# VNA2V-W21: Lab X

## Student A and Student B

#### I. Deliverable 1

## A. Math Equations

For example, one can type the following equation:

$$\mathbf{t}^{W} = \mathbf{R}_{r}^{W} \mathbf{t}^{r} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$
 (1)

Later in the course, you may want to type an optimization problem:

$$f^* = \min_{\boldsymbol{x} \in \mathbb{R}^n} \quad f(\boldsymbol{x}),$$
 subject to  $\boldsymbol{x} \in \mathcal{X},$  (2)

subject to 
$$x \in \mathcal{X}$$
, (3)

and refer to this optimization as problem (2). For mathematical symbols, it is suggested that you define shortcuts to commonly used symbols and formats.

# B. Lists

You may also make your answers more organized by using bulleted list:

- Observation 1 ...
- Observation 2 ...

and numbered list:

- 1) Observation 1 ...
- 2) Observation 2 ...

## C. Citations

You can make a citation to a paper by [1].

# D. Figures

You can also include a plot in Fig. 1.



Fig. 1. A drone.

### II. DELIVERABLE 2

One can refer Deliverable 1 in Section I.

#### REFERENCES

[1] B. K. Horn, "Closed-form solution of absolute orientation using unit quaternions," Josa a, vol. 4, no. 4, pp. 629-642, 1987.