

Zhexiao Xiong

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BIOGRAPHY

I am a third-year CS Ph.D. candidate at Washington University in St. Louis(WashU), advised by **Dr. Nathan Jacobs**. My research lies broadly in computer vision and multi-modal learning, especially generative models and AIGC-related topics, including personalized text-to-image generation, image editing, cross-view & novel view synthesis. I am also interested in geometric computer vision and its combination with generative models.

EDUCATION

- **Washington University in St. Louis** 2022.08 – 2027.05(Expected)
Ph.D. Candidate in Computer Science St. Louis, MO, USA
Advisor: [Prof. Nathan Jacobs](#)
- **Tianjin University** 2018.09 – 2022.06
B.S. in Electrical and Information Engineering Tianjin, China

WORK EXPERIENCE


- **OPPO US Research Center**  2024.05 – 2024.08
Research Intern Palo Alto, CA, USA
 - Researched on text-guided 3D Scene Generation, use Large-language model(LLM)-based dreaming and move-and-lookaround strategy to generate both geometric and semantic consistent 3D scene.
- **OPPO Research Institute**  2022.02 – 2022.05
Research Intern Beijing, China
 - Researched on image matting, proposed a framework to use human pose as guidance to achieve whole body matting.
- **Institute of Automation, Chinese Academy of Sciences, Beijing, China(CASIA)**  2021.01 – 2022.01
Research Intern Beijing, China
 - Researched on model compression and network pruning, especially the application on Vision Transformers.

SELECTED PUBLICATIONS

C=CONFERENCE, J=JOURNAL, P=PRE-PRINT

- [P.1] **Zhexiao Xiong**, Wei Xiong, Jing Shi, He Zhang, Yizhi Song, Nathan Jacobs. **GroundingBooth: Grounding Text-to-Image Customization**. *Arxiv Pre-print*.
- [P.2] **Zhexiao Xiong**, Xin Xing, Scott Workman, Subash Khanal, Nathan Jacobs. **Mixed-View Panorama Synthesis using Geospatially Guided Diffusion**. *Arxiv Pre-print*.
- [P.3] Feng Qiao, **Zhexiao Xiong**, Xinge Zhu, Yuexin Ma, Qiumeng He, Nathan Jacobs. **MCPDepth: Omnidirectional Depth Estimation via Stereo Matching from Multi-Cylindrical Panoramas**. *Arxiv Pre-print*.
- [C.1] **Zhexiao Xiong**, Feng Qiao, Yu Zhang, Nathan Jacobs. **StereoFlowGAN: Co-training for Stereo and Flow with Unsupervised Domain Adaptation**. In *British Machine Vision Conference(BMVC)*, 2023.
- [C.2] Xin Xing, **Zhexiao Xiong**, Abby Stylianou, Srikumar Sastry, Liyu Gong, Nathan Jacobs. **Vision-Language Pseudo-Labels for Single-Positive Multi-Label Learning**. In *IEEE/CVF Conference on Computer Vision and Pattern Recognition Workshops(CVPRW)*, 2024.
- [C.3] Subash Khanal, Eric Xing, Srikumar Sastry, Aayush Dhakal, **Zhexiao Xiong**, Adeel Ahmad, Nathan Jacobs. **PSM: Learning Probabilistic Embeddings for Multi-scale Zero-Shot Soundscape Mapping**. In *ACM Multimedia(ACM MM)*, 2024.
- [J.1] Nanfei Jiang, **Zhexiao Xiong**, Hui Tian, Xu Zhao, Xiaojie Du, Chaoyang Zhao, Jinqiao Wang. **PruneFaceDet: Pruning lightweight face detection network by sparsity training**. *Cognitive Computation and Systems*, 2022.

PROJECTS

- **Grounded text-to-image Customization** 2024.01 – 2024.09
Collabroration with Adobe Research 
 - Proposed a framework that achieved zero-shot instance-level spatial grounding on both foreground subjects and background objects in the text-to-image customization task, enabling the customization of multiple subjects.
 - Our work is the first work to achieve a joint grounding on both subject-driven foreground generation and text-driven background generation.
 - Results show the effectiveness of our model in text-image alignment, identity preservation, and layout alignment.

• Text to 360-Degree Scene Generation

2024.05 – 2024.11

- Proposed a holistic text to 360-degree scene generation pipeline, which achieved consistent text-to-360-degree scene generation with customized trajectory-guided scene extension.
- Introduced semantically guided novel view synthesis into the refinement of 3D-GS optimization, reducing artifacts and improving geometric consistency.

• Mixed-View Panorama Synthesis Using Geospatially-Guided Diffusion

2023.06 – 2023.11



- Introduced the task of mixed-view panorama synthesis, where the goal is to synthesize a novel panorama given a small set of input panoramas and a satellite image of the area.
- Introduced an approach that utilizes diffusion-based modeling and an attention-based architecture for extracting information from all available input imagery.

• Omnidirectional Depth Estimation via Stereo Matching

2023.10 – 2024.03



- Proposed a two-stage framework for omnidirectional depth estimation via stereo matching between multiple cylindrical panoramas.

• Co-training for Stereo and Flow with Unsupervised Domain Adaptation

2023.01 – 2023.05



- Built an end-to-end joint learning framework to combine unsupervised domain translation with optical flow estimation and stereo matching in the absence of real ground truth optical flow and disparity.
- Applied novel constraints on the cycle domain translation process to achieve cross-domain translation with global and local consistency.
- Employed task-specific multi-scale feature warping loss and iterative feature warping loss during the training phase to regulate the training process in both spatial and temporal dimensions.

• Vision-Language Pseudo-Labels for Single-Positive Multi-Label Learning

2022.11 – 2023.05



- Proposed a novel approach called Vision-Language Pseudo-Labeling (VLPL), which uses a vision-language model to suggest strong positive and negative pseudo-labels, and outperforms the current SOTA methods by 5.5% on Pascal VOC, 18.4% on MS-COCO, 15.2% on NUS-WIDE, and 8.4% on CUB-Birds.

• Pruning Lightweight Face Detection Network by Sparsity Training

2021.01 – 2022.01



- Performed the network training with sparsity regularization on channel scaling factors of each layer, and then removed the connections and the corresponding weights with the near-zero scaling factors after the sparsity training.
- Applied the proposed pruning pipeline on a state-of-the-art face detection method, EagleEye, and got a shrunken model which has a reduced number of computing operations and parameters.
- Achieved 56.3% reduction of parameter size with almost no accuracy loss on WiderFace dataset.

• Mobile AI 2021 Real-Time Camera Scene Detection Challenge

2021.01 – 2021.03

Mobile AI Workshop @ CVPR 2021



- Used two-stage fine-tuning method to improve the accuracy and the model pruning method to improve the model's efficiency.
- Used the float32-to-int8 quantization and model pruning methods to optimize our model.

SERVICES

- **Reviewer:** ECCV(2024), NeurIPS(2024), ICLR(2025)
- **Teaching Services (WashU):** CSE 559A Computer Vision (Teaching Assistant/Grader)

TECHNICAL SKILLS

Programming: Python, C/C++, Java, Matlab

Deep Learning Frameworks: Pytorch, Tensorflow

Research Frameworks: Diffusion models, Transformer, GAN, 3DGS, NeRF, CNN, CLIP

Languages: English, Chinese