Stan Can Use GPUs Now!

(almost!)

Steve Bronder June 1st, 2018

Stan has access to GPUs

- We see speedups of 8x for GPs with N=5000
- · Parameter estimates retain precision $\left(10^{-14}\right)$
- In production by July
- GPUs + MPI + threading is very exciting!

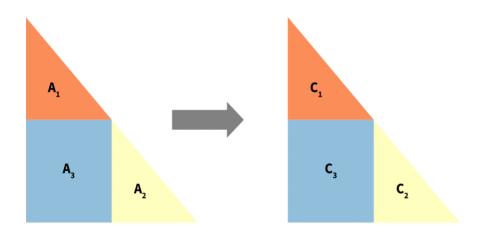
What do we have so far?

- 1. Matrix transpose
- 2. Multiplication of matrices with a diagonal and scalar
- 3. Addition/Subtraction of matrices
- 4. Copying submatrices
- 5. Matrix multiplication
- 6. Lower triangular matrix inverse
- 7. Cholesky decomposition
- 8. First derivative of Cholesky decomposition

Hows it Work? - Inverse

· Calculate A1 and A2 inverse sequentially (C1 and C2)

$$C3 = -C2 \times A3 \times C1$$

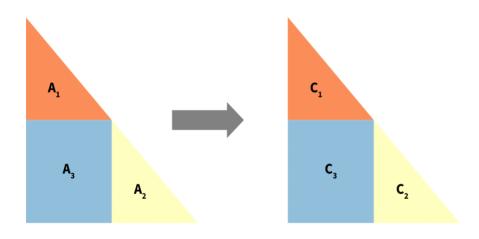


• Blocking algorithm by (Mahfoudhi, 2012)

Calculating A1 and A2 Inverse

· Calculate $A1_{A1}$ and $A1_{A2}$ inverse sequentially ($A1_{C1}$ and $A1_{C2}$)

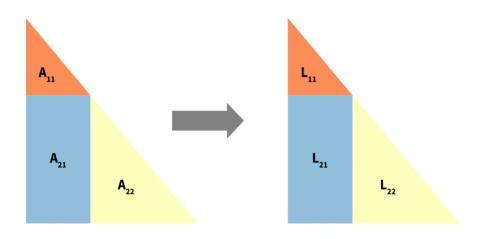
$$A1_{C3} = A1_{-C2} \times A1_{A3} \times A_{C1}$$



Hows it Work? - Cholesky

• Same as inverse, but only sequential for A_{11}

$$L_{21} = A_{21}(L_{11}^T)^{(-1)}$$
 $L_{22} = A_{22} - L_{21}(L_{21})^T$



Blocking algorithm of (LouterNool, 1992)

Example: 1D GP Regresssion

- Example from (Betancourt, 2017)
- · Relationship between x and y with added Gaussian noise:

$$x_i \sim_{\text{iid}} U(-10, 10)$$

$$y_i | x_i \sim_{\text{iid}} N\left(f(x), \frac{1}{10}\right), i = 1..n,$$

where

$$f(x) = \beta(x + x^2 - x^3 + 100\sin 2x - \alpha)$$

• Parameters β and α s.t. E[f] = 0 and Var[f] = 1.

Code Example

- · Take Michael's code from his GP tutorial online
- replace

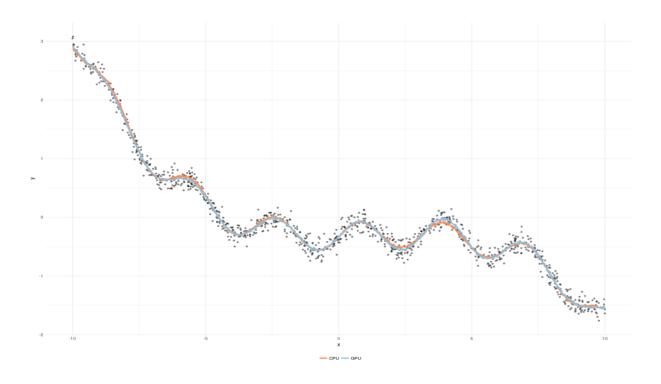
```
matrix[N1, N1] L_K = cholesky_decompose(K);
with

matrix[N1, N1] L_K = cholesky_decompose_gpu(K);

Pass compiler options:

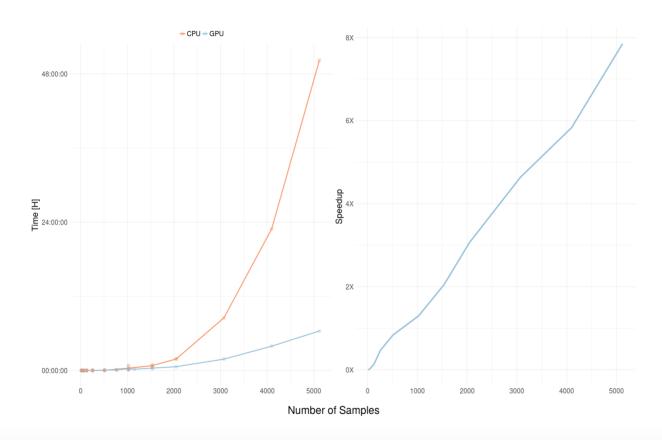
STAN_OPENCL=true
OPENCL_DEVICE_ID=0
OPENCL_PLATFORM_ID=0
```

How do the Samples Look?



- · Pretty good!
- 500 warmup and 500 iterations

But The Speed?



Nice!

Results

- Things are fast and precise!
- · We'll be wrapped up (hopefully) in July
- · Email: sab2287@columbia.edu

Bibliography

Mahfoudhi, Ryma et al. "High Performance Recursive Matrix Inversion for Multicore Architectures." 2017 International Conference on High Performance Computing & Simulation (HPCS) (2017): 675-682.

Betancourt, Michael. "Robust Gaussian Processes In Stan, Part 3". Betanalpha.Github.lo, 2018, https://betanalpha.github.io/assets/case_studies/gp_part3/part3.html.

Louter-Nool, Margreet. 1992. "Block-Cholesky for Parallel Processing." Appl. Numer. Math. 10 (1). Amsterdam, The Netherlands, The Netherlands: Elsevier Science Publishers B. V.: 37–57. doi:10.1016/0168-9274(92)90054-H.

Slides/Paper/Code:

https://github.com/SteveBronder/stancon2018/tree/r_in_finance