

# Chapter 12

## Vectors and the Geometry of Space

### 12.1 Two and Three Dimensional Space

**Definition 1.** Let  $\mathbb{R}$  be the collection of real numbers, let  $\mathbb{R}^2$  be the collection of all **ordered pairs** of real numbers, and let  $\mathbb{R}^3$  be the collection of all **ordered triples** of real numbers.

$\mathbb{R}$  is known as the **real line**,  $\mathbb{R}^2$  is known as the **real plane** or the  **$xy$ -plane**, and  $\mathbb{R}^3$  is known as **real (3D) space** or  **$xyz$ -space**.

**Definition 2.** The **distance** between two points  $P = (x_1, y_1)$  and  $Q = (x_2, y_2)$  in  $\mathbb{R}^2$  is given by the formula

$$d(P, Q) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

The **distance** between two points  $P = (x_1, y_1, z_1)$  and  $Q = (x_2, y_2, z_2)$  in  $\mathbb{R}^3$  is given by the formula

$$d(P, Q) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

**Problem 3.** Plot and find the distance between the following pairs of points:

- $(-2, 6)$  and  $(3, -6)$
- $(0, 0, 0)$  and  $(4, 2, 4)$
- $(3, 7, -2)$  and  $(-1, 7, 1)$
- $(8, 2, 1)$  and  $(4, -2, 7)$

**Definition 4.** **Simple lines** in  $\mathbb{R}^2$  are given by the relations  $x = a$ , and  $y = b$  for real numbers  $a, b$ .

**Simple planes** in  $\mathbb{R}^3$  are given by the relations  $x = a$ ,  $y = b$ ,  $z = c$  for real numbers  $a, b, c$ .

**Definition 5.** A **circle** in  $\mathbb{R}^2$  is the set of all points a fixed distance (called its **radius**) from a fixed point (called its **center**). For a center  $(a, b)$  and radius  $r$ , the equation for a circle is

$$(x - a)^2 + (y - b)^2 = r^2$$

A **sphere** in  $\mathbb{R}^3$  is the set of all points a fixed distance (called its **radius**) from a fixed point (called its **center**). For a center  $(a, b, c)$  and radius  $r$ , the equation for a sphere is

$$(x - a)^2 + (y - b)^2 + (z - c)^2 = r^2$$

**Question 6.** Sketch the following curves and surfaces.

- $x = 3$  in the  $xy$ -plane and  $xyz$ -space.
- $y = -1$  in the  $xy$ -plane and  $xyz$ -space.
- $z = 0$  in  $xyz$ -space.
- $(x - 2)^2 + (y + 1)^2 = 9$  in the  $xy$ -plane.
- $x^2 + y^2 + z^2 = 4$  in  $xyz$ -space.
- $x^2 + (y - 1)^2 + z^2 = 1$  in  $xyz$ -space.

Suggested Homework: Section 12.1 numbers 4, 6, 7, 8, 10, 11, 12, 14, 15, 16

## 12.2 Vectors

**Definition 7** (Vector). A **vector**  $\vec{v}$  is a mathematical object that stores a **magnitude** (a nonnegative real number often thought of as length) and **direction**. Two vectors are **equal** if and only if they have the same magnitude and direction.

**Definition 8.** The **zero vector**  $\vec{0}$  has zero magnitude and no direction. (This is the only vector without a direction.)

**Definition 9.** For a given point  $P = (a, b)$  in  $\mathbb{R}^2$ , its **position vector** is given by  $\vec{P} = \langle a, b \rangle$ : the vector from the origin  $(0, 0)$  to the point  $P = (a, b)$ .

For a given point  $P = (a, b, c)$  in  $\mathbb{R}^3$ , its **position vector** is given by  $\vec{P} = \langle a, b, c \rangle$ : the vector from the origin  $(0, 0, 0)$  to the point  $P = (a, b, c)$ .

**Theorem 10.** Two vectors are equal if and only if they share the same magnitude and direction as a common position vector.

**Definition 11.** Since all vectors are equal to some position vector  $\langle a, b \rangle$  or  $\langle a, b, c \rangle$ , we usually define vectors by a position vector written in this **component form**. Since the component form of a vector stores the same information as a point, we will use both interchangeably, that is,  $\langle a, b \rangle = (a, b) \in \mathbb{R}^2$  and  $\langle a, b, c \rangle = (a, b, c) \in \mathbb{R}^3$  (although we usually sketch them differently).

**Problem 12.** Plot the following points and position vectors.

- $(1, 3)$  and  $\langle 1, 3 \rangle$  in the  $xy$ -plane.
- $(-2, 5)$  and  $\langle -2, 5 \rangle$  in the  $xy$ -plane.
- $(1, 1, -3)$  and  $\langle 1, 1, -3 \rangle$  in  $xyz$ -space.
- $(0, 5, 0)$  and  $\langle 0, 5, 0 \rangle$  in  $xyz$ -space.

**Definition 13.** Let  $P = (x_1, y_1, z_1)$  and  $Q = (x_2, y_2, z_2)$ . Then the vector with initial point  $P$  and terminal point  $Q$  is defined as

$$\overrightarrow{\mathbf{PQ}} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$$

**Problem 14.** Plot and sketch the points  $P$ ,  $Q$  and the vector  $\overrightarrow{\mathbf{PQ}}$  for each.

- $P = (1, 3)$ ,  $Q = (-3, 6)$  in the  $xy$ -plane
- $P = (3, 1)$ ,  $Q = (0, -2)$  in the  $xy$ -plane
- $P = (1, 1, 1)$ ,  $Q = (-3, -1, 3)$  in  $xyz$ -space
- $P = (-2, 0, 3)$ ,  $Q = (1, 3, -3)$  in  $xyz$ -space

**Definition 15.** The magnitude  $|\vec{\mathbf{v}}|$  of a vector  $\vec{\mathbf{v}}$  in  $\mathbb{R}^2$  or  $\mathbb{R}^3$  is the distance between its initial and terminal points.

**Theorem 16.** The magnitude of  $\vec{\mathbf{v}} = \langle a, b \rangle$  is given by

$$|\vec{\mathbf{v}}| = \sqrt{a^2 + b^2}$$

The magnitude of  $\vec{\mathbf{v}} = \langle a, b, c \rangle$  is given by

$$|\vec{\mathbf{v}}| = \sqrt{a^2 + b^2 + c^2}$$

**Problem 17.** Evaluate the magnitude of the following vectors:

- $\langle 5, 5 \rangle$
- $\langle -4, 3 \rangle$
- $\langle 12, -5 \rangle$
- $\langle 3, 1, -2 \rangle$
- $\langle 4, -2, -4 \rangle$
- $\langle 8, 0, -6 \rangle$

### 12.2.1 Basic Vector Operations

**Definition 18.** **Vector addition** is defined component-wise as follows for  $\mathbb{R}^2$  and  $\mathbb{R}^3$

$$\vec{u} + \vec{v} = \langle u_1, u_2 \rangle + \langle v_1, v_2 \rangle = \langle u_1 + v_1, u_2 + v_2 \rangle$$

$$\vec{u} + \vec{v} = \langle u_1, u_2, u_3 \rangle + \langle v_1, v_2, v_3 \rangle = \langle u_1 + v_1, u_2 + v_2, u_3 + v_3 \rangle$$

**Definition 19.** A **scalar** is simply a real number by itself (as opposed to a vector of real numbers).

**Definition 20.** **Scalar multiplication of a vector** is defined component-wise as follows for  $\mathbb{R}^2$  and  $\mathbb{R}^3$ :

$$k\vec{u} = k\langle u_1, u_2 \rangle = \langle ku_1, ku_2 \rangle$$

$$k\vec{u} = k\langle u_1, u_2, u_3 \rangle = \langle ku_1, ku_2, ku_3 \rangle$$

**Problem 21.** Sketch the following vectors.

- $\vec{\mathbf{u}} = \langle 1, -3 \rangle$ ,  $\vec{\mathbf{v}} = \langle 3, 1 \rangle$  and  $\vec{\mathbf{u}} + \vec{\mathbf{v}}$  in the  $xy$ -plane.
- $\vec{\mathbf{u}} = \langle 2, 0, 1 \rangle$ ,  $\vec{\mathbf{v}} = \langle -2, 4, 2 \rangle$  and  $\vec{\mathbf{u}} + \vec{\mathbf{v}}$  in  $xyz$ -space.
- $\vec{\mathbf{u}} = \langle 8, -2 \rangle$  and  $\frac{1}{2}\vec{\mathbf{u}}$  in the  $xy$ -plane.
- $\vec{\mathbf{u}} = \langle 5, 3, -1 \rangle$  and  $3\vec{\mathbf{u}}$  in  $xyz$ -space.

**Definition 22.** A vector  $\vec{\mathbf{v}}$  is a **unit vector** if  $|\vec{\mathbf{v}}| = 1$ .

**Theorem 23.** For any non-zero vector  $\vec{\mathbf{v}}$ , the vector

$$\frac{1}{|\vec{\mathbf{v}}|} \vec{\mathbf{v}} = \frac{\vec{\mathbf{v}}}{|\vec{\mathbf{v}}|}$$

is a unit vector.

**Definition 24.** The **direction** of a vector  $\vec{\mathbf{v}}$  is the unit vector  $\frac{\vec{\mathbf{v}}}{|\vec{\mathbf{v}}|}$ .

**Theorem 25.** Any vector  $\vec{\mathbf{v}}$  is the scalar product of its magnitude and direction:

$$\vec{\mathbf{v}} = |\vec{\mathbf{v}}| \frac{\vec{\mathbf{v}}}{|\vec{\mathbf{v}}|}$$

**Problem 26.** Write the following vectors as the scalar product of their magnitude and direction:

- $\langle 5, 5 \rangle$
- $\langle -4, 3 \rangle$
- $\langle 12, -5 \rangle$
- $\langle 3, 1, -2 \rangle$
- $\langle 4, -2, -4 \rangle$
- $\langle 8, 0, -6 \rangle$

**Definition 27.** The **standard unit vectors** in  $\mathbb{R}^2$  are  $\hat{\mathbf{i}} = \langle 1, 0 \rangle$  and  $\hat{\mathbf{j}} = \langle 0, 1 \rangle$ , and any vector in  $\mathbb{R}^2$  can be expressed in **standard unit vector form**:

$$\langle a, b \rangle = a\hat{\mathbf{i}} + b\hat{\mathbf{j}}$$

The **standard unit vectors** in  $\mathbb{R}^3$  are  $\hat{\mathbf{i}} = \langle 1, 0, 0 \rangle$ ,  $\hat{\mathbf{j}} = \langle 0, 1, 0 \rangle$ , and  $\hat{\mathbf{k}} = \langle 0, 0, 1 \rangle$ , and any vector in  $\mathbb{R}^3$  can be expressed in **standard unit vector form**:

$$\langle a, b, c \rangle = a\hat{\mathbf{i}} + b\hat{\mathbf{j}} + c\hat{\mathbf{k}}$$

**Note 28.** Since the  $xy$ -plane is the plane  $z = 0$  in  $xyz$ -space, we say the points  $(a, b) = (a, b, 0)$  and vectors  $\langle a, b \rangle = \langle a, b, 0 \rangle = a\hat{\mathbf{i}} + b\hat{\mathbf{j}} + 0\hat{\mathbf{k}}$  are equal.

Suggested Homework: Section 12.2 numbers 3, 5, 13, 14, 15, 19, 21, 24, 26