

LoANs: Weakly Supervised Object Detection with Localizer Assessor Networks

Christian Bartz, Haojin Yang, Joseph Bethge, Christoph Meinel

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Motivation

Success Factors of Deep Learning

- availability of hardware for massive parallel computations
 - large-scale labeled datasets
 - ImageNet dataset contains more than 14 mio labeled images
 - Youtube-8M dataset contains more than 7 mio labeled videos



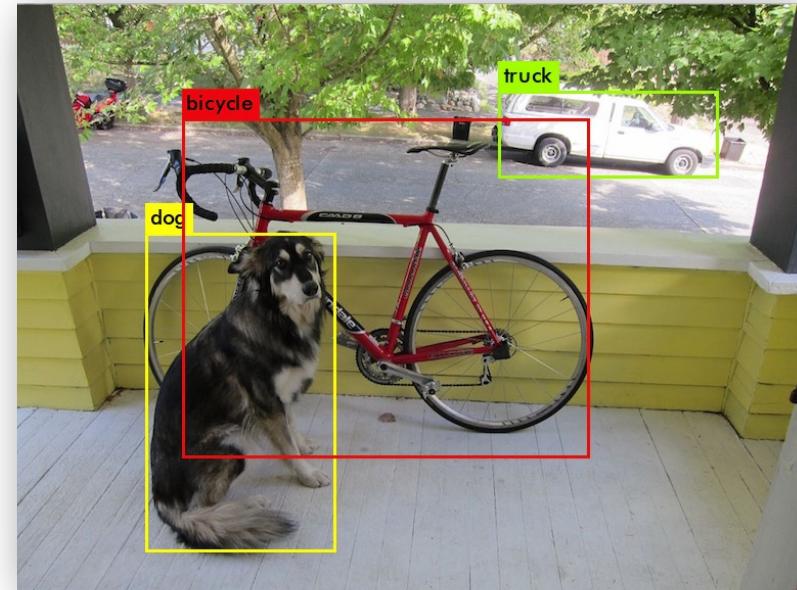
Motivation Object Detection

- recent breakthroughs [Redmon16, Liu16, Ren15] use fully annotated datasets
 - labels for locations of objects and classes of objects



+ =

```
[  
  {  
    "class": "dog",  
    "box": [200, 50, 400, 100]  
  },  
  {  
    "class": "bicycle",  
    "box": [100, 60, 350, 225]  
  },  
  {  
    "class": "truck",  
    "box": [75, 200, 150, 300]  
  }  
]
```



Motivation

Weakly Supervised Object Detection

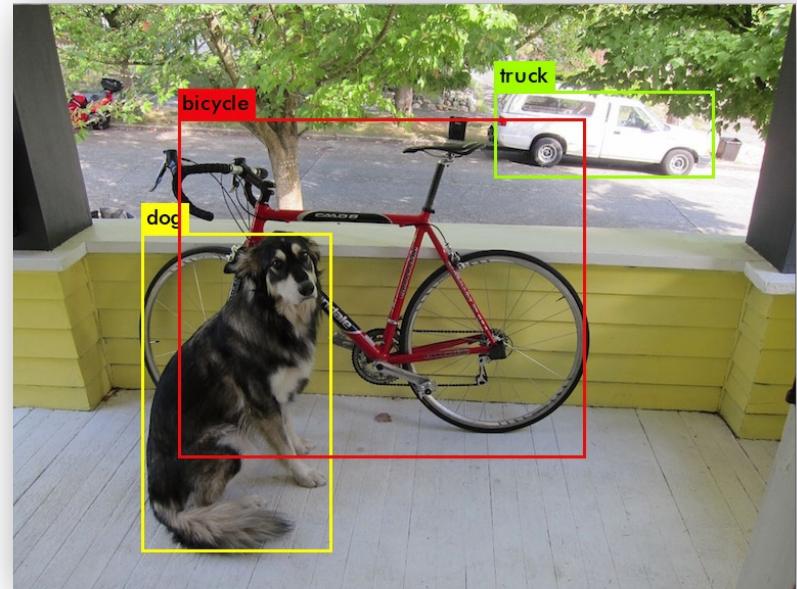
- recent methods [Wei18, Tang18] only use class labels
 - leverage implicit localization capability of feature extractor



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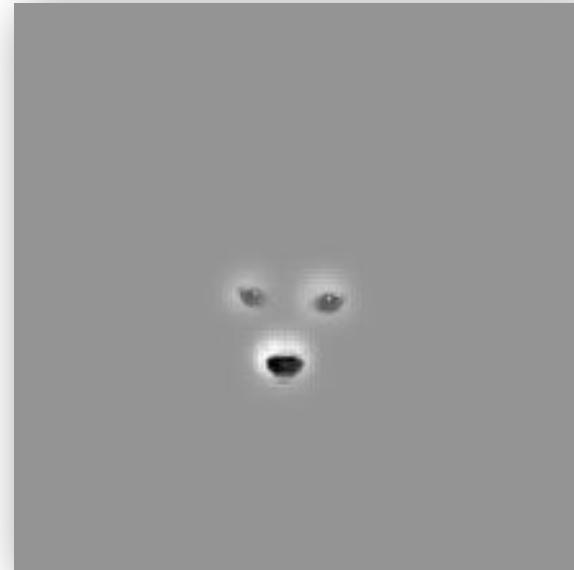
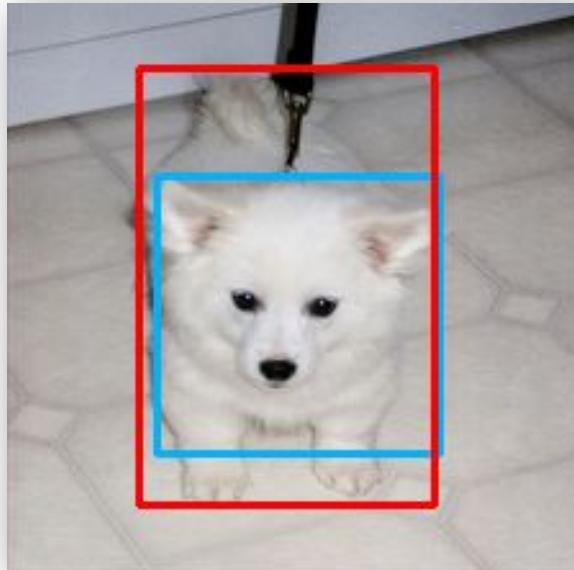
```
[  
  {"class": "dog"},  
  {"class": "bicycle"},  
  {"class": "truck"}  
]
```

=



Weakly Supervised Object Detection

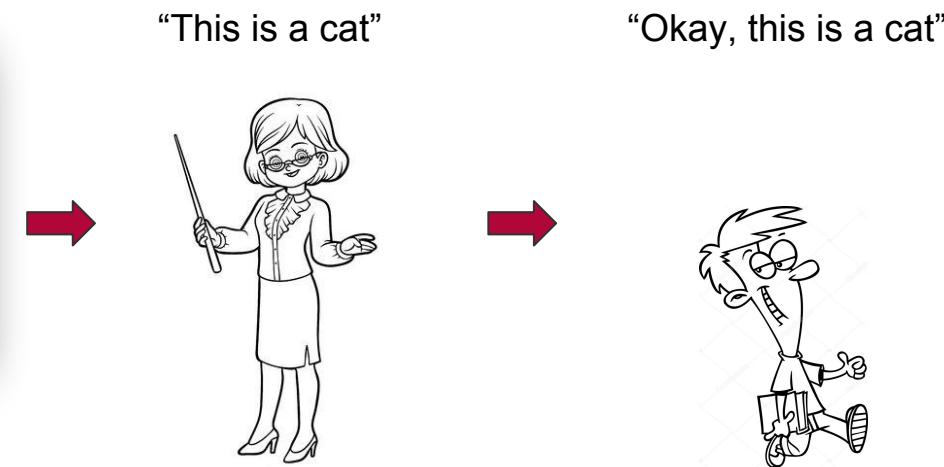
- current weakly supervised methods have inherent problems



Motivation

Teacher Student Networks

- knowledge transfer [Hinton15, Chen16] between networks does not need labels for training the student



Motivation Idea



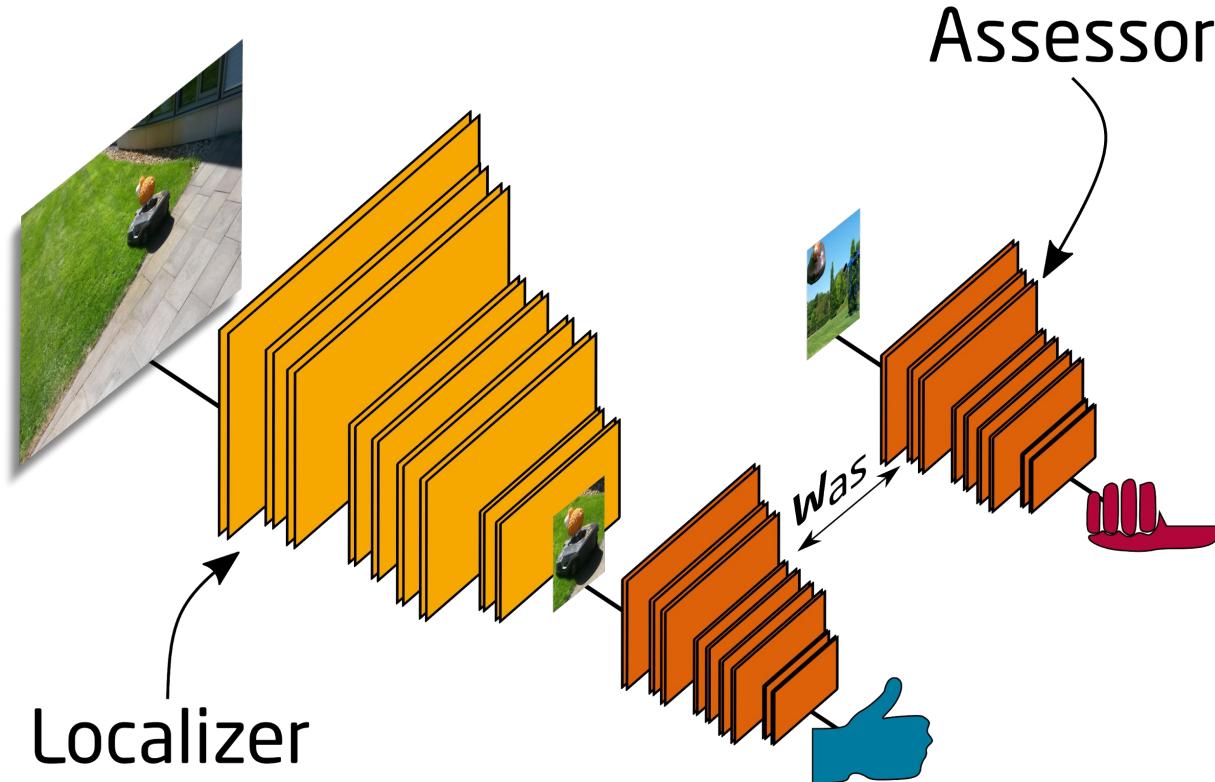
Motivation Idea

- no labels for bounding boxes necessary
- no model pre-trained on ImageNet necessary
- can use artificial data for training teacher model



Proposed System

Localizer Assessor Networks



Proposed System Assessor

- predict intersection over union (IOU) of image crop and shown object
- trained on synthetically generated data
- needs background and template images



LoANs: Localizer Assessor Networks

Bartz, Yang, Bethge, Meinel

Chart 10



Step 0: select a background image



Step 1: place template image at random location in background image



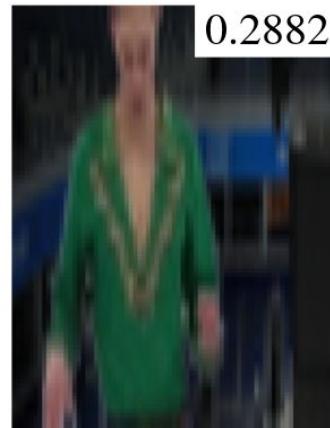
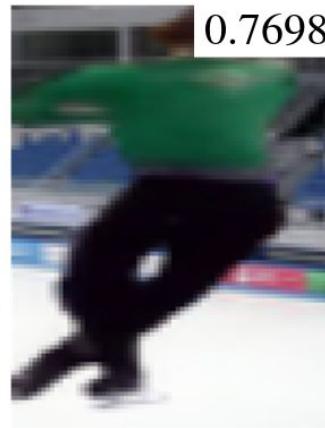
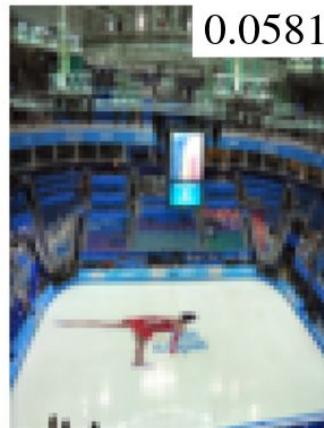
Step 2: find a box with desired intersection over union



Step 3: crop box and resize image

Proposed System Assessor

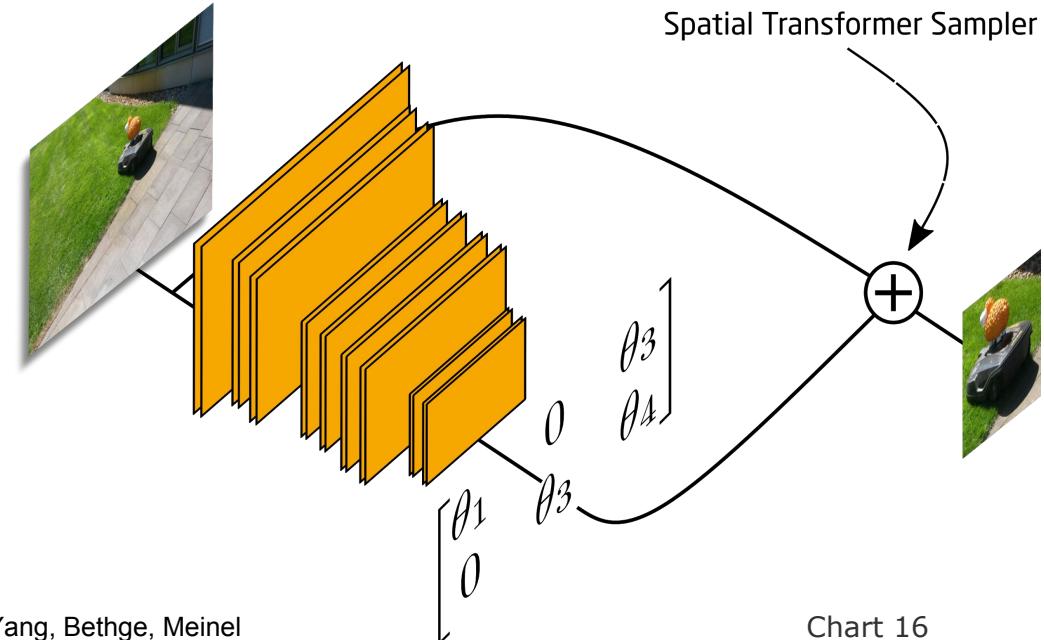
- save image and intersection over union of crop with bounding box of object



Proposed System

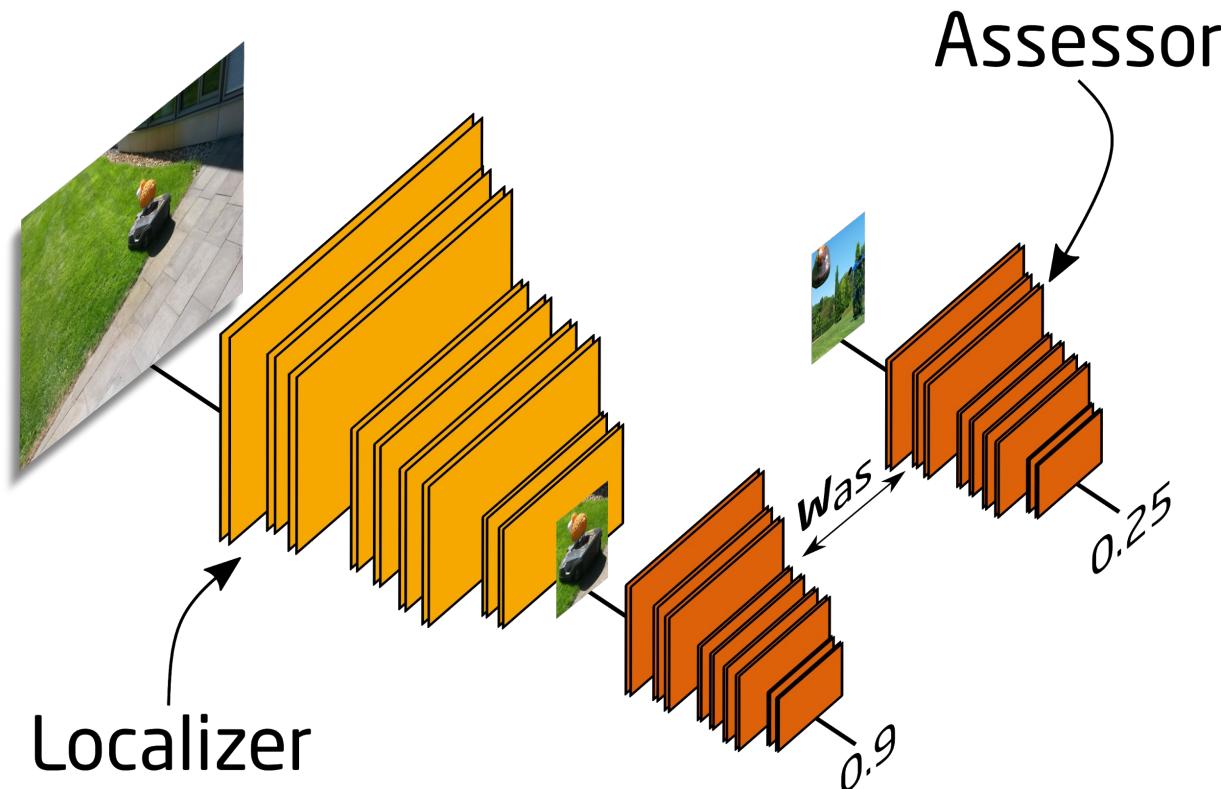
Localizer

- predict a image region that is likely to contain target object
- crop image region with a spatial transformer [Jaderberg15]
- trained on unlabeled data
- entirely supervised by assessor



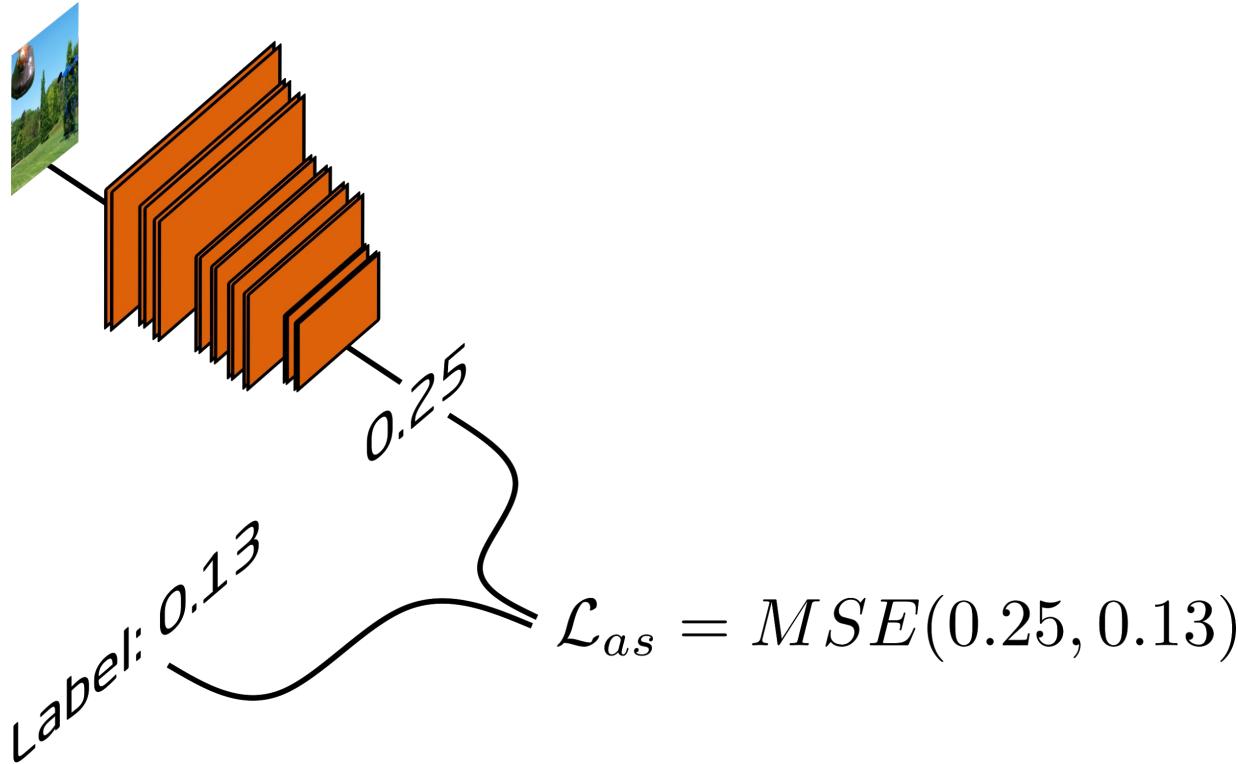
Proposed System

Training of Both Networks



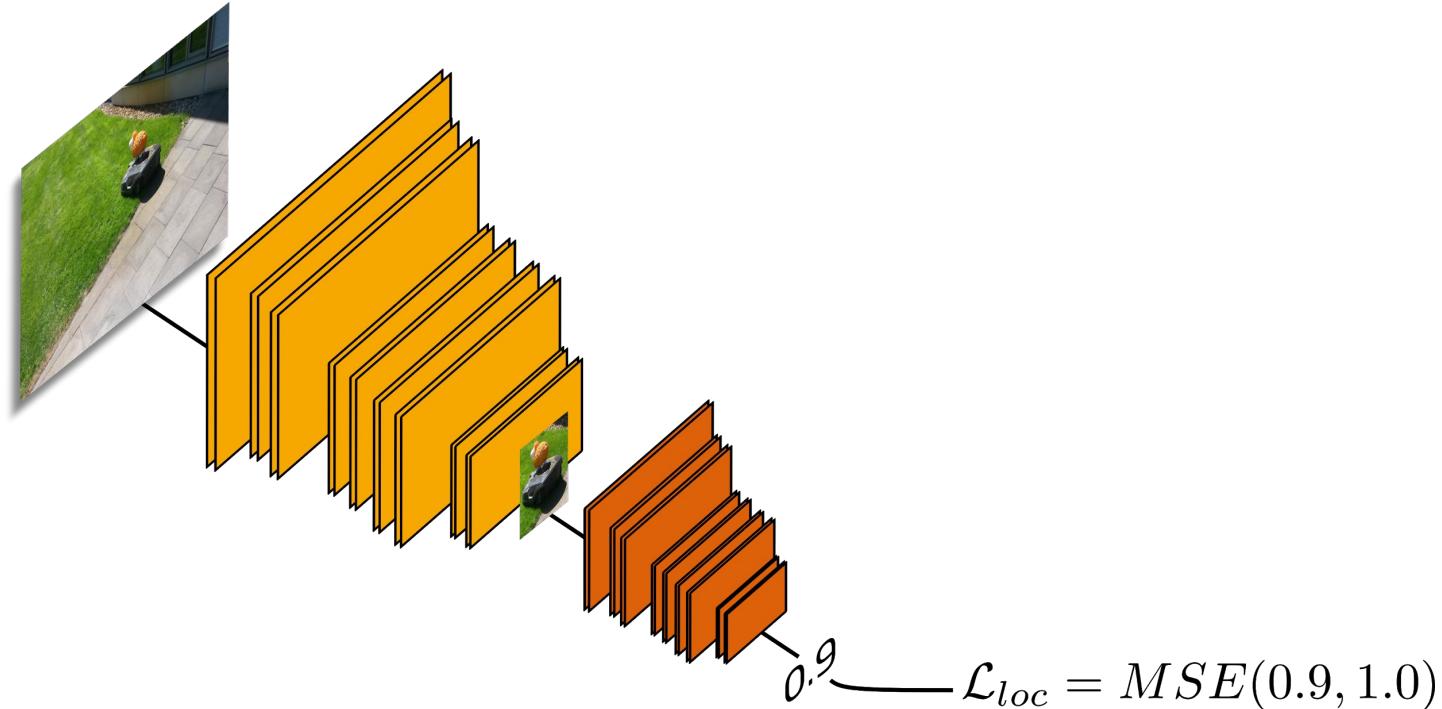
Proposed System

Training of Assessor



Proposed System

Training of Localizer

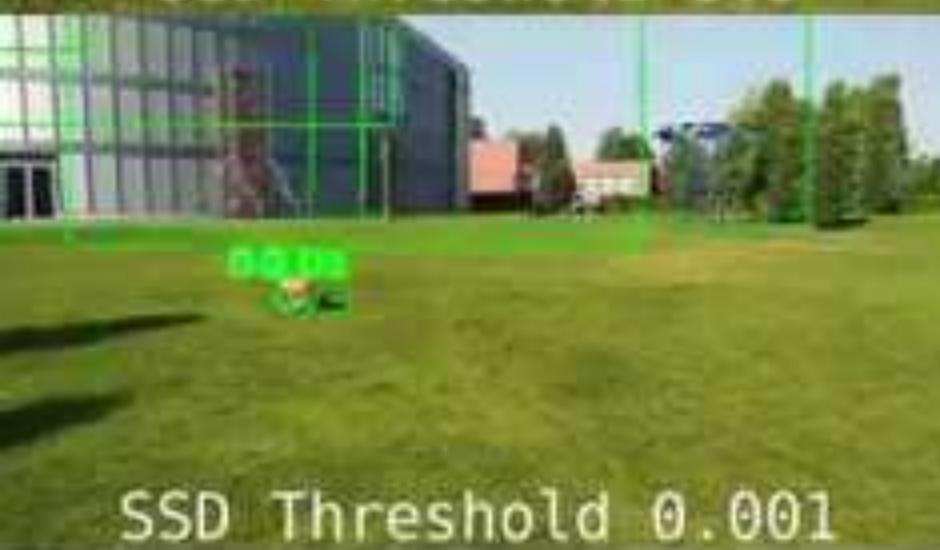


Experiments

Sheep Dataset

- 8,320 fully annotated images for training localizer
 - full annotation enables comparison to fully supervised approach
- 10,000 images for training assessor

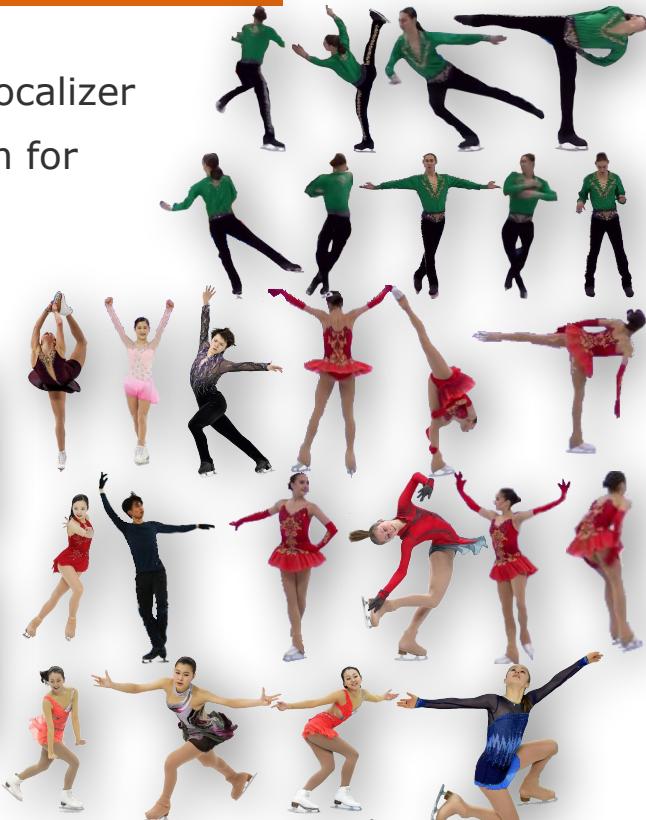
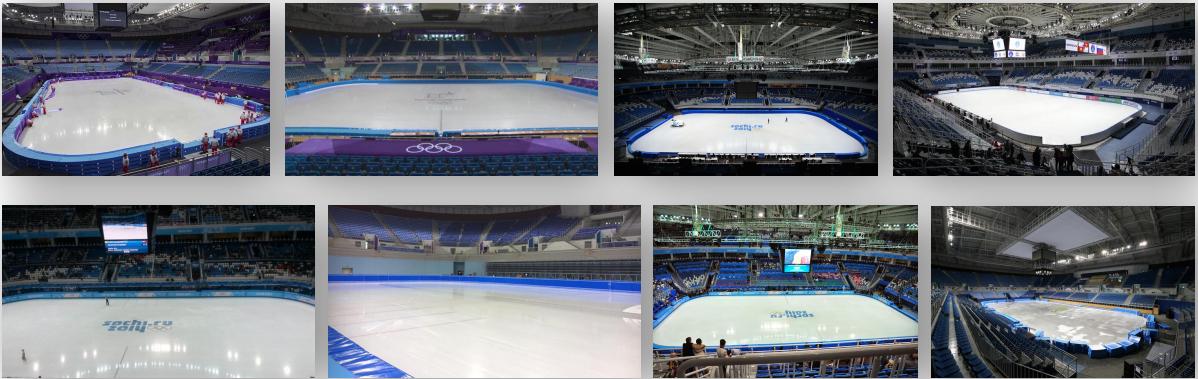
Method	224 x 224	300 x 300	512 x 512
SSD [Liu16]	-	0.887	0.969
ResNet-18	0.887	0.937	0.967
ResNet-50	0.959	0.958	0.976



Experiments

Figure Skating Dataset

- 4 YouTube videos are enough to create train dataset for localizer
- 8 background images and 25 template images are enough for generation of assessor dataset



Experiments

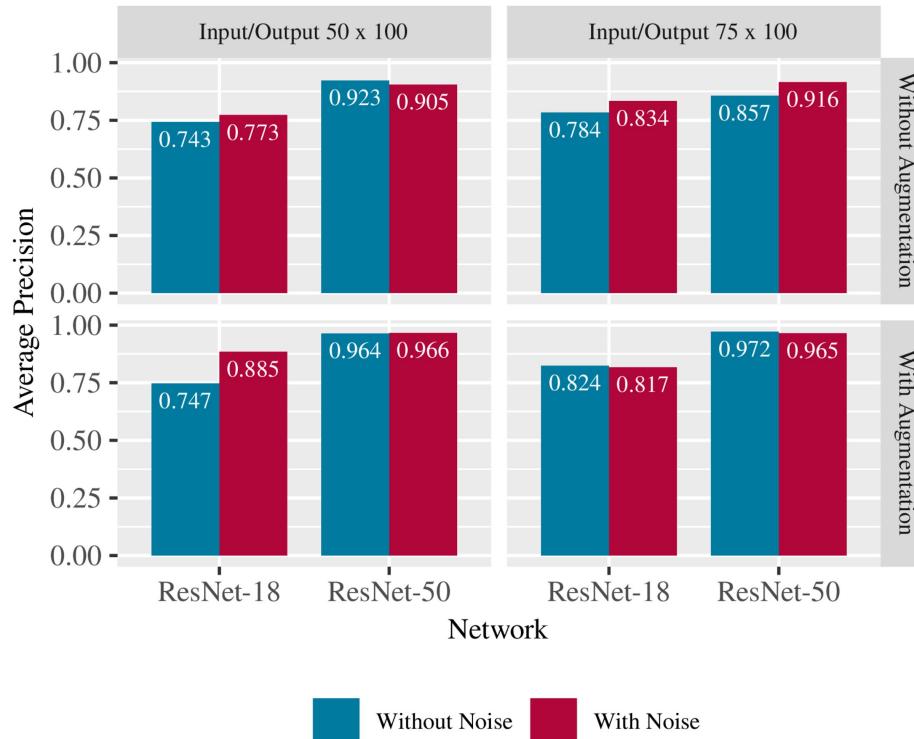
Figure Skating Dataset

- YouTube videos contain a lot of noisy images
- experimented with noisy data and without noise
 - dataset without noise only contains 48% of the number of original images



Experiments

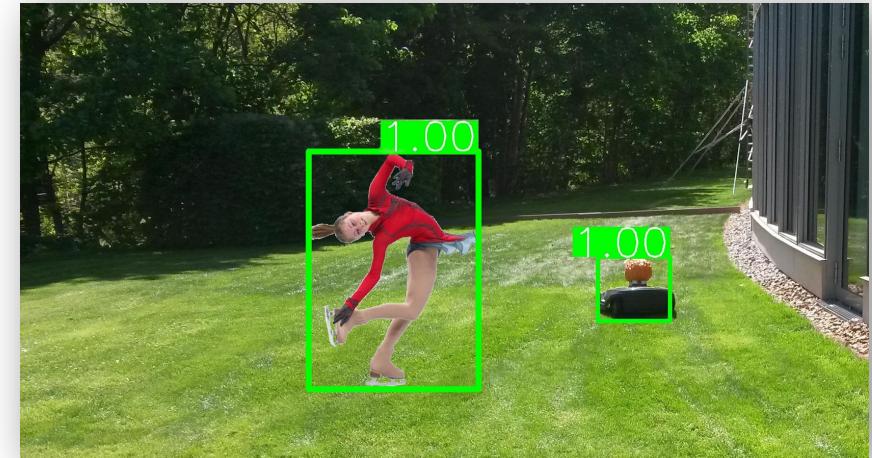
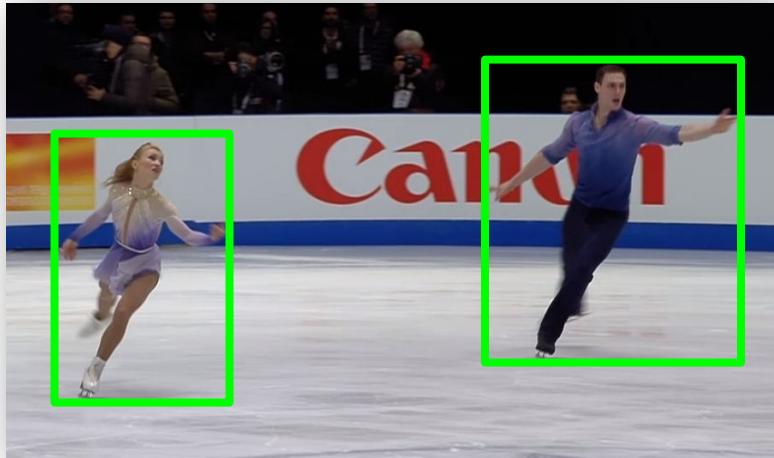
Results on Figure Skating Dataset



Limitations and Future Work

- approach only works for one class at a time
- only works with images containing a single object
- we have no means to determine whether system detected object or not

What we would like to have in the future:



Conclusion

- presented a novel approach for weakly supervised detection
- should be simple and cost efficient to create training data for specialized systems
- code, models and datasets are available online:

<https://github.com/Bartzl/loans>





Thank you for your attention



Thank you for your attention

- [Redmon16] - Redmon, Joseph, et al. "You only look once: Unified, real-time object detection." *Proceedings of the IEEE conference on computer vision and pattern recognition*. 2016.
- [Liu16] - Liu, Wei, et al. "Ssd: Single shot multibox detector." *European conference on computer vision*. Springer, Cham, 2016.
- [Ren15] - Faster R-CNN: Towards Real-Time Object Detection with Region Proposal Networks
- [Wei18] - Wei, Yunchao, et al. "TS2C: tight box mining with surrounding segmentation context for weakly supervised object detection." European Conference on Computer Vision. Springer, Cham, 2018.

- [Tang18] - Tang, Peng, et al. "Weakly supervised region proposal network and object detection." Proceedings of the European Conference on Computer Vision (ECCV). 2018.
- [Hinton15] - Hinton, Geoffrey, Oriol Vinyals, and Jeff Dean. "Distilling the Knowledge in a Neural Network." NIPS Deep Learning and Representation Learning Workshop. 2015.
- [Chen16] - Chen, Tianqi, Ian Goodfellow, and Jonathon Shlens. "Net2net: Accelerating learning via knowledge transfer." International Conference on Learning Representations. 2016.

- [Jaderberg15] - Jaderberg, Max, Karen Simonyan, and Andrew Zisserman. "Spatial transformer networks." Advances in neural information processing systems. 2015.