**Problem 26.** Write the following vectors as the scalar product of their magnitude and direction:

- · (5,5) → (5,5) = \(\overline{\tau\_1} + 25 = \int 50 = 552 \rightarrow \((5,5) = \int 552 \left\rangle \frac{1}{\tau\_2}, \frac{1}{\tau\_2}\right)
- · (-4,3) (-4,3) = 516+9 = 525=5 > (-4,3) = 5(-4,3)
- · (12,-5) -> ((12,-5) = J144-25 = J169 = 13 -> (12,-5) = [13 (12/13,-5/13)
- · (3,1,-2) -) (3,1,-2) = J9+1+4 = J14 -> (3,1,-2) = J14 (3,1,-2)
- · (4,-2,-4) -) (4,-2,-4) (= 16+4+16=536=6-8 (4,-3,-4) = 6 (3,-13,-13)

Definition 27. The standard unit vectors in  $\mathbb{R}^2$  are  $\hat{\mathbf{i}} = \langle 1, 0 \rangle$  and  $\hat{\mathbf{j}} = \langle 0, 1 \rangle$ , and any vector in  $\mathbb{R}^2$  can be expressed in standard unit vector form:

$$\langle a, b \rangle = a\hat{\mathbf{i}} + b\hat{\mathbf{j}}$$

The standard unit vectors in  $\mathbb{R}^3$  are  $\hat{\mathbf{i}} = \langle 1, 0, 0 \rangle$ ,  $\hat{\mathbf{j}} = \langle 0, 1, 0 \rangle$ , and  $\hat{\mathbf{k}} = \langle 0, 0, 1 \rangle$ , and any vector in  $\mathbb{R}^3$  can be expressed in standard unit vector form:

$$\langle a, b, c \rangle = a\hat{\mathbf{i}} + b\hat{\mathbf{j}} + c\hat{\mathbf{k}}$$

Note 28. Since the xy-plane is the plane z=0 in xyz-space, we say the points (a,b)=(a,b,0) and vectors  $\langle a,b\rangle=\langle a,b,0\rangle=a\widehat{\mathbf{i}}+b\widehat{\mathbf{j}}+0\widehat{\mathbf{k}}$  are equal.

Problem 29. Write the following vectors in standard unit vector form.

- (5,5) = 5î+5ĵ
- (-4,3) = -47 + 35
- $\langle 12, -5 \rangle = |2 \hat{7} 5 \hat{5}$
- $(3,1,-2) = 3^+ 2^+$
- $\langle 4, -2, -4 \rangle = 41 21 4k$
- · (8,0,-6) = 8↑ +08 -6 k

**Theorem 30.** The following properties hold for any two vectors  $\vec{\mathbf{u}}$ ,  $\vec{\mathbf{v}}$  and scalars a, b.

- $\bullet \ \overrightarrow{\mathbf{u}} + \overrightarrow{\mathbf{v}} = \overrightarrow{\mathbf{v}} + \overrightarrow{\mathbf{u}}$
- $\bullet \ (\overrightarrow{u} + \overrightarrow{v}) + \overrightarrow{w} = \overrightarrow{u} + (\overrightarrow{v} + \overrightarrow{w})$
- $\bullet \ \overrightarrow{\mathbf{u}} + \overrightarrow{\mathbf{0}} = \overrightarrow{\mathbf{u}}$
- $\bullet \ \vec{\mathbf{u}} + (-\vec{\mathbf{u}}) = \vec{\mathbf{0}}$
- $0\vec{\mathbf{u}} = \vec{\mathbf{0}}$
- $1\vec{\mathbf{u}} = \vec{\mathbf{u}}$
- $a(b\vec{\mathbf{u}}) = (ab)\vec{\mathbf{u}}$
- $a(\vec{\mathbf{u}} + \vec{\mathbf{v}}) = a\vec{\mathbf{u}} + a\vec{\mathbf{v}}$
- $(a+b)\vec{\mathbf{u}} = a\vec{\mathbf{u}} + b\vec{\mathbf{u}}$

Definition 31. Vector subtraction is defined as the addition of a negative:

$$\vec{\mathbf{u}} - \vec{\mathbf{v}} = \vec{\mathbf{u}} + (-\vec{\mathbf{v}}) = \langle u_1 - v_1, u_2 - v_2 \rangle$$
$$\vec{\mathbf{u}} - \vec{\mathbf{v}} = \vec{\mathbf{u}} + (-\vec{\mathbf{v}}) = \langle u_1 - v_1, u_2 - v_2, u_3 - v_3 \rangle$$

Suggested Homework: Section 12.2 numbers 3, 5, 13, 14, 15, 19, 21, 24, 26

## The Dot Product 12.3

**Definition 32.** Let  $\theta$  be the angle between two non-zero vectors  $\vec{\mathbf{u}}$ ,  $\vec{\mathbf{v}}$ . The dot product  $\vec{\mathbf{u}} \cdot \vec{\mathbf{v}}$  is the product of their lengths when projected into the same direction, obtained by this formula:

$$\vec{\mathbf{u}} \cdot \vec{\mathbf{v}} = |\vec{\mathbf{u}}| |\vec{\mathbf{v}}| \cos \theta$$

**Definition 33.** The dot product with a zero vector is always zero:

$$\vec{\mathbf{v}} \cdot \vec{\mathbf{0}} = \vec{\mathbf{0}} \cdot \vec{\mathbf{v}} = 0$$

**Theorem 34.** By the Law of Cosines:

$$\vec{\mathbf{u}} \cdot \vec{\mathbf{v}} = \langle u_1, u_2 \rangle \cdot \langle v_1, v_2 \rangle = u_1 v_1 + u_2 v_2$$

$$\vec{\mathbf{u}} \cdot \vec{\mathbf{v}} = \langle u_1, u_2, u_3 \rangle \cdot \langle v_1, v_2, v_3 \rangle = u_1 v_1 + u_2 v_2 + u_3 v_3$$

Definition 35. Two vectors  $\vec{\mathbf{u}}, \vec{\mathbf{v}}$  are orthogonal if  $\vec{\mathbf{u}} \cdot \vec{\mathbf{v}} = 0$ .

**Theorem 36.** Two non-zero vectors are orthogonal if the angle  $\theta$  between them is  $\frac{\pi}{2}$  radians.

**Theorem 37.** The following properties hold for any three vectors  $\vec{\mathbf{u}}$ ,  $\vec{\mathbf{v}}$ ,  $\vec{\mathbf{w}}$  and scalar c.

$$\bullet \ \vec{\mathbf{u}} \cdot \vec{\mathbf{v}} = \vec{\mathbf{v}} \cdot \vec{\mathbf{u}}$$

• 
$$(c\vec{\mathbf{u}}) \cdot \vec{\mathbf{v}} = \vec{\mathbf{u}} \cdot (c\vec{\mathbf{v}}) = c(\vec{\mathbf{u}} \cdot \vec{\mathbf{v}})$$

$$\bullet \ \vec{u} \cdot (\vec{v} + \vec{w}) = \vec{u} \cdot \vec{v} + \vec{u} \cdot \vec{w}$$

• 
$$\vec{\mathbf{u}} \cdot \vec{\mathbf{u}} = |\vec{\mathbf{u}}|^2$$

**Problem 38.** Solve for  $\cos \theta$  for the following pairs of vectors.

roblem 38. Solve for cos θ for the following pairs of vectors.

• 
$$\vec{\mathbf{u}} = \langle 4, -3 \rangle$$
 $\vec{\mathbf{v}} = \langle 5, 12 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 1, 4, 2 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 1, 4, 2 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 5, -11 \rangle$ 

•  $\vec{\mathbf{v}} = \langle 2, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 5, -11 \rangle$ 

•  $\vec{\mathbf{v}} = \langle 2, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0, 0, 0, 0 \rangle$ 

•  $\vec{\mathbf{u}} = \langle 0, 0, 0, 0,$ 

**Definition 39.** The work W done by a force vector  $\overrightarrow{\mathbf{F}}$  over a displacement vector  $\overrightarrow{\mathbf{D}}$  is given  $W = \overrightarrow{\mathbf{F}} \cdot \overrightarrow{\mathbf{D}} = |\overrightarrow{\mathbf{F}}| |\overrightarrow{\mathbf{D}}| \cos \theta$ 

Suggested Homework: Section 12.3 numbers 3, 5, 6, 7, 8, 9, 10, 11, 15, 17, 21, 27, 41, 42, 44

## 12.4 The Cross Product

**Definition 40.** For any two non-parallel vectors  $\vec{\mathbf{u}}$ ,  $\vec{\mathbf{v}}$  in  $\mathbb{R}^3$ , the **Right-Hand Rule** gives a specific direction orthogonal to both: position  $\vec{\mathbf{u}}$  with your right thumb and  $\vec{\mathbf{v}}$  with your right index finger, and let your middle finger extend orthogonal to both to give this direction.

**Definition 41.** Let  $\theta$  be the angle between two non-zero vectors  $\vec{\mathbf{u}}$ ,  $\vec{\mathbf{v}}$  in  $\mathbb{R}^3$ , and let  $\vec{\mathbf{n}}$  be the direction given by the Right-Hand Rule. The **cross product**  $\vec{\mathbf{u}} \times \vec{\mathbf{v}}$  is the vector orthogonal to both which follows the Right-Hand Rule and has magnitude equal to the area of the parallelogram formed from both.

$$\vec{\mathbf{u}} \times \vec{\mathbf{v}} = (|\vec{\mathbf{u}}||\vec{\mathbf{v}}|\sin\theta)\vec{\mathbf{n}}$$
$$|\vec{\mathbf{u}} \times \vec{\mathbf{v}}| = |\vec{\mathbf{u}}||\vec{\mathbf{v}}|\sin\theta$$

Definition 42. The cross product with a zero vector is always the zero vector:

$$\vec{\mathbf{v}} \times \vec{\mathbf{0}} = \vec{\mathbf{0}} \times \vec{\mathbf{v}} = \vec{\mathbf{0}}$$

**Theorem 43.** The following properties hold for any three vectors  $\vec{\mathbf{u}}$ ,  $\vec{\mathbf{v}}$ ,  $\vec{\mathbf{w}}$  and scalars a,b.

- $(a\overrightarrow{\mathbf{u}}) \times (b\overrightarrow{\mathbf{v}}) = (ab)(\overrightarrow{\mathbf{u}} \times \overrightarrow{\mathbf{v}})$
- $\bullet \ \overrightarrow{\mathbf{u}} \times (\overrightarrow{\mathbf{v}} + \overrightarrow{\mathbf{w}}) = \overrightarrow{\mathbf{u}} \times \overrightarrow{\mathbf{v}} + \overrightarrow{\mathbf{u}} \times \overrightarrow{\mathbf{w}}$
- $\bullet \ (\overrightarrow{\mathbf{v}} + \overrightarrow{\mathbf{w}}) \times \overrightarrow{\mathbf{u}} = \overrightarrow{\mathbf{v}} \times \overrightarrow{\mathbf{u}} + \overrightarrow{\mathbf{w}} \times \overrightarrow{\mathbf{u}}$
- $\bullet \ \overrightarrow{\mathbf{v}} \times \overrightarrow{\mathbf{u}} = -(\overrightarrow{\mathbf{u}} \times \overrightarrow{\mathbf{v}})$

**Definition 44.** Two vectors  $\vec{\mathbf{u}}, \vec{\mathbf{v}}$  are parallel if  $\vec{\mathbf{u}} \times \vec{\mathbf{v}} = 0$ .

Theorem 45. Two non-zero vectors are parallel if the angle  $\theta$  between them is 0 or  $\pi$  radians.

**Definition 46.** The cross products of the standard unit vectors are given as follows:

- $\bullet \ \widehat{\mathbf{i}} \times \widehat{\mathbf{j}} = \widehat{\mathbf{k}}$
- $\hat{\mathbf{j}} \times \hat{\mathbf{k}} = \hat{\mathbf{i}}$
- $\hat{\mathbf{k}} \times \hat{\mathbf{i}} = \hat{\mathbf{j}}$

**Definition 47.** A **determinant** is a short hand for writing certain commonly occurring algebraic expressions:

$$\begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} = a_1 b_2 - a_2 b_1$$

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$$

Theorem 48. By breaking up  $\vec{\mathbf{u}}$ ,  $\vec{\mathbf{v}}$  into standard unit vectors:

$$\vec{\mathbf{u}} \times \vec{\mathbf{v}} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = \left\langle \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix}, - \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix}, \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} \right\rangle$$

Problem 49. Use the cross product to find a vector normal to both  $\vec{\mathbf{u}}$  and  $\vec{\mathbf{v}}$ .

• 
$$\vec{u} = \langle 4, -3, 0 \rangle$$
 $\vec{v} = \langle 2, 6, -3 \rangle$ 
•  $\vec{u} = \langle 1, 4, 2 \rangle$ 
 $\vec{v} = \langle 4, 1, -2 \rangle$ 
•  $\vec{u} = \langle 0, 5, -11 \rangle$ 
 $\vec{v} = \langle 2, 0, 0 \rangle$ 

•  $\vec{u} = \langle 0, 5, -11 \rangle$ 
 $\vec{v} = \langle 2, 0, 0 \rangle$ 

•  $\vec{u} = \langle 0, 5, -11 \rangle$ 
 $\vec{v} = \langle 2, 0, 0 \rangle$ 

•  $\vec{u} = \langle 0, 5, -11 \rangle$ 
 $\vec{v} = \langle 2, 0, 0 \rangle$ 

•  $\vec{u} = \langle 0, 5, -11 \rangle$ 
 $\vec{v} = \langle 2, 0, 0 \rangle$ 

•  $\vec{u} = \langle 0, 5, -11 \rangle$ 
 $\vec{v} = \langle 2, 0, 0 \rangle$ 

•  $\vec{u} = \langle 0, 5, -11 \rangle$ 
 $\vec{v} = \langle 0, 5$ 

**Definition 50.** The torque  $\tau$  done by a force vector  $\vec{F}$  on an arm given by  $\vec{D}$  is given by

$$\tau = |\overrightarrow{\mathbf{F}} \times \overrightarrow{\mathbf{D}}| = |\overrightarrow{\mathbf{F}}||\overrightarrow{\mathbf{D}}|\sin\theta$$

Theorem 51. The volume of a parallelpiped determined by the vectors  $\vec{\mathbf{u}}$ ,  $\vec{\mathbf{v}}$ ,  $\vec{\mathbf{w}}$ , is given by the triple scalar product

$$(\vec{\mathbf{u}} \times \vec{\mathbf{v}}) \cdot \vec{\mathbf{w}} = \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

Suggested Homework: Section 12.4 numbers 1-3, 17, 19, 28, 29, 33, 35

## 12.5 Lines and Planes in Space

**Theorem 52.** Let L be the line in  $\mathbb{R}^2$  normal to the vector  $\overrightarrow{\mathbf{N}} = \langle A, B \rangle$  and passing through the point  $P_0 = (x_0, y_0)$ . Then every point P = (x, y) on the line L must satisfy the following equations:

$$\mathbf{\overline{N}} \cdot \mathbf{\overline{P_0P}} = 0$$

$$A(x - x_0) + B(y - y_0) = 0$$

Let M be the plane in  $\mathbb{R}^3$  normal to the vector  $\overrightarrow{\mathbf{N}} = \langle A, B, C \rangle$  and passing through the point  $P_0 = (x_0, y_0, z_0)$ . Then every point P = (x, y, z) on the plane M must satisfy the following equations:

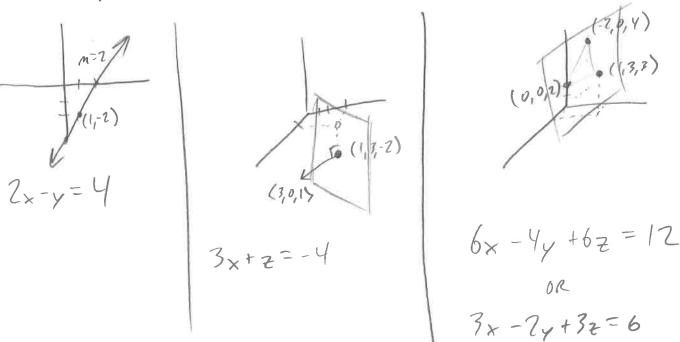
$$\overrightarrow{\mathbf{N}} \cdot \overrightarrow{\mathbf{P_0 P}} = 0$$

$$A(x - x_0) + B(y - y_0) + C(z - z_0) = 0$$

Problem 53. Sketch and find equations for the following lines and planes:

- The line passing through (1, -2) and parallel to the line with equation 2x y = 3.
- The plane passing through (1, 3, -2) and normal to the vector (3, 0, 1).
- The plane passing through (-2,0,4), (1,3,3), and (0,0,2).

( Work omitted)



**Definition 54. Parametric equations** x(t), y(t) for a curve in  $\mathbb{R}^2$  assign a point (x(t), y(t)) of the curve to each value of t.

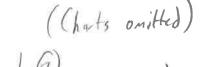
Parametric equations x(t), y(t), z(t) for a curve in  $\mathbb{R}^3$  assign a point (x(t), y(t), z(t)) of the curve to each value of t.

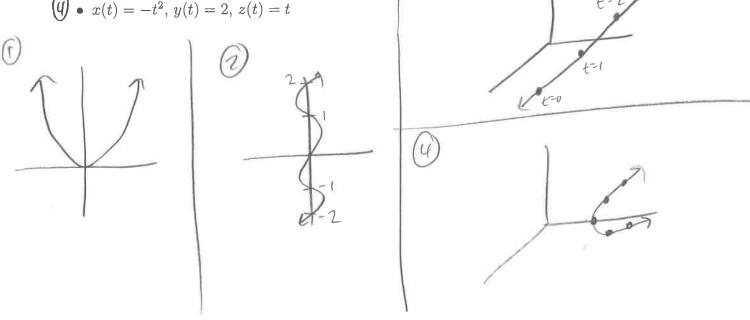
Problem 55. Sketch the curves given by the following parametric equations.

$$0 \bullet x(t) = t, y(t) = t^2$$

$$0 \bullet x(t) = \sin t, \ y(t) = \frac{t}{\pi}$$

$$(y) \bullet x(t) = -t^2, y(t) = 2, z(t) = t$$





**Theorem 56.** Let L be the line in  $\mathbb{R}^2$  parallel to the vector  $\vec{\mathbf{v}} = \langle a, b \rangle$  and passing through the point  $P_0 = (x_0, y_0)$ . Then every point P = (x, y) on the line L must satisfy the following vector equation for some t:

 $\overrightarrow{\mathbf{P}} = \overrightarrow{\mathbf{v}}t + \overrightarrow{\mathbf{P_0}}$ 

Thus the line is given by the parametric equations

$$x(t) = at + x_0$$

$$y(t) = bt + y_0$$

Let L be the line in  $\mathbb{R}^3$  parallel to the vector  $\vec{\mathbf{v}} = \langle a, b, c \rangle$  and passing through the point  $P_0 = (x_0, y_0, z_0)$ . Then every point P = (x, y, z) on the line L must satisfy the following vector equation for some t:

 $\vec{P} = \vec{\mathbf{v}}t + \vec{P_0}$ 

Thus the line is given by the parametric equations

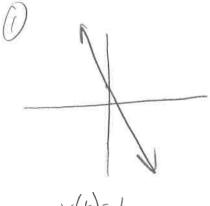
$$x(t) = at + x_0$$

$$y(t) = bt + y_0$$

$$z(t) = ct + z_0$$

Problem 57. Sketch and give parametric equations for the following lines.

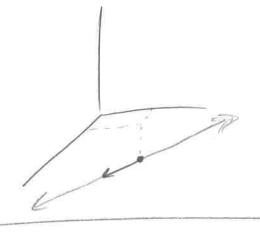
- The line with equation y = -3x + 1 in the xy plane.
- The line passing through (1, 3, -2) and parallel to (3, 0, 1).
  - The line normal to the plane with equation x+y+2z=4 and passing through (1,1,1).



$$x(t)=t$$
  
 $y(t)=-3t+1$ 

(2)

$$x(t) = 3t + 1$$
  
 $y(t) = 0t + 3$   
 $z(t) = t - 2$ 



(3) 
$$x(t)=1+1$$
  
 $y(t)=1+1$   
 $z(t)=2+1$ 

