

Jonathan Bucher

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[Games Portfolio](#) | [GitHub](#) | [Itch.io](#) | [LinkedIn](#)

EDUCATION

- 2023 - **Technical University of Munich** M.Sc. Informatics
- 2026 • Grade: 1.6/5.0 (German scale - 1.0 is highest)
• Thesis: Redesigned a voxel-based flood-fill algorithm using a chunk-based, data-oriented approach with Unity's C# Job System and Burst compiler
- 2025 **École Polytechnique de Montréal** Exchange Semester
• Built AI agent behaviors in Unreal Engine: pathfinding, obstacle avoidance, navigation meshes, and physics-based locomotion
- 2024 **Norwegian University of Science and Technology** Exchange Semester
• Implemented a stylized water shader in C++/OpenGL, with toggleable rendering stages demonstrating progressive shader construction
- 2019 - **Technical University of Munich** B.Sc. Informatics: Games Engineering
- 2023 • Grade: 1.9/5.0 (German scale - 1.0 is highest)
• Thesis: Designed formal spatial representations for machine learning based AI players in a 4X strategy game using Unity's ML Agents
• Coursework spanning real-time rendering (OpenGL), game physics, low-level & OS programming in C++, and parallel programming

WORK EXPERIENCE

- 2023 **Software Engineering Intern - Itestra**
• Data migration from legacy system using Java, PostgreSQL, Elasticsearch, and Spring Boot
- 2023 **Full Stack Developer Intern - Medigital**
• Developed web app for hospitals using React, Django, TypeScript, and Python

PROJECTS & PROGRAMMING EXPERTISE

- 2025 **Voxel-Based Spatial Partitioning Algorithm - M.Sc. Thesis, TUM**
• Developed chunk-based parallel voxel flood fill algorithm using Unity C# Jobs
• Rewrote codebase to utilize Burst-compatible C#
• Optimized data layout to improve caching behavior and reduce memory footprint
• Drastically improved scalability, performance (highest speedup over x71) and theoretical complexity of queries (linear to amortized constant)
• Built tooling for validation and benchmarking; received highest possible grade
- 2025 **Autonomous Drone - Mobile Robotics Practicals, TUM**
• Built a full autonomous navigation pipeline in C++, including camera projection, visual-inertial localization, sparse landmark matching, and feedback-controlled pathfinding under real-time frame-time constraints
• Implementation in C++ with a reverse-engineered extended API
• Completed the task in 25 seconds, fastest of 8 teams and well under the 40-second threshold for top grade
- 2025 **VR Alchemy Game - École Polytechnique**
• Developed gameplay systems and a movement-aware URP liquid shader for VR

SKILLS & INTERESTS

Languages	German (native), English (fluent), French (B1), Norwegian (A1)
Technology	C++, Unity, C#, DirectX, OpenGL, C, Python, Java, SQL, Linux
Tools	Unity (advanced), Godot, Unreal Engine (basic), Linux, Git, Blender
Interests	Language Learning, Board Games, FPV Drones