Section M.1 Section M.2 Section M.3

Module M: Understanding Matrices Algebraically

Section M.1 Section M.2 Section M.3

What algebraic structure do matrices have?

Section M.1 Section M.2 Section M.3

At the end of this module, students will be able to...

- M1. Matrix Multiplication. ... multiply matrices.
- **M2. Invertible Matrices.** ... determine if a square matrix is invertible or not.
- M3. Matrix inverses. ... compute the inverse matrix of an invertible matrix.

Readiness Assurance Outcomes

Before beginning this module, each student should be able to...

- Compose functions of real numbers
- Solve systems of linear equations E3
- Find the matrix corresponding to a linear transformation A1
- Determine if a linear transformation is injective and/or surjective A3
- Interpret the ideas of injectivity and surjectivity in multiple ways

Section M.1 Section M.2 Section M.3

The following resources will help you prepare for this module.

• Function composition (Khan Academy): http://bit.ly/2wkz7f3

Math 237

Module M

Section M.1 Section M.2 Section M.3

Module M Section 1

Observation M.1.1

Recall that to quickly compute $T(\mathbf{v})$ from its standard matrix A, compute the **dot product** (defined in Calculus 3) of each matrix row with the vector. For example, if T has the standard matrix

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 2 & -1 & 0 \end{bmatrix}$$

then for
$$\mathbf{v} = \begin{bmatrix} 3 \\ 0 \\ -2 \end{bmatrix}$$
 we may write

$$T(\mathbf{v}) = A\mathbf{v} = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 2 & -1 & 0 \end{bmatrix} \begin{bmatrix} 3 \\ 0 \\ -2 \end{bmatrix} = \begin{bmatrix} 1(3) + 2(0) + 3(-2) \\ 0(3) + 1(0) - 2(-2) \\ 2(3) - 1(0) + 0(-2) \end{bmatrix} = \begin{bmatrix} -3 \\ 4 \\ 6 \end{bmatrix}.$$

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the $4 imes 2$ standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

What is the domain of the composition map $S \circ T$?

- (a) ℝ
- (b) \mathbb{R}^2
- (c) \mathbb{R}^3
- (d) \mathbb{R}^4

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the $4 imes 2$ standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

What is the codomain of the composition map $S \circ T$?

- (a) ℝ
- (b) \mathbb{R}^2
- (c) \mathbb{R}^3
- (d) \mathbb{R}^4

Let $T: \mathbb{R}^3 \to \mathbb{R}^2$ be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S: \mathbb{R}^2 o \mathbb{R}^4$$
 be given by the $4 imes 2$ standard matrix $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$.

What size will the standard matrix of $S \circ \mathcal{T} : \mathbb{R}^3 \to \mathbb{R}^4$ be? (Rows \times Columns)

(a)
$$4 \times 3$$

(c)
$$3 \times 4$$

(e)
$$2 \times 4$$

(d)
$$3 \times 2$$

(f)
$$2 \times 3$$

Module M Section M.1 Section M.2 Section M.3 Let $T:\mathbb{R}^3 o \mathbb{R}^2$ be given by the 2 imes 3 standard matrix $B=\begin{bmatrix} 2 & 1 & -3 \ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the $4 imes 2$ standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the $4 imes 2$ standard matrix $A=egin{bmatrix}1&2\\0&1\\3&5\\-1&-2\end{bmatrix}$.

Part 1: Compute

$$(S \circ T)(\mathbf{e}_1) = S(T(\mathbf{e}_1)) = S\left(\begin{bmatrix} 2\\5 \end{bmatrix}\right) = \begin{bmatrix} 1 & 2\\0 & 1\\3 & 5\\-1 & -2 \end{bmatrix} \begin{bmatrix} 2\\5 \end{bmatrix} = \begin{bmatrix} ?\\?\\?\\?\\? \end{bmatrix}$$

using the dot product of each matrix row with the vector.

Let
$$\mathcal{T}:\mathbb{R}^3 o\mathbb{R}^2$$
 be given by the $2 imes3$ standard matrix $B=\begin{bmatrix}2&1&-3\\5&-3&4\end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the $4 imes 2$ standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

Part 1: Compute

$$(S \circ T)(\mathbf{e}_1) = S(T(\mathbf{e}_1)) = S\left(\begin{bmatrix}2\\5\end{bmatrix}\right) = \begin{bmatrix}1 & 2\\0 & 1\\3 & 5\\-1 & -2\end{bmatrix}\begin{bmatrix}2\\5\end{bmatrix} = \begin{bmatrix}?\\?\\?\\?\end{bmatrix}$$

using the dot product of each matrix row with the vector.

Part 2: Compute $(S \circ T)(\mathbf{e}_2)$.

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the $4 imes 2$ standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

Part 1: Compute

$$(S \circ T)(\mathbf{e}_1) = S(T(\mathbf{e}_1)) = S\left(\begin{bmatrix}2\\5\end{bmatrix}\right) = \begin{bmatrix}1 & 2\\0 & 1\\3 & 5\\-1 & -2\end{bmatrix}\begin{bmatrix}2\\5\end{bmatrix} = \begin{bmatrix}?\\?\\?\\?\end{bmatrix}$$

using the dot product of each matrix row with the vector.

- Part 2: Compute $(S \circ T)(\mathbf{e}_2)$.
- Part 3: Compute $(S \circ T)(\mathbf{e}_3)$.

Let $T: \mathbb{R}^3 \to \mathbb{R}^2$ be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the $4 imes 2$ standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

Part 1: Compute

$$(S \circ T)(\mathbf{e}_1) = S(T(\mathbf{e}_1)) = S\left(\begin{bmatrix}2\\5\end{bmatrix}\right) = \begin{bmatrix}1 & 2\\0 & 1\\3 & 5\\-1 & -2\end{bmatrix}\begin{bmatrix}2\\5\end{bmatrix} = \begin{bmatrix}?\\?\\?\\?\end{bmatrix}$$

using the dot product of each matrix row with the vector.

- Part 2: Compute $(S \circ T)(\mathbf{e}_2)$.
- Part 3: Compute $(S \circ T)(\mathbf{e}_3)$.
- Part 4: Find the 4 \times 3 standard matrix of $S \circ T : \mathbb{R}^3 \to \mathbb{R}^4$.

Definition M.1.6

We define the **product** AB of a $m \times n$ matrix A and a $n \times k$ matrix B to be the $m \times k$ standard matrix of the composition map of the two corresponding linear functions.

For the previous activity, S had a 4×2 matrix and T had a 2×3 matrix, so $S \circ T$ had a 4×3 standard matrix:

$$AB = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 2 \\ 5 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ -3 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} -3 \\ 4 \end{bmatrix} = \begin{bmatrix} 12 & -5 & 5 \\ 5 & -3 & 4 \\ 31 & -12 & 11 \\ -12 & 5 & -5 \end{bmatrix}$$

Section M.2 Section M.3

Observation M.1.7

Each cell of a matrix product is found by taking the dot product of a first matrix row and a second matrix column. Since 3(-3) + 5(4) = 11:

$$AB = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ \hline 3 & 5 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 2 & 1 & \boxed{-3} \\ 5 & -3 & \boxed{4} \end{bmatrix} = \begin{bmatrix} 12 & -5 & 5 \\ 5 & -3 & 4 \\ 31 & -12 & \boxed{11} \\ -12 & 5 & -5 \end{bmatrix}$$

Let
$$T:\mathbb{R}^2 o \mathbb{R}^3$$
 be given by the matrix $B=\begin{bmatrix} 2&3\\1&-1\\0&-1 \end{bmatrix}$ and $S:\mathbb{R}^3 o \mathbb{R}^2$ be given

by the matrix
$$A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$$
.

Find the standard matrix BA of $T \circ S$.

Let
$$T:\mathbb{R}^2 o\mathbb{R}^3$$
 be given by the matrix $B=\begin{bmatrix}2&3\\1&-1\\0&-1\end{bmatrix}$ and $S:\mathbb{R}^3 o\mathbb{R}^2$ be given

by the matrix
$$A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$$
.

Find the standard matrix AB of $S \circ T$.

Matrix multiplication only makes sense if the first matrix has as many columns as the second matrix has rows. Label each of these matrices with $\mathbf{rows} \times \mathbf{columns}$, and then figure out which of the products AB, AC, BA, BC, CA, CB can actually be computed.

$$A = \begin{bmatrix} 1 & 0 & -3 \\ 3 & 2 & 1 \end{bmatrix} \qquad B = \begin{bmatrix} 2 & 2 & 1 & 0 & 1 \\ 1 & 1 & 1 & -1 & 0 \\ 0 & 0 & 3 & 2 & 1 \\ -1 & 5 & 7 & 2 & 1 \end{bmatrix} \qquad C = \begin{bmatrix} 2 & 2 \\ 0 & -1 \\ 3 & 1 \\ 4 & 0 \end{bmatrix}$$

Observation M.1.11

Note that an \mathbb{R}^n vector acts exactly the same as an $n \times 1$ matrix, so we will use them interchangablely, as follows.

$$A = \begin{bmatrix} 3 & 1 & -1 \\ 2 & 0 & 4 \\ -1 & 3 & 5 \end{bmatrix} \qquad X = \mathbf{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \qquad B = \mathbf{b} = \begin{bmatrix} 5 \\ -7 \\ 2 \end{bmatrix}$$

So we may study the linear system

$$3x + y - z = 5$$
$$2x + 4z = -7$$
$$-x + 3y + 5z = 2$$

as both a vector equation $A\mathbf{x} = \mathbf{b}$ and a matrix equation AX = B:

$$\begin{bmatrix} 3 & 1 & -1 \\ 2 & 0 & 4 \\ -1 & 3 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 5 \\ -7 \\ 2 \end{bmatrix}$$

Module M Section 2

Let
$$A = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$
. Find a 3×3 matrix I such that $IA = A$, that is,

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

Definition M.2.2

The identity matrix I_n (or just I when n is obvious from context) is the $n \times n$ matrix

$$I_n = egin{bmatrix} 1 & 0 & \dots & 0 \ 0 & 1 & \ddots & dots \ dots & \ddots & \ddots & 0 \ 0 & \dots & 0 & 1 \end{bmatrix}.$$

It has a 1 on each diagonal element and a 0 in every other position.

Fact M.2.3

For any square matrix A, IA = AI = A:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

Each row operation can be interpreted as a type of matrix multiplication.

Each row operation can be interpreted as a type of matrix multiplication.

Part 1: Tweak the identity matrix slightly to create a matrix that doubles the third row of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 2 & 2 & -2 \end{bmatrix}$$

Each row operation can be interpreted as a type of matrix multiplication.

Part 1: Tweak the identity matrix slightly to create a matrix that doubles the third row of A:

Part 2: Create a matrix that swaps the second and third rows of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 1 & 1 & -1 \\ 0 & 3 & 2 \end{bmatrix}$$

Each row operation can be interpreted as a type of matrix multiplication.

Part 1: Tweak the identity matrix slightly to create a matrix that doubles the third row of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 2 & 2 & -2 \end{bmatrix}$$

Part 2: Create a matrix that swaps the second and third rows of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 1 & 1 & -1 \\ 0 & 3 & 2 \end{bmatrix}$$

Part 3: Create a matrix that adds 5 times the third row of A to the first row:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2+5 & 7+5 & -1-5 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

Fact M.2.5

If R is the result of applying a row operation to I, then RA is the result of applying the same row operation to A.

This means that for any matrix A, we can find a series of matrices R_1, \ldots, R_k corresponding to the row operations such that

$$R_1R_2\cdots R_kA=\mathsf{RREF}(A).$$

That is, row reduction can be thought of as the result of matrix multiplication.

Let $T : \mathbb{R}^n \to \mathbb{R}^m$ be a linear map with standard matrix A. Sort the following items into groups of statements about T.

- (a) T is injective (i.e. one-to-one)
- (b) T is surjective (i.e. onto)
- (c) *T* is bijective (i.e. both injective and surjective)
- (d) AX = B has a solution for all $m \times 1$ matrices B
- (e) AX = B has a unique solution for all $m \times 1$ matrices B
- (f) AX = 0 has a unique solution.

- (g) The columns of A span \mathbb{R}^m
- (h) The columns of A are linearly independent
- (i) The columns of A are a basis of \mathbb{R}^m
- (j) Every column of RREF(A) has a pivot
- (k) Every row of RREF(A) has a pivot
- (I) m = n and RREF(A) = I

Let $T : \mathbb{R}^n \to \mathbb{R}^m$ be a linear map with matrix A. If T is injective, which of the following cannot be true?

- (a) A has strictly more columns than rows
- (b) A has the same number of rows as columns (i.e. A is square)
- (c) A has strictly more rows than columns

Let $T: \mathbb{R}^n \to \mathbb{R}^m$ be a linear map with matrix A. If T is surjective, which of the following cannot be true?

- (a) A has strictly more columns than rows
- (b) A has the same number of rows as columns (i.e. A is square)
- (c) A has strictly more rows than columns

Let $T: \mathbb{R}^n \to \mathbb{R}^m$ be a linear map with matrix A. If T is bijective, which of the following cannot be true?

- (a) A has strictly more columns than rows
- (b) A has the same number of rows as columns (i.e. A is square)
- (c) A has strictly more rows than columns

Module M Section 3

Definition M.3.1

Let $T: \mathbb{R}^n \to \mathbb{R}^n$ be a linear map with standard matrix A.

- If T is a bijection and B is any \mathbb{R}^n vector, then T(X) = AX = B has a unique solution X.
- So we may define an **inverse map** $T^{-1}: \mathbb{R}^n \to \mathbb{R}^n$ by setting $T^{-1}(B) = X$ to be this unique solution.
- Let A^{-1} be the standard matrix for T^{-1} . We call A^{-1} the **inverse matrix** of A, so we also say that A is **invertible**.

Activity M.3.2 (~10 min)

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the bijective linear map defined by $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2x - 3y \\ -3x + 5y \end{bmatrix}$. It can be shown that T is bijective and has the inverse map

$$\mathcal{T}^{-1}\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 5x + 3y \\ 3x + 2y \end{bmatrix}.$$

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the bijective linear map defined by $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2x - 3y \\ -3x + 5y \end{bmatrix}$. It can be shown that T is bijective and has the inverse map

$$T^{-1}\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 5x + 3y \\ 3x + 2y \end{bmatrix}.$$

Part 1: Compute
$$(T^{-1} \circ T) \begin{pmatrix} -2 \\ 1 \end{pmatrix}$$
.

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the bijective linear map defined by $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2x - 3y \\ -3x + 5y \end{bmatrix}$.

It can be shown that ${\mathcal T}$ is bijective and has the inverse map

$$\mathcal{T}^{-1}\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 5x + 3y \\ 3x + 2y \end{bmatrix}.$$

Part 1: Compute
$$(T^{-1} \circ T) \begin{pmatrix} \begin{bmatrix} -2 \\ 1 \end{bmatrix} \end{pmatrix}$$
.

Part 2: If A is the standard matrix for T and A^{-1} is the standard matrix for T^{-1} , what must $A^{-1}A$ be?

Math 237

Section M.1 Section M.2 Section M.3

Observation M.3.3

 $T^{-1} \circ T = T \circ T^{-1}$ is the identity map for any bijective linear transformation T. Therefore $A^{-1}A = AA^{-1} = I$ is the identity matrix for any invertible matrix A.

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^3$$
 be given by the matrix $A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}$.

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^3$$
 be given by the matrix $A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}$.

Part 1: Solve $T(X) = \mathbf{e}_1$ to find $T^{-1}(\mathbf{e}_1)$.

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^3$$
 be given by the matrix $A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}$.

Part 1: Solve
$$T(X) = \mathbf{e}_1$$
 to find $T^{-1}(\mathbf{e}_1)$.
Part 2: Solve $T(X) = \mathbf{e}_2$ to find $T^{-1}(\mathbf{e}_2)$.

Let
$$T:\mathbb{R}^3 o \mathbb{R}^3$$
 be given by the matrix $A=\begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}$.

Part 1: Solve $T(X) = \mathbf{e}_1$ to find $T^{-1}(\mathbf{e}_1)$.

Part 2: Solve $T(X) = \mathbf{e}_2$ to find $T^{-1}(\mathbf{e}_2)$.

Part 3: Solve $T(X) = \mathbf{e}_3$ to find $T^{-1}(\mathbf{e}_3)$.

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^3$$
 be given by the matrix $A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}$.

- Part 1: Solve $T(X) = \mathbf{e}_1$ to find $T^{-1}(\mathbf{e}_1)$.
- Part 2: Solve $T(X) = \mathbf{e}_2$ to find $T^{-1}(\mathbf{e}_2)$.
- Part 3: Solve $T(X) = \mathbf{e}_3$ to find $T^{-1}(\mathbf{e}_3)$.
- Part 4: Compute A^{-1} , the standard matrix for T^{-1} .

Observation M.3.5

We could have solved these three systems simultaneously by row reducing the matrix [A | I] at once.

$$A = \begin{bmatrix} 2 & -1 & -6 & 1 & 0 & 0 \\ 2 & 1 & 3 & 0 & 1 & 0 \\ 1 & 1 & 4 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 & -2 & 3 \\ 0 & 1 & 0 & -5 & 14 & -18 \\ 0 & 0 & 1 & 1 & -3 & 4 \end{bmatrix}$$

Activity M.3.6 (∼10 min)

Find the inverse A^{-1} of the matrix $A = \begin{bmatrix} 1 & 3 \\ 0 & -2 \end{bmatrix}$ by row-reducing $[A \mid I]$.

Is the matrix
$$\begin{bmatrix} 2 & 3 & 1 \\ -1 & -4 & 2 \\ 0 & -5 & 5 \end{bmatrix}$$
 invertible? Give a reason for your answer.

4 □ → 4 同 → 4 目 → 4 目 → 9 Q (^

Section M.1 Section M.2 Section M.3

Observation M.3.8

A matrix $A \in \mathbb{R}^{n \times n}$ is invertible if and only if $\mathsf{RREF}(A) = I_n$.