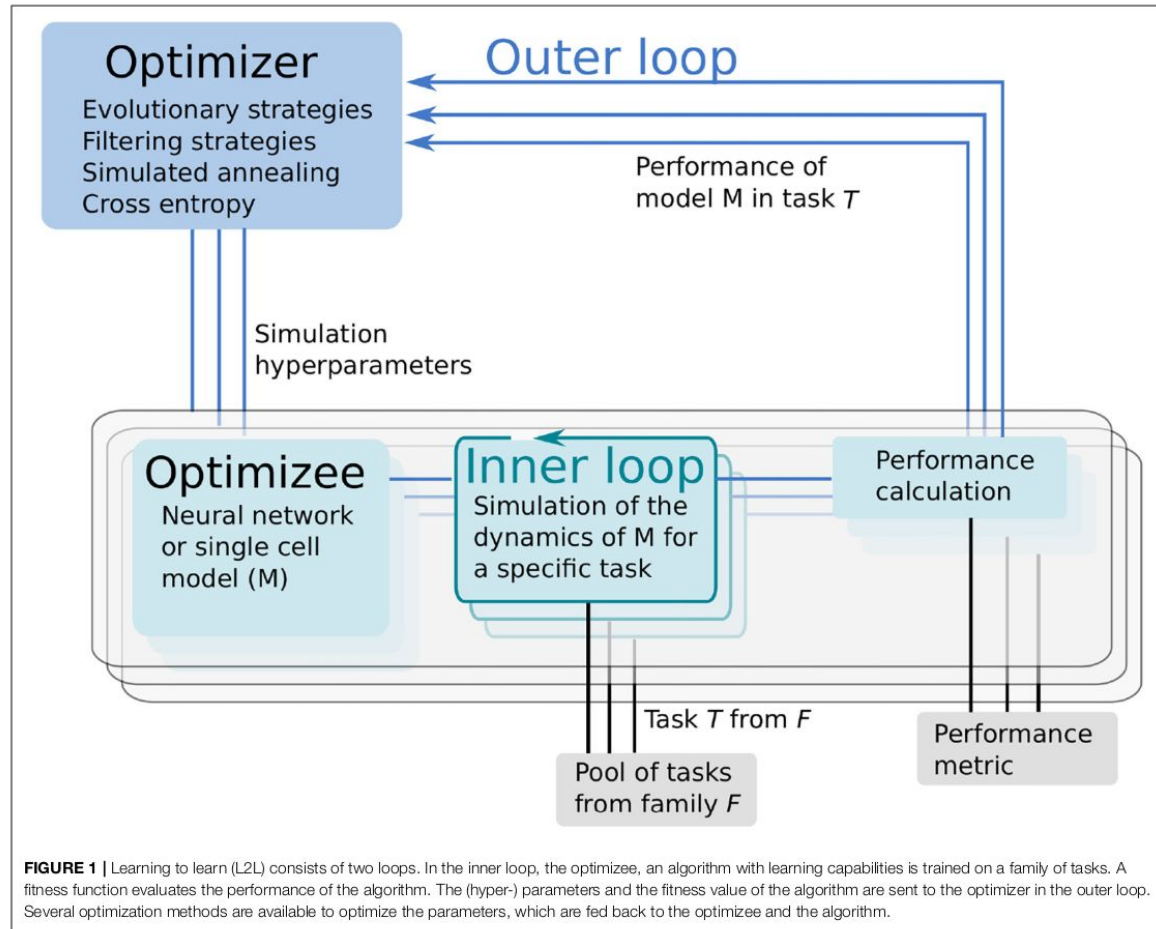


- Population size (32): Determines the number of individuals in each generation. A larger population size allows for more diverse solutions but increases computational load.
- Crossover probability (0.7): The likelihood of two individuals exchanging genetic information, promoting diversity in the population. (Exploration)
- Mutation probability (0.7): Governs the chance of random alterations in an individual's genetic, introducing variability. ( $\Delta\text{Mut} \sim \mathcal{N}(\mu = 0, \sigma = 1)$ ) (Exploration)
- Number of generations (1000): The total number of iterations for the GA, affecting the convergence of the algorithm.
- Tournament size (4): Used in the selection process to choose individuals for reproduction. (Exploitation)
- Mating Bend (0.5): Half of each parent genetics is used for crossover operation.

source : researchgate.net

## Literature Review

### Learning to learn (L2L)



source : [frontiersin.org/articles/10.3389/fncom.2022.885207/full](https://frontiersin.org/articles/10.3389/fncom.2022.885207/full)

## Methodology & Results

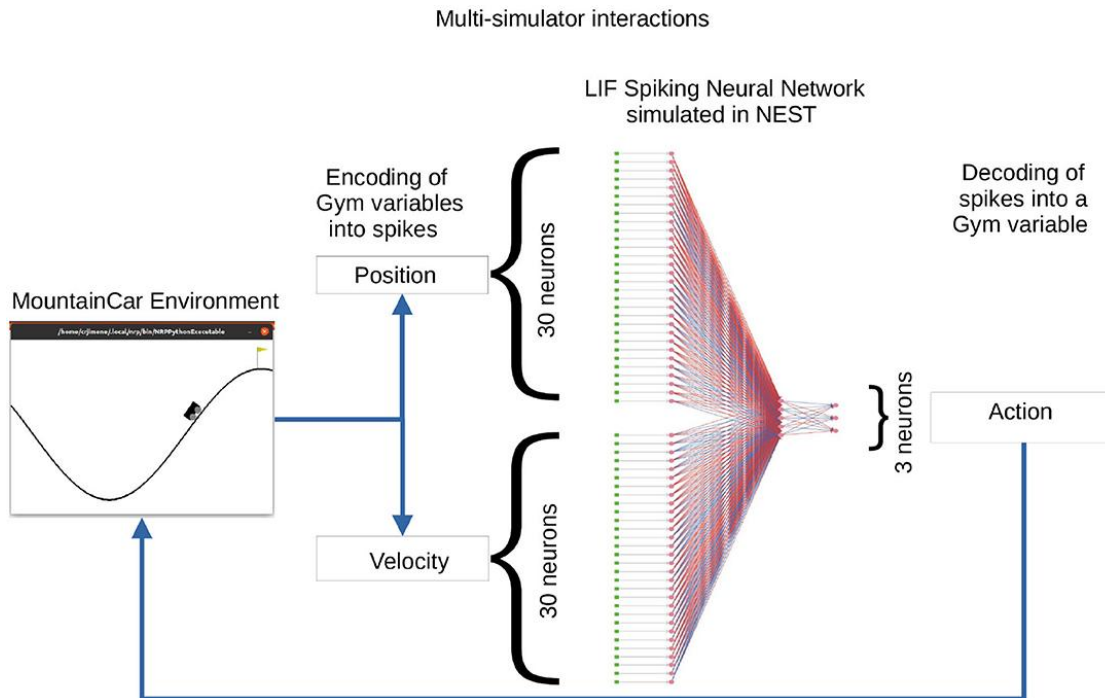
- Optimizing Static-synapses SNNs
- Enhancing SNNs with Synaptic Plasticity

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# Methodology

## Optimizing Static-synapses SNNs



source : [frontiersin.org/articles/10.3389/fncom.2022.885207/full](https://www.frontiersin.org/articles/10.3389/fncom.2022.885207/full)

## Setup

**Population size : 32**

Number of individuals per generation

**Training parameters : Weights**

Static synapses -> Static weights value

**Simulation : 110 steps :**

Number of steps allowed for the agent to solve the challenge

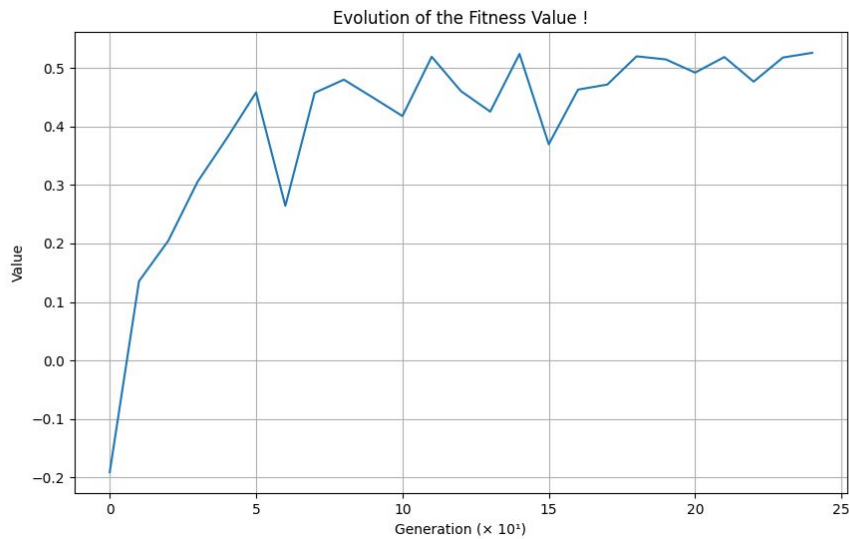
$$\text{Fitness}(I) = f(\text{paramètres}(I)) = \max_T(PET)$$



# Results

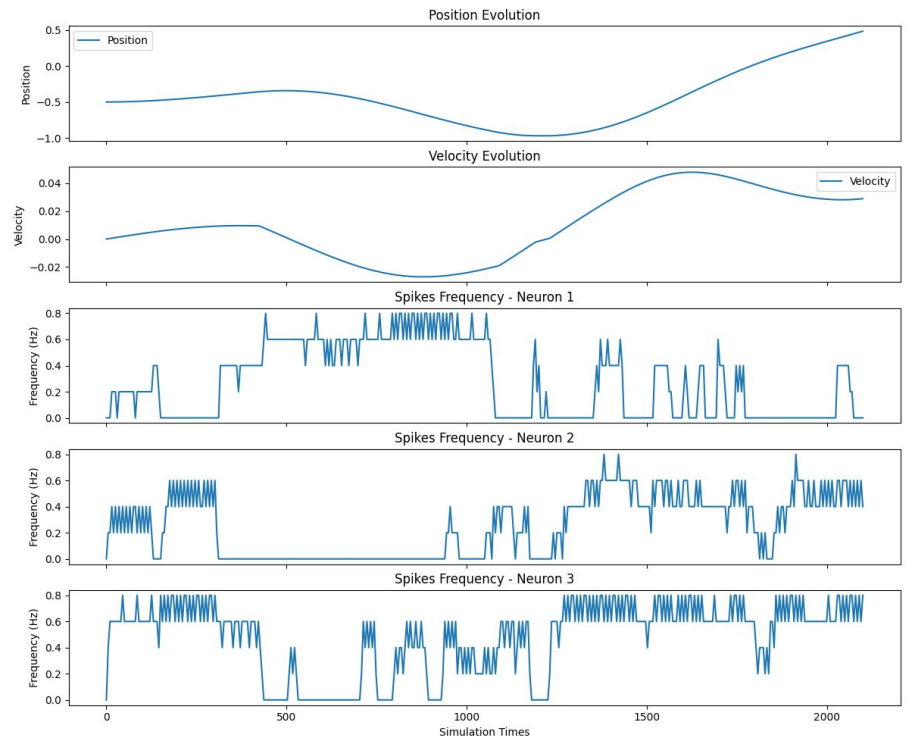
## Optimizing Static-synapses SNNs

### Training Fitness Evolution



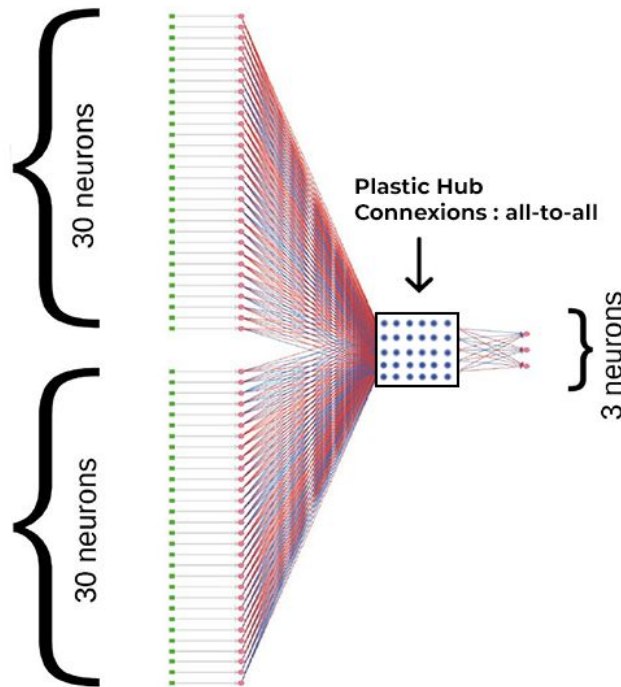
- The x-axis represents the Generation Index (times 10)
- The y-axis denotes the best individual fitness value of each generation.
- Convergence of the GA from the 110th Generation.

### Environment Dynamics



# Methodology

## Enhancing SNNs with Synaptic Plasticity



### Updates

#### Population size : 96

This configuration aligns with the hardware's capacity : 96 CPUs

#### Training parameters :

Plasticity\_flags & Initial Weights value

#### Simulation : 600 steps allowed :

Requires a higher number of simulation steps.

#### Plastic Hub :

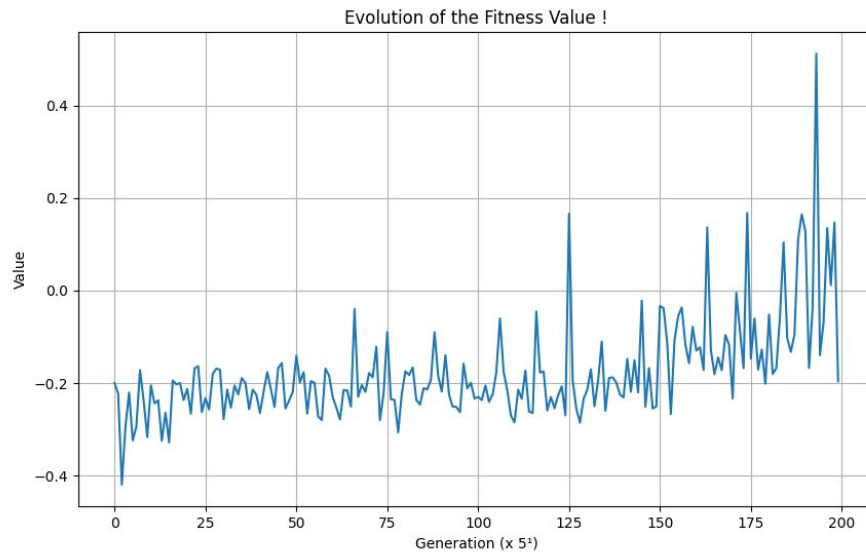
All-to-all connectivity pattern with no self-connections.

$$\text{Fitness}(I) = f(\text{paramètres}(I)) = \max_T(PET)$$

## Results

### Enhancing SNNs with Synaptic Plasticity

#### Training Fitness Evolution



- The x-axis indicates the generation index (factor of 5)
- The y-axis denotes the best individual fitness value of each generation.
- This peak signifies the emergence of an individual that successfully solved the challenge.

#### Best individual

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#### Plastic synapses :

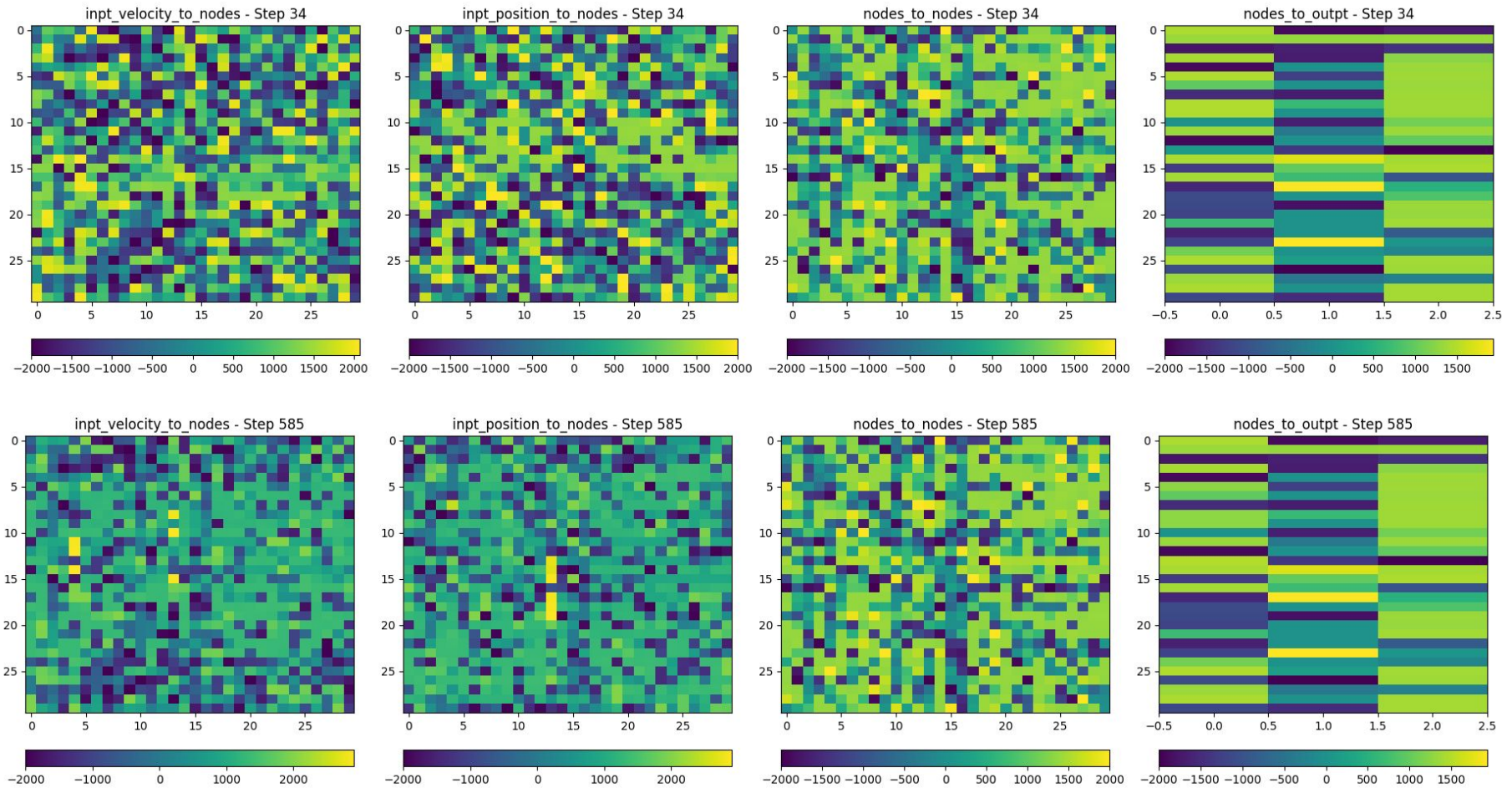
1389/2700 (51.44%) plasticity flag = 1

#### Simulation steps :

585 over 600 steps

# Results

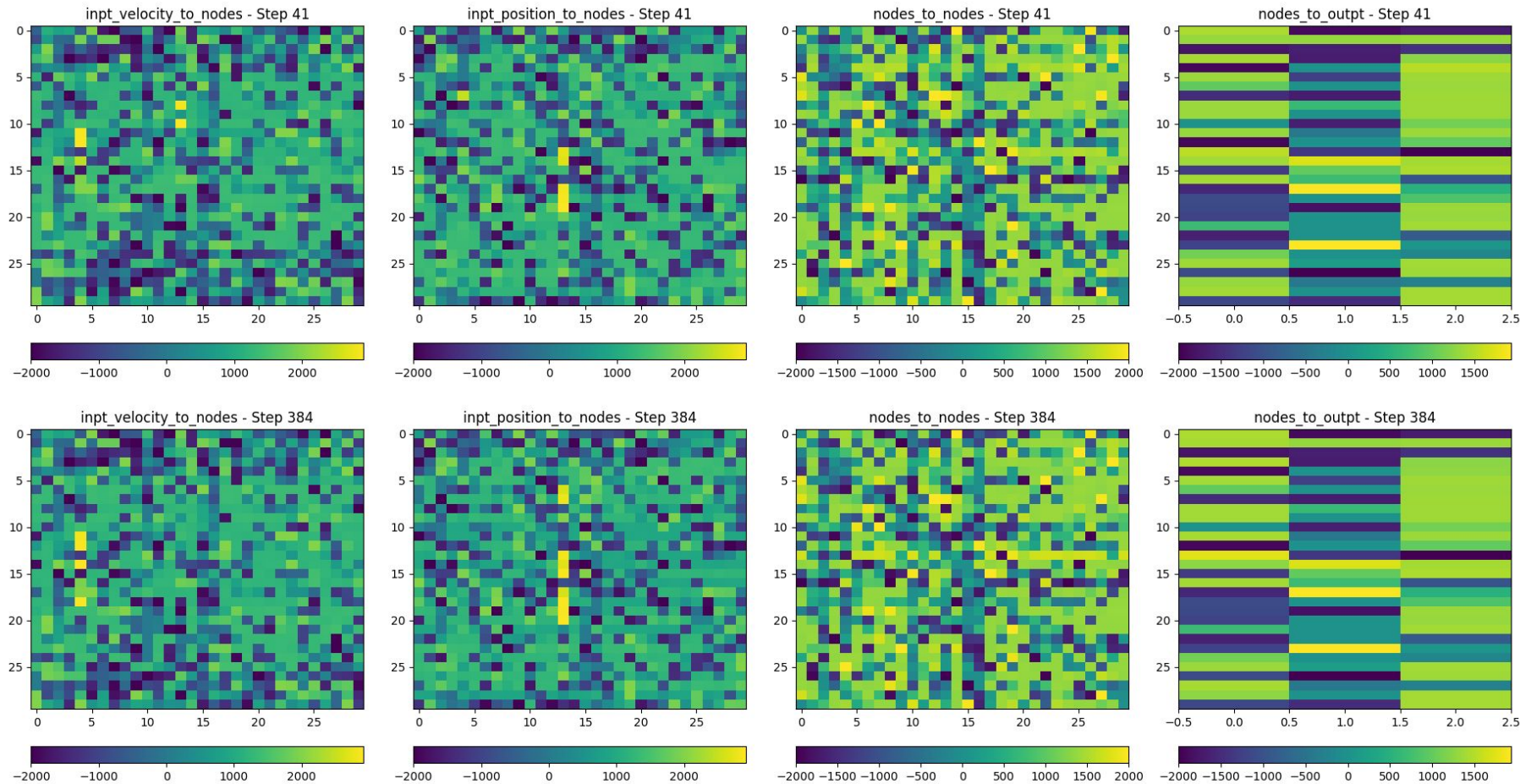
## Network Evolution Simulation 1





## Results

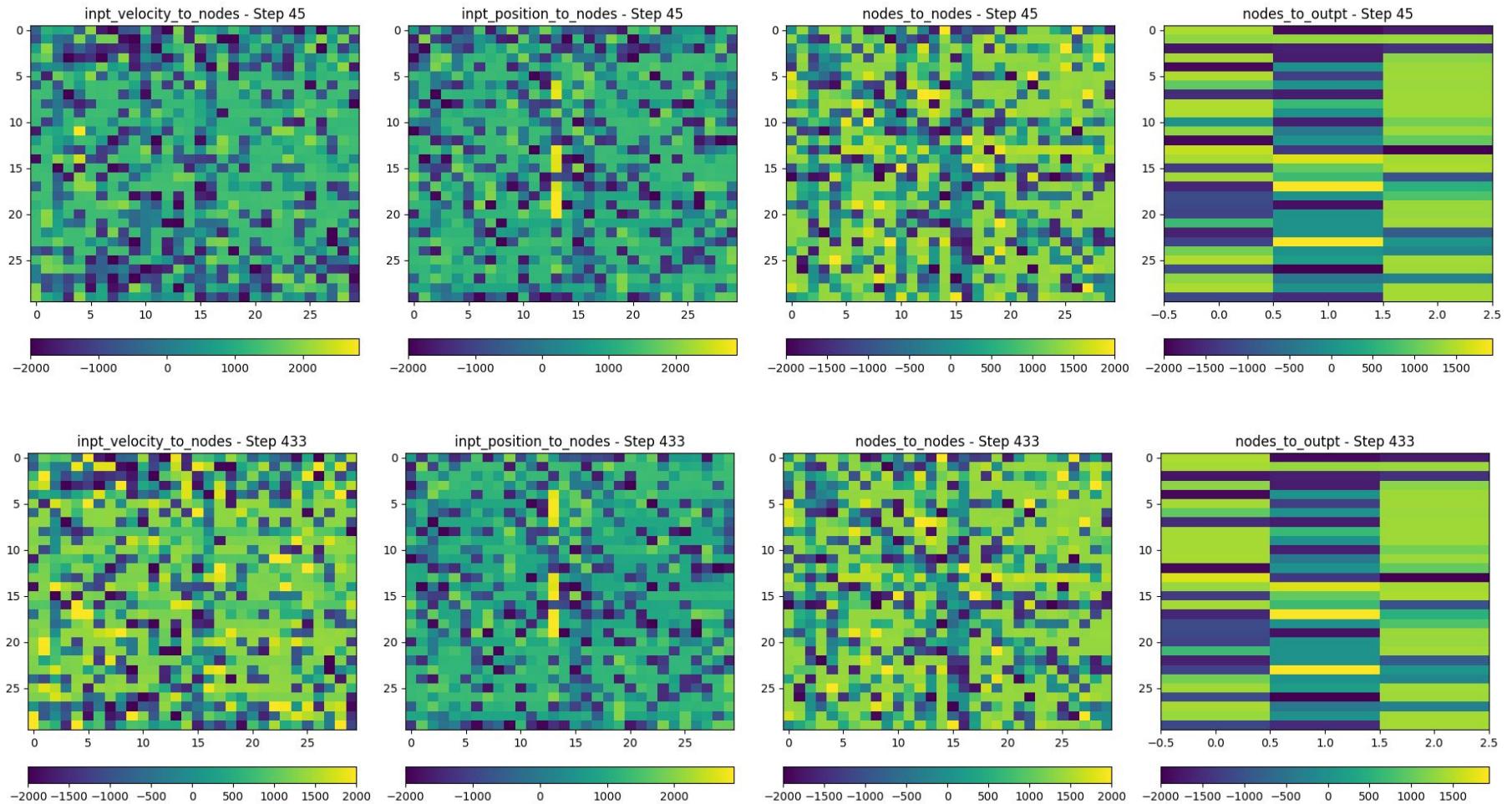
### Network Evolution Simulation 2





## Results

### Network Evolution Simulation 3



## Conclusion

- Discussion
- Future work insights

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**01****Feasibility Demonstration**

Our experiments show that plasticity-driven SNNs can effectively solve complex RL problems.

**02****Potentials & Benefits**

Opens up new possibilities for creating more adaptable and efficient AI systems.

**03****Generation**

Pushing the boundaries of what these networks can achieve with several different random initial state.

**04****Scalability**

Adapt for more complex tasks and larger datasets in future applications.



**01****Allow more steps to the SNN : 600 -> 1000**

As a plastic network requires a higher number of simulation steps compared to a static one.

**03****Novel fitness function**

If  $\text{MaxPosition} < 0.5$  :  $\text{Fitness} = \text{MaxPosition}$

If  $\text{MaxPosition} \geq 0.5$  :  $\text{Fitness} = \text{MaxPosition} + 100/\text{sim\_step}$



01

2014

Wulfram et al. Neuronal dynamics - a neuroscience textbook, cambridge university press.

02

2022

Yegenoglu et al. Exploring Parameter and Hyper-Parameter Spaces of Neuroscience Models on High Performance Computers With Learning to Learn. Frontiers in Computational Neuroscience

03

2022

Haşegan et al. Evolutionary and spike-timing-dependent reinforcement learning train spiking neuronal network motor control,

04

2019

Wunderlich et al. Demonstrating Advantages of Neuromorphic Computation.

05

2007

Marc-Oliver Gewaltig and Markus Diesmann, NEST (NEural Simulation Tool)

06

2019

Bing et al. Supervised learning in SNN via reward-modulated spike-timing- dependent plasticity for a target reaching vehicle.



# Questions



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