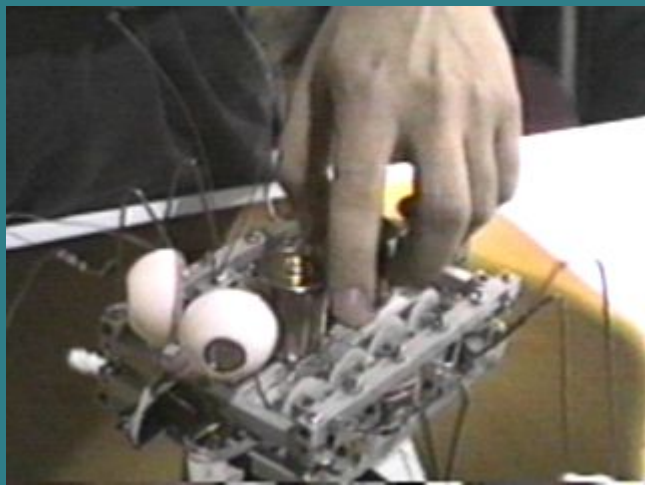


## Another Spider!



Toronto 1994, jpeg from video via Snappy, made by Dave Hrynkiw.

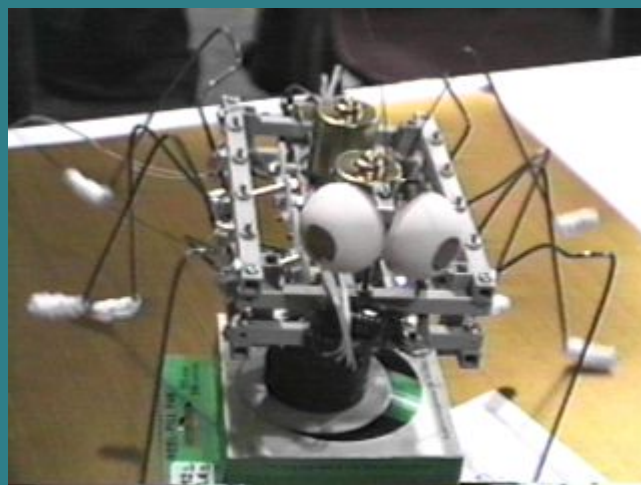
I really had the idea for the Spider mechanism all by myself - no outside inspiration or examples at all. But when I showed the preliminary drawings to the BEAMers, Dave Hrynkiw ( [Solarbotics](#)) yelled:

"I saw EXACTLY the same sort of robot at the BEAM Games in Toronto in '94(?)"

He was supported by Richard Weait:

Dave's right (of course :-)) about the spider at BEAM - '94. I think it was Rob from Ottawa (?) It was powered through a tether, and skittered along on golf-ball-like feet. It was pretty quick, but I believe it was run by switches through the tether. Forward and reverse only, if I recall correctly. I trust Rob (?) has carried the design further since then.

The designer's name is actually Mark Lanthier. He calls his `bot the Creeper, and it can be found on [this page](#), which also shows a few other, multimotor critters and a rope-climbing device.



Toronto 1994, jpeg from video via Snappy, made by Dave Hrynkiw.

[previous \(Spider parts\)](#) / [next \(Guest corner\)](#)