

Packet 2

Part 1: Sections 13.3-13.4

13.3 Arc Length and Curvature

Problem 1. Let $\vec{r}(t) = \langle 6t, t^3, 3t^2 \rangle$. Use the lengths of the line segments connecting $\vec{r}(0)$, $\vec{r}(1)$, $\vec{r}(2)$, and $\vec{r}(3)$ to approximate the length of the curve from $t = 0$ to $t = 3$.

Solution.

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Definition 2. Let $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$ be a vector function. Then the **arclength** or **length** of the curve given by $\vec{r}(t)$ from $t = a$ to $t = b$ is

$$L = \int_a^b \left| \lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t} \right| dt = \int_a^b |\vec{r}'(t)| dt$$

Problem 3. Find the length of the curve given by $\vec{r}(t) = \langle 6t, t^3, 3t^2 \rangle$ from $t = 0$ to $t = 3$. (Hint: $9t^4 + 36t^2 + 36$ is a perfect square polynomial.)

Solution.

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Definition 4. Let $s(t)$ be the **arclength function/parameter** representing the length of a curve from the point given by $\vec{r}(0)$ to the point given by $\vec{r}(t)$. (Assume $s(t) < 0$ for $t < 0$.)

Theorem 5. The arclength function $s(t)$ is given by the definite integral

$$s(t) = \int_0^t |\vec{r}'(\tau)| d\tau$$

Theorem 6. The derivative of the arclength function gives the lengths of the tangent vectors given by the derivative of the position function:

$$\frac{ds}{dt} = \left| \frac{d\vec{r}}{dt} \right|$$

Problem 7. Compute $s(t)$ for $\vec{r}(t) = \langle 6t, t^3, 3t^2 \rangle$, and use it to find the arclength parameter corresponding to $t = -2$.

Solution.

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Problem 8. Find the length of an arc of the circular helix with vector equation $\vec{\mathbf{r}}(t) = \langle \cos(t), \sin(t), t \rangle$ from $(1, 0, 0)$ to $(1, 0, 2\pi)$.

Definition 9. The **unit tangent vector** $\vec{\mathbf{T}}$ to a curve $\vec{\mathbf{r}}$ is the direction of the derivative $\vec{\mathbf{r}}'(t) = \frac{d\vec{\mathbf{r}}}{dt}$.

Theorem 10.

$$\vec{\mathbf{T}} = \frac{d\vec{\mathbf{r}}/dt}{|d\vec{\mathbf{r}}/dt|} = \frac{d\vec{\mathbf{r}}}{ds}$$

Problem 11. Find the unit tangent vector to the curve given by $\vec{\mathbf{r}}(t) = \langle 3t^2, 2t \rangle$ at the point where $t = -3$.

Solution.

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Definition 12. The **curvature** κ of a curve C at a given point is the magnitude of the rate of change of $\vec{\mathbf{T}}$ with respect to arclength s .

Theorem 13.

$$\kappa = \left| \frac{d\vec{\mathbf{T}}}{ds} \right| = \left| \frac{1}{ds/dt} \frac{d\vec{\mathbf{T}}}{dt} \right| = \frac{1}{|d\vec{\mathbf{r}}/dt|} \left| \frac{d\vec{\mathbf{T}}}{dt} \right|$$

Theorem 14. An alternate formula for curvature is given by

$$\kappa = \frac{|\vec{\mathbf{r}}'(t) \times \vec{\mathbf{r}}''(t)|}{|\vec{\mathbf{r}}'(t)|^3}$$

Problem 15. Prove that the helix given by the vector equation $\vec{\mathbf{r}}(t) = \langle \cos(t), \sin(t), t \rangle$ has constant curvature.

Solution.

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Problem 16. (OPTIONAL) Prove that the alternate formula for curvature is accurate by showing

$$\frac{1}{|d\vec{\mathbf{r}}/dt|} \left| \frac{d\vec{\mathbf{T}}}{dt} \right| = \frac{|\vec{\mathbf{r}}' \times \vec{\mathbf{r}}''|}{|\vec{\mathbf{r}}'|^3}$$

(Some of the solution has been provided.)

Solution. Begin by observing that $\vec{\mathbf{r}}' = \left| \frac{d\vec{\mathbf{r}}}{dt} \right| \vec{\mathbf{T}} = \frac{ds}{dt} \vec{\mathbf{T}}$, and by the product rule it follows that $\vec{\mathbf{r}}'' = \frac{d^2s}{dt^2} \vec{\mathbf{T}} + \frac{ds}{dt} \vec{\mathbf{T}}'$.
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Definition 17. The **unit normal vector** \vec{N} to a curve \vec{r} is the direction of the derivative of the unit tangent vector $\vec{T}'(t) = \frac{d\vec{T}}{dt}$. (By definition, this vector points into the direction of the curve.)

Theorem 18.

$$\vec{N} = \frac{\vec{T}'}{|\vec{T}'|}$$

Problem 19. Prove that \vec{N} actually is normal to the curve by using a theorem from a previous section. (Hint: $|\vec{T}| = 1$.)

Solution. ◇

Problem 20. Plot the curve given by $\vec{r}(t) = \langle \cos(2t), \sin(2t) \rangle$, along with \vec{T}, \vec{N} at the point where $t = \frac{\pi}{2}$.

Problem 21. Give formulas for \vec{T}, \vec{N} in terms of t for the vector function

$$\vec{r}(t) = \langle \sqrt{2} \sin t, 2 \cos t, \sqrt{2} \sin t \rangle$$

Solution. ◇

Definition 22. The **binormal vector** \vec{B} is the direction normal to both \vec{T} and \vec{N} according to the right-hand rule.

Theorem 23.

$$\vec{B} = \vec{T} \times \vec{N}$$

Problem 24. Prove that $\vec{T} \times \vec{N}$ is a unit vector.

Solution. ◇

Problem 25. Given the following information about $\vec{r}(t)$ at a point, evaluate the binormal vector \vec{B} and curvature κ at that same point:

$$\frac{d\vec{r}}{dt} = \langle -3, 0, 3\sqrt{3} \rangle$$

$$\frac{d\vec{T}}{dt} = \langle -\sqrt{3}, 0, -1 \rangle$$

$$\vec{T} = \langle -\frac{1}{2}, 0, \frac{\sqrt{3}}{2} \rangle$$

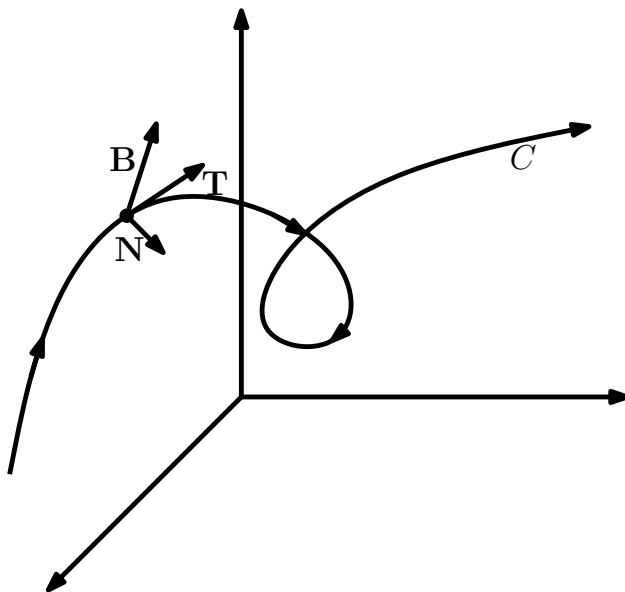
$$\vec{N} = \langle -\frac{\sqrt{3}}{2}, 0, -\frac{1}{2} \rangle$$

Solution.

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Definition 26. A **right-handed frame** is a group of three unit vectors which are all normal to one another and satisfy the right hand rule.

Example 27. $\hat{i}, \hat{j}, \hat{k}$ and $\vec{T}, \vec{N}, \vec{B}$ are examples of right-handed frames.



Theorem 28. Any vector is a linear combination of the vectors in a right-handed frame.

13.4 Motion in Space, Velocity, and Acceleration

Definition 29. The **velocity** $\vec{v}(t)$ of a particle at time t on a position function $\vec{r}(t)$ is its rate of change with respect to t .

Definition 30. The **speed** $|\vec{v}(t)|$ of a particle at time t on a position function $\vec{r}(t)$ is the magnitude of its velocity.

Definition 31. The **direction** $\vec{T}(t)$ of a particle at time t on a position function $\vec{r}(t)$ is the direction of its velocity.

Definition 32. The **acceleration** $\vec{a}(t)$ of a particle at time t on a position function $\vec{r}(t)$ is the rate of change of its velocity with respect to t .

Theorem 33.

$$\begin{aligned}\vec{v}(t) &= \vec{r}'(t) \\ |\vec{v}(t)| &= |\vec{r}'(t)| = \frac{ds}{dt} \\ \vec{T}(t) &= \frac{\vec{v}}{|\vec{v}|} \\ \vec{a}(t) &= \vec{v}'(t) = \vec{r}''(t)\end{aligned}$$

Problem 34. Given a position function $\vec{\mathbf{r}}(t) = \langle t^3, t^2 \rangle$ find its velocity, speed, and acceleration at $t = 1$.

Definition 35. Ideal projectile motion is an approximation of real-world motion assuming constant acceleration due to gravity in the y direction and no acceleration in the x direction:

$$\vec{\mathbf{a}}(t) = \langle 0, -g \rangle$$

Theorem 36. The velocity and position functions for a particle with initial velocity $\vec{\mathbf{v}}_0 = \langle v_{x,0}, v_{y,0} \rangle$ and beginning at position $P_0 = \langle x_0, y_0 \rangle$ assuming ideal projectile motion are:

$$\vec{\mathbf{v}}(t) = \langle v_{x,0}, -gt + v_{y,0} \rangle$$

$$\vec{\mathbf{r}}(t) = \left\langle v_{x,0}t + x_0, -\frac{1}{2}gt^2 + v_{y,0}t + y_0 \right\rangle$$

Problem 37. Assume ideal projectile motion and $g = 10 \frac{m}{s^2}$. What is the flight time of a projectile shot from the ground at an angle of $\pi/6$ with initial speed $100 \frac{m}{s}$?

Solution.

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Problem 38. Assume ideal projectile motion and $g = 10 \frac{m}{s^2}$. What must have been the initial speed of a projectile shot from the ground at an angle of $\pi/3$ if it traveled 60 meters horizontally after 4 seconds?

Solution.

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