

Lesson 17 Servo

Introduction

In this lesson, you will learn how to use Servo. Servo is a type of geared motor that can only rotate 180 degrees. It is controlled by sending electrical pulses from your UNO R3 board. These pulses tell the servo what position it should move to.

Hardware Required

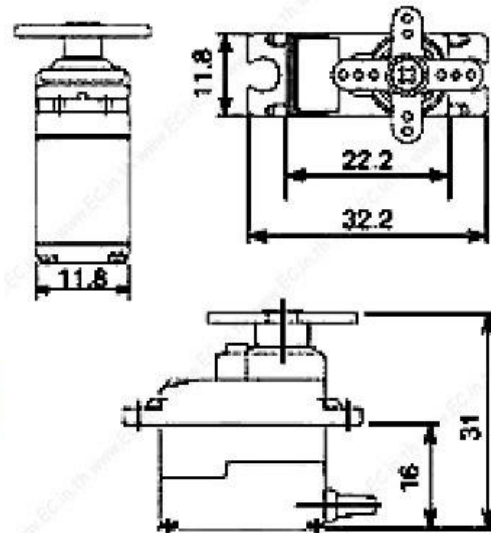
- ✓ 1 * RexQualis UNO R3
- ✓ 1 * Servo
- ✓ 3 * M-M Jumper Wires



Principle

SG90 Servo

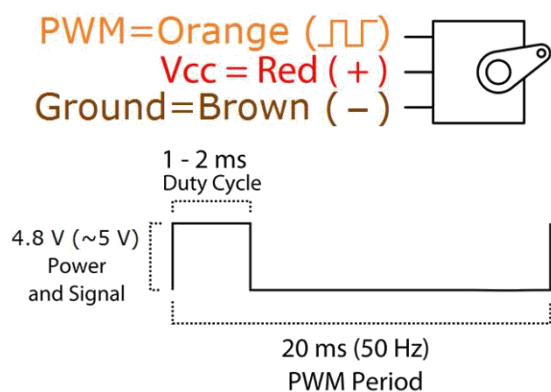
Tiny and lightweight with high output power. Servo can rotate approximately 180 degrees (90 in each direction), and works just like the standard kinds but SMALLER. You can use any servo code, hardware or library to control these servos. Good for beginners who want to make stuff move without building a motor controller with feedback & gear box, especially since it will fit in small places. It comes with a 3 horns (arms) and hardware.



Specifications

- Weight: 9 g
- Dimension: 22.2 x 11.8 x 31 mm approx.
- Stall torque: 1.8 kgf·cm
- Operating speed: 0.1 s/60 degree
- Operating voltage: 4.8 V (~5V)
- Dead band width: 10 μ s
- Temperature range: 0 °C – 55 °C

Position "0" (1.5 ms pulse) is middle, "90" (~2 ms pulse) is all the way to the right, "-90" (~1 ms pulse) is all the way to the left.



Code interpretation

```
#include <Servo.h>
```

```
Servo myservo; // create servo object to control a servo,can get  
to eight
```

```
int pos = 0; // variable to store the servo position
```

```
void setup() {
```

```
myservo.attach(9); // attaches the servo on pin 9 to the servo  
object
```

```
}
```

```
void loop() {
```

```
for (pos = 0; pos <= 180; pos += 1) { // goes from 0 degrees to 180  
degrees
```

```
// in steps of 1 degree
```

```
myservo.write(pos);
```

```
delay(15); // waits 15ms for the servo to  
reach the position
```

```
}
```

```
for (pos = 180; pos >= 0; pos -= 1) { // goes from 180 degrees to 0 degrees
```

```
myservo.write(pos);
```

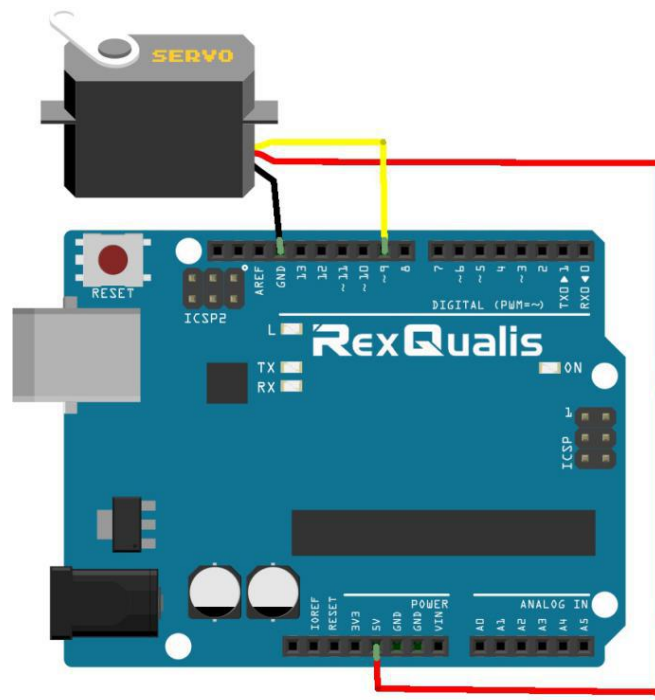
```
delay(15); // waits 15ms for the servo to reach the position
```

```
}
```

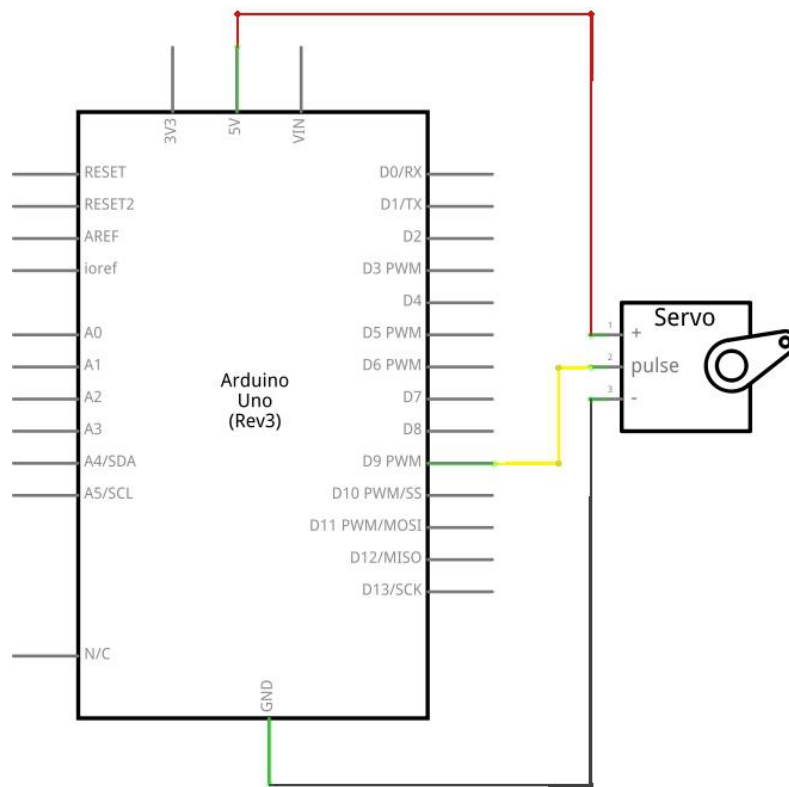
```
}
```

Experimental Procedures

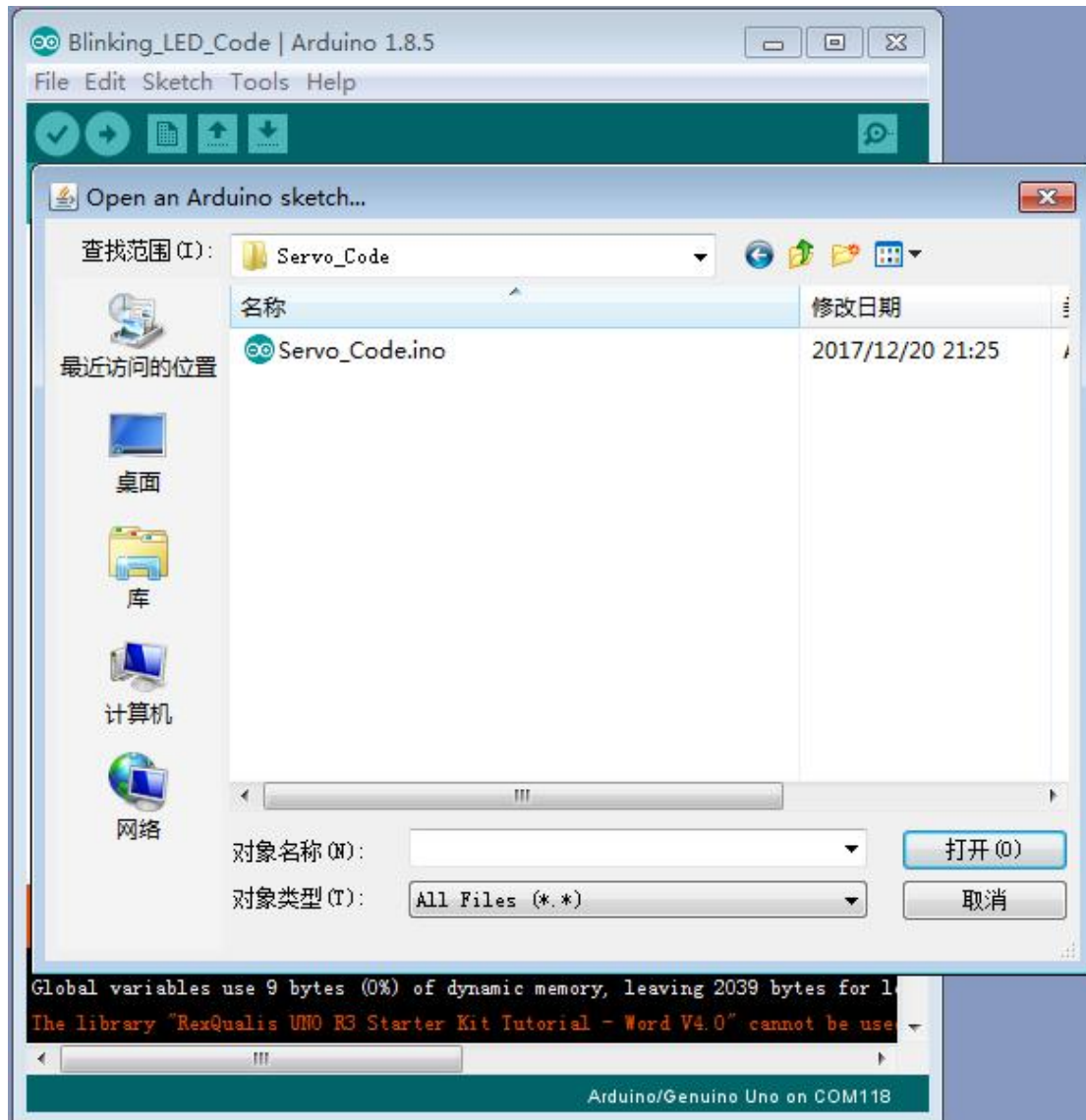
Step 1: Build the circuit



Schematic Diagram

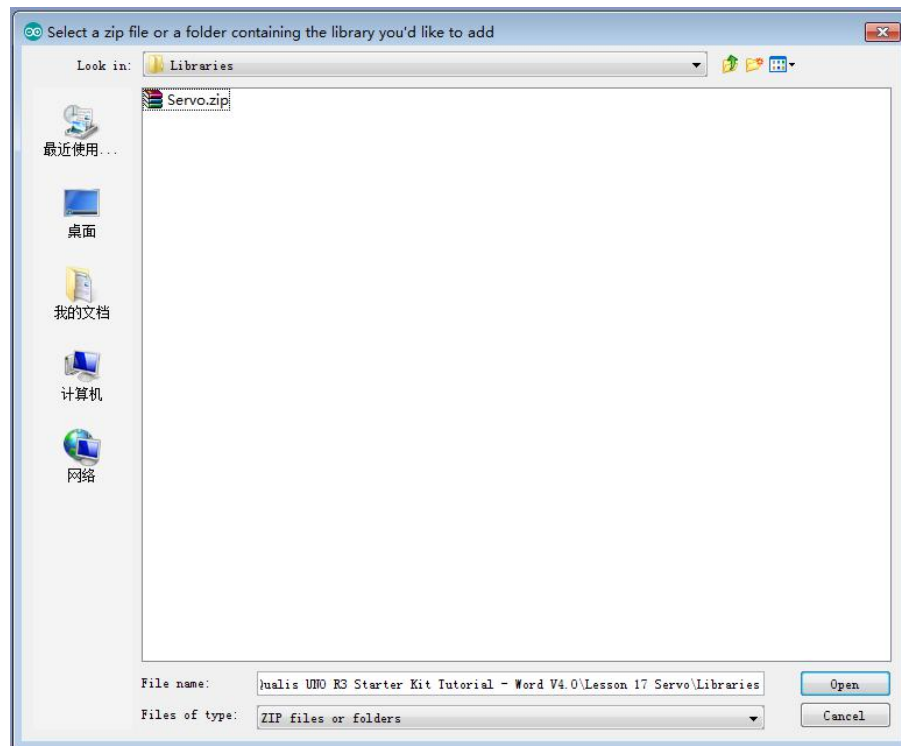


Step 2:Open the code:Servo_Code



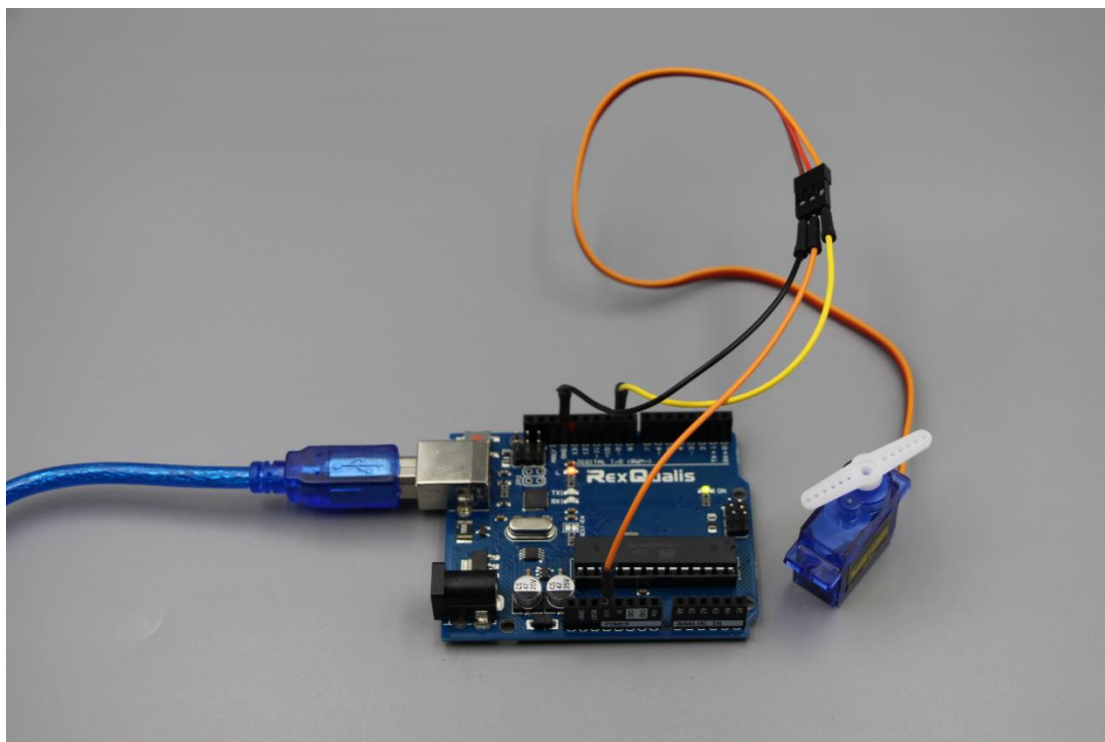
Step 3: Attach Arduino UNO R3 board to your computer via USB cable and check that the 'Board Type' and 'Serial Port' are set correctly.

Step 4: Load the Library:Servo



Step 5: Upload the code to the RexQualis UNO R3 board.

Then, You can see the servo turns anticlockwise and then turns clockwise.



If it isn' t working, make sure you have assembled the circuit correctly, verified and uploaded the code to your board. For how to upload the code and install the library, check Lesson 0 Preface.