

Exercise 10: Semantic Segmentation

Semantic Segmentation

- Output of the model:
 - Assign label of classes to each pixel in the image.

- Loss metric:
 - We use pixel-wise cross-entropy loss.
 - Note that there are unlabelled pixels, and we should filter the unlabelled pixels and compute the loss only over remaining pixels.

Network Architecture - Feature

```
class SegmentationNN(nn.Module):
   def init (self, num classes=23, hparams=None):
       super(). init ()
       self.hparams = hparams
                                  YOUR CODE
       from torchvision import models
       self.features = models.mobilenet v2(pretrained=True, progress=True).features
       self.classifier = nn.Sequential(
           nn.Conv2d(1280, 512, kernel size=3, padding=1, stride=1),
           nn.BatchNorm2d(512),
           nn.ReLU(inplace=True),
           nn.Dropout(p=0.2),
           nn.Conv2d(512, 256, kernel size=3, padding=1, stride=1),
           nn.BatchNorm2d(256),
           nn.ReLU(inplace=True),
           nn.Conv2d(256, 128, kernel size=3, padding=1, stride=1),
           nn.BatchNorm2d(128),
           nn.ReLU(inplace=True),
           nn.Conv2d(128, 64, kernel size=3, padding=1, stride=1),
           nn.Upsample(scale factor=30),
           nn.Conv2d(64, num classes, kernel size=3, padding=1)
```

 Remark: For the feature extraction we use the pretrained mobilenet_v2, this model is quite lightweight and suitable for our task.

Network Architecture - Classifier

```
class SegmentationNN(nn.Module):
   def init (self, num classes=23, hparams=None):
       super(). init ()
       self.hparams = hparams
                                YOUR CODE
      from torchvision import models
      self.features = models.mobilenet v2(pretrained=True, progress=True).features
      self.classifier = nn.Seguential(
          nn.Conv2d(1280, 512, kernel size=3, padding=1, stride=1),
          nn.BatchNorm2d(512),
          nn.ReLU(inplace=True),
          nn.Dropout(p=0.2),
          nn.Conv2d(512, 256, kernel size=3, padding=1, stride=1),
          nn.BatchNorm2d(256),
          nn.ReLU(inplace=True),
          nn.Conv2d(256, 128, kernel size=3, padding=1, stride=1),
          nn.BatchNorm2d(128),
          nn.ReLU(inplace=True),
          nn.Conv2d(128, 64, kernel size=3, padding=1, stride=1),
          nn.Upsample(scale factor=30),
          nn.Conv2d(64, num classes, kernel size=3, padding=1)
```

 Remark: For the classifier we offer a simple architecture that has a nn. Upsample to let the final Height and Width align with our original input size.

Network-forward

```
def forward(self, x):
    Forward pass of the convolutional neural network. Should not be called
    manually but by calling a model instance directly.
    Inputs:
    - x: PyTorch input Variable
                                  YOUR CODE
    x = self.features(x)
    x = self.classifier(x)
    return x
```

Remark: We need to make sure the tensor taken by the classifier has the same channels that our feature extractor produces, and the final output should have the size of (B, #classes, H, W)

Training Loop (1)

```
model = SegmentationNN()
      - Train Your Model
import torch.optim as optim
num epochs = 40
batch size = 12
learning rate = 1e-4
optimizer = optim.Adam(
    model.parameters(),
   lr=learning rate,
   betas=(0.9, 0.999),
    eps=1e-8.
    weight decay=0.0
log nth = 10 # log nth: log training accuracy and loss every nth iteration
train loss history = []
train acc history = []
val acc history = []
val loss history = []
train loader = torch.utils.data.DataLoader(train data,batch size=batch size, shuffle=True,num workers=0)
val loader = torch.utils.data.DataLoader(val data, batch size=batch size, shuffle=False, num workers=0)
iter per epoch = len(train loader)
device = torch.device("cuda:0" if torch.cuda.is available() else "cpu")
model.to(device)
```

Remark: We can define a Pytorch-style training loop directly inside the coding block.

Training Loop (2)

```
print('START TRAIN.')
for epoch in range(num epochs):
    # TRAINING
    train acc epoch = []
   for i, (inputs, targets) in enumerate(train loader, 1):
       inputs, targets = inputs.to(device), targets.to(device)
       optimizer.zero grad()
       outputs = model(inputs)
       loss = loss func(outputs, targets)
       loss.backward()
       optimizer.step()
       train loss history.append(loss.cpu().detach().numpy())
       if log nth and i % log nth == 0:
           last_log_nth_losses = train_loss_history[-log_nth:]
           train loss = np.mean(last log nth losses)
           print('[Iteration %d/%d] TRAIN loss: %.3f' %
                 (i + epoch * iter per epoch.
                  iter per epoch * num epochs.
                  train loss))
        , preds = torch.max(outputs, 1)
       # Only allow images/pixels with label >= 0 e.g. for segmentation
       targets mask = targets >= 0
       train acc = np.mean((preds == targets)[
                           targets mask].cpu().detach().numpy())
       train acc history.append(train acc)
       train_acc_epoch.append(train_acc)
       train acc = np.mean(train acc epoch)
       print('[Epoch %d/%d] TRAIN acc/loss: %.3f/%.3f' % (epoch + 1, num epochs, train acc, train loss))
    # VALIDATION
   val losses = []
   val scores = []
   model.eval()
   for inputs, targets in val loader:
       inputs, targets = inputs.to(device), targets.to(device)
       outputs = model.forward(inputs)
       loss = loss func(outputs, targets)
       val_losses.append(loss.detach().cpu().numpy())
       _, preds = torch.max(outputs, 1)
       # Only allow images/pixels with target >= 0 e.g. for
       # segmentation
       targets mask = targets >= 0
       scores = np.mean((preds == targets)[
                        targets mask].cpu().detach().numpy())
       val scores.append(scores)
   val acc, val loss = np.mean(val scores), np.mean(val losses)
   val acc history.append(val acc)
    val_loss_history.append(val_loss)
       print('[Epoch %d/%d] VAL acc/loss: %.3f/%.3f' % (epoch + 1, num epochs, val acc, val loss))
```

• Remark: This is the actual training loop, where we have the forward and the backward pass of the model, compute the loss, optimize the parameters, and log the loss/accuracy information.

Hyperparameters

```
num_epochs = 40
batch_size = 12
learning_rate = 1e-4
optimizer = optim.Adam(
    model.parameters(),
    lr=learning_rate,
    betas=(0.9, 0.999),
    eps=1e-8,
    weight_decay=0.0
)
```

- Remark: This is the hyperparameters that we set in our sample solution. You can also use a hyperparameter search to get a set of hyperparameters that suit your model well.
- For the sample model and this set of hyperparameters, we can reach an accuracy around 88%.

Semantic Segmentation

- Different Model Designs:
 - In this exercise, we show an easy way to achieve reasonable scores on our assignment by using pretrained model, you can try with different pretrained models that pytorch offers and compare them.
 - For this field of task, there are also some famous models that you may also learn from the lecture, e.g., FCN, U-Net, etc., for which you can have a closer look if you are interested.

Long et al. "Fully Convolutional Networks for Semantic Segmentation", CVPR, 2015

Ronneberger et al. "U-Net: Convolutional Networks for Biomedical Image Segmentation", MICCAI, 2015



Questions? Piazza

