You're braver than you believe, stronger than you seem, and smarter than you think. - A.A. Milne



Optimization

Why Optimization?

Optimization is important in many businesses to find the **best set of decisions** for a particular performance. For example...

Optimize operational efficiency: capital, personnel, equipment, vehicles, facilities.

Create measurable return on investment: **Optimize costs, earnings and service**.

There are applications of optimization in most industries including: manufacturing, transportation, logistics, financial services, utilities, energy, telecommunications, government, defense and retail.



What is optimization in the mathematical sciences?

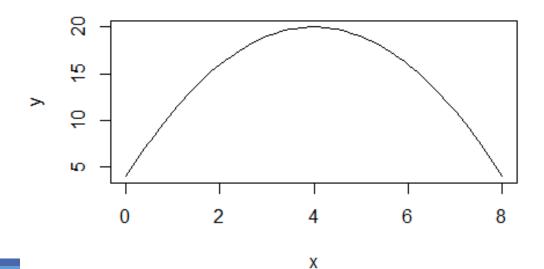
Optimizing a function is finding the maximum (or minimum) a function can take.



What is optimization in the mathematical sciences?

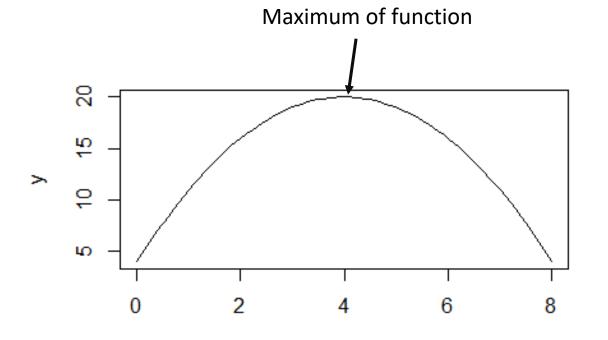
Optimizing a function is finding the maximum (or minimum) a function can take.

Goal is find out what values of the "decision variables" (or input variables) optimize this function



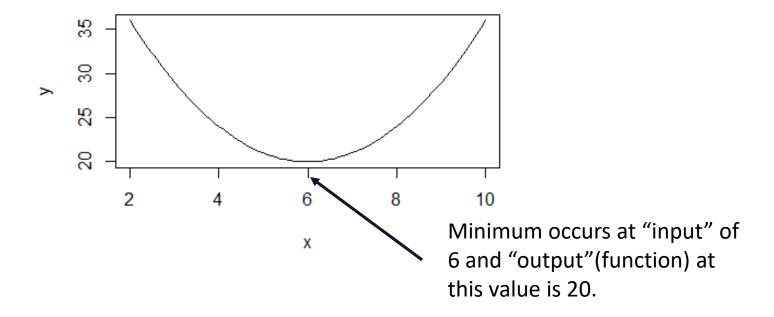
What is optimization in the mathematical sciences?

In example below, the x-variable is the "decision variable" and the y is the function we are trying to optimize...



The maximum occurs when the decision or "input" variable is 4 (the optimal value of the "output" is 20).

Minimize a function



Terminology

The "input" variables are the variables in which we can change to optimize a function. These variables are referred to as the **decision** variables.

The **objective function** is the function in which we are trying to optimize (either maximize or minimize). This function is a function of the decision variables. We are trying to find the best values of the decision variables that optimize this function.

The **constraints** are functions of the decision variables that define the constraints of the problem.

Parameters are values inherent in the problem that we are not able to control

Decision variables: $x_1, x_2, ... x_k$

Objective function:

$$\sum a_i x_i = a_1 x_1 + a_2 x_2 + a_3 x_3 + \dots + a_k x_k$$

 $a_1, a_2, ...a_k$ are the coefficients in the objective function

Constraints:

$$\sum b_{1i}x_i \leq c_1$$

$$\sum b_{2i}x_i \ge c_2$$

$$\Sigma b_{3i}x_i = c_3$$

• • •

Decision variables: $x_1, x_2, ... x_k$

Objective function:

$$\sum a_i x_i = a_1 x_1 + a_2 x_2 + a_3 x_3 + \dots + a_k x_k$$

 $a_1, a_2, ...a_k$ are the coefficients in the objective function

Constraints:

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$$\Sigma b_{3i}x_i = c_3$$

• • •

Decision variables: $x_1, x_2, ... x_k$

Objective function:

$$\left[\sum a_i x_i = a_1 x_1 + a_2 x_2 + a_3 x_3 + \dots + a_k x_k \right]$$

 $a_1, a_2, ...a_k$ are the coefficients in the objective function

Constraints:

$$\sum b_{1i}x_i \leq c_1$$

$$\sum b_{2i}x_i \ge c_2$$

$$\Sigma b_{3i}x_i = c_3$$

• • •

Decision variables: $x_1, x_2, ... x_k$

Objective function:

$$\sum a_i x_i = a_1 x_1 + a_2 x_2 + a_3 x_3 + \dots + a_k x_k$$

 $a_1, a_2, ...a_k$ are the coefficients in the objective function

Constraints:

$$\sum b_{1i}x_i \leq c_1$$

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$$\Sigma b_{3i}x_i = c_3$$

• • •

Decision variables: $x_1, x_2, ... x_k$

Objective function:

$$\sum a_i x_i = a_1 x_1 + a_2 x_2 + a_3 x_3 + \dots + a_k x_k$$

 $a_1, a_2, ...a_k$ are the coefficients in the objective function

Constraints:

$$\sum b_{1i} x_i \le c_1$$

$$\sum b_{2i} x_i \ge c_2$$

$$\sum b_{3i} x_i = c_3$$

$$\sum b_{2i}x_i \ge c_2$$

$$\Sigma b_{3i}x_i = c_3$$

Decision variables: $x_1, x_2, ... x_k$

Objective function:

$$\sum a_i x_i = a_1 x_1 + a_2 x_2 + a_3 x_3 + \dots + a_k x_k$$

 $a_1, a_2, ...a_k$ are the coefficients in the objective function

Constraints:

$$\sum_{i} x_i \leq c_1$$

$$\sum b_2 x_i \ge c_2$$

$$\sum b_3 x_i = c_3$$

Decision variables: $x_1, x_2, ... x_k$

Objective function:

$$\sum a_i x_i = a_1 x_1 + a_2 x_2 + a_3 x_3 + \dots + a_k x_k$$

 $a_1, a_2, ...a_k$ are the coefficients in the objective function

Constraints:

$$\sum b_{1i}x_i \underbrace{\langle c_1 \rangle}$$

$$\sum b_{2i}x_i \stackrel{\triangleright}{\triangleright} c_2$$

$$\Sigma b_{3i}x_i \neq c_3$$

• • •

Outputs from an optimization

No optimization exists

More than one solution exists

There exists one unique solution to the problem

Other possibilities, but these are the most recognized

4 main types of optimization problems

Linear programming – objective function and constraints are linear (LP)

Integer linear programming – objective function and constraints are linear, but decision variables MUST be integers (ILP)

Mixed integer linear programming (MILP)— same as ILP with only some decision variables restricted to integers

Non-linear programming – objective function and constraints are continuous, but not all are linear

Linear Programming

The **feasible region** is the region defined by the constraints (need to find the optimal solution to the objective function over this region)

One of the easiest solutions for solving a linear programming problem is the *Simplex* method

 Strategy is to move along the edges of the feasible region until the optimal value of the objective function is found

Example

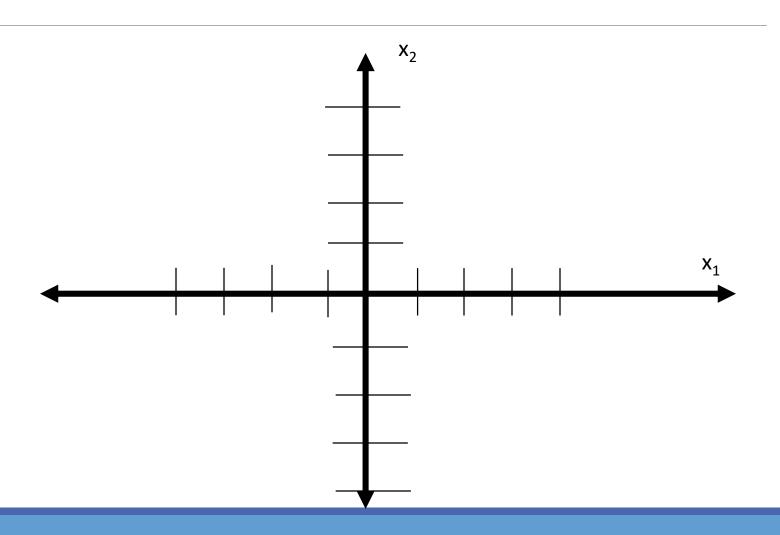
Decision variables: x_1 , x_2

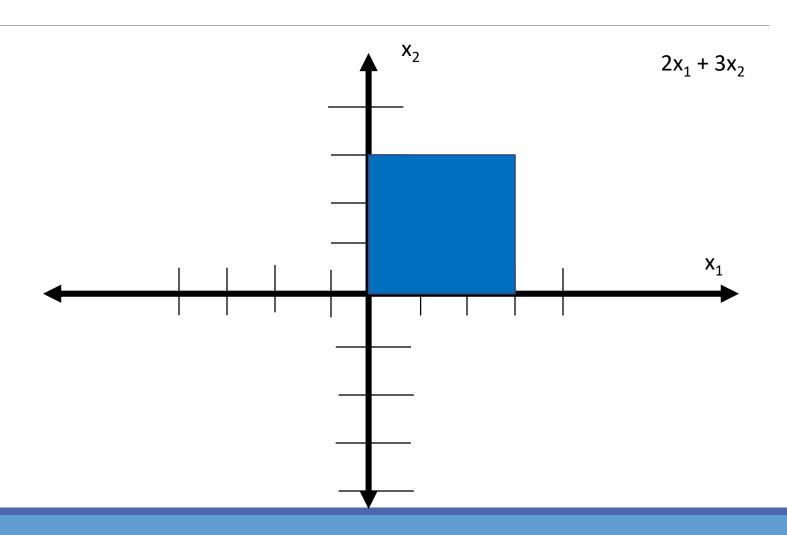
Find maximum of $2x_1 + 3x_2$ (this is the objective function)

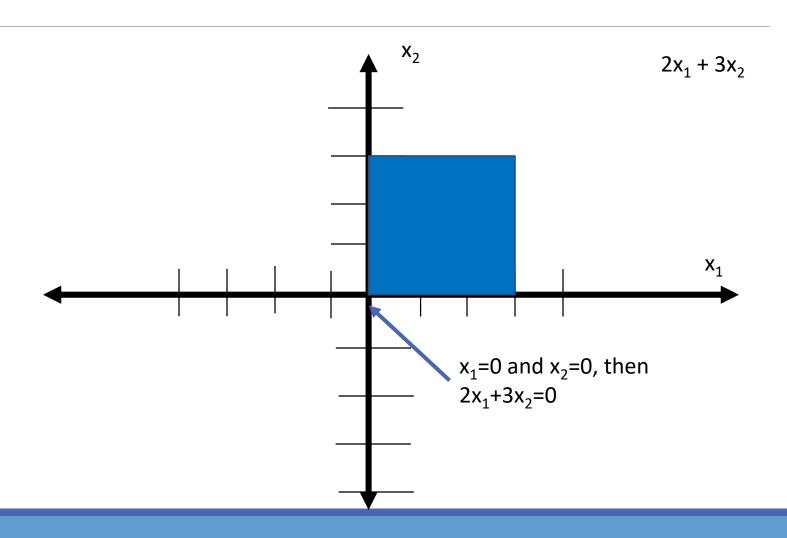
Constraints:

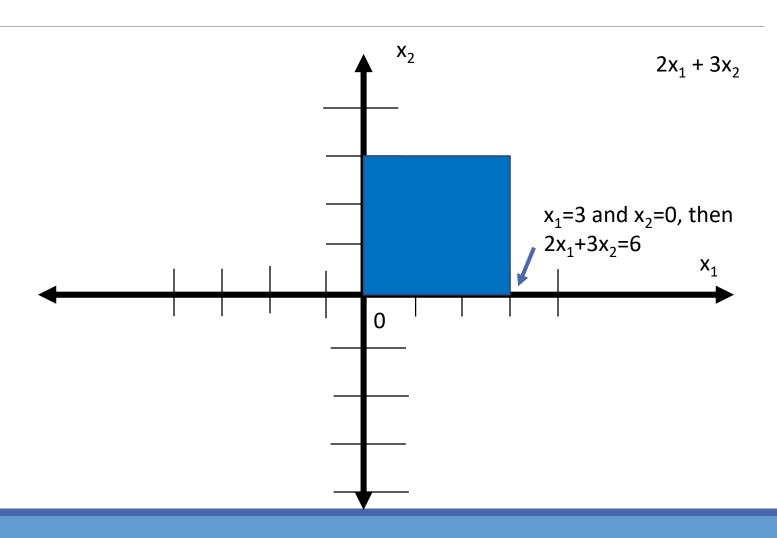
$$0 \le x_1 \le 3$$

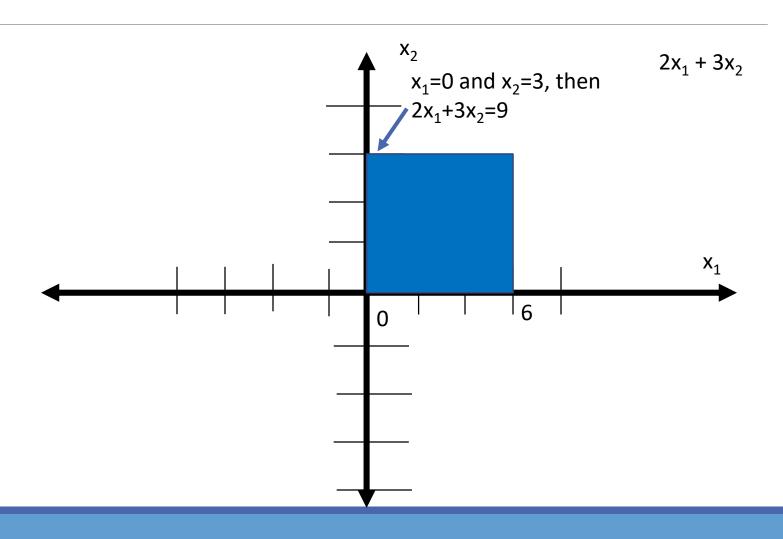
$$0 \le x_2 \le 3$$

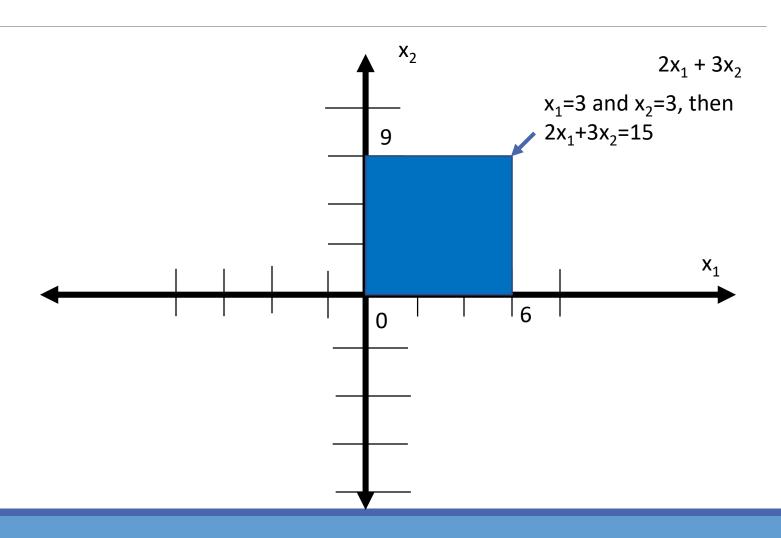


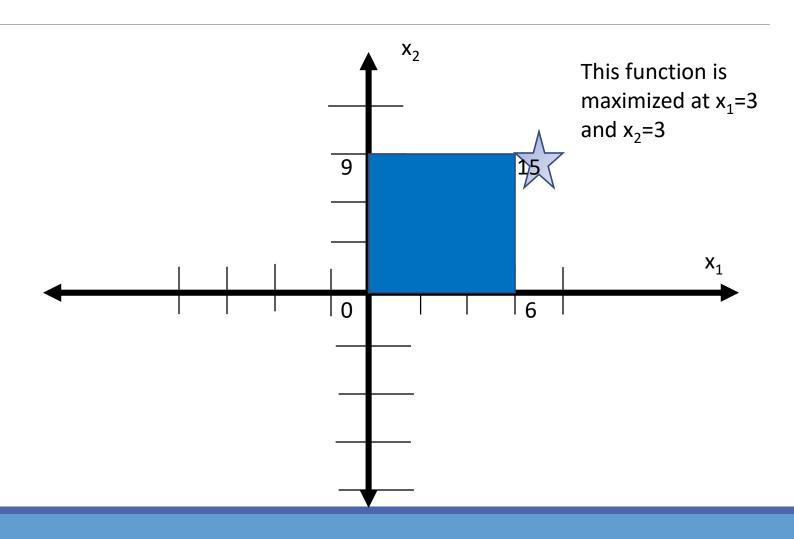












Second Example of Simplex algorithm (Chairs=C, Desks=D)

MAXIMIZE Profit: 15C + 24D

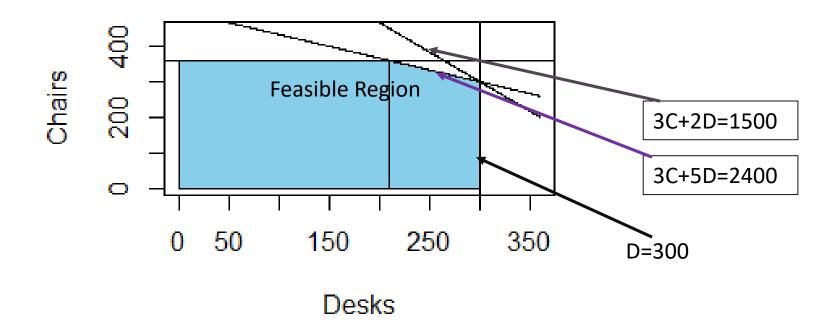
CONSTRAINTS:

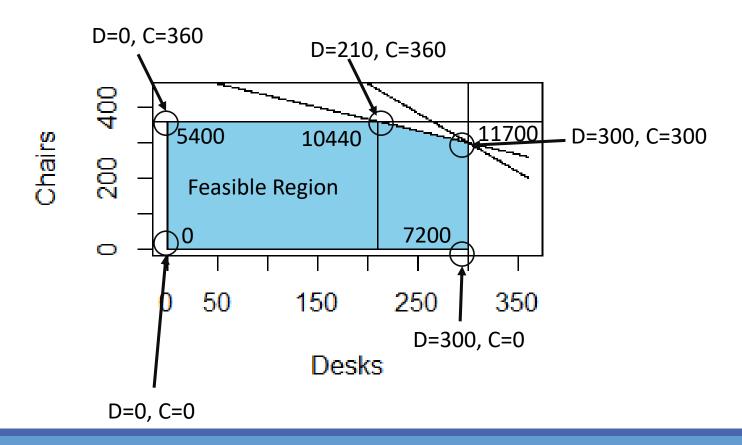
3C + 5D < 2400

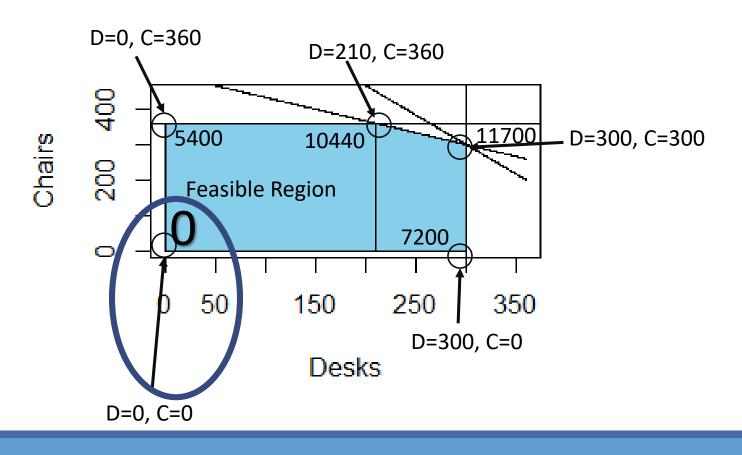
 $3C + 2D \leq 1500$

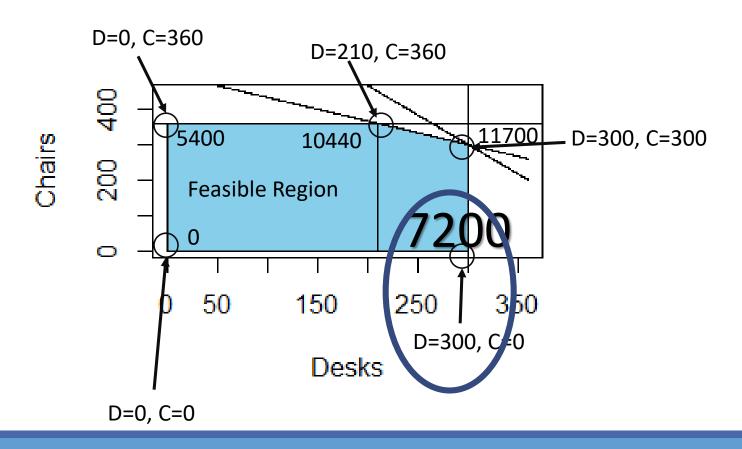
0<C < 360

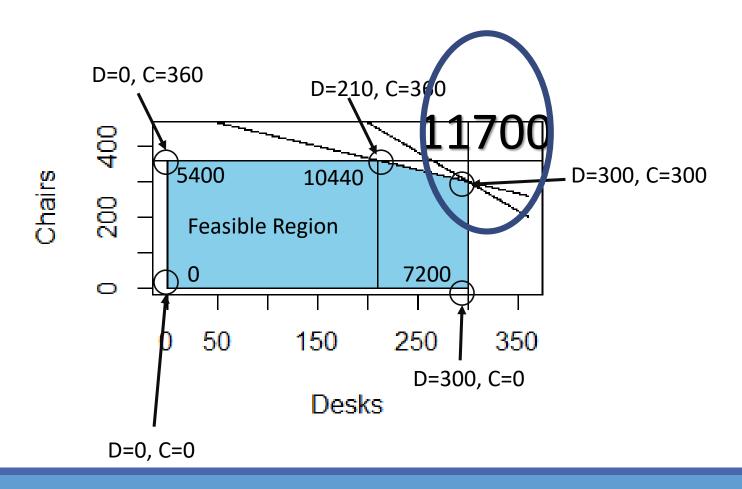
 $0 \le D \le 300$

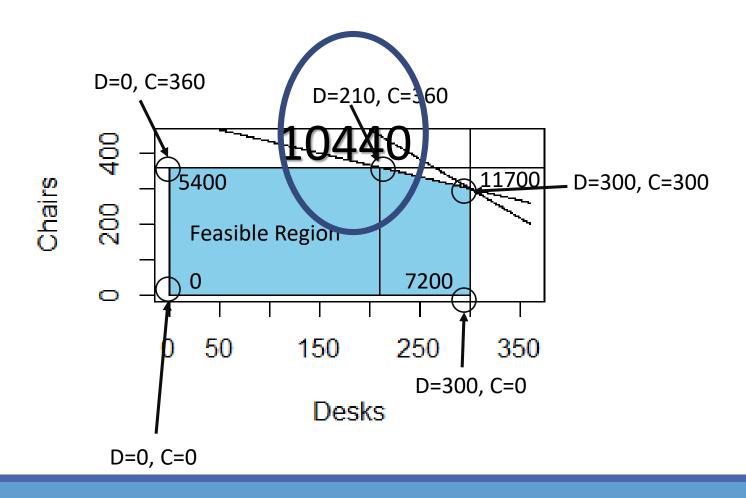


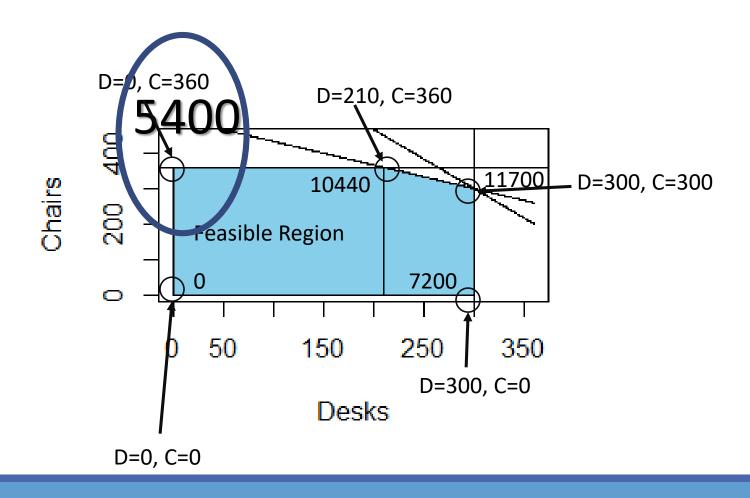


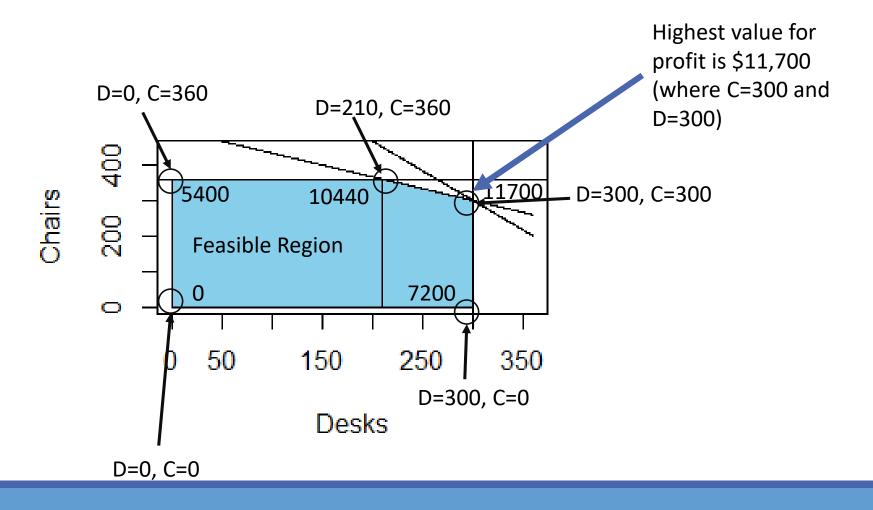












Example

Veerman Furniture Company makes chairs, desks and tables with the following information

	Hours per unit			
Department	Chairs	Desks	Tables	Hours Avail
Fabrication	4	6	2	1850
Assembly	3	5	7	2400
Shipping	3	2	4	1500
Demand potential	360	300	100	
Profit	\$15	\$24	\$18	

Want to maximize profit

Example:

Objective function:

MAXIMIZE: 15C + 24D + 18T

Constraints:

• Fabri: $4C + 6D + 2T \le 1850$

• Assem: $3C + 5D + 7T \le 2400$

• Shipp: $3C + 2D + 4T \le 1500$

∘ C ≤ 360

∘ D ≤ 300

∘ T ≤ 100

∘ C ≥0, D≥0, T≥0

```
proc optmodel;
var Chairs>=0, Desks>=0, Tables>=0;
max Profit = 15*Chairs + 24*Desks + 18*Tables;
con Assembly: 3*Chairs + 5*Desks +7*Tables<=2400;
con Shipping: 3*Chairs + 2*Desks + 4*Tables<=1500;
con Fabrication: 4*Chairs+6*Desks+2*Tables<=1850;
con DemandC: Chairs <=360;</pre>
con DemandD: Desks<=300;
con DemandT: Tables<=100;
solve with lp;
print Chairs Desks Tables;
quit;
```

```
proc optmodel;
var Chairs>=0, Desks>=0, Tables>=0;
max Profit = 15*Chairs + 24*Desks + 18*Tables;
con Assembly: 3*Chairs + 5*Desks + 7*Tables<=2400;
con Shipping: 3*Chairs + 2*Desks + 4*Tables<=1500;
con Fabrication: 4*Chairs+6*Desks+2*Tables<=1850;
con DemandC: Chairs <=360;
con DemandD: Desks<=300;
con DemandT: Tables<=100;
solve with lp;
print Chairs Desks Tables;
quit;</pre>
```

Define decision variables

```
proc optmodel;
var Chairs>=0, Desks>=0, Tables>=0;
max Profit = 15*Chairs + 24*Desks + 18*Tables;
con Assembly: 3*Chairs + 5*Desks + 7*Tables<=2400;
con Shipping: 3*Chairs + 2*Desks + 4*Tables<=1500;
con Fabrication: 4*Chairs+6*Desks+2*Tables<=1850;
con DemandC: Chairs <=360;
con DemandD: Desks<=300;
con DemandT: Tables<=100;
solve with lp;
print Chairs Desks Tables;
quit;</pre>
```

Define objective function

```
proc optmodel;
var Chairs>=0, Desks>=0, Tables>=0;
max Profit = 15*Chairs + 24*Desks + 18*Tables;
con Assembly: 3*Chairs + 5*Desks +7*Tables<=2400;
con Shipping: 3*Chairs + 2*Desks + 4*Tables<=1500;
con Fabrication: 4*Chairs+6*Desks+2*Tables<=1850;
con DemandC: Chairs <=360;
con DemandD: Desks<=300;
con DemandT: Tables<=100;
solve with lp;
print Chairs Desks Tables;
quit;
```

```
proc optmodel;
var Chairs>=0, Desks>=0, Tables>=0;
max Profit = 15*Chairs + 24*Desks + 18*Tables;
con Assembly: 3*Chairs + 5*Desks + 7*Tables<=2400;
con Shipping: 3*Chairs + 2*Desks + 4*Tables<=1500;
con Fabrication: 4*Chairs+6*Desks+2*Tables<=1850;
con DemandC: Chairs <=360;
con DemandD: Desks<=300;
con DemandT: Tables<=100;
solve with lp;
print Chairs Desks Tables;
quit;</pre>
```

Print the results

Output

The SAS System

The OPTMODEL Procedure

Problem Summary	
Objective Sense	Maximization
Objective Function	Profit
Objective Type	Linear
Number of Variables	3
Bounded Above	0
Bounded Below	3
Bounded Below and Above	0
Free	0
Fixed	0
Number of Constraints	6
Linear LE (<=)	6

Output cont

Chairs	Desks	Tables
0	275	100

The OPTMODEL Procedure

Solution Summary		
Solver	LP	
Algorithm	Cual Simplex	
Objective Function	Profit	
Solution Status	Optimal	
Objective Value	8400	
Primal Infeasibility	0	
Dual Infeasibility	0	
Bound Infeasibility	0	
Iterations	2	
Presolve Time	0.00	
Solution Time	0.00	

```
from gurobipy import *
# Create a new model
m = Model("Veerman")
# Create variables
c = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Chair")
d = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Desk")
t = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Table")
# Set objective
m.setObjective(15*c+24*d+18*t, GRB.MAXIMIZE)
```

```
m.addConstr(4*c + 6*d + 2*t <=
1850, "c0")
m.addConstr(3*c + 5*d + 7*t < =
2400, "c1")
m.addConstr(3*c + 2*d + 4*t \le 
1500, "c2")
m.addConstr(c <= 360, "c3")
m.addConstr(d <= 300, "c4")
m.addConstr(t <= 100, "c5")
m.optimize()
for v in m.getVars():
  print('%s %g' % (v.varName, v.x))
print('Obj: %g' % m.objVal)
```

Add constraints

```
from gurobipy import *
# Create a new model
m = Model("Veerman")
                              DEFINE MODEL
# Create variables
c = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Chair")
d = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Desk")
t = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Table")
# Set objective
m.setObjective(15*c+24*d+18*t, GRB.MAXIMIZE)
```

```
# Add constraints
m.addConstr(4*c + 6*d + 2*t < =
1850, "c0")
m.addConstr(3*c + 5*d + 7*t < =
2400, "c1")
m.addConstr(3*c + 2*d + 4*t \le 
1500, "c2")
m.addConstr(c <= 360, "c3")
m.addConstr(d <= 300, "c4")
m.addConstr(t <= 100, "c5")
m.optimize()
for v in m.getVars():
  print('%s %g' % (v.varName, v.x))
print('Obj: %g' % m.objVal)
```

```
from gurobipy import *

# Create a new model
m = Model("Veerman")

# Create variables
c = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Chair")
d = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Desk")
t = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Table")
```

```
# Set objective
m.setObjective(15*c+24*d+18*t, GRB.MAXIMIZE)
```

```
# Add constraints
m.addConstr(4*c + 6*d + 2*t < =
1850, "c0")
m.addConstr(3*c + 5*d + 7*t < =
2400, "c1")
m.addConstr(3*c + 2*d + 4*t \le 
1500, "c2")
  DEFINE DECISION VARIABLES
m.addConstr(c <= 360, "c3")
m.addConstr(d \le 300, "c4")
m.addConstr(t <= 100, "c5")
m.optimize()
for v in m.getVars():
  print('%s %g' % (v.varName, v.x))
print('Obj: %g' % m.objVal)
```

```
from gurobipy import *
# Create a new model
m = Model("Veerman")
# Create variables
c = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Chair")
d = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Desk")
t = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Table")
# Set objective
```

m.setObjective(15*c+24*d+18*t, GRB.MAXIMIZE)

```
# Add constraints
m.addConstr(4*c + 6*d + 2*t < =
1850, "c0")
m.addConstr(3*c + 5*d + 7*t < =
2400, "c1")
m.addConstr(3*c + 2*d + 4*t \le 
1500, "c2")
m.addConstr(c <= 360, "c3")
m.addConstr(d <= 300, "c4")
m.addConstr(t <= 100, "c5")
m.optimize()
   DEFINE OBJECTIVE FUNCTION
for v in m.getVars():
```

print('%s %g' % (v.varName, v.x))

print('Obj: %g' % m.objVal)

```
from gurobipy import *
# Create a new model
m = Model("Veerman")
# Create variables
c = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Chair")
d = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Desk")
t = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Table")
# Set objective
m.setObjective(15*c+24*d+18*t, GRB.MAXIMIZE)
```

```
# Add constraints
m.addConstr(4*c + 6*d + 2*t <=
1850, "c0")
m.addConstr(3*c + 5*d + 7*t < =
2400, "c1")
m.addConstr(3*c + 2*d + 4*t <=
1500, "c2")
m.addConstr(c <= 360, "c3")
m.addConstr(d <= 300, "c4")
m.addConstr(t <= 100, "c5")
```

m.optimize()

DEFINE CONSTRAINTS

for v in m.getVars():
 print('%s %g' % (v.varName, v.x))
 print('Obj: %g' % m.objVal)

```
from gurobipy import *
# Create a new model
m = Model("Veerman")
# Create variables
c = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Chair")
d = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Desk")
t = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Table")
# Set objective
m.setObjective(15*c+24*d+18*t, GRB.MAXIMIZE)
```

```
# Add constraints
m.addConstr(4*c + 6*d + 2*t <=
1850, "c0")
m.addConstr(3*c + 5*d + 7*t <=
2400, "c1")
m.addConstr(3*c + 2*d + 4*t <=
1500, "c2")

m.addConstr(c <= 360, "c3")
m.addConstr(d <= 300, "c4")
m.addConstr(t <= 100, "c5")
```

m.optimize()

```
for v in m.getVars():

print('%s %g' % (v.varName, v.x))

print('Obj: %g' % m.objVal)
```

```
from gurobipy import *
# Create a new model
m = Model("Veerman")
# Create variables
c = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Chair")
d = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Desk")
t = m.addVar(vtype=GRB.CONTINUOUS, lb=0,
name="Table")
# Set objective
m.setObjective(15*c+24*d+18*t, GRB.MAXIMIZE)
```

```
# Add constraints
m.addConstr(4*c + 6*d + 2*t <=
1850, "c0")
m.addConstr(3*c + 5*d + 7*t < =
2400, "c1")
m.addConstr(3*c + 2*d + 4*t \le 
1500, "c2")
m.addConstr(c <= 360, "c3")
m.addConstr(d <= 300, "c4")
m.addConstr(t <= 100, "c5")
                   PRINT RESULTS
m.optimize()
for v in m.getVars():
  print('%s %g' % (v.varName, v.x))
```

print('Obj: %g' % m.objVal)

Output from Gurobi (Python)

Solved in 1 iterations and 0.02 seconds

Optimal objective 8.40000000e+03

Chair 0

Desk 275

Table 100

Obj: 8400

Example (recall..):

Objective function:

MAXIMIZE: 15C + 24D + 18T

Constraints:

• Fabri: $4C + 6D + 2T \le 1850$

• Assem: $3C + 5D + 7T \le 2400$

• Shipp: $3C + 2D + 4T \le 1500$

∘ C ≤ 360

∘ D ≤ 300

∘ T ≤ 100

∘ C ≥0, D≥0, T≥0

```
library(gurobi)
library(prioritizr)
model <- list()
model$obj <- c(15,24,18)
model$modelsense <- "max"
model$rhs <- c(1850,2400,1500,360,300,100)
model$sense <- c("<=","<=","<=","<=","<=")
model$vtype <- "C"
model$A <- matrix(c(4,6,2,3,5,7,3,2,4,1,0,0,0,1,0,0,0,1),nrow=6,byrow=T)
result <- gurobi(model, list())
print(result$status)
f.names=c('Chairs','Desks','Tables')
names(result$x)=f.names
print(result$x)
print(result$objval)
```

```
library(gurobi)
                                            Need to define all parts of optimization
library(prioritizr)
                                            in a 'list' (we will call it 'model')
model <- list()
model$obj
              <- c(15,24,18)
model$modelsense <- "max"
model$rhs <- c(1850,2400,1500,360,300,100)
model$sense <- c("<=","<=","<=","<=","<=")
model$vtype <- "C"
model$A
            <- matrix(c(4,6,2,3,5,7,3,2,4,1,0,0,0,1,0,0,0,1),nrow=6,byrow=T)
result <- gurobi(model, list())
print(result$status)
f.names=c('Chairs','Desks','Tables')
names(result$x)=f.names
print(result$x)
print(result$objval)
```

```
library(gurobi)
library(prioritizr)
                                           The objective function..only put in the
                                           coefficients...be sure to note order and
model <- list()
             <- c(15,24,18)
                                           MUST keep same order throughout!!
model$obj
model$modelsense <- "max"
model$rhs <- c(1850,2400,1500,360,300,100)
model$sense <- c("<=","<=","<=","<=","<=")
model$vtype <- "C"
model$A
              <- matrix(c(4,6,2,3,5,7,3,2,4,1,0,0,0,1,0,0,0,1),nrow=6,byrow=T)
result <- gurobi(model, list())
print(result$status)
f.names=c('Chairs','Desks','Tables')
names(result$x)=f.names
print(result$x)
print(result$objval)
```

```
library(gurobi)
library(prioritizr)
                                          This is where you define if you want to
model <- list()
                                          maximize or minimize
model$obj <- c(15,24,18)
model$modelsense <- "max"
model$rhs <- c(1850,2400,1500,360,300,100)
model$sense <- c("<=","<=","<=","<=","<=")
model$vtype <- "C"
model$A
          <- matrix(c(4,6,2,3,5,7,3,2,4,1,0,0,0,1,0,0,0,1),nrow=6,byrow=T)
result <- gurobi(model, list())
print(result$status)
f.names=c('Chairs','Desks','Tables')
names(result$x)=f.names
print(result$x)
print(result$objval)
```

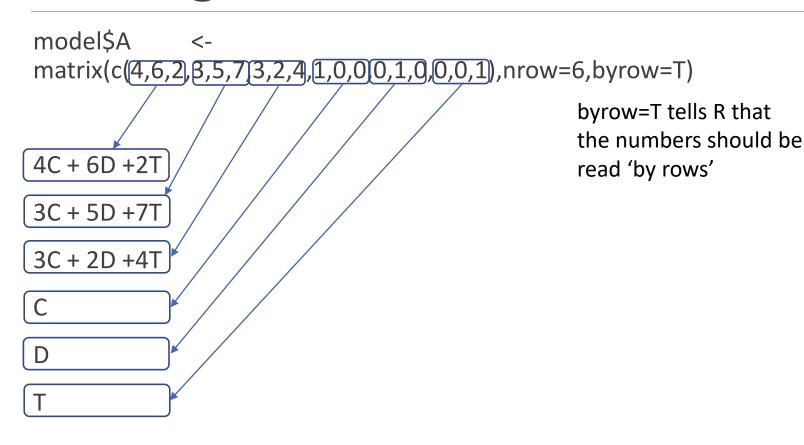
```
library(gurobi)
library(prioritizr)
                                           These are the values on the right hand
model <- list()
                                          side of the constraints (parameters)
model$obj
             <- c(15,24,18)
model$modelsense <- "max"
model$rhs <- c(1850,2400,1500,360,300,100)
model$sense <- c("<=","<=","<=","<=","<=")
model$vtype <- "C"
model$A
           <- matrix(c(4,6,2,3,5,7,3,2,4,1,0,0,0,1,0,0,0,1),nrow=6,byrow=T)
result <- gurobi(model, list())
print(result$status)
f.names=c('Chairs','Desks','Tables')
names(result$x)=f.names
print(result$x)
print(result$objval)
```

```
library(gurobi)
library(prioritizr)
                                           The inequalities for each line of the
model <- list()
                                           constraints (the length of the rhs vector
model$obj <- c(15,24,18)
                                           should equal length of this vector)
model$modelsense <- "max"
model$rhs <- c(1850,2400,1500,360,300,100)
model$sense <- c("<=","<=","<=","<=","<=")
model$vtype <- "C"
model$A
              <- matrix(c(4,6,2,3,5,7,3,2,4,1,0,0,0,1,0,0,0,1),nrow=6,byrow=T)
result <- gurobi(model, list())
print(result$status)
f.names=c('Chairs','Desks','Tables')
names(result$x)=f.names
print(result$x)
print(result$objval)
```

```
library(gurobi)
library(prioritizr)
model <- list()
model$obj <- c(15,24,18)
model$modelsense <- "max"
model$rhs <- c(1850,2400,1500,360,300,100)
model$sense <- c("<=","<=","<=","<=","<=","<=")
model$vtype <- "C"
                                                           This indicates decision
                                                           variables are continuous
model$A
              <- matrix(c(4,6,2,3,5,7,3,2,4,1,0,0,0,1,0,0,0,1),nrow=6,byrow=T)
result <- gurobi(model, list())
print(result$status)
f.names=c('Chairs','Desks','Tables')
names(result$x)=f.names
print(result$x)
print(result$objval)
```

```
library(gurobi)
library(prioritizr)
model <- list()
model$obj <- c(15,24,18)
model$modelsense <- "max"
model$rhs <- c(1850,2400,1500,360,300,100)
model$sense <- c("<=","<=","<=","<=","<=")
model$vtype <- "C"
              <- matrix(c(4,6,2,3,5,7,3,2,4,1,0,0,0,1,0,0,0,1),nrow=6,byrow=T)
model$A
result <- gurobi(model, list())
print(result$status)
f.names=c('Chairs','Desks','Tables')
                                                        These are the coefficients for
names(result$x)=f.names
                                                        the left hand side of the
print(result$x)
                                                        constraints....
print(result$objval)
```

Writing out 'left-hand' side



```
library(gurobi)
library(prioritizr)
model <- list()
model$obj <- c(15,24,18)
model$modelsense <- "max"
model$rhs <- c(1850,2400,1500,360,300,100)
model$sense <- c("<=","<=","<=","<=","<=")
model$vtype <- "C"
<u>model$A</u> <- matrix(c(4,6,2,3,5,7,3,2,4,1,0,0,0,1,0,0,0,1),nrow=6,byrow=T)
result <- gurobi(model, list())
print(result$status)
f.names=c('Chairs','Desks','Tables')
                                                     Runs the model
names(result$x)=f.names
print(result$x)
print(result$objval)
```

```
library(gurobi)
library(prioritizr)
model <- list()
model$obj <- c(15,24,18)
model$modelsense <- "max"
model$rhs <- c(1850,2400,1500,360,300,100)
model$sense <- c("<=","<=","<=","<=","<=")
model$vtype <- "C"
model$A
           <- matrix(c(4,6,2,3,5,7,3,2,4,1,0,0,0,1,0,0,0,1),nrow=6,byrow=T)
result <- gurobi(model, list())
print(result$status)
f.names=c('Chairs','Desks','Tables')
names(result$x)=f.names
                                                  Print the output (f.names is
print(result$x)
                                                  just to make it look nicer and
print(result$objval)
                                                  to label the output)
```

Output from Gurobi (R)

```
print(result$status)
[1] "OPTIMAL"
> f.names=c('Chairs','Desks','Tables')
> names(result$x)=f.names
> print(result$x)
Chairs Desks Tables 0 275 100
> print(result$objval) [1] 8400
```